

# System identification, Estimation and Filtering

## Exercise 1

### Hair dryer model identification (real data).

Consider an hair dryer whose input is the electric power and output is the air temperature.

#### Problem:

- 1) Identify from experimental data several ARX, ARMAX and OE models of different orders for the hair dryer.
- 2) Select the "best" model among the ones identified at step 1. Use the following criteria/methods for the selection:
  - AIC
  - MDL
  - best FIT, where the FIT index is defined as

$$FIT = 1 - \frac{\sqrt{\sum_{t=1}^N (y(t) - \hat{y}(t))^2}}{\sqrt{\sum_{t=1}^N (y(t) - m_y)^2}}, \quad m_y = \text{sample mean of } y$$

- cross validation
- residual analysis.

#### Main steps:

- 1) Open the *Ident GUI* by means of the *Matlab* command *ident*.
- 2) Import the dryer data (*Import data/Example*).
- 3) Remove means.
- 4) Partition the whole data set in two subsets: estimation data set (ES) and validation data set (VS).
- 5) Insert ES as the working data and VS as the validation data in the *Ident GUI*.
- 6) Perform the order selection (*Linear Parametric Models*) using an ARX structure and considering the AIC, MDL and best FIT criteria.
- 7) Identify several models of different orders using the following structures:
  - ARX(na,nb,nk)
  - ARMAX(na,nb,nc,nk)
  - OE(nb,nf,nk)where na, nb, and nk have been selected at step 6.
- 7) Compare the identified models on the set VS considering the best FIT index and the residual analysis.
- 8) Select the "best" model.

## Exercise 2

### Parameter convergence in ARX model identification (simulated data)

Consider the following ARX(1,2,1) system:

$$y(t) = -0.93y(t-1) + 1.5u(t-1) - 3u(t-2) + e(t)$$

where  $e(t) \sim WN(0, 9)$ .

#### Problem:

- 1) Supposing that the parameter vector  $\theta_o = [0.93, 1.5, -3]^T$  is unknown, derive the least-squares estimate  $\hat{\theta}_N$  of  $\theta_o$  using  $N$  data.
- 2) Considering increasing values of  $N$ , verify the asymptotic convergence of the least-squares estimate  $\hat{\theta}_N$  to the true parameter vector  $\theta_o$ :

$$\hat{\theta}_N \xrightarrow[N \rightarrow \infty]{} \theta_o.$$

#### Main steps:

- 1) Create a Matlab script for the simulation of the ARX(1,2,1) system:
  - Use a *for* loop with  $N = 1 : T$ .
  - Both standard and recursive least-squares can be used for identification (the latter are lighter from a computational standpoint).
  - Use the command *randn* to generate both the input  $u$  and the noise  $e$ .
- 2) At each step  $N$  of the *for* loop:
  - Derive an estimate  $\hat{\theta}_N$  using the data  $y(t)$  and  $u(t)$  with  $t \leq N$ .
  - Insert the estimate  $\hat{\theta}_N$  in the  $N$ -th column of a  $3 \times T$  matrix  $P$ .
- 3) Plot  $P'$  in function of  $N$ .