

1 Formulas

Formulas
<div><div><div>• Permutation:</div><div><math display="block">\frac{n!}{(n-r)!}</math></div></div><div><div>• Combinations:</div><div><math display="block">\binom{n}{r} = \frac{n!}{r!(n-r)!}</math></div></div><div><div>• Geometric Series:</div><div><math display="block">\sum_{k=0}^{\infty} ar^k = \frac{a}{1-r}</math></div></div><div><div>• Infinity Series:</div><div><math display="block">\sum_{k=0}^{\infty} \frac{z^k}{k!} = e^z</math></div></div><div><div>• Exponential Result:</div><div><math display="block">\lim_{n \rightarrow \infty} \left(1 + \frac{x}{n}\right)^n = e^x</math></div></div></div>

2 Basic Properties

- PMF (Probability Mass Function) for Discrete RV:
  - $p(k) \geq 0$  for all  $k$
  - $\sum_i p(k_i) = 1$
- PDF (Probability Density Function) for Continuous RV:
  - $f(x) \geq 0$  for all  $x$
  - $\int_{-\infty}^{\infty} f(x) \, dx = 1$
- CDF (Cumulative Distribution Function):
  - Non-decreasing function.
  - $\lim_{x \rightarrow -\infty} F(x) = 0$  and  $\lim_{x \rightarrow \infty} F(x) = 1$

Joint Distribution	
Joint CDF: $F(x,y) = P(X \leq x, Y \leq y)$	
Joint PMF: $p(x,y) = P(X = x, Y = y)$	Joint PDF: $f(x,y) = P(X = x, Y = y)$
Marginal PMF: $p_X(x) = \sum_y p(x,y)$ $p_Y(y) = \sum_x p(x,y)$ <ul style="list-style-type: none"><li>• <math>p(x,y) \geq 0</math> for all <math>x,y</math></li><li>• <math>\sum_x \sum_y p(x,y) = 1</math></li></ul>	Marginal PDF: $f_X(x) = \int_{-\infty}^{\infty} f(x,y) \, dy$ $f_Y(y) = \int_{-\infty}^{\infty} f(x,y) \, dx$ <ul style="list-style-type: none"><li>• <math>f(x,y) \geq 0</math> for all <math>x,y</math></li><li>• <math>\int_x \int_y p(x,y) \partial y \partial x = 1</math></li></ul>

3 Conditional

Conditional Probability for Event
<div><div><div>• Definition:</div><div><math display="block">P(A B) = \frac{P(A \cap B)}{P(B)}</math></div></div><div><div>• Multiplicative Law:</div><div><math display="block">P(A \cap B) = P(B \cap A) = P(A B)P(B)</math></div></div></div>
<div><div><div>• Law of Total Probability, Union of all <math>B_i</math> is the <math>\Omega</math></div><div><math display="block">P(A) = \sum_{i=1}^n P(A B_i)P(B_i)</math></div></div></div>

Conditional Probability for Multivariate
<div><div><div>• Definition:</div><div><math display="block">p(X = x Y = y) = \frac{p_{X,Y}(x,y)}{p_Y(y)} \qquad f(X = x Y = y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}</math></div></div><div><div>• If <math>X</math> and <math>Y</math> are independent, then their margin PMF/PDF can factor into the product of their Marginal, and canceled by the denominator, thus we got:</div><div><math display="block">p(X = x Y = y) = p(X = x) \qquad f(X = x Y = y) = f(X = x)</math></div></div></div>
<div><div><div>• Multiplication Law:</div><div><math display="block">p_{XY}(x,y) = p_{X Y}(x y)p_Y(y) \qquad f_{XY}(x,y) = f_{X Y}(x y)f_Y(y)</math></div></div></div>
<div><div><div>• Law of Total Probability:</div><div><math display="block">p_X(x) = \sum_y p(x,y) = \sum_y p_{X Y}(x y)p_Y(y)</math><math display="block">f_X(x) = \int_{-\infty}^{\infty} f(x,y) \, dy = \int_{-\infty}^{\infty} f_{X Y}(x y)f_Y(y) \, dy</math></div></div></div>

Bayes's Rule
$P(B A) = \frac{P(A B)P(B)}{P(A)}$

4 Independence

Independence
<div><div><div>• RV <math>X</math> and <math>Y</math> are independent iff:</div><div><math display="block">\frac{f(x,y)}{p(x,y)} = \frac{f_X(x)f_Y(y)}{p_X(x)p_Y(y)} \quad \text{or} \quad M_{X,Y}(x,y) = M_X(x)M_Y(y)</math></div></div><div><div>• Event <math>A</math> and <math>B</math> are independent iff:</div><div><math display="block">P(A \cup B) = P(A)P(B)</math></div></div></div>

5 Transformation

Normal Transformation (Normalize)
$X \sim N(\mu, \sigma^2) \implies \frac{X - \mu}{\sigma} \sim N(0, 1)$
Direct Transformation Method
Given $f_X(x)$ , find $F_X(x)$ , then construct $F_Y(y)$ in terms of $F_X(y)$ , next we find the derivative of $F_Y(y)$ to find $f_Y(y)$ .
Monotone Transformation Method
If $Y = g(X)$ , where $g$ is differentiable and strictly monotonic on some interval $I$ , then the PMF/PDF of $Y$ is given as: <div><math display="block">f_Y(y) = f_X(g^{-1}(y)) \left  \frac{d}{dy} g^{-1}(y) \right </math></div>
Probability Integral Transformation
If $Z = F_X(X)$ then $Z \sim Uni(0, 1)$ .
Inverse Integral Transformation
If $X = F^{-1}(U)$ where $U \sim Uni(0, 1)$ then $X$ has PDF $F(x)$ .
Convolution Method (Sum of two RV)
Given $Z = X + Y$ , then we have: <div><math display="block">p_Z(z) = \sum_x p(x, z - x) \qquad f_Z(z) = \int_{-\infty}^{\infty} f(x, z - x) \, dx</math></div> If $X$ and $Y$ are independent, we got: <div><math display="block">p_Z(z) = \sum_x p_X(x)p_Y(z - x) \qquad f_Z(z) = \int_{-\infty}^{\infty} f_X(x)f_Y(z - x) \, dx</math></div>

Bivariate Transformation Method
Suppose $X$ and $Y$ continuous RV and independent, we have two RV, defined as transformation of $X$ and $Y$ , we first use $U, V$ represent $X, Y$ : <div><math display="block">U = g_1(X, Y) \quad V = g_2(X, Y) \quad \text{and} \quad X = h_1(U, V) \quad Y = h_2(U, V)</math></div> Then the joint PDF of $U$ and $V$ is given as: <div><math display="block">f_{U,V}(u,v) = f_{X,Y}(h_1(u,v), h_2(u,v))  \det(J(u,v)) </math></div> Where $J(u,v)$ is the Jacobian Matrix, defined as: <div><math display="block">J(u,v) = \begin{bmatrix} \frac{\partial h_1}{\partial u} &amp; \frac{\partial h_1}{\partial v} \\ \frac{\partial h_2}{\partial u} &amp; \frac{\partial h_2}{\partial v} \end{bmatrix}</math></div> And the determinate is calculated as: <div><math display="block">\frac{\partial h_1}{\partial u} \times \frac{\partial h_2}{\partial v} - \frac{\partial h_1}{\partial v} \times \frac{\partial h_2}{\partial u}</math></div>

6 Expected Value

<div><div><div><math display="block">E(X) = \sum_x xp(x) \qquad E(X) = \int_{-\infty}^{\infty} xf(x) \, dx</math></div></div></div>
Properties of Expected Value
<div><div><div>• Expectation of a constant:</div><div><math display="block">E(E(X)) = E(X)</math></div></div><div><div>• Expectation of Linear Combinations of RV:</div><div><math display="block">E\left(a + \sum_{i=1}^n b_i X_i\right) = a + \sum_{i=1}^n b_i E(X_i)</math></div></div></div>
<div><div><div>Especially:</div><div><math display="block">E(aX + b) = aE(X) + b</math></div></div><div><div>When <math>a = 0, b = 1</math> we got:</div><div><math display="block">E\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n E(X_i)</math></div></div></div>
<div><div><div>• Notice:</div><div><math display="block">E(g(X)) \neq g(E(X))</math></div></div><div><div>• Expectation of product of RV, If <math>X</math> and <math>Y</math> are independent:</div><div><math display="block">E(XY) = E(X)E(Y)</math></div></div></div>
<div><div><div>• Expected Value of a function of RV, suppose <math>Y = g(X)</math>:</div><div><math display="block">E(Y) = \sum_x g(x)p(x) \qquad E(Y) = \int_{-\infty}^{\infty} g(x)f(x) \, dx</math></div></div><div><div>Especially:</div><div><math display="block">E(X^2) = \sum_x x^2 p(x) \qquad E(x^2) = \int_{-\infty}^{\infty} x^2 f(x) \, dx</math></div></div></div>

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Conditional Expectation
<div><div><div>• Expectation of <math>Y</math> given <math>X = x</math> (fixed), and <math>h(Y)</math> is a function of <math>Y</math>:</div><div><math display="block">E(h(Y) X = x) = \sum_{y_i} h(y_i)p(Y = y_i X = x)</math><math display="block">E(h(Y) X = x) = \int_{-\infty}^{\infty} h(y_i)p(Y = y_i X = x)</math></div></div><div><div>• Law of total Expectation:</div><div><math display="block">E(Y) = E_X(E(Y X))</math></div></div><div><div>The key here is <math>E(Y X)</math> is a function of <math>X</math>.</div></div></div>

7 Variance

$Var(X) = E([X - \mu]^2)$
Standard Deviation
$Std(X) = \sqrt{Var(X)}$
Properties of Variance
<div><div><div>• Alternative Variance Form:</div><div><math display="block">Var(X) = E(X^2) - [E(X)]^2</math></div></div><div><div>• Variance of sum of RV:</div><div><math display="block">Var(X + Y) = Var(X) + Var(Y) + 2Cov(X, Y)</math><math display="block">Var(X - Y) = Var(X) + Var(Y) - 2Cov(X, Y)</math>If <math>X</math> and <math>Y</math> are independent, the covariance term is 0, thus:<math display="block">Var(X + Y) = Var(X - Y) = Var(X) + Var(Y)</math></div></div><div><div>In General:</div><div><math display="block">Var\left(a + \sum_{i=1}^n b_i X_i\right) = \sum_{i=1}^n \sum_{j=1}^n b_i b_j Cov(X_i, X_j)</math></div></div><div><div>Especially:</div><div><math display="block">Var(aX + b) = a^2 Var(X)</math></div></div><div><div>• If all <math>X_i</math> are mutually independent, then:</div><div><math display="block">Var\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n Var(X_i)</math></div></div><div><div>• Variance of product of RV:</div><div><math display="block">Var(XY) = E(X^2Y^2) - [E(XY)]^2</math></div></div></div>

Law of total Variance
$Var(Y) = Var(E(Y X)) + E(Var(Y X))$

Covariance
<div><div><div>• The Covariance of <math>X</math> and <math>Y</math> is defined as:</div><div><math display="block">Cov(X, Y) = E((X - E(X)) * (Y - E(Y)))</math></div></div><div><div>Notice that covariance can be positive or negative, contrast to variance which can only take positive value.</div><div>• Alternative Covariance Form:</div><div><math display="block">Cov(X, Y) = E(XY) - E(X)E(Y)</math></div></div><div><div>• Property 1:</div><div><math display="block">Cov(a + X, Y) = Cov(X, Y)</math></div></div><div><div>• Property 2:</div><div><math display="block">Cov(aX, bY) = abCov(X, Y)</math></div></div><div><div>• Property 3:</div><div><math display="block">Cov(X, Y + Z) = Cov(X, Y) + Cov(X, Z)</math></div></div><div><div>• Property 4:</div><div><math display="block">Cov(aX + bW, cY + dZ) = \frac{ac * Cov(X, Y) + ad * Cov(X, Z) + bc * Cov(W, Y) + bd * Cov(W, Z)}{}</math></div></div><div><div>In General, if <math>U = a + \sum_{i=1}^n b_i X_i, V = c + \sum_{i=1}^n d_i X_i</math>, we have:</div><div><math display="block">Cov(U, V) = \sum_{i=1}^n \sum_{j=1}^m b_i d_j Cov(X_i, Y_j)</math></div></div><div><div>• Property 5:</div><div><math display="block">Cov(X, X) = Var(X)</math></div></div><div><div>• Property 6: If <math>X</math> and <math>Y</math> are independent then:</div><div><math display="block">Cov(X, Y) = 0</math></div></div><div><div>But <math>Cov(X, Y) = 0</math> can't gives us <math>X</math> and <math>Y</math> independent.</div></div></div>

Correlation
<div><div><div>• The Correlation of <math>X</math> and <math>Y</math> is defined as:</div><div><math display="block">\rho(X, Y) = \frac{Cov(X, Y)}{\sqrt{Var(X)Var(Y)}} \qquad -1 \leq \rho \leq 1</math></div></div><div><div>• When <math>\rho</math> is close to 1, then <math>X</math> and <math>Y</math> are positively associated.</div><div>• When <math>\rho</math> is close to <math>-1</math>, then <math>X</math> and <math>Y</math> are negatively associated.</div><div>• When <math>\rho</math> is equals to 0, then <math>X</math> and <math>Y</math> are not associated.</div></div></div>

8 Markov and Chebyshev

Markov's Inequality
<div><div><div>If <math>X</math> only defined on non negative values, then:</div><div><math display="block">P(X \geq t) \leq \frac{E(X)}{t}</math></div></div></div>

Chebyshev's Inequality
<div><div><div>Let <math>\mu</math> and <math>\sigma^2</math> be the mean and variance, then for <math>t &gt; 0</math>, we set <math>t = k\sigma</math>:</div><div><math display="block">P( X - \mu  &gt; t) \leq \frac{\sigma^2}{t^2} \qquad P( X - \mu  &gt; k\sigma) \leq \frac{1}{k^2}</math></div></div></div>

9 Moment Generating Function

<div><div><div><math display="block">M(t) = E(e^{tx}) = \sum_x e^{tx} p(x)</math></div></div><div><div><math display="block">M(t) = E(e^{tx}) = \int_{-\infty}^{\infty} e^{tx} f(x) \, dx</math></div></div></div>
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Properties of Moment Generating Function
<div><div><div>• MGF is unique for a distribution, so can prove the distribution that an RV follows.</div><div>• MGF can be used to calculate some form of Expectation. That is, the <b>rth moment</b> is:</div><div><math display="block">E(X^r) = M^{(r)}(0)</math></div></div><div><div>So Variance can also be calculated as the second moment of <math>X</math> subtract the square of the first moment of <math>X</math>, that is:</div><div><math display="block">Var(X) = M^{(2)}(0) - [M^{(1)}(0)]^2</math></div></div><div><div>• <b>rth central moment</b> is defined as:</div><div><math display="block">E([X - E(X)]^r)</math></div></div><div><div>• MGF of a transformed function is:</div><div><math display="block">M_{aX+b}(t) = e^{bt} M_X(at)</math></div></div><div><div>• If <math>X</math> and <math>Y</math> are independent RV, then:</div><div><math display="block">M_{X+Y}(t) = M_X(t)M_Y(t)</math></div></div></div>

10 Gamma Function

<div><div><div><math display="block">\Gamma(\alpha) = \int_0^{\infty} u^{\alpha-1} e^{-u} \, du</math></div></div><div><div>• when <math>\alpha</math> is fraction : <math>\Gamma(\alpha + 1) = \alpha \Gamma(\alpha)</math></div><div>• when <math>\alpha</math> is integer : <math>\Gamma(\alpha + 1) = \alpha!</math></div></div></div>
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$a$	1/2	3/2	1	2	3	4
$\Gamma(a)$	$\sqrt{\pi}$	$\sqrt{\pi}/2$	1	1	2	6

11 Law of Large Number (LLN)

Let  $X_1, X_2, \dots$  be independent RV, and  $E(X_i) = \mu, Var(X_i) = \sigma^2$  (we only require the variance is finite), Let:  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$  then for any  $\varepsilon > 0$ :

$$P(|\bar{X}_n - \mu| \geq \varepsilon) \rightarrow 0 \qquad \text{as } n \rightarrow \infty$$

That is when  $n \rightarrow \infty$ , then the sample mean convergence in probability to the true mean  $\bar{X}_n \rightarrow \mu$ .

12 Monte Carlo Integration

<div><div><div>We want to find:</div><div><math display="block">I(g) = \int_0^1 g(x) \, dx</math></div></div><div><div>We first generate <math>n</math> RV <math>X_1, \dots, X_n</math> from <math>Uni(0, 1)</math>, then we have:</div><div><math display="block">\bar{X}_n = \hat{I}(f) = \frac{1}{n} \sum_{i=1}^n f(X_i) \qquad \text{as } n \rightarrow \infty</math></div></div></div>
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The key here is that the Uniform distribution on  $[0, 1]$  has PDF 1, thus the expectation of sample mean is just the function we want.

13 Convergence in Distribution

Let  $X_1, \dots, X_n$  be independent RV. Let  $X$  be RV. Then  $X_n$  convergence in distribution to  $X$  if:

$$\lim_{n \rightarrow \infty} F_n(x) = F(x)$$

At all points which  $F$  is continuous. We often use MGF to prove convergence in distribution, that is:

$$\lim_{n \rightarrow \infty} M_n(t) = M(t) \implies \lim_{n \rightarrow \infty} F_n(x) = F(x)$$

For  $t$  in an open interval containing zero.  
We can use Standard Normal to approximate Poisson, when  $\lambda$  gets large enough, but we first need to Standardiz the Poisson.

14 Central Limit Theorem (CLT)

Let  $X_1, X_2, \dots$  be independent RV, and  $E(X_i) = 0, Var(X_i) = \sigma^2$  and common CDF/PDF and MGF defined in a neighbourhood of zero.

<div><div><div>• If we want Sum of <math>X_i</math>, we define:</div><div><math display="block">S_n = \sum_{i=1}^n X_i</math></div></div><div><div>Then we have:</div><div><math display="block">\lim_{n \rightarrow \infty} P\left(\frac{S_n}{\sigma\sqrt{n}} \leq x\right) = \Phi(x)</math></div></div><div><div>• If we want Average of <math>X_i</math>, we define:</div><div><math display="block">\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i</math></div></div><div><div>Then we have:</div><div><math display="block">\lim_{n \rightarrow \infty} P\left(\frac{\bar{X}_n}{\sigma/\sqrt{n}} \leq x\right) = \Phi(x)</math></div></div></div>
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For  $-\infty < x < \infty$ , that is when  $n \rightarrow \infty$ , then  $\bar{X} \sim (\mu, \sigma^2/n)$ .

If we don't have Expected value 0, we can subtract off the mean and shift the distribution to make it have an expected value of 0.

Normal Approximation
<div><div><div>In practise, we can normalize the sum to make it a standard normal:</div><div><math display="block">\frac{S - E(S)}{Std(S)} \sim N(0, 1)</math></div></div><div><div>• Binomial: Let <math>X_1, \dots, X_n</math> be RV that follows Bernoulli distribution with parameter <math>p</math>. So their sum:</div><div><math display="block">S_n = \sum_{i=1}^n X_i</math></div></div><div><div>follows a Binomial distribution, that is: <math>S_n \sim Bin(n, p)</math>, we have that:</div><div><math display="block">Z_n = \frac{S_n - np}{\sqrt{np(1-p)}}</math></div></div><div><div>Where <math>Z_n \sim N(0, 1)</math>.</div></div></div>