week3_task1_first_cnn_cifar10_clean

January 3, 2021

1 Your first CNN on CIFAR-10

In this task you will: * define your first CNN architecture for CIFAR-10 dataset * train it from scratch * visualize learnt filters

CIFAR-10 dataset contains 32x32 color images from 10 classes: **airplane**, **automobile**, **bird**, **cat**, **deer**, **dog**, frog, horse, ship, truck:

2 Import stuff

1.2.1 2.0.6

```
In [3]: import sys
        sys.path.append("..")
        import grading
        import download_utils
In []: #!!! remember to clear session/graph if you rebuild your graph to avoid out-of-memory
In [2]: download_utils.link_all_keras_resources()
In [4]: import tensorflow as tf
        import keras
        from keras import backend as K
        import numpy as np
        %matplotlib inline
        import matplotlib.pyplot as plt
        print(tf.__version__)
        print(keras.__version__)
        import grading_utils
        import keras_utils
        from keras_utils import reset_tf_session
Using TensorFlow backend.
```

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```
In [5]: grader = grading.Grader(assignment_key="s1B1I5DuEeeyLAqI7dCYkg",
                               all_parts=["7W4tu", "nQOsg", "96eco"])
In [6]: # token expires every 30 min
       COURSERA_TOKEN = '5xddopyBxSg6v513' ### YOUR TOKEN HERE
       COURSERA_EMAIL = 'knowtech94@gmail.com' ### YOUR EMAIL HERE
```

Load dataset

```
In [20]: from keras.datasets import cifar10
         (x_train, y_train), (x_test, y_test) = cifar10.load_data()
Downloading data from http://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
169803776/170498071 [=============>.] - ETA: Os
In [21]: print("Train samples:", x_train.shape, y_train.shape)
        print("Test samples:", x_test.shape, y_test.shape)
Train samples: (50000, 32, 32, 3) (50000, 1)
Test samples: (10000, 32, 32, 3) (10000, 1)
In [22]: NUM_CLASSES = 10
        cifar10_classes = ["airplane", "automobile", "bird", "cat", "deer",
                           "dog", "frog", "horse", "ship", "truck"]
In [23]: # show random images from train
        cols = 8
        rows = 2
        fig = plt.figure(figsize=(2 * cols - 1, 2.5 * rows - 1))
        for i in range(cols):
            for j in range(rows):
                 random_index = np.random.randint(0, len(y_train))
                 ax = fig.add_subplot(rows, cols, i * rows + j + 1)
                 ax.grid('off')
                 ax.axis('off')
                 ax.imshow(x_train[random_index, :])
                 ax.set_title(cifar10_classes[y_train[random_index, 0]])
        plt.show()
```



5 Prepare data

We need to normalize inputs like this:

$$x_{norm} = \frac{x}{255} - 0.5$$

We need to convert class labels to one-hot encoded vectors. Use **keras.utils.to_categorical**.

6 Define CNN architecture

Convolutional networks are built from several types of layers: - Conv2D - performs convolution: - filters: number of output channels; - kernel_size: an integer or tuple/list of 2 integers, specifying the width and height of the 2D convolution window; - padding: padding="same" adds zero padding to the input, so that the output has the same width and height, padding='valid' performs convolution only in locations where kernel and the input fully overlap; - activation: "relu", "tanh", etc. - input_shape: shape of input. - MaxPooling2D - performs 2D max pooling. - Flatten - flattens the input, does not affect the batch size. - Dense - fully-connected layer. - Activation - applies an activation function. - LeakyReLU - applies leaky relu activation. - Dropout - applies dropout.

You need to define a model which takes (None, 32, 32, 3) input and predicts (None, 10) output with probabilities for all classes. None in shapes stands for batch dimension.

Simple feed-forward networks in Keras can be defined in the following way:

```
model = Sequential() # start feed-forward model definition
model.add(Conv2D(..., input_shape=(32, 32, 3))) # first layer needs to define "input_shape"
... # here comes a bunch of convolutional, pooling and dropout layers
model.add(Dense(NUM_CLASSES)) # the last layer with neuron for each class
model.add(Activation("softmax")) # output probabilities
```

Stack 4 convolutional layers with kernel size (3, 3) with growing number of filters (16, 32, 32, 64), use "same" padding.

Add 2x2 pooling layer after every 2 convolutional layers (conv-conv-pool scheme).

Use **LeakyReLU** activation with recommended parameter **0.1** for all layers that need it (after convolutional and dense layers):

```
model.add(LeakyReLU(0.1))
```

Add a dense layer with 256 neurons and a second dense layer with 10 neurons for classes. Remember to use Flatten layer before first dense layer to reshape input volume into a flat vector! Add Dropout after every pooling layer (0.25) and between dense layers (0.5).

```
In [31]: def make_model():
             Define your model architecture here.
             Returns `Sequential` model.
             model = Sequential()
             ### YOUR CODE HERE
             model.add(Conv2D(filters = 16, kernel_size = (3, 3), padding = 'same',
                                 input_shape = (32, 32, 3)))
             model.add(LeakyReLU(0.1))
             model.add(Conv2D(filters = 32, kernel_size = (3, 3), padding = 'same'))
             model.add(LeakyReLU(0.1))
             model.add(MaxPooling2D(pool_size = (2, 2)))
             model.add(Dropout(rate = 0.25))
             ##
             model.add(Conv2D(filters = 32, kernel_size = (3, 3), padding = 'same'))
             model.add(LeakyReLU(0.1))
             model.add(Conv2D(filters = 64, kernel_size = (3, 3), padding = 'same'))
             model.add(LeakyReLU(0.1))
             model.add(MaxPooling2D(pool_size = (2, 2)))
             model.add(Dropout(rate = 0.25))
             model.add(Flatten())
             model.add(Dense(units = 256))
             model.add(LeakyReLU(0.1))
             model.add(Dropout(rate = 0.5))
             model.add(Dense(units = NUM_CLASSES))
```

model.add(Activation('softmax'))
return model

In [32]: # describe model
 s = reset_tf_session() # clear default graph
 model = make_model()
 model.summary()

Layer (type)	Output	Shape	 Param #
conv2d_1 (Conv2D)	(None,	32, 32, 16)	448
leaky_re_lu_1 (LeakyReLU)	(None,	32, 32, 16)	0
conv2d_2 (Conv2D)	(None,	32, 32, 32)	4640
leaky_re_lu_2 (LeakyReLU)	(None,	32, 32, 32)	0
max_pooling2d_1 (MaxPooling2	(None,	16, 16, 32)	0
dropout_1 (Dropout)	(None,	16, 16, 32)	0
conv2d_3 (Conv2D)	(None,	16, 16, 32)	9248
leaky_re_lu_3 (LeakyReLU)	(None,	16, 16, 32)	0
conv2d_4 (Conv2D)	(None,	16, 16, 64)	18496
leaky_re_lu_4 (LeakyReLU)	(None,	16, 16, 64)	0
max_pooling2d_2 (MaxPooling2	(None,	8, 8, 64)	0
dropout_2 (Dropout)	(None,	8, 8, 64)	0
flatten_1 (Flatten)	(None,	4096)	0
dense_1 (Dense)	(None,	256)	1048832
leaky_re_lu_5 (LeakyReLU)	(None,	256)	0
dropout_3 (Dropout)	(None,	256)	0
dense_2 (Dense)	(None,	10)	2570
activation_1 (Activation)	 (None,	10)	0
Total params: 1,084,234			

7 Train model

Training of your model can take approx. 4-8 minutes per epoch.

During training you should observe the decrease in reported loss on training and validation. If the loss on training is not decreasing with epochs you should revise your model definition

If the loss on training is not decreasing with epochs you should revise your model definition and learning rate.

```
In [18]: INIT_LR = 5e-3 # initial learning rate
        BATCH_SIZE = 32
        EPOCHS = 10
         s = reset_tf_session() # clear default graph
         # don't call K.set_learning_phase() !!! (otherwise will enable dropout in train/test sa
        model = make_model() # define our model
         # prepare model for fitting (loss, optimizer, etc)
        model.compile(
             loss='categorical_crossentropy', # we train 10-way classification
             optimizer=keras.optimizers.adamax(lr=INIT_LR), # for SGD
             metrics=['accuracy'] # report accuracy during training
         )
         # scheduler of learning rate (decay with epochs)
         def lr_scheduler(epoch):
             return INIT_LR * 0.9 ** epoch
         # callback for printing of actual learning rate used by optimizer
         class LrHistory(keras.callbacks.Callback):
             def on_epoch_begin(self, epoch, logs={}):
                 print("Learning rate:", K.get_value(model.optimizer.lr))
```

Training takes approximately **1.5 hours**. You're aiming for ~0.80 validation accuracy.

```
In [19]: # we will save model checkpoints to continue training in case of kernel death
        model_filename = 'cifar.{0:03d}.hdf5'
         last_finished_epoch = None
         #### uncomment below to continue training from model checkpoint
         #### fill `last_finished_epoch` with your latest finished epoch
         # from keras.models import load_model
         # s = reset_tf_session()
         # last_finished_epoch = 7
         # model = load_model(model_filename.format(last_finished_epoch))
In [20]: # fit model
        model.fit(
             x_train2, y_train2, # prepared data
             batch_size=BATCH_SIZE,
             epochs=EPOCHS,
             callbacks=[keras.callbacks.LearningRateScheduler(lr_scheduler),
                        LrHistory(),
                        keras_utils.TqdmProgressCallback(),
                        keras_utils.ModelSaveCallback(model_filename)],
             validation_data=(x_test2, y_test2),
             shuffle=True,
             verbose=0,
             initial_epoch=last_finished_epoch or 0
         )
Learning rate: 0.005
Epoch 1/10
A Jupyter Widget
50000/|/loss: 1.3324; acc: 0.5227: 100%|| 50000/50000 [11:02<00:00, 82.03it/s]
Model saved in cifar.000.hdf5
Learning rate: 0.0045
Epoch 2/10
A Jupyter Widget
50000/|/loss: 0.9377; acc: 0.6698: 100%|| 50000/50000 [11:23<00:00, 74.41it/s]
Model saved in cifar.001.hdf5
Learning rate: 0.00405
Epoch 3/10
```

A Jupyter Widget

50000/|/loss: 0.8120; acc: 0.7154: 100%|| 50000/50000 [11:12<00:00, 79.76it/s]

 ${\tt Model \ saved \ in \ cifar.002.hdf5}$

Learning rate: 0.003645

Epoch 4/10

A Jupyter Widget

50000/|/loss: 0.7241; acc: 0.7451: 100%|| 50000/50000 [11:02<00:00, 77.60it/s]

Model saved in cifar.003.hdf5 Learning rate: 0.0032805

Epoch 5/10

A Jupyter Widget

50000/|/loss: 0.6679; acc: 0.7659: 100%|| 50000/50000 [11:02<00:00, 74.98it/s]

Model saved in cifar.004.hdf5 Learning rate: 0.00295245

Epoch 6/10

A Jupyter Widget

50000/|/loss: 0.6161; acc: 0.7829: 100%|| 50000/50000 [11:02<00:00, 75.73it/s]

Model saved in cifar.005.hdf5 Learning rate: 0.00265721

Epoch 7/10

A Jupyter Widget

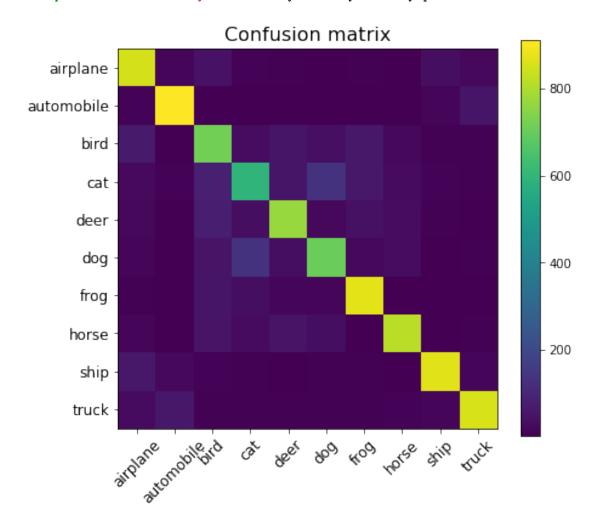
50000/|/loss: 0.5805; acc: 0.7950: 100%|| 50000/50000 [10:52<00:00, 79.73it/s]

Model saved in cifar.006.hdf5 Learning rate: 0.00239148

Epoch 8/10

```
A Jupyter Widget
50000/|/loss: 0.5393; acc: 0.8115: 100%|| 50000/50000 [10:41<00:00, 68.31it/s]
Model saved in cifar.007.hdf5
Learning rate: 0.00215234
Epoch 9/10
A Jupyter Widget
50000/|/loss: 0.5124; acc: 0.8184: 100%|| 50000/50000 [11:02<00:00, 78.27it/s]
Model saved in cifar.008.hdf5
Learning rate: 0.0019371
Epoch 10/10
A Jupyter Widget
50000/|/loss: 0.4831; acc: 0.8284: 100%|| 50000/50000 [11:22<00:00, 66.30it/s]
Model saved in cifar.009.hdf5
Out[20]: <keras.callbacks.History at 0x7f5580304278>
In [21]: # save weights to file
        model.save_weights("weights.h5")
In [35]: # load weights from file (can call without model.fit)
        model.load_weights("weights.h5")
  Evaluate model
8
In [36]: # make test predictions
        y_pred_test = model.predict_proba(x_test2)
        y_pred_test_classes = np.argmax(y_pred_test, axis=1)
        y_pred_test_max_probas = np.max(y_pred_test, axis=1)
10000/10000 [========== - 41s
In [37]: # confusion matrix and accuracy
        from sklearn.metrics import confusion_matrix, accuracy_score
        plt.figure(figsize=(7, 6))
        plt.title('Confusion matrix', fontsize=16)
```

```
plt.imshow(confusion_matrix(y_test, y_pred_test_classes))
plt.xticks(np.arange(10), cifar10_classes, rotation=45, fontsize=12)
plt.yticks(np.arange(10), cifar10_classes, fontsize=12)
plt.colorbar()
plt.show()
print("Test accuracy:", accuracy_score(y_test, y_pred_test_classes))
```



Test accuracy: 0.7967

Submitted to Coursera platform. See results on assignment page!

```
In [29]: # inspect preditions
            cols = 8
            rows = 2
            fig = plt.figure(figsize=(2 * cols - 1, 3 * rows - 1))
            for i in range(cols):
                 for j in range(rows):
                       random_index = np.random.randint(0, len(y_test))
                      ax = fig.add_subplot(rows, cols, i * rows + j + 1)
                      ax.grid('off')
                      ax.axis('off')
                      ax.imshow(x_test[random_index, :])
                      pred_label = cifar10_classes[y_pred_test_classes[random_index]]
                      pred_proba = y_pred_test_max_probas[random_index]
                      true_label = cifar10_classes[y_test[random_index, 0]]
                      ax.set_title("pred: {}\nscore: {:.3}\ntrue: {}".format(
                                pred_label, pred_proba, true_label
                      ))
            plt.show()
          pred: deer
                                              pred: truck
                                                                     pred: automobile
                      pred: horse
                                   pred: cat
                                                           pred: frog
                                                                                    pred: bird
                                                                                                pred: frog
         score: 0.961
                      score: 0.912
                                  score: 0.352
                                              score: 0.999
                                                          score: 0.698
                                                                       score: 0.93
                                                                                   score: 0.999
                                                                                               score: 0.999
          true deer
                      true: horse
                                   true: frog
                                               true: truck
                                                           true: frog
                                                                     true: automobile
                                                                                    true: bird
                                                                                                true: frog
        pred: airplane
                                   pred: frog
                                              pred: truck
                                                          pred: horse
                                                                                    pred: ship
                                                           score: 0.484
          score: 0.96
                      score: 0.85
                                  score: 0.897
                                              score: 0.653
                                                                       score: 0.862
                                                                                   score: 0.491
                                                                                                .
score: 0.998
                      true: frog
         true: airplane
                                   true: frog
                                              true: truck
                                                         true: automobile
                                                                       true: deer
                                                                                  true: airplane
                                                                                                true: truck
```

9 Visualize maximum stimuli

We want to find input images that provide maximum activations for particular layers of our network.

We will find those maximum stimuli via gradient ascent in image space.

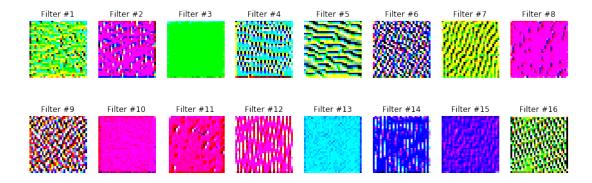
For that task we load our model weights, calculate the layer output gradient with respect to image input and shift input image in that direction.

```
In [15]: s = reset_tf_session() # clear default graph
    K.set_learning_phase(0) # disable dropout
    model = make_model()
    model.load_weights("weights.h5") # that were saved after model.fit
```

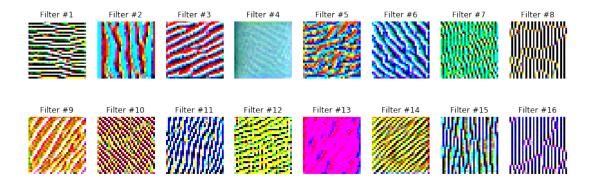
Layer (type)	Output	Shape	 Param #
conv2d_1 (Conv2D)	(None,	32, 32, 16)	448
leaky_re_lu_1 (LeakyReLU)	(None,	32, 32, 16)	0
conv2d_2 (Conv2D)	(None,	32, 32, 32)	4640
leaky_re_lu_2 (LeakyReLU)	(None,	32, 32, 32)	0
max_pooling2d_1 (MaxPooling2	(None,	16, 16, 32)	0
dropout_1 (Dropout)	(None,	16, 16, 32)	0
conv2d_3 (Conv2D)	(None,	16, 16, 32)	9248
leaky_re_lu_3 (LeakyReLU)	(None,	16, 16, 32)	0
conv2d_4 (Conv2D)	(None,	16, 16, 64)	18496
leaky_re_lu_4 (LeakyReLU)	(None,	16, 16, 64)	0
max_pooling2d_2 (MaxPooling2	(None,	8, 8, 64)	0
dropout_2 (Dropout)	(None,	8, 8, 64)	0
flatten_1 (Flatten)	(None,	4096)	0
dense_1 (Dense)	(None,	256)	1048832
leaky_re_lu_5 (LeakyReLU)	(None,	256)	0
dropout_3 (Dropout)	(None,	256)	0
dense_2 (Dense)	(None,	10)	2570
activation_1 (Activation)			0
Total params: 1,084,234 Trainable params: 1,084,234 Non-trainable params: 0	==:		== = =

```
def image_values_to_rgb(x):
    # normalize x: center on 0 (np.mean(x\_train2)), ensure std is 0.25 (np.std(x\_train2))
    # so that it looks like a normalized image input for our network
    x = (x - np.mean(x_train2))/np.std(x_train2)
                                                    ### YOUR CODE HERE
    # do reverse normalization to RGB values: x = (x_norm + 0.5) * 255
    x = (x + 0.5) * 255
                           ### YOUR CODE HERE
    # clip values to [0, 255] and convert to bytes
    x = np.clip(x, 0, 255).astype('uint8')
    return x
# this is the placeholder for the input image
input_img = model.input
img_width, img_height = input_img.shape.as_list()[1:3]
# find the layer output by name
layer_output = list(filter(lambda x: x.name == layer_name, model.layers))[0].output
# we build a loss function that maximizes the activation
# of the filter_index filter of the layer considered
if is_conv:
    # mean over feature map values for convolutional layer
   loss = K.mean(layer_output[:, :, :, filter_index])
else:
    loss = K.mean(layer_output[:, filter_index])
# we compute the gradient of the loss wrt input image
grads = K.gradients(loss, input_img)[0] # [0] because of the batch dimension!
# normalization trick: we normalize the gradient
grads = grads / (K.sqrt(K.sum(K.square(grads))) + 1e-10)
# this function returns the loss and grads given the input picture
iterate = K.function([input_img], [loss, grads])
# we start from a gray image with some random noise
input_img_data = np.random.random((1, img_width, img_height, 3))
input_img_data = (input_img_data - 0.5) * (0.1 if is_conv else 0.001)
# we run gradient ascent
for i in range(iterations):
    loss_value, grads_value = iterate([input_img_data])
    input_img_data += grads_value * step
        print('Current loss value:', loss_value)
```

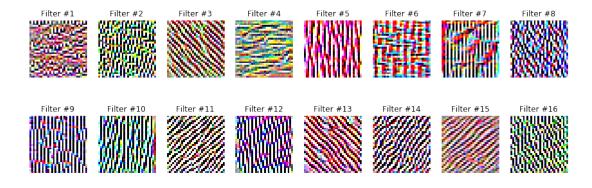
```
# decode the resulting input image
             img = image_values_to_rgb(input_img_data[0])
             return img, loss_value
In [25]: # sample maximum stimuli
         def plot_filters_stimuli(layer_name, is_conv, model, iterations=20, step=1., verbose=Fa
             cols = 8
             rows = 2
             filter_index = 0
             max_filter_index = list(filter(lambda x: x.name == layer_name, model.layers))[0].ou
             fig = plt.figure(figsize=(2 * cols - 1, 3 * rows - 1))
             for i in range(cols):
                 for j in range(rows):
                     if filter_index <= max_filter_index:</pre>
                         ax = fig.add_subplot(rows, cols, i * rows + j + 1)
                         ax.grid('off')
                         ax.axis('off')
                         loss = -1e20
                         while loss < 0 and filter_index <= max_filter_index:</pre>
                             stimuli, loss = find_maximum_stimuli(layer_name, is_conv, filter_in
                                                                    iterations, step, verbose=verb
                             filter_index += 1
                         if loss > 0:
                             ax.imshow(stimuli)
                             ax.set_title("Filter #{}".format(filter_index))
             plt.show()
In [26]: # maximum stimuli for convolutional neurons
         conv_activation_layers = []
         for layer in model.layers:
             if isinstance(layer, LeakyReLU):
                 prev_layer = layer.inbound_nodes[0].inbound_layers[0]
                 if isinstance(prev_layer, Conv2D):
                     conv_activation_layers.append(layer)
         for layer in conv_activation_layers:
             print(layer.name)
             plot_filters_stimuli(layer_name=layer.name, is_conv=True, model=model)
leaky_re_lu_1
```



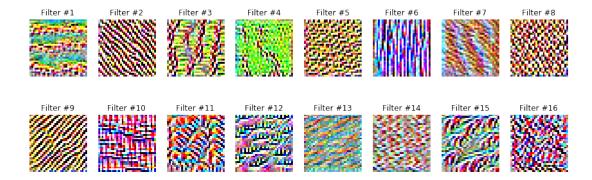
leaky_re_lu_2



leaky_re_lu_3



leaky_re_lu_4





That's it! Congratulations!

What you've done: - defined CNN architecture - trained your model - evaluated your model - visualised learnt filters