Topic 2: Classification

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Statistics 561



On choices

I'd rather be rich than stupid.
—Pierre-Joseph Proudhon



On having to cover classification in two lectures

I needed to think last night. So I galloped into a wooded glen, and after punch dancing out my rage and suffering an extremely long and very painful fall, I realized what has to be done.

-Rod

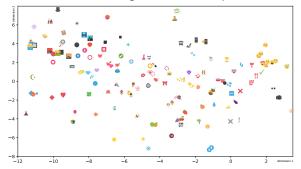


Warm-up (5 minutes)

- Explain to your group
 - ▶ What is classification? What are come canonical examples?
 - What is the separability problem?
 - What is zero-one loss?
- ► True or false
 - Regression is a misnomer in 'logistic regression'
 - Classification is in the "inner loop" of many RL algorithms
 - McDonald's is the most prevalent fast-food chain in NC

Classification: quick overview

- Input-output pairs where output is one of finitely many categories
 - High-risk v low-risk for complications in surgery
 - Spam v not spam
 - Handwritten digit recognition
- Example from sex-trafficking classification problem





Setup: binary classification

- ▶ Observe $\{(X_i, Y_i)\}_{i=1}^n$ comprising i.i.d. draws from P
 - ▶ Inputs: $\boldsymbol{X} \in \mathbb{R}^p$
 - Outputs: $Y \in \{-1,1\}$, aka, label
- ▶ Classifier $c: \mathbb{R}^p \to \{-1,1\}$ so that $c(\mathbf{x})$ is the predicted label at input $\mathbf{X} = \mathbf{x}$

0-1 loss

▶ Natural measure of classification performance is 0-1 loss

$$\ell_0(\mathbf{x}, y; c) \triangleq 1_{y \neq c(\mathbf{x})}$$

so that the expected loss (risk) is

$$\tau(c) \triangleq P\ell_0(\boldsymbol{X}, Y, c) = P1_{Y \neq c(\boldsymbol{X})} = P\{Y \neq c(\boldsymbol{X})\}$$

▶ E.g., linear classifier $c(x; \beta) = sign(X^T\beta)$ which has loss

$$\tau(\boldsymbol{\beta}) \triangleq P1_{Y \neq \operatorname{sign}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{\beta})} = P1_{Y\boldsymbol{X}^{\mathsf{T}}\boldsymbol{\beta} < 0}$$



Bayes classifier

Let \mathcal{C} be class of all (msbl) maps from \mathbb{R}^p into $\{-1,1\}$ and

$$c^{ ext{opt}} = \arg\min_{c \in \mathcal{C}} \tau(c) = \arg\min_{c \in \mathcal{C}} P\left\{Y \neq c(\boldsymbol{X})\right\}$$

then

$$c^{ ext{opt}}({m{x}}) = \left\{ egin{array}{ll} 1 & ext{if } P(Y=1|{m{X}}={m{x}}) \geq 1/2 \ -1 & ext{otherwise} \end{array}
ight.$$

i.e.,
$$c^{\mathrm{opt}}(\mathbf{x}) = \mathrm{sign} \left\{ 2q(\mathbf{x}) - 1 \right\} \text{ w} / q(\mathbf{x}) \stackrel{\triangle}{=} P(Y = 1 | \mathbf{X} = \mathbf{x})$$







Probabilistic classifiers

- Natural approach to classification is to estimate construct an estimator $\widehat{q}_n(\mathbf{x})$ of $q(\mathbf{x}) = P(Y = 1 | \mathbf{X} = \mathbf{x})$
- Logistic regression posits a model of the form

$$q(\mathbf{x}; \mathbf{\beta}^*) = \operatorname{expit}(\mathbf{x}^{\mathsf{T}} \mathbf{\beta}^*) = \frac{\operatorname{exp}(\mathbf{x}^{\mathsf{T}} \mathbf{\beta}^*)}{1 + \operatorname{exp}(\mathbf{x}^{\mathsf{T}} \mathbf{\beta}^*)}$$

Derive log-likelihood for logistic regression





In-class exercise (5 min)

► In your group derive a stochastic gradient descent algorithm for logistic regression: then on to logistic_regression.R

Separability problem

- ► If classes linearly separable estimates diverge
- ► Use ridge with logistic regression¹
- Penalized negative log-likelihood (0-1 coding for simplicity)

$$\ell_n(\boldsymbol{\beta}) = -\mathbb{P}_n\left[\boldsymbol{X}^{\mathsf{T}}\boldsymbol{\beta}\boldsymbol{Y} + \{1 - q(\boldsymbol{X}; \boldsymbol{\beta})\}\right] + \lambda||\boldsymbol{\beta}||^2$$

differentiate wrt β to obtain

$$-\mathbb{P}_n \mathbf{X} \{Y - q(\mathbf{X}; \boldsymbol{\beta})\} + 2\lambda \boldsymbol{\beta}$$

¹That's right, I'm stating this without qualification of any kind. What's it to you? That's what I thought.



Warm-up (5 min)

- ▶ What's the definition of a convex function?
- ▶ Show that if $\phi : \mathbb{R} \to \mathbb{R}$ is convex then $\beta \mapsto P\phi(YX^{\mathsf{T}}\beta)$ is convex (note: we're not assuming ϕ is differentiable)

Large-margin classifiers

- ▶ Decision boundary $\{x : q(x) = 1/2\}$
- ▶ Don't need P(Y|X = x) just sign $\{2q(x) 1\}$, i.e., we don't need to know the boundary just which side we're on
- ▶ Idea! Construct loss functions that penalize distance from correct side of boundary

Surrogate loss functions: laber draws a picture

Surrogate loss functions

- Common surrogate loss functions include
 - ► Squared error loss: $\ell(\mathbf{x}, y; \boldsymbol{\beta}) = (1 y\mathbf{x}^{\mathsf{T}}\boldsymbol{\beta})^2$
 - ► Exponential loss: $\ell(\mathbf{x}, y; \boldsymbol{\beta}) = \exp(-y\mathbf{x}^{\mathsf{T}}\boldsymbol{\beta})$
 - ► Hinge loss: $\ell(\mathbf{x}, y; \boldsymbol{\beta}) = (1 y\mathbf{x}^{\mathsf{T}}\boldsymbol{\beta})_+$
 - ► Logistic loss: $\ell(\mathbf{x}, y : \boldsymbol{\beta}) = \log \{1 + \exp(-y\mathbf{x}^{\mathsf{T}}\boldsymbol{\beta})\}$
- Can also consider penalized versions of these loss functions

Nice and relaxing derivation

▶ Show $\widehat{\boldsymbol{\beta}}_n = \arg\min_{\boldsymbol{\beta}} \mathbb{P}_n \log \{1 + \exp(-Y\boldsymbol{X}^{\mathsf{T}}\boldsymbol{\beta})\}$ recovers the logistic regression estimator



Price of using surrogates

- Pro tip: don't google "price of using surrogates," it will lead you down a fascinating (but time consuming) rabbit hole about surrogate mothers and the ethics of paying them
- ▶ We replaced the loss of interest (0-1) with a convex surrogate what are the statistical consequences?
 - ► Will we still recover Bayes classifier?
 - ► Can any surrogate be used? Are some better than others?
 - Are there any additional benefits/drawbacks of using a surrogate?

Pointwise consistency aka Fisher Consistency

- ► Idea: compare population minimizer of surrogate with minimizer of 0-1 loss, if these agree then we say that the surrogate classifier is Fisher consistent
- Note all the surrogates we considered are functions of yf(x) for some real-valued function f, e.g., in linear case $yx^{\mathsf{T}}\beta$
 - ▶ Let $f : \mathbb{R}^p \to \mathbb{R}$ be generic fn indexing $\mathbf{x} \mapsto \operatorname{sign} \{f(\mathbf{x})\}$
 - Let $\phi: \mathbb{R} \to \mathbb{R}$ denote a surrogate acting on the margin
 - Squared error loss: $\phi(\alpha) = (1 \alpha)^2$
 - **Exponential loss:** $\phi(\alpha) = \exp(-\alpha)$
 - ▶ Hinge loss: $\phi(\alpha) = (1 \alpha)_+$
 - ▶ Logistic loss: $\phi(\alpha) = \log \{1 + \exp(-\alpha)\}$



Pointwise consistency aka Fisher Consistency: defns

- ► $R(f) \triangleq P1_{Yf(X)<0}$ the misclassification error at f
- ▶ R^* the Bayes error and define excess risk at f as $R(f) R^*$
- ► $R_{\phi}(f) \triangleq P\phi \{Yf(X)\}$ to be the ϕ -risk at f
- $ightharpoonup R_\phi^* riangleq \inf_f R_\phi(f)$ and define the $\operatorname{excess} \phi$ -risk at f as $R_\phi(f) R_\phi^*$



Relating excess risks

▶ Goal is to find a function ψ such that $\psi(\tau) \to 0$ iff $\tau \to 0$ and

$$\psi\left\{R(f)-R*\right\} \leq R_{\phi}(f)-R^*$$

What does such a result buy us?

Conditional ϕ -risk

ightharpoonup Conditional ϕ -risk

$$\mathbb{E}\left[\phi\left\{\mathsf{Y} f(\boldsymbol{\mathsf{X}})\right\} \middle| \boldsymbol{\mathsf{X}} = \boldsymbol{\mathsf{x}}\right] = q(\boldsymbol{\mathsf{x}}) \phi\left\{f(\boldsymbol{\mathsf{x}})\right\} + \left\{1 - q(\boldsymbol{\mathsf{x}})\right\} \phi\left\{-f(\boldsymbol{\mathsf{x}})\right\}$$

It will be convenient to define

$$C_q(\alpha) \triangleq q\phi(\alpha) + (1-\alpha)\phi(-\alpha)$$

and

$$H(q) \triangleq \inf_{\alpha} C_q(\alpha) = \inf_{\alpha} \{q\phi(\alpha) + (1-q)\phi(-\alpha)\}$$



Conditional ϕ -risk cont'd

Practice with the notation: show that

$$R_{\phi}^* = \inf_{f} R_{\phi}(f)) = PH\left\{q(\boldsymbol{X})\right\}$$





Classification-calibration

▶ For $q \in [0,1]$ define

$$H^{-}(q) \triangleq \inf_{\alpha : \alpha(2q-1) \leq 0} C_q(\alpha)$$

to be optimal conditional ϕ -risk if you disagree with Bayes rule

lacktriangle We say that a loss function ϕ is classification calibrated if

$$H^-(q) > H(q)$$

for all $q \neq 1/2$. Thus, ϕ is CC if disagreeing with Bayes rule increases ϕ -risk.

Ex. classification-calibrated loss

▶ Show exponential loss is classification-calibrated





Bounding the excess ϕ -risk

Theorem

Let ϕ be convex. Then ϕ is classification calibrated iff it is differentiable at 0 and $\phi'(0) < 0$. Furthermore, if ϕ is classification calibrated then

$$\psi(heta) = \phi(0) - H\left(rac{1+ heta}{2}
ight)$$

satisfies

$$\psi\left\{R(f)-R^*\right\} \le R_{\phi}(f)-R_{\phi}^*,$$

where $\psi(\theta) \to 0$ iff $\theta \to 0$.

Statistical inference

- Convexity buys you a lot, many derivations much simpler
- High-level overview of assumptions
 - (A1) $\ell(\mathbf{x}, y; \boldsymbol{\beta})$ is convex in $\boldsymbol{\beta}$ for each (\mathbf{x}, y)
 - (A2) $Q(\beta) = P\ell(X, Y; \beta)$ exists and is finite for all β
 - (A3) $\boldsymbol{\beta}^* = \operatorname{arg\,min} Q(\boldsymbol{\beta})$ exists an is unique
 - (A4) $Q(\beta)$ is twice continuously differentiable in a nbrhd of β^* and $H = \nabla^2 Q(\beta^*)$ is positive definite

Theorem

Assume (A1)-(A4) and let $\Omega = P\nabla \ell(\pmb{X},Y;\pmb{\beta}^*)\nabla \ell(\pmb{X},Y;\pmb{\beta}^*)^\intercal$ then

$$\sqrt{n}(\widehat{\boldsymbol{\beta}}_n - \boldsymbol{\beta}^*) \rightsquigarrow \text{Normal}(0, H^{-1}\Omega H^{-1}).$$



Statistical inference cont'd

- Asymptotic normality \Rightarrow we can use standard methods of inference for β^* as in the regression case, e.g., Wald-type intervals etc.
- Unlike regression case, measures of performance are not well-behaved
- Recall our measures of performance
 - Population-level error: $R \triangleq P1_{YX^{\top}\beta^* < 0}$
 - ► Conditional error: $C(\widehat{\boldsymbol{\beta}}_n) \triangleq P1_{Y\boldsymbol{X}^{\mathsf{T}}\widehat{\boldsymbol{\beta}}_n < 0}$
 - Average error: $A_n \triangleq \mathbb{E}C(\widehat{\beta}_n)$



Comparing measures of performance

► Fact: the three measures of performance need not coincide even in infinite samples





Potpourri: local linear models

- ► Let $K_{\sigma}: \mathbb{R}^{p} \times \mathbb{R}^{p} \to \mathbb{R}_{+}$ be a kernel fn, e.g., $K_{\sigma}(\mathbf{x}, \mathbf{x}') = \exp\left\{-||\mathbf{x} \mathbf{x}'||^{2}/\sigma^{2}\right\}$
- Local linear model: estimate coefficient fn $\widehat{\beta}_n(\mathbf{x})$ for each \mathbf{x} via

$$\widehat{\boldsymbol{\beta}}_n(\boldsymbol{x}) = \arg\min_{\boldsymbol{\beta}} \mathbb{P}_n (Y - \boldsymbol{X}^{\mathsf{T}} \boldsymbol{\beta})^2 \, K_{\sigma}(\boldsymbol{X}, \boldsymbol{x}),$$

tune σ using CV etc.

- Natural (and easy!) extension of linear model
- Studying coeff fn can generate insights about how the mean of Y changes in different regions of the input space (but this is not trivial if p is large)

Potpourri: local large-margin classifiers

Let K_{σ} be a kernel and ϕ a surrogate loss function, define

$$\widehat{m{eta}}_n(m{x}) = rg \min_{m{eta}} \mathbb{P}_n \phi(Ym{X}^{\intercal}m{eta}) K_{\sigma}(m{X},m{x})$$

► E.g., local logistic regression with ridge penalty

$$\widehat{\boldsymbol{\beta}}_n^{\lambda}(\boldsymbol{x}) = \arg\min_{\boldsymbol{\beta}} \mathbb{P}_n \log \left\{ 1 + \exp(-YX^{\mathsf{T}}\boldsymbol{\beta}) \right\} K_{\sigma}(\boldsymbol{X}, \boldsymbol{x}) + \lambda ||\boldsymbol{\beta}||^2$$

Potpourri: trees

- Canonical local model: classification and regression trees
- laber draws a tree:

► Tree is an additive model with form $f(\mathbf{x}) = \sum_{m=1}^{M} \beta_m 1_{\mathbf{x} \in R_m}$

where R_1, \ldots, R_M partition the input space



Potpourri: trees cont'd

Note that if regions R_1, \ldots, R_m were given and Y were continuous then

$$\widehat{\boldsymbol{\beta}}_n = \arg\min_{\boldsymbol{\beta} \in \mathbb{R}^M} \mathbb{P}_n \left\{ Y - \mathcal{I}(\boldsymbol{X})^{\mathsf{T}} \boldsymbol{\beta} \right\}^2,$$

where
$$\mathcal{I}(\mathbf{x}) = (1_{\mathbf{x} \in R_1}, \dots, 1_{\mathbf{x} \in R_M})^{\mathsf{T}}$$
 and $\widehat{\beta}_j = \mathbb{P}_n Y 1_{\mathbf{X} \in R_j} / \mathbb{P}_n 1_{\mathbf{X} \in R_j}$

▶ Note that this is a local constant model with

$$\widehat{\beta}_n(\mathbf{x}) = \arg\min_{\beta} \mathbb{P}_n(Y - \beta)^2 K_{\sigma}(\mathbf{X}, \mathbf{x})$$

and
$$K_{\sigma}(\mathbf{x},\mathbf{x}')=1_{\mathbf{x},\mathbf{x}'\in R_{i}}$$
, for some j



Potpourri: trees cont'd

- Estimating optimal partition R_1, \ldots, R_M generally combinatorially hard
- Two approaches:
 - ▶ A1: restrict regions to rectangles and optimize greedily
 - ► A2: randomly generate a bunch of (overlapping) regions aka tile coding

Potpourri notes: greedy optimization

Potpourri notes: tile coding

Thank you.

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