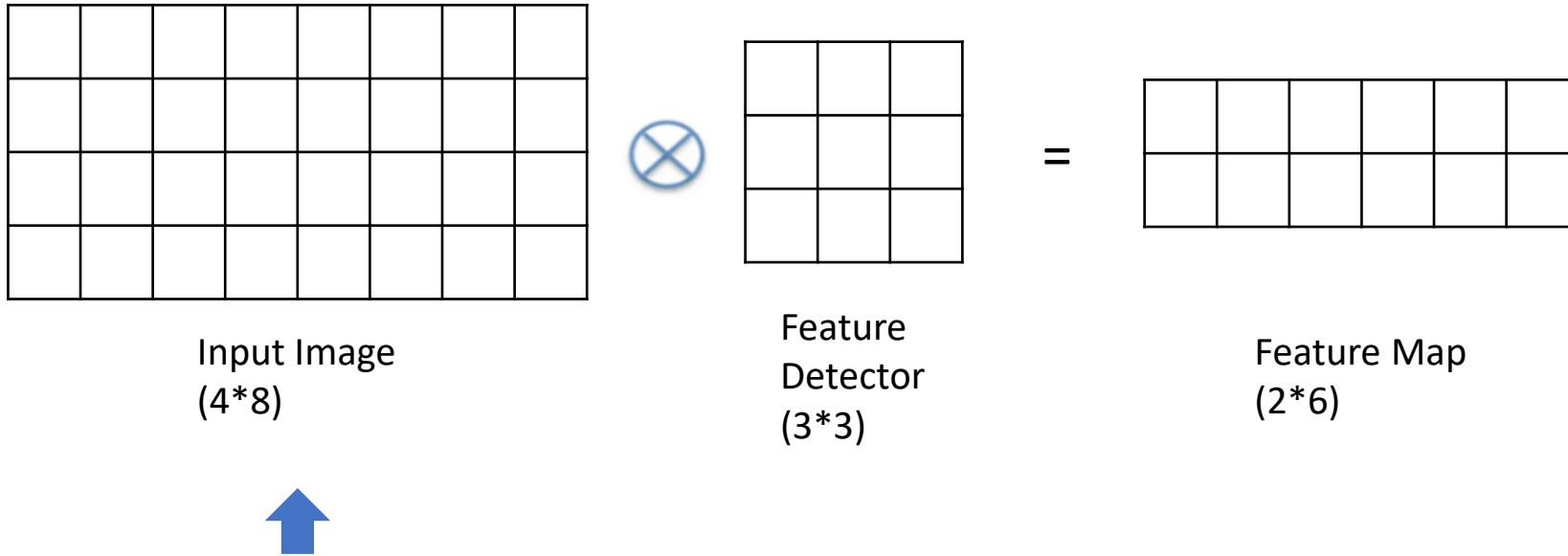


Research of AI accelerator

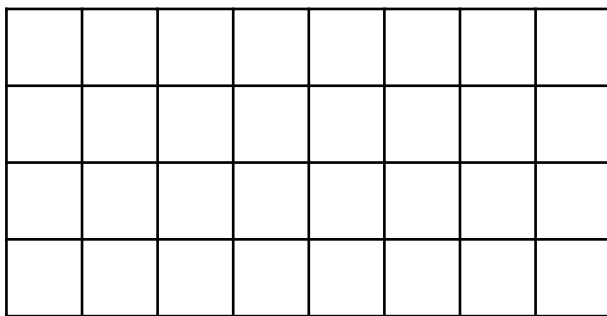
Con2d Transformation



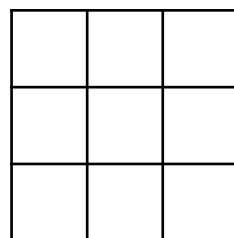
To split input image to fit hardware constraints

1.

**Along input
width dimension**

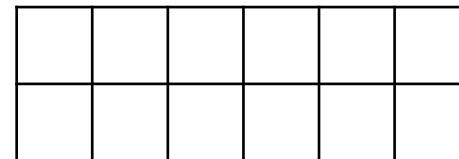


Input Image
(4*8)



Feature
Detector
(3*3)

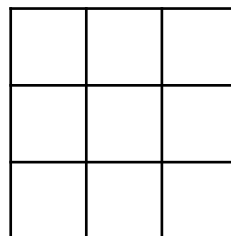
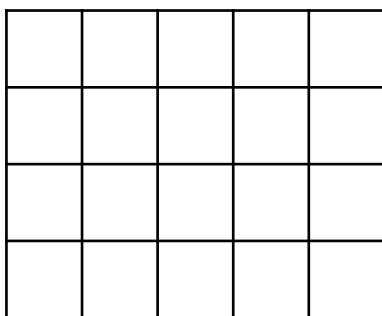
=



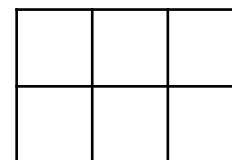
Feature Map
(2*6)



Split image



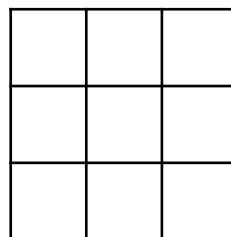
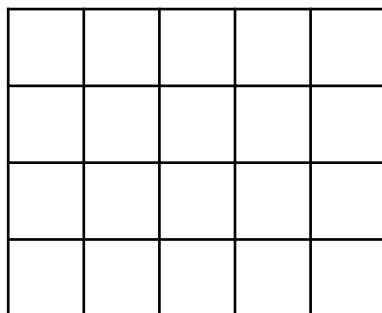
=



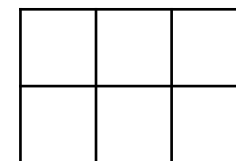
(=)



Concat

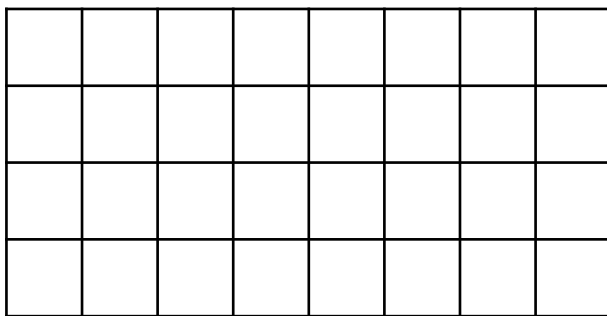


=

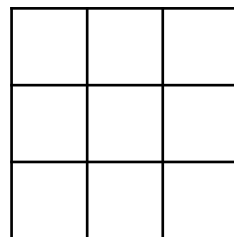


2.

**Along input
height dimension**

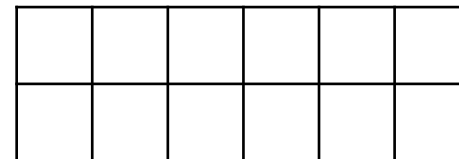


Input Image
(4*8)



Feature
Detector
(3*3)

=



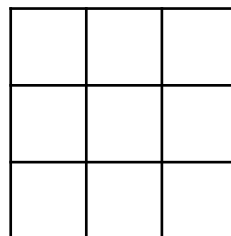
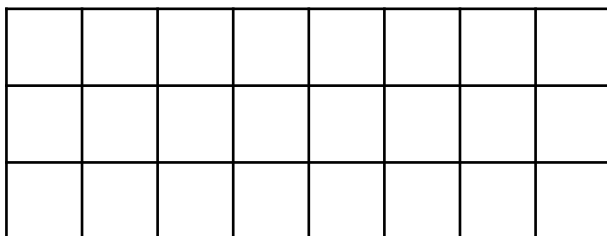
Feature Map
(2*6)



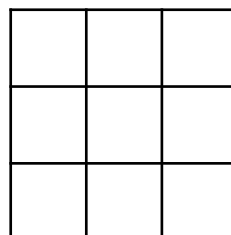
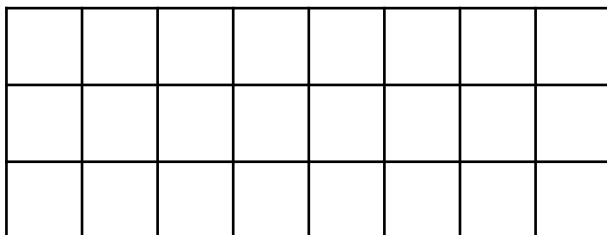
Split image



(=)



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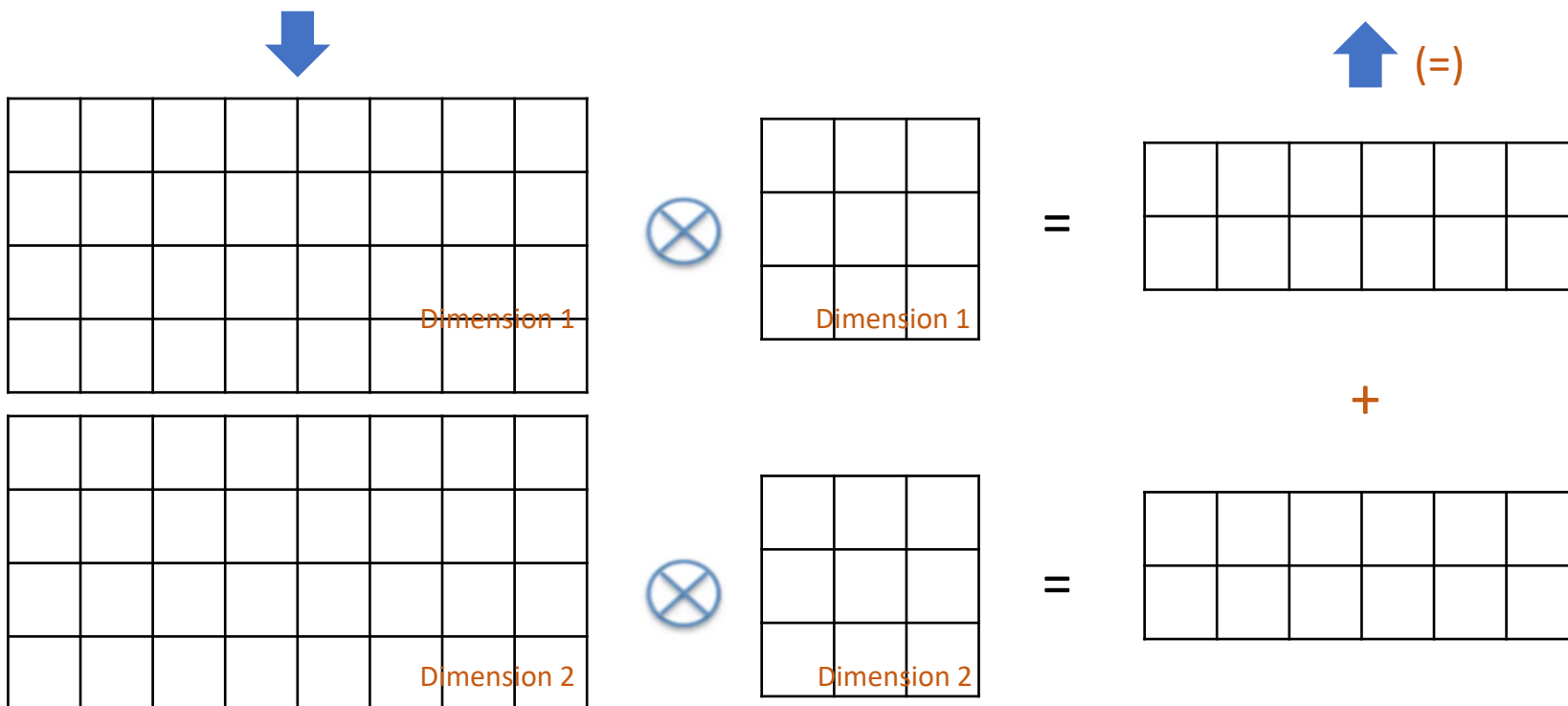
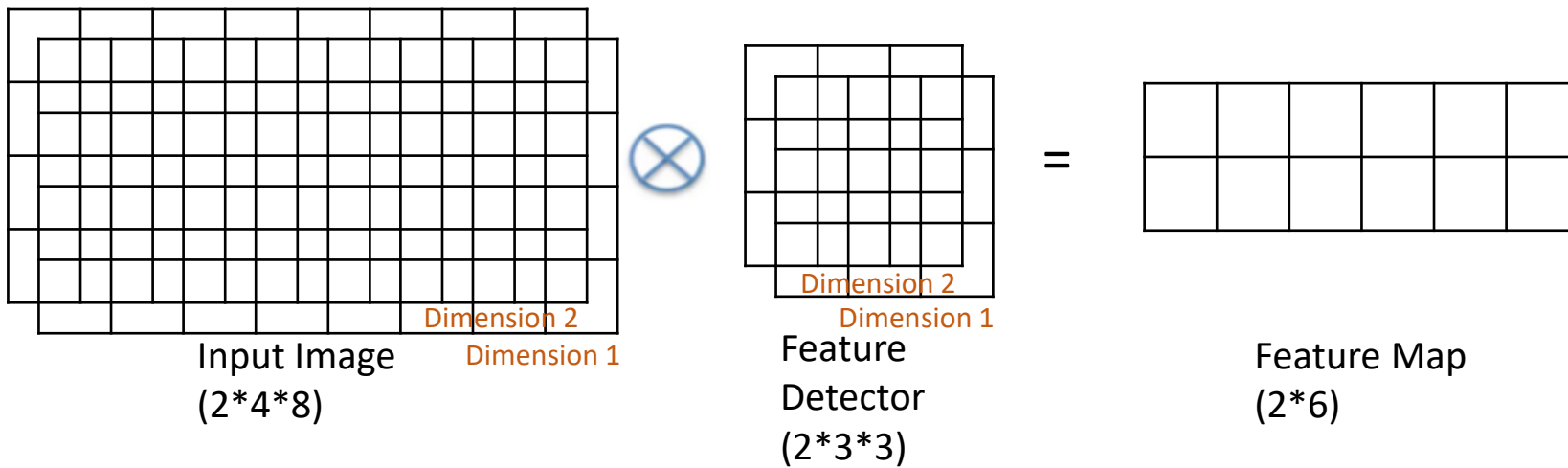
=



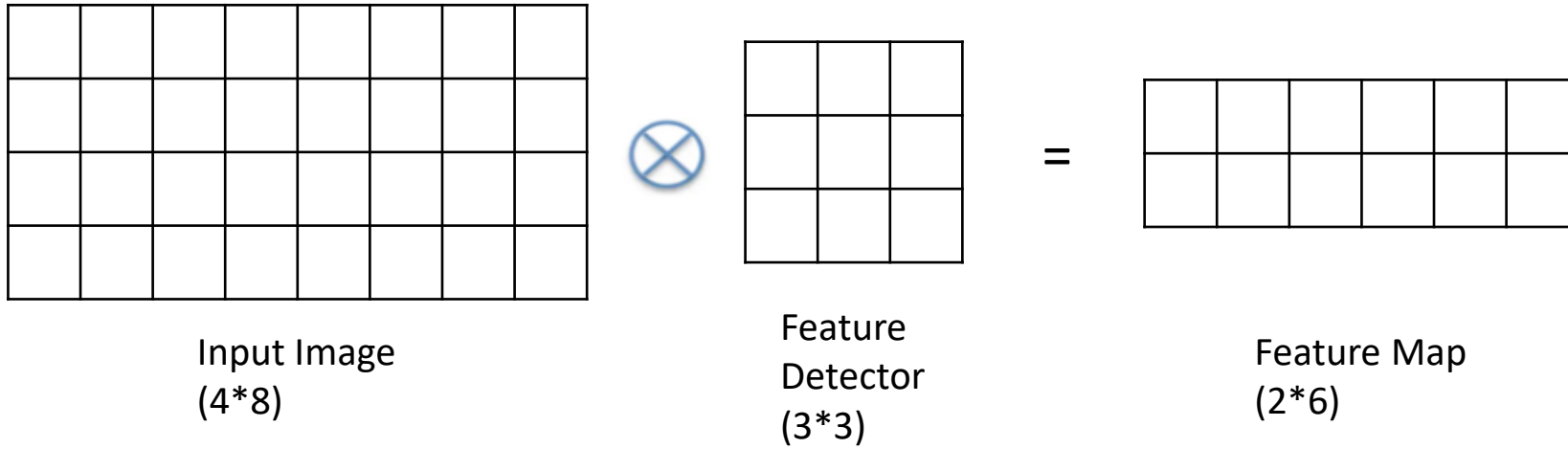
Concat

3.

**Along input
channel dimension**

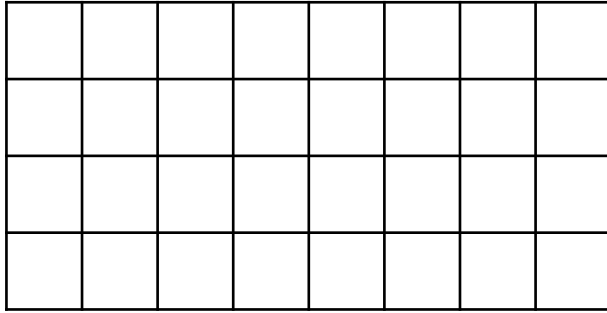


Appendix

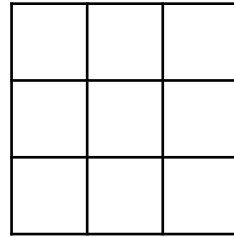


Split input image with weight

To split input image to fit hardware resource constraints

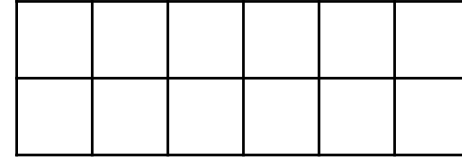


Input Image
(4*8)



Feature
Detector
(3*3)

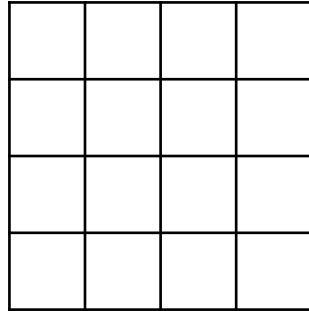
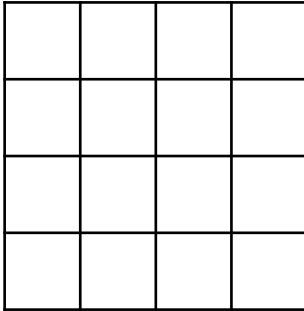
=



Feature Map
(2*6)



Split image



Input Image
(4*8)



Feature
Detector
(3*3)

=

Feature Map
(2*6)



Split image

				0	0
				0	0
				0	0
				0	0

Zero padding

0	0				
0	0				
0	0				
0	0				

Zero padding

Input Image
(4*8)



Feature
Detector
(3*3)

=

Feature Map
(2*6)



Split image

				0	0
				0	0
				0	0
				0	0

Zero padding



=

0	0				
0	0				
0	0				
0	0				

Zero padding



=

Input Image
(4*8)



Feature
Detector
(3*3)

=

Feature Map
(2*6)



Split image

				0	0
				0	0
				0	0
				0	0

Zero padding



=

				0	0
				0	0

Zero padding

0	0				
0	0				
0	0				
0	0				

Zero padding



=

0	0				
0	0				

Zero padding

Input Image
(4*8)



Feature
Detector
(3*3)

=

Feature Map
(2*6)



Split image

				0	0
				0	0
				0	0
				0	0

Zero padding



=

				0	0
				0	0

Zero padding



+

0	0				
0	0				
0	0				
0	0				

Zero padding



=

0	0				
0	0				

Zero padding

Follow up

1. To consider input /weight and output stationary to do the optimization.