

# Winning Space Race with Data Science

Homame Soussi  
09/05/2024



# Outline

---

- Executive Summary
- Introduction
- Methodology
- Results
- Conclusion
- Appendix

# Executive Summary

---

- The following methodologies were used to analyze data:
  1. Data Collection
  2. Data Wrangling
  3. Exploratory Data Analysis with Data Visualization
  4. Exploratory Data Analysis with SQL
  5. Building an interactive map with Folium
  6. Building a dashboard with Ploty Dash
  7. Predictive Analysis and Classification
- Summary of all results
  1. Exploratory Data Analysis
  2. Interactive Analytics
  3. Predictive analysis results

# Introduction

---

SpaceX advertises Falcon 9 rocket launches on its website, with a cost of 62 million dollars; much of the savings is because SpaceX can reuse the first stage.

Therefore, if we can determine if the first stage will land, we can determine the cost of a launch. Based on public information and machine learning models, we are going to predict if SpaceX will reuse the first stage.

## Questions to be answered:

- How do the variables affect the success of the first stage landing ?
- Does the rate of successful landings increase over the years ?
- What is the best algorithm that can be used for binary classification in this case?

Section 1

# Methodology

# Data Collection

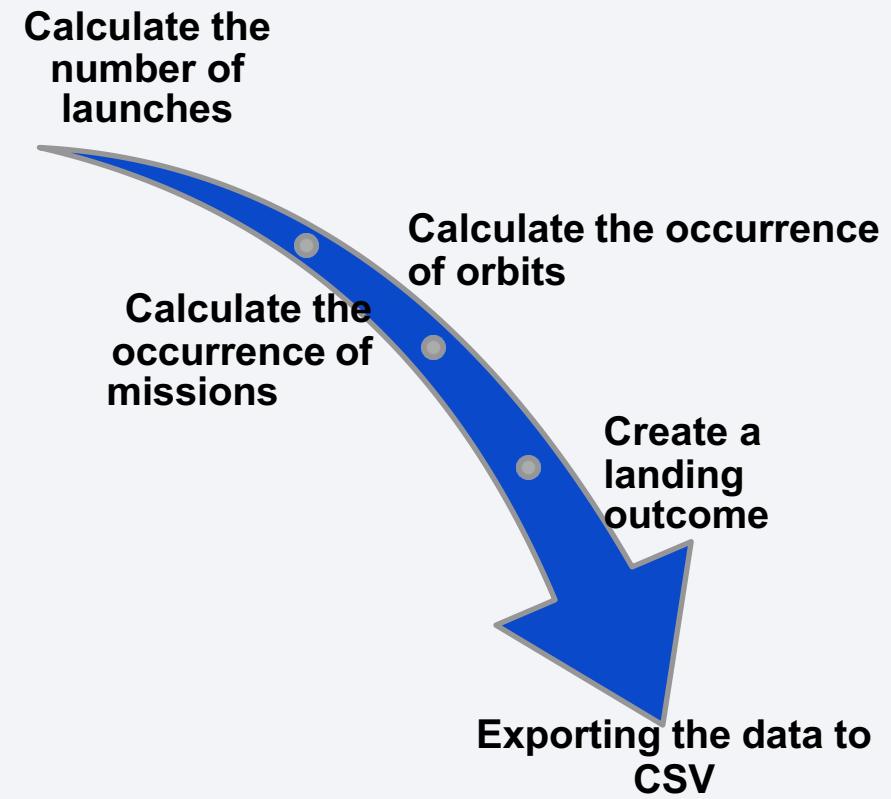
---

- We had to use a process involving a combination of API requests from SpaceX REST API and Web Scraping data from a table in SpaceX Wikipedia entry, to get the complete information about the launching for a more detailed analysis.
- Using SpaceX REST API we can obtain the Flight Number, Dates, Booster Version, Payloads, Orbit, Launch Sites, Outcome, Flights, Landing Pads, ..., etc.
- Using Wikipedia Web scraping we can obtain Flight Numbers, Payloads, Customer, Time, Launch Outcome, ...

# Data Wrangling

---

True RTLS means the mission outcome was successfully landed to a ground pad False RTLS means the mission outcome was unsuccessfully landed to a ground pad. True ASDS means the mission outcome was successfully landed on a drone ship False ASDS means the mission outcome was unsuccessfully landed on a drone ship. We mainly convert those outcomes into Training Labels with “1” means the booster successfully landed, “0” means it was unsuccessful.



# EDA with Data Visualization

---

- A scatter plot shows the relationship between variables: it can be then used in the machine learning model.
- A bar chart show a comparison between categories: the relationship between categories is measured.
- A line chart shows the trend of the data over time.
- We plotted multiple charts including:
- Flight Number vs. Payload Mass, Flight Number vs. Launch Site, Payload Mass vs. Launch Site, Orbit Type vs. Success Rate, Flight Number vs. Orbit Type, Payload Mass vs Orbit Type and Success Rate Yearly Trend

# Predictive Analysis

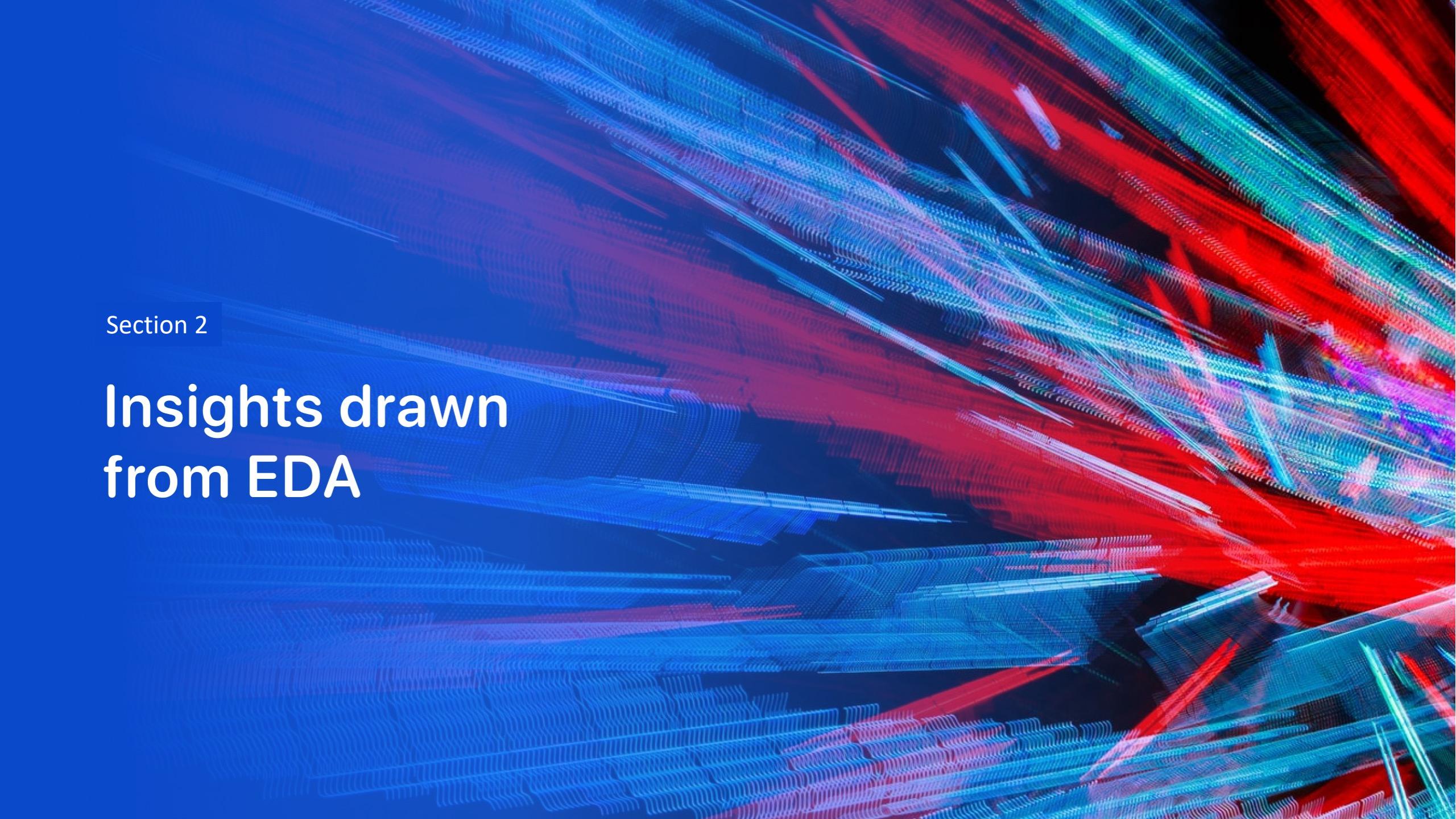
---

- 1- Create a NumPy array from the “Class” in data
- 2- Standardize the data with Standard Scaler as well as fit and transform it.
- 3- Split the data into training and testing sets.
- 4- Create a GridSearchCV object to find the parameter.
- 5- Apply it on LogReg, SVM, Decision Tree, KNN.
- 6- Calculate the Accuracy on the test data.
- 7- Examine the confusion matrix for these models.
- 8- Find the method that performed the best.

# Results

---

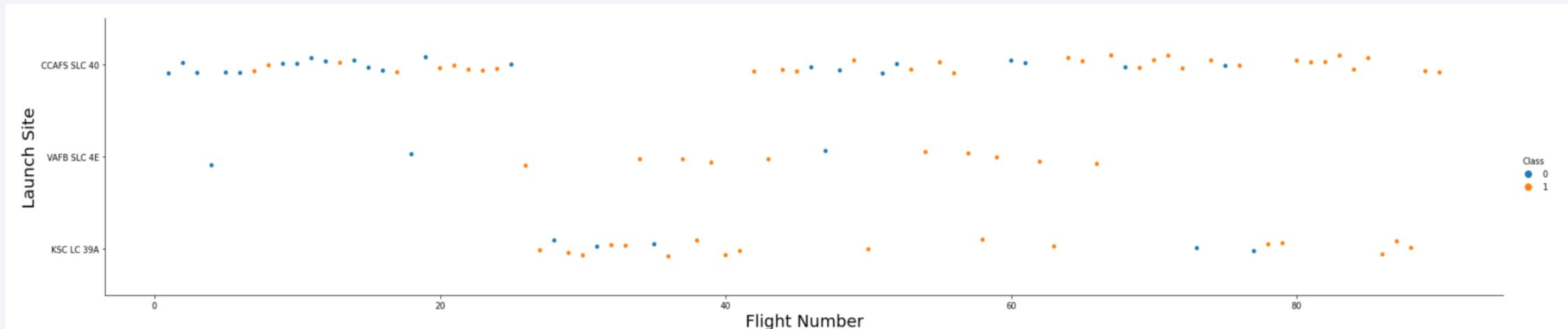
- Exploratory data analysis results
- Interactive analytics demo in screenshots
- Predictive analysis results

The background of the slide features a complex, abstract digital visualization. It consists of numerous thin, glowing lines that create a sense of depth and motion. The lines are primarily blue and red, with some green and purple highlights. They form a grid-like structure that curves and twists across the frame, resembling a three-dimensional space or a network of data points. The overall effect is futuristic and dynamic.

Section 2

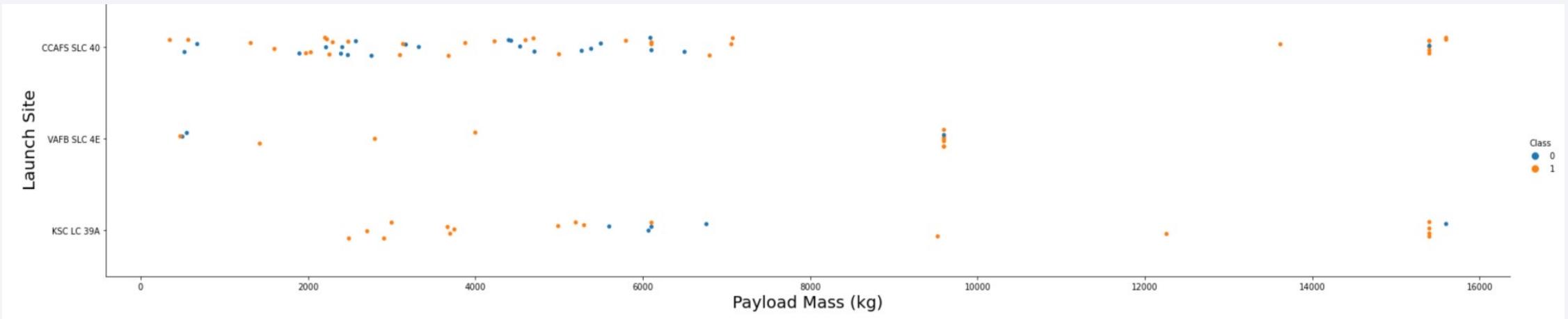
## Insights drawn from EDA

# Flight Number vs. Launch Site



- The earliest flights all failed while the latest flights all succeeded.
- The CCAFS SLC 40 launch site has about a half of all launches.
- VAFB SLC 4E and KSC LC 39A have higher success rates.
- It can be assumed that each new launch has a higher rate of success.

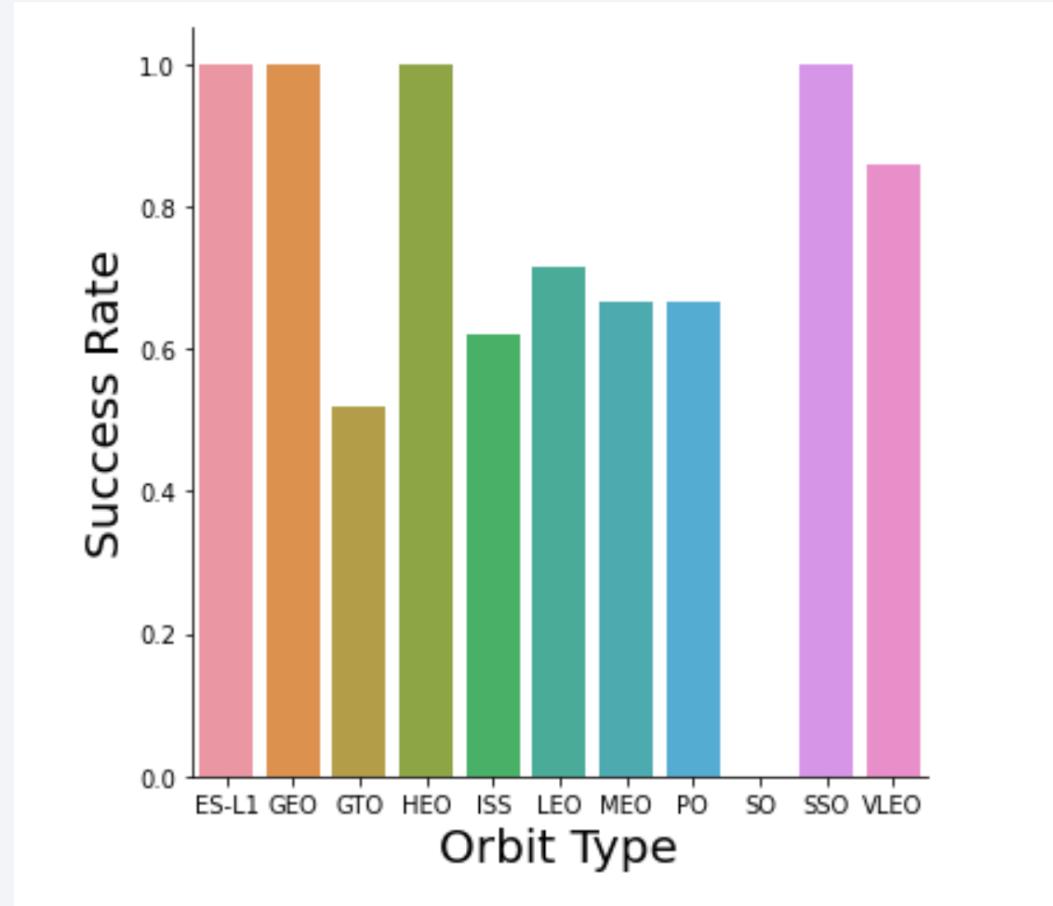
# Payload vs. Launch Site



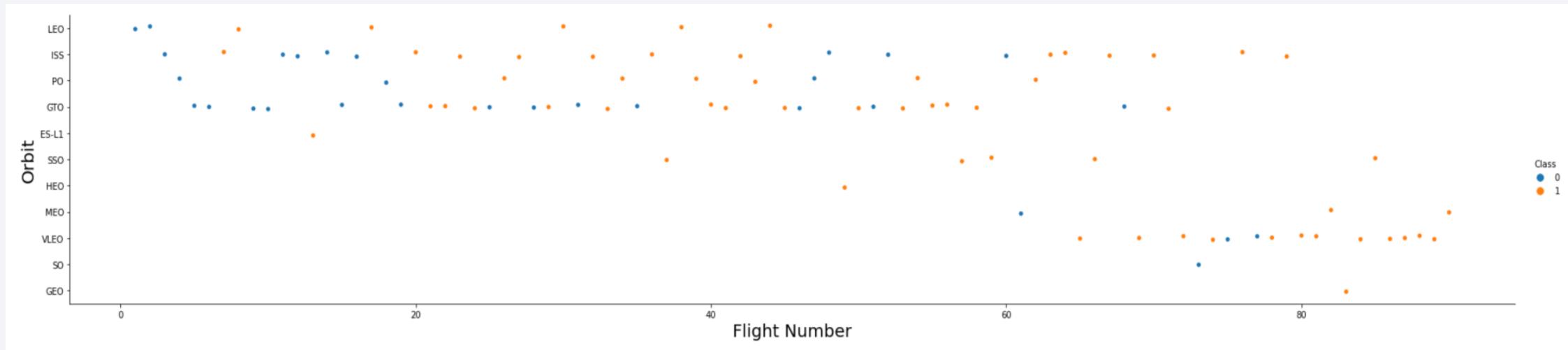
- For every launch site the higher the payload mass, the higher the success rate.
- Most of the launches with payload mass over 7000 kg were successful.
- KSC LC 39A has a 100% success rate for payload mass under 5500 kg too.

# Success Rate vs. Orbit Type

- Orbit types with 100% success rate are: ES-L1, GEO, HEO, SSO
- Orbit type with 0% success rate is: SO
- Orbit types with success rates between 50% and 85%: GTO, ISS, LEO, MEO, PO

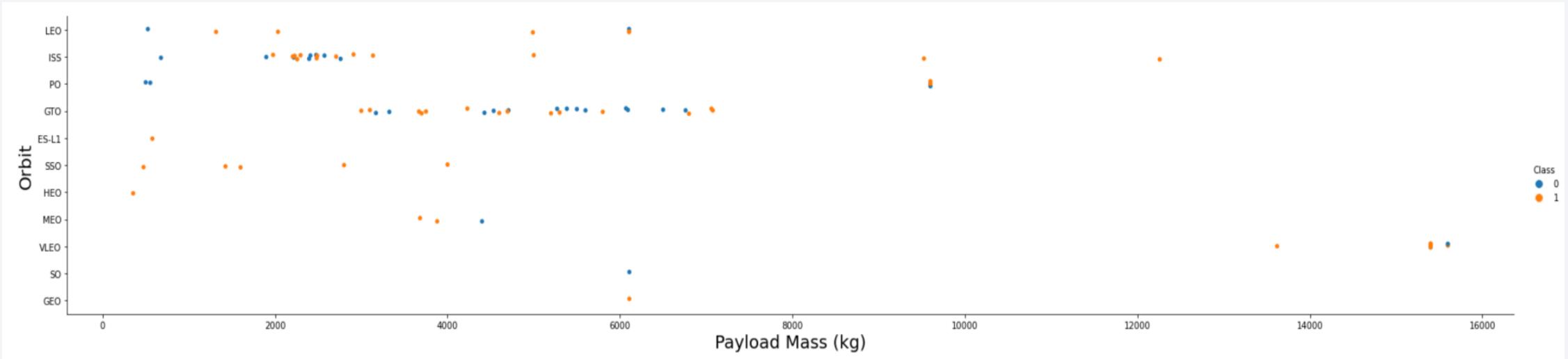


# Flight Number vs. Orbit Type



In the LEO orbit the Success appears related to the number of flights; on the other hand, there seems to be no relationship between flight number when in GTO orbit.

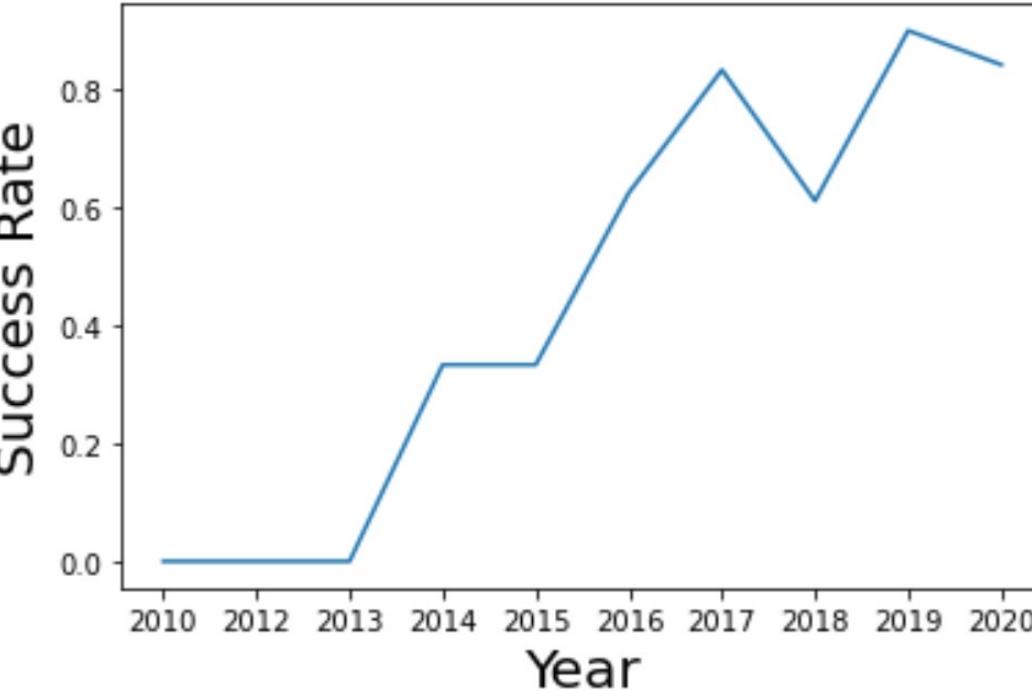
# Payload vs. Orbit Type



In the LEO orbit the Success appears related to the number of flights; on the other hand, there seems to be no relationship between flight number when in GTO orbit.

# Launch Success Yearly Trend

---



The success rate since 2013 kept increasing till 2020

# All Launch Site Names

---

launch_site
CCAFS LC-40
CCAFS SLC-40
KSC LC-39A
VAFB SLC-4E

The names of the launch sites for the mission

# Launch Site Names Begin with 'CCA'

DATE	time_utc	booster_version	launch_site	payload	payload_mass_kg	orbit	customer	mission_outcome	landing_outcome
2010-06-04	18:45:00	F9 v1.0 B0003	CCAFS LC-40	Dragon Spacecraft Qualification Unit	0	LEO	SpaceX	Success	Failure (parachute)
2010-12-08	15:43:00	F9 v1.0 B0004	CCAFS LC-40	Dragon demo flight C1, two CubeSats, barrel of Brouere cheese	0	LEO (ISS)	NASA (COTS) NRO	Success	Failure (parachute)
2012-05-22	07:44:00	F9 v1.0 B0005	CCAFS LC-40	Dragon demo flight C2	525	LEO (ISS)	NASA (COTS)	Success	No attempt
2012-10-08	00:35:00	F9 v1.0 B0006	CCAFS LC-40	SpaceX CRS-1	500	LEO (ISS)	NASA (CRS)	Success	No attempt
2013-03-01	15:10:00	F9 v1.0 B0007	CCAFS LC-40	SpaceX CRS-2	677	LEO (ISS)	NASA (CRS)	Success	No attempt

The records shown are all for launch sites with their name biggening with CCA.

# Total Payload Mass

---

<b>total_payload_mass</b>
45596

The total payload mass carried by boosters launched by NASA

# Average Payload Mass by F9 v1.1

---

average_payload_mass
2534

The average payload mass carried by the booster F9 v1.1

# First Successful Ground Landing Date

---

first_successful_landing
2015-12-22

The date when the first successful landing outcome in ground pad was achieved

## Successful Drone Ship Landing with Payload between 4000 and 6000

---

booster_version
F9 FT B1022
F9 FT B1026
F9 FT B1021.2
F9 FT B1031.2

# Total Number of Successful and Failure Mission Outcomes

---

mission_outcome	total_number
Failure (in flight)	1
Success	99
Success (payload status unclear)	1

- Total number of successful and failure mission outcomes

# Boosters Carried Maximum Payload

---

booster_version
F9 B5 B1048.4
F9 B5 B1049.4
F9 B5 B1051.3
F9 B5 B1056.4
F9 B5 B1048.5
F9 B5 B1051.4
F9 B5 B1049.5
F9 B5 B1060.2
F9 B5 B1058.3
F9 B5 B1051.6
F9 B5 B1060.3
F9 B5 B1049.7

# 2015 Launch Records

---

MONTH	DATE	booster_version	launch_site	landing_outcome
January	2015-01-10	F9 v1.1 B1012	CCAFS LC-40	Failure (drone ship)
April	2015-04-14	F9 v1.1 B1015	CCAFS LC-40	Failure (drone ship)

- The failed landing\_outcomes in drone ship, their booster versions, and launch site names for in year 2015

## Rank Landing Outcomes Between 2010-06-04 and 2017-03-20

---

landing_outcome	count_outcomes
No attempt	10
Failure (drone ship)	5
Success (drone ship)	5
Controlled (ocean)	3
Success (ground pad)	3
Failure (parachute)	2
Uncontrolled (ocean)	2
Precluded (drone ship)	1

The background of the slide is a photograph taken from space at night. It shows the curvature of the Earth against a dark blue-black void of space. City lights are visible as numerous small white and yellow dots, primarily concentrated in the lower right quadrant where the United States appears. In the upper right, the green and yellow glow of the aurora borealis is visible. The atmosphere of the Earth is thin and hazy, appearing as a light blue band near the horizon.

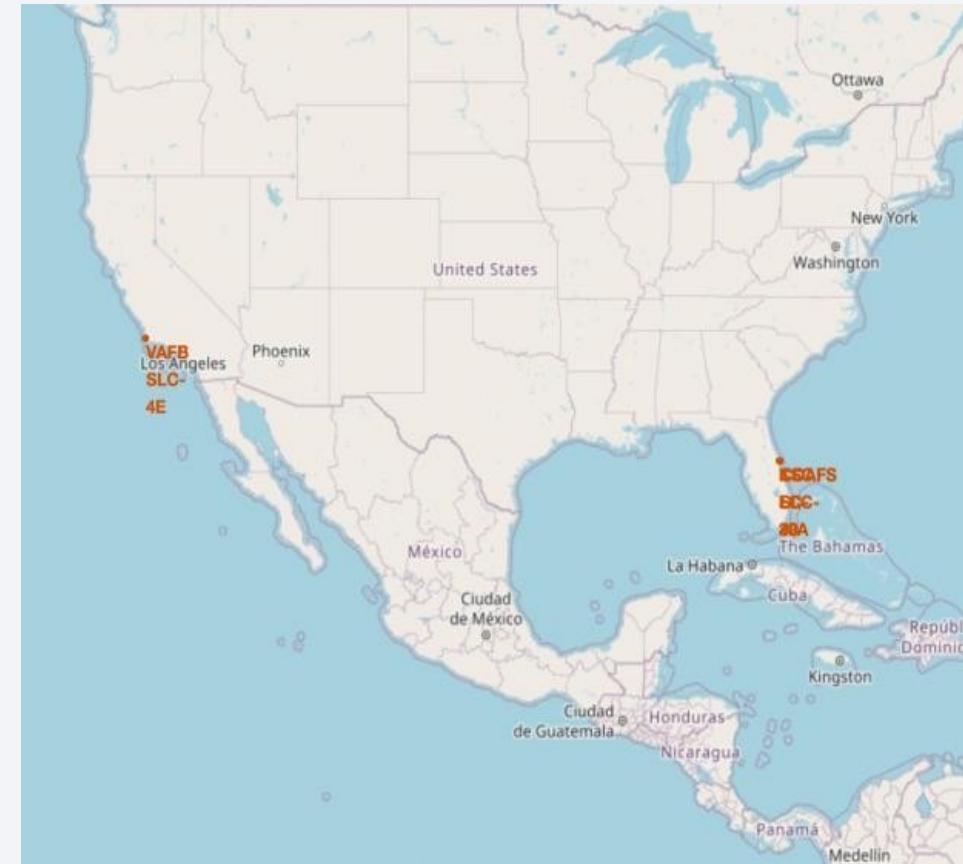
Section 3

# Launch Sites Proximities Analysis

# Launch Sites Locations on the Global Map

---

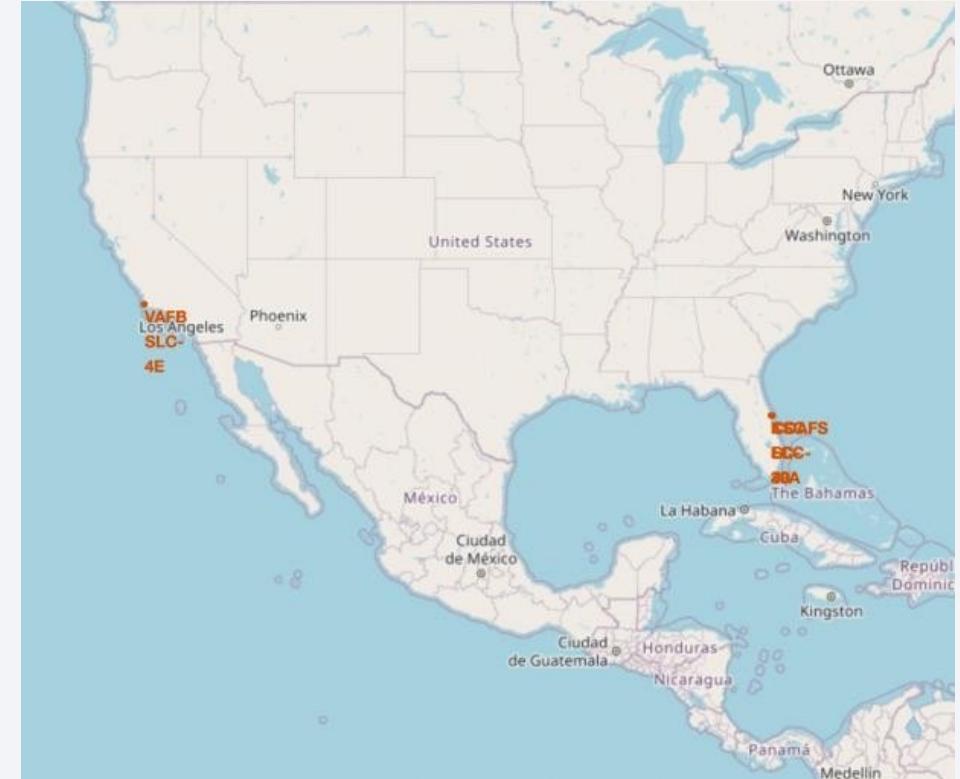
Most of Launch sites considered in this project are in proximity to the Equator line. Launch sites are made at the closest point possible to Equator line, because anything on the surface of the Earth at the equator is already moving at the maximum speed (1670 kilometers per hour). For example, launching from the equator makes the spacecraft move almost 500 km/hour faster once it is launched compared halfway to north pole.



# Launch Sites Locations on the Global Map

---

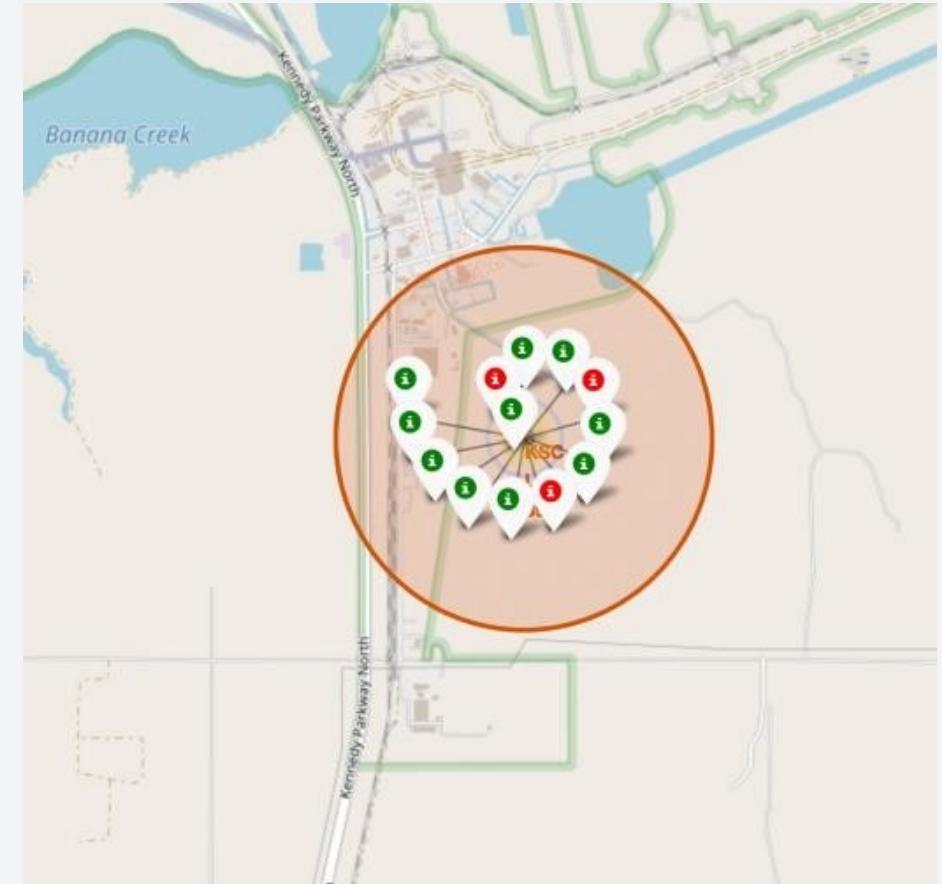
All launch sites considered in this project are in very close proximity to the coast. While starting rockets towards the ocean we minimize the risk of having any debris dropping or exploding near people.



# Labels for Launch Records on the map

---

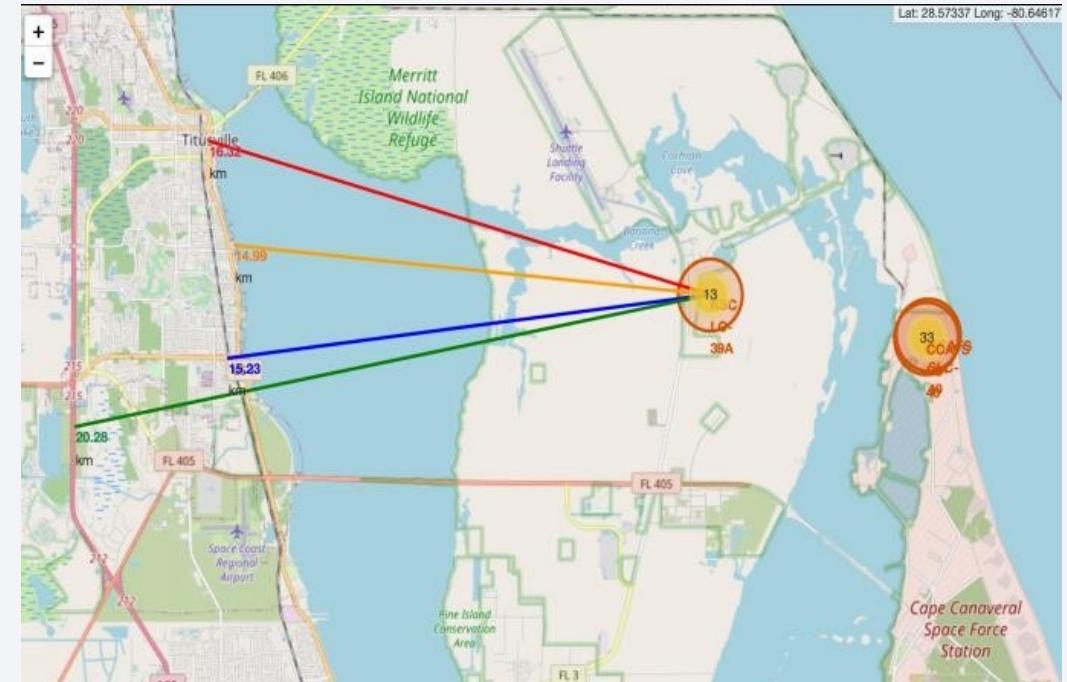
From the color-labeled markers in marker clusters, you should be able to easily identify which launch sites have relatively high success rates.



# Distance from the Launch Site KSC LC-39A

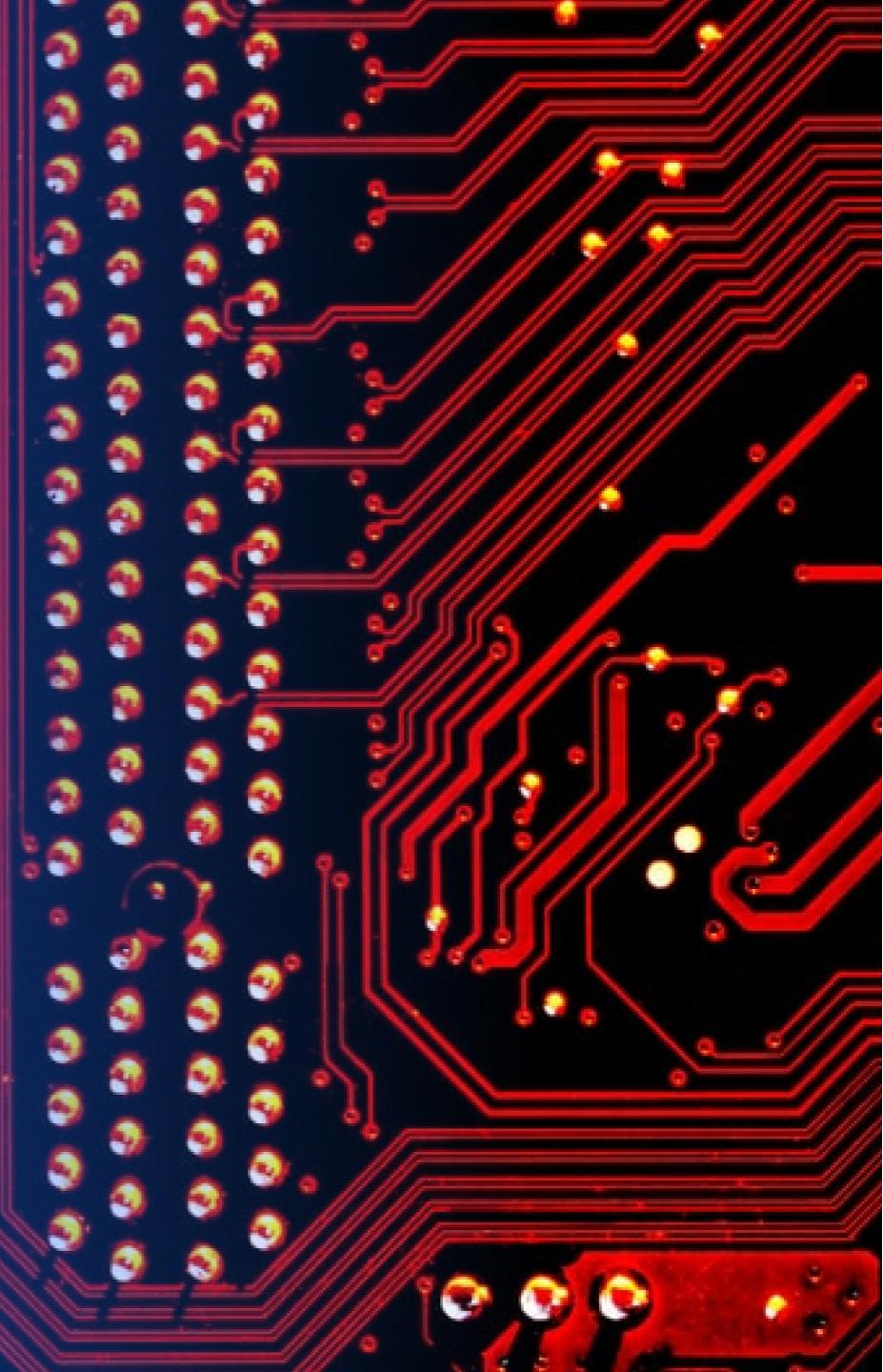
---

- From the visual analysis of the launch site KSC LC-39A we can clearly see that it is:
  - relatively close to railway (15.23 km)
  - relatively close to highway (20.28 km)
  - relatively close to coastline (14.99 km)
- Also, the launch site KSC LC-39A is relatively close to its closest city Titusville (16.32 km).
- Failed rocket with its high speed can cover distances like 15-20 km in few seconds. It could be potentially dangerous to populated areas.



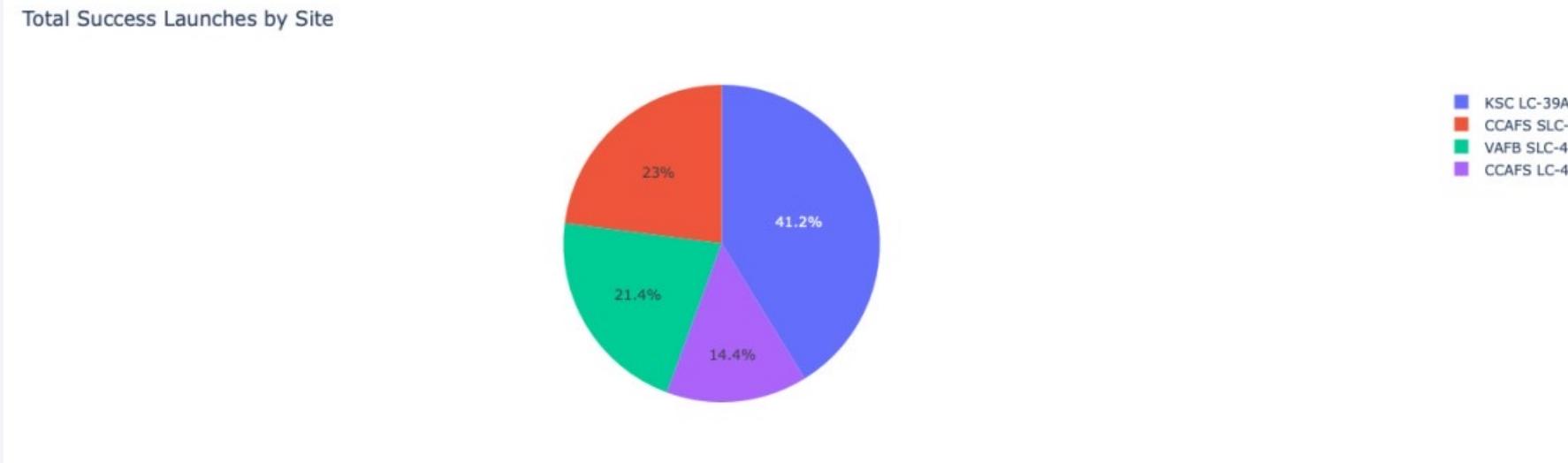
Section 4

# Build a Dashboard with Plotly Dash



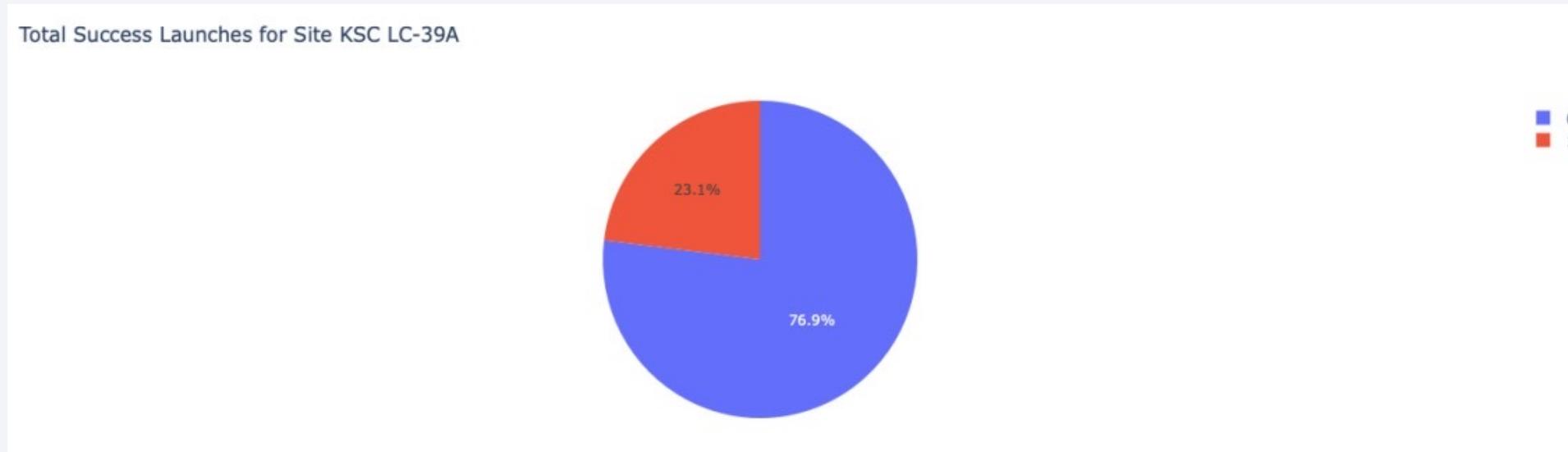
# Launch Success Count for all sites

---

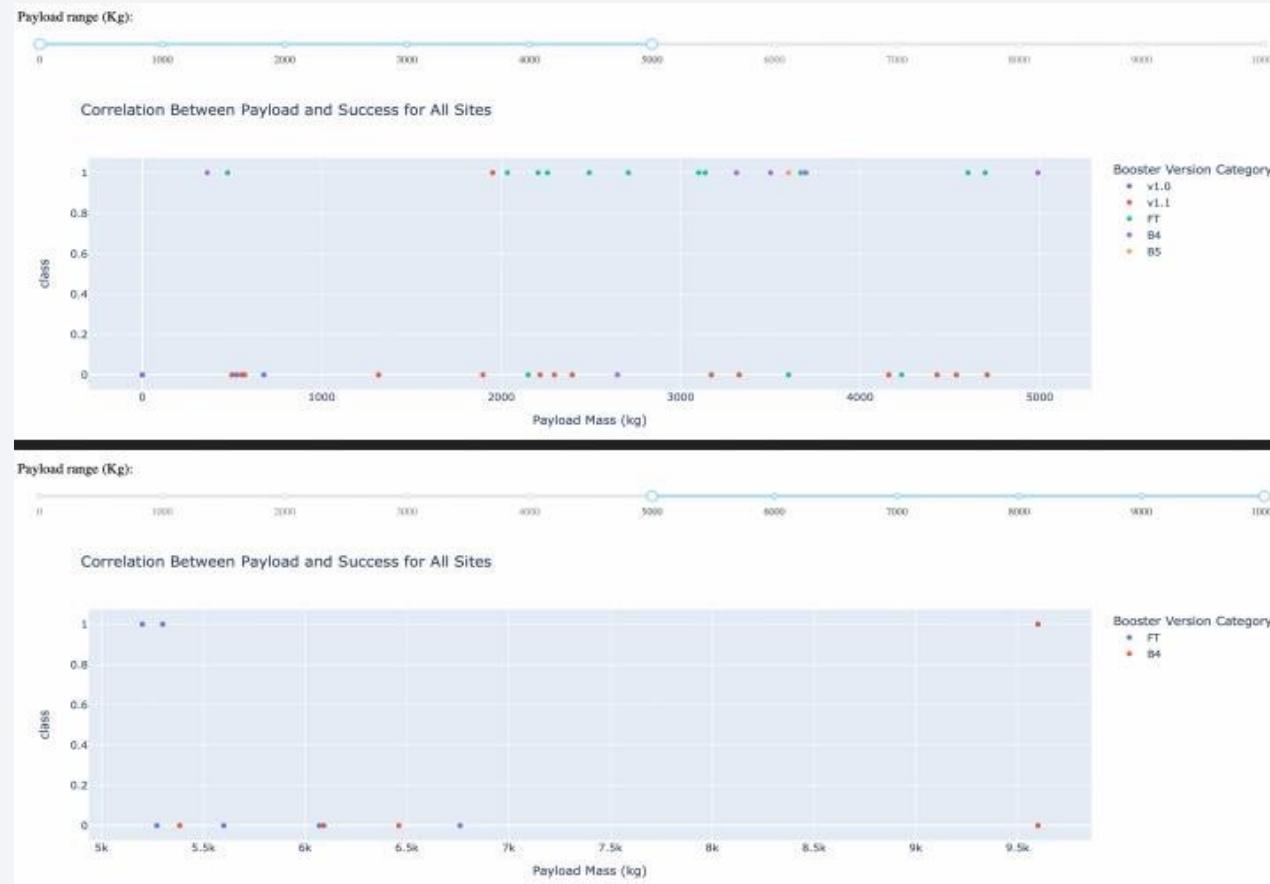


# KSC LC-39A the Site With the highest launch Success ratio

---



# Payload Mass vs Launch Outcomes for all Sites



The background of the slide features a dynamic, abstract design. It consists of several thick, curved lines that transition from a bright yellow at the top right to a deep blue at the bottom left. These lines create a sense of motion and depth, resembling a tunnel or a stylized road. The overall effect is modern and professional.

Section 5

# Predictive Analysis (Classification)

# Classification Accuracy

---

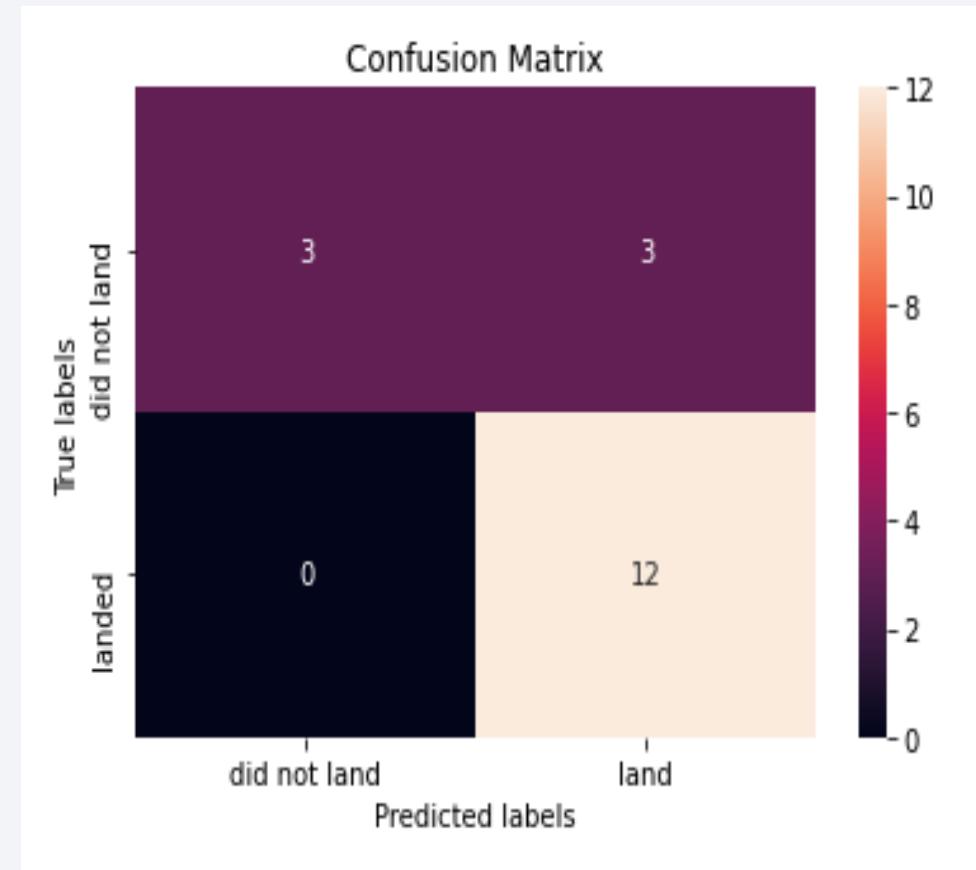
- Based on the scores of the Test Set, we can not confirm which method performs best.
- Same Test Set scores may be due to the small test sample size (18 samples). Therefore, we tested all methods based on the whole Dataset.
- The scores of the whole Dataset confirm that the best model is the Decision Tree Model. This model has not only higher scores, but also the highest accuracy.

# Confusion Matrix

---

Examining the confusion matrix, we see that logistic regression can distinguish between the different classes.

We see that the major problem is false positives.



# Conclusions

---

1. The decision Tree Model is the best algorithm for this dataset
2. Most of the launch sites are in proximity to the Equator Line and all the sites are in very close proximity to the coast.
3. The success rate increased over the years.
4. KSC LC-39A has the highest success rate.
5. Orbit ES-L1, GEO, HEO, and SSO have 100% success rate.

Thank you!

