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# Locally-informed proposals in Metropolis-Hastings algorithm with applications

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#### Markov chain

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#### Definition

A Markov chain is a stochastic process describing a sequence on some countable state space S in which the probability of each event depends only on the state of previous event.

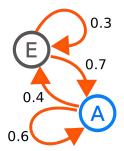


Figure: A diagram representing a two-state Markov chain, source: wiki.

## **Properties**

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#### Definition (Irreducibility)

A Markov chain is irreducible if there is a possibility to reach every state from every state.

#### Definition (Periodicity)

A state is periodic if there is a possibility of coming back to it after some period.

#### Definition (Stationarity)

A probability distribution  $\pi = (\pi_1, \dots, \pi_N)$  is called stationary if it satisfies

$$\pi_j = \sum_{i \in S} \pi_i p_{ij},$$

## Ergodic chains

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#### Definition (Ergodicity)

A Markov chain is ergodic when it is irreducible and aperiodic.

#### Theorem

Let  $\{X_k\}$  be a ergodic Markov chain, then:

$$\lim_{k \to \infty} p_{ij}(k) = \pi_j.$$

# Metropolis-Hastings algorithm

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Construct a MC, which has a stationary distribution  $\pi$  ( $\pi_i > 0$ ). Assume that  $\mathbf{Q}$  is stochastic matrix which is irreducible, aperiodic and  $\mathbf{Q}_{i,j} > 0 \iff \mathbf{Q}_{j,i} > 0$ . Let us consider a matrix defined as:

$$\mathbf{P}_{i,j} = \begin{cases} \mathbf{Q}_{i,j} \min\left(1, \frac{\pi_j \mathbf{Q}_{j,i}}{\pi_i \mathbf{Q}_{i,j}}\right) & \text{if } i \neq j, \\ 1 - \sum_{j \in S \setminus \{i\}} \mathbf{P}_{i,j} & \text{if } i = j. \end{cases}$$
 (1)

#### Theorem

A matrix defined in 1 is stochastic, irreducible, aperiodic and has a stationary distribution  $\pi$ .

# Metropolis-Hastings algorithm

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#### **Algorithm** Metropolis-Hastings algorithm

- 1: Choose a state  $i \in S$ .
- 2:  $X_0 \leftarrow i$
- 3: **for**  $k = 0, 1, \dots$  **do**
- Sample  $j \sim \mathbf{Q}_i = (\mathbf{Q}_{i,1}, \mathbf{Q}_{i,2}, \dots, \mathbf{Q}_{i,N})$ . 4:
- 5: Sample  $U \sim Unif(0,1)$ .
- 6: **if**  $U \leq \min\left(1, \frac{\pi_j \mathbf{Q}_{j,i}}{\pi_i \mathbf{Q}_{i,j}}\right)$  then
- 7:
- else 8:
- $X_{k+1} \leftarrow X_k$ 9.
- 10: end if
- 11: end for

## Traveling salesman problem

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#### Definition (TSP)

Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?

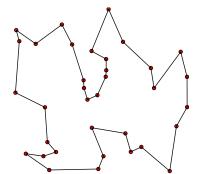


Figure: Traveling salesman problem, source: wiki.

## Traveling salesman problem

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#### Definition (Traveling salesman problem)

Given an undirected weighted graph  $G=(V,E),\ |V|=n$  find a permutation  $\sigma_{\min}$  of vertices such that

$$\sigma_{\min} = \operatorname*{arg\,min}_{\sigma \in S_n} \left( \sum_{i=1}^{n-1} w_{\sigma(i),\sigma(i+1)} + w_{\sigma(n),\sigma(1)} \right),$$

where  $S_n$  is a set of all permutations of vertices and  $w_{i,j}$  is distance (weight) between state i and j.

#### Softmax

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#### Definition

For a given vector  $\mathbf{x}=(x_1,x_2,\dots,x_d)^T\in\mathbb{R}^d$  a softmax function  $s:\mathbb{R}^d\to[0,1]^d$  is defined as

$$s(\mathbf{x})_i = \frac{e^{x_i}}{\sum_{j=1}^d e^{x_j}},$$
  
$$s(\mathbf{x}) = (s(\mathbf{x})_1, s(\mathbf{x})_2, \dots, s(\mathbf{x})_d).$$

$$\sigma_{\min} = \underset{\sigma \in S_n}{\arg \min} (w_{\sigma}) = \underset{\sigma \in S_n}{\arg \max} \frac{e^{-w_{\sigma}}}{\sum_{\sigma' \in S_n} e^{-w_{\sigma'}}},$$

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$$\frac{\pi_j \mathbf{Q}_{j,i}}{\pi_i \mathbf{Q}_{i,j}} = e^{-(w_j - w_i)} \cdot \frac{\mathbf{Q}_{j,i}}{\mathbf{Q}_{i,j}}.$$

$$\log\left(\frac{\pi_j \mathbf{Q}_{j,i}}{\pi_i \mathbf{Q}_{i,j}}\right) = -(w_j - w_i) + \log(\mathbf{Q}_{j,i}) - \log(\mathbf{Q}_{i,j}).$$

#### **Candidates**

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#### Definition

A neighbour  $\sigma'$  of a permutation  $\sigma$  is a permutation, that for some k,l it satisfies  $\sigma'(k)=\sigma(l),\,\sigma'(l)=\sigma(k)$  and  $\sigma'(i)=\sigma(i)$  for the rest of indices.

These neighbours are the original tour with two swaped indices. This let us consider a smaller space – there are  $\binom{n}{2} = \frac{n(n-1)}{2} \approx n^2$  neighbours if the number of vertices is n.

## Random candidates (RN)

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Sample neighbours uniformly. It is equivalent to choosing random indices to swap

# Random candidates (RN)

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When given a tour  $\sigma$  and its neighbour  $\sigma'$  they differ only on those edges where swap is happening, let us say k, l. So for this situation we have tours:

$$\sigma = (\ldots, \sigma(k-1), \sigma(k), \sigma(k+1), \ldots, \sigma(l-1), \sigma(l), \sigma(l+1), \ldots)$$
  
$$\sigma' = (\ldots, \sigma(k-1), \sigma(l), \sigma(k+1), \ldots, \sigma(l-1), \sigma(k), \sigma(l+1), \ldots)$$

We need to remove weights  $w_{\sigma(k-1),\sigma(k)}$ ,  $w_{\sigma(k),\sigma(k+1)}$ ,  $w_{\sigma(l-1),\sigma(l)}$ ,  $w_{\sigma(l),\sigma(l+1)}$  and add  $w_{\sigma(k-1),\sigma(l)}$ ,  $w_{\sigma(l),\sigma(k+1)}$ ,  $w_{\sigma(l-1),\sigma(k)}$ ,  $w_{\sigma(k),\sigma(l+1)}$ .

# Locally-informed proposals (LIP)

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The idea is to balance the increase in the probability of neighbour with decrease of reverse probability, such that it will be easy to compute.

$$\mathbf{Q}_{i,j} \propto e^{\frac{-(w_j - w_i)}{\tau}}.$$

The distribution is chosen in such a way, so that we can easily group up the terms in acceptance criterion:

$$\frac{\pi_{j} \mathbf{Q}_{j,i}}{\pi_{i} \mathbf{Q}_{i,j}} = e^{-(w_{j} - w_{i})} \cdot \frac{e^{\frac{-(w_{i} - w_{j})}{\tau}}}{e^{\frac{-(w_{j} - w_{i})}{\tau}}} \cdot \frac{C_{j}}{C_{i}} = e^{\left(-(w_{j} - w_{i})\left(1 - \frac{2}{\tau}\right)\right)} \cdot \frac{C_{j}}{C_{i}},$$

# Example

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Let us set k=2 and l=7, then the set of indices to consider is  $\{1,2,3,6,7,8\}$  and the permutations:

$$\sigma = (1, \mathbf{2}, 3, 4, 5, 6, \mathbf{7}, 8, 9, \ldots)$$

$$\sigma' = (1, 7, 3, 4, 5, 6, 2, 8, 9, \ldots).$$

## Example

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	2	3	4	5	6	7	8	9	10
1	(1,2)	(1,3)	(1,4)	(1,5)	(1,6)	(1,7)	(1,8)	(1,9)	
2		(2,3)	(2,4)	(2,5)	(2,6)	(2,7)	(2,8)	(2,9)	
3			(3,4)	(3,5)	(3,6)	(3,7)	(3,8)	(3,9)	
4				(4,5)	(4,6)	(4,7)	(4,8)	(4,9)	
5					(5,6)	(5,7)	(5,8)	(5,9)	• • •
6						(6,7)	(6,8)	(6,9)	
7							(7,8)	(7,9)	
8								(8,9)	

Table: Neighbour representation.

# Simulated annealing

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The idea is to describe a probability of state using a cooling parameter  $t_k$  such that it reminds the cooling of a metal and may change with each step:

$$\pi_i = \frac{e^{\frac{-E_i}{t_k}}}{C},$$

where  ${\cal C}$  is normalizing constant. The quotient of probabilities then is:

$$\frac{\pi_j}{\pi_i} = e^{\frac{E_i - E_j}{t_k}}$$

#### Initial condition

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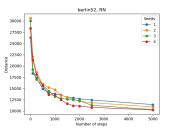
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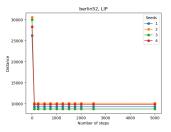
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- (a) Random neighbours.
- (b) Locally-informed proposals.

Figure: Different initial states for berlin52.

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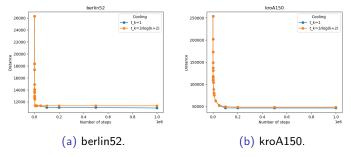


Figure: Different cooling parameters for berlin52 and kroA150.

#### **Temperature**

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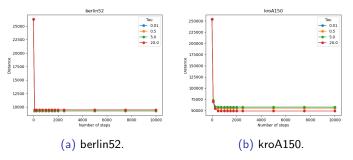


Figure: Different temperature parameters for berlin52 and kroA150.

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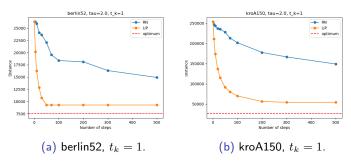


Figure: Comparing RN and LIP for *berlin52* and *kroA150* with low number of iterations.

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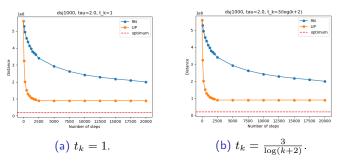


Figure: Comparing RN and LIP for *dsj1000* with different cooling parameters.

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	RN			LIP			
dataset	dist.	time $[s]$	ratio	dist.	time $[s]$	ratio	
berlin52	11344	1.32	1.50	9276	116	1.23	
kroA150	62467	1.24	2.36	53988	454	2.04	
att532	165445	1.38	5.98	78150	2462	2.82	
dsj1000	199343433	1.5	10.68	89105687	6439	4.78	

Table: Methods comparison,  $t_k = 1$ , 20000-th step.

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	RN			LIP			
dataset	step	distance	time [s]	step	distance	time [s]	
berlin52	20000	11344	1.32	27	11198	0.22	
kroA150	20000	62467	1.24	139	62459	3.64	
att532	20000	165445	1.38	199	165247	24.65	
dsj1000	20000	199343433	1.5	256	199338468	80.54	

Table: Amount of time and number of steps required for LIP algorithm to reach the result of RN after 20000 steps,  $t_k = 1$ .

#### **Conclusions**

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- LIP algorithm is decreasing the distance quicker than RN,
- LIP converges to some value, which is always smaller than the RN,
- LIP reaches better results in feasible time,
- Only first hundreds iterations matter,
- LIP algorithm is considerably slower for a longer run,

### **Improvements**

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- Use of interning in *Pyton3*,
- use of concurrency,
- lacksquare sampling from  $\mathbf{Q}_i$  using MCMC methods,
- better tuning of temperature and cooling parameters.

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Conclusions

Thank you for your attention.