```
1 # set tf 1.x for colab
2 %tensorflow_version 1.x
```

### Generating human faces with Adversarial Networks



This time we'll train a neural net to generate plausible human faces in all their subtlty: appearance, expression, accessories, etc. 'Cuz when us machines gonna take over Earth, there won't be any more faces left. We want to preserve this data for future iterations. Yikes...

Based on <a href="https://github.com/Lasagne/Recipes/pull/94">https://github.com/Lasagne/Recipes/pull/94</a> .

# Running on Google Colab

3 import numpy as np

```
1 ! shred -u setup_google_colab.py
2 ! wget https://raw.githubusercontent.com/hse-aml/intro-to-dl/master/setup_google_colab
3 import setup_google_colab
4 setup_google_colab.setup_week4()
   --2021-02-02 23:16:25-- https://raw.githubusercontent.com/hse-aml/intro-to-dl/master
   Resolving raw.githubusercontent.com (raw.githubusercontent.com)... 151.101.0.133, 151
   Connecting to raw.githubusercontent.com (raw.githubusercontent.com)|151.101.0.133|:44
   HTTP request sent, awaiting response... 200 OK
   Length: 3636 (3.6K) [text/plain]
   Saving to: 'setup_google_colab.py'
   setup_google_colab. 100%[============>] 3.55K --.-KB/s
                                                                      in 0s
   2021-02-02 23:16:26 (64.3 MB/s) - 'setup_google_colab.py' saved [3636/3636]
   lfw-deepfunneled.tgz
   lfw.tgz
   lfw_attributes.txt
1 import sys
2 sys.path.append("..")
3 import grading
4 import download utils
5 import tqdm_utils
1 download utils.link week 4 resources()
1 import matplotlib.pyplot as plt
2 %matplotlib inline
```

```
4 plt.rcParams.update({'axes.titlesize': 'small'})
5
6 from sklearn.datasets import load_digits
7 #The following line fetches you two datasets: images, usable for autoencoder training a
8 #Those attributes will be required for the final part of the assignment (applying smile
9 from lfw_dataset import load_lfw_dataset
10 data,attrs = load_lfw_dataset(dimx=36,dimy=36)
11
12 #preprocess faces
13 data = np.float32(data)/255.
14
15 IMG_SHAPE = data.shape[1:]
```

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

```
1 #print random image
2 plt.imshow(data[np.random.randint(data.shape[0])], cmap="gray", interpolation="none")
```



# Generative adversarial nets 101

\_© torch.github.io\_

Deep learning is simple, isn't it?

- build some network that generates the face (small image)
- make up a measure of how good that face is
- optimize with gradient descent :)

The only problem is: how can we engineers tell well-generated faces from bad? And i bet you we won't ask a designer for help.

If we can't tell good faces from bad, we delegate it to yet another neural network!

That makes the two of them:

• Generator - takes random noize for inspiration and tries to generate a face sample.

- Let's call him **G**(z), where z is a gaussian noize.
- Discriminator takes a face sample and tries to tell if it's great or fake.
  - Predicts the probability of input image being a real face
  - $\circ$  Let's call him **D**(x), x being an image.

2 from keras\_utils import reset\_tf\_session

1 import tensorflow as tf

 $\circ$  **D(x)** is a predition for real image and **D(G(z))** is prediction for the face made by generator.

Before we dive into training them, let's construct the two networks.

```
3 s = reset_tf_session()
 5 import keras
 6 from keras.models import Sequential
 7 from keras import layers as L
    Using TensorFlow backend.
    WARNING:tensorflow:From /content/keras_utils.py:68: The name tf.get_default_session i
    WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
    WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
    WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
    WARNING:tensorflow:From /content/keras_utils.py:75: The name tf.ConfigProto is deprec
    WARNING:tensorflow:From /content/keras_utils.py:77: The name tf.InteractiveSession is
                                                                                         ▶
 1 \text{ CODE SIZE} = 256
 3 generator = Sequential()
 4 generator.add(L.InputLayer([CODE_SIZE],name='noise'))
 5 generator.add(L.Dense(10*8*8, activation='elu'))
 6
 7 generator.add(L.Reshape((8,8,10)))
 8 generator.add(L.Deconv2D(64,kernel_size=(5,5),activation='elu'))
 9 generator.add(L.Deconv2D(64,kernel_size=(5,5),activation='elu'))
10 generator.add(L.UpSampling2D(size=(2,2)))
11 generator.add(L.Deconv2D(32,kernel_size=3,activation='elu'))
12 generator.add(L.Deconv2D(32,kernel_size=3,activation='elu'))
13 generator.add(L.Deconv2D(32,kernel size=3,activation='elu'))
14
15 generator.add(L.Conv2D(3,kernel_size=3,activation=None))
16
    WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
     WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
```

#### 1 generator.summary()

| Layer (type)                 | Output | Shape          | Param #        |
|------------------------------|--------|----------------|----------------|
| noise (InputLayer)           | (None, | 256)           | 0              |
| dense_1 (Dense)              | (None, | 640)           | 164480         |
| reshape_1 (Reshape)          | (None, | 8, 8, 10)      | 0              |
| conv2d_transpose_1 (Conv2DTr | (None, | 12, 12, 64)    | 16064          |
| conv2d_transpose_2 (Conv2DTr | (None, | 16, 16, 64)    | 102464         |
| up_sampling2d_1 (UpSampling2 | (None, | 32, 32, 64)    | 0              |
| conv2d_transpose_3 (Conv2DTr | (None, | 34, 34, 32)    | 18464          |
| conv2d_transpose_4 (Conv2DTr | (None, | 36, 36, 32)    | 9248           |
| conv2d_transpose_5 (Conv2DTr | (None, | 38, 38, 32)    | 9248           |
| conv2d_1 (Conv2D)            | (None, | 36, 36, 3)<br> | 867<br>======= |

Total params: 320,835 Trainable params: 320,835 Non-trainable params: 0

1 assert generator.output\_shape[1:] == IMG\_SHAPE, "generator must output an image of shap

#### Discriminator

- Discriminator is your usual convolutional network with interlooping convolution and pooling layers
- The network does not include dropout/batchnorm to avoid learning complications.
- We also regularize the pre-output layer to prevent discriminator from being too certain.

#### 1 IMG\_SHAPE

```
(36, 36, 3)
```

```
1 discriminator = Sequential()
2
3 discriminator.add(L.InputLayer(IMG_SHAPE))
4
5 #<build discriminator body>
6 discriminator.add(L.Conv2D(filters = 16, kernel_size = (5, 5), activation = 'elu'))
7 discriminator.add(L.MaxPooling2D(pool_size = (2, 2)))
8 discriminator.add(L.Conv2D(filters = 32, kernel_size = (3, 3), padding = 'same',
9 activation = 'elu'))
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl Instructions for updating:

keep\_dims is deprecated, use keepdims instead

1 discriminator.summary()

| Layer (type)                                    | Output | Shape       | Param #         |
|---|--------|-------------|-----------------|
| input_1 (InputLayer)                            | (None, | 36, 36, 3)  | 0               |
| conv2d_2 (Conv2D)                               | (None, | 32, 32, 16) | 1216            |
| max_pooling2d_1 (MaxPooling2                    | (None, | 16, 16, 16) | 0               |
| conv2d_3 (Conv2D)                               | (None, | 16, 16, 32) | 4640            |
| max_pooling2d_2 (MaxPooling2                    | (None, | 8, 8, 32)   | 0               |
| conv2d_4 (Conv2D)                               | (None, | 8, 8, 64)   | 18496           |
| <pre>max_pooling2d_3 (MaxPooling2</pre>         | (None, | 4, 4, 64)   | 0               |
| flatten_1 (Flatten)                             | (None, | 1024)       | 0               |
| dense_2 (Dense)                                 | (None, | 256)        | 262400          |
| dense_3 (Dense)                                 | (None, | 2)          | 514<br>======== |
| Total params: 287,266 Trainable params: 287,266 |        |             |                 |

# Training

We train the two networks concurrently:

Non-trainable params: 0

- Train discriminator to better distinguish real data from current generator
- Train **generator** to make discriminator think generator is real
- Since discriminator is a differentiable neural network, we train both with gradient descent.

 $\mathbb{Z}_{\mathbb{Q}}$  deeplearning4j.org\_

 $\blacktriangleright$ 

Training is done iteratively until discriminator is no longer able to find the difference (or until you run out of patience).

#### Tricks:

- · Regularize discriminator output weights to prevent explosion
- Train generator with adam to speed up training. Discriminator trains with SGD to avoid problems with momentum.
- More: <a href="https://github.com/soumith/ganhacks">https://github.com/soumith/ganhacks</a>

```
1 noise = tf.placeholder('float32',[None,CODE_SIZE])
2 real_data = tf.placeholder('float32',[None,]+list(IMG_SHAPE))
3
4 logp_real = discriminator(real_data)
5
6 #generated_data = <gen(noise)>
7 generated_data = generator(noise)
8
9 #logp_gen = <log P(real | gen(noise))
10 logp_gen = discriminator(generated_data)
11</pre>
```

WARNING:tensorflow:From /tensorflow-1.15.2/python3.6/tensorflow\_core/python/ops/math\_ Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where

```
1 s.run(tf.global_variables_initializer())
```

## Auxiliary functions

Here we define a few helper functions that draw current data distributions and sample training batches.

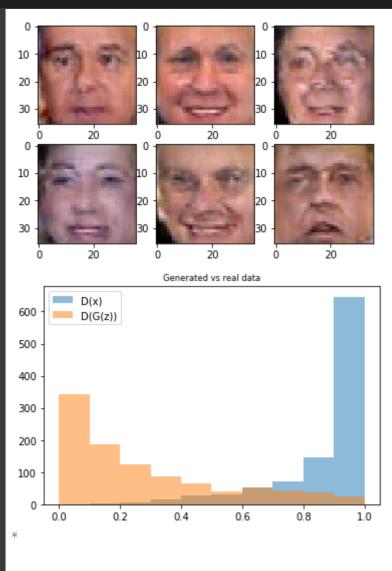
```
1 def sample_noise_batch(bsize):
       return np.random.normal(size=(bsize, CODE_SIZE)).astype('float32')
 4 def sample_data_batch(bsize):
       idxs = np.random.choice(np.arange(data.shape[0]), size=bsize)
       return data[idxs]
 8 def sample_images(nrow,ncol, sharp=False):
       images = generator.predict(sample_noise_batch(bsize=nrow*ncol))
10
       if np.var(images)!=0:
           images = images.clip(np.min(data),np.max(data))
11
       for i in range(nrow*ncol):
12
13
          plt.subplot(nrow,ncol,i+1)
14
           if sharp:
15
               plt.imshow(images[i].reshape(IMG_SHAPE),cmap="gray", interpolation="none")
16
17
               plt.imshow(images[i].reshape(IMG_SHAPE),cmap="gray")
18
       plt.show()
19
20 def sample probas(bsize):
       plt.title('Generated vs real data')
21
      plt.hist(np.exp(discriminator.predict(sample_data_batch(bsize)))[:,1],
22
23
                label='D(x)', alpha=0.5, range=[0,1])
      plt.hist(np.exp(discriminator.predict(generator.predict(sample_noise_batch(bsize)))
24
25
                label='D(G(z))',alpha=0.5,range=[0,1])
      plt.legend(loc='best')
27
      plt.show()
```

## Training

Main loop. We just train generator and discriminator in a loop and plot results once every N iterations.

```
1 from IPython import display
2
3 for epoch in tqdm_utils.tqdm_notebook_failsafe(range(50000)):
4
5    feed_dict = {
6        real_data:sample_data_batch(100),
7        noise:sample_noise_batch(100)
8    }
9
10    for i in range(5):
11        s.run(disc_optimizer,feed_dict)
```

```
12
13    s.run(gen_optimizer,feed_dict)
14
15    if epoch %100==0:
16        display.clear_output(wait=True)
17        sample_images(2,3,True)
18        sample_probas(1000)
19
```



```
1 from submit_honor import submit_honor
```

- 2 #submit\_honor((generator, discriminator), <YOUR\_EMAIL>, <YOUR\_TOKEN>)
- 3 submit\_honor((generator, discriminator), 'knowtech94@gmail.com', '11RyCzY9UQ027NpB')

Submitted to Coursera platform. See results on assignment page!

```
1 #The network was trained for about 15k iterations.
```

- 2 #Training for longer yields MUCH better results
- 3 plt.figure(figsize=[16,24])
- 4 sample\_images(16,8)

