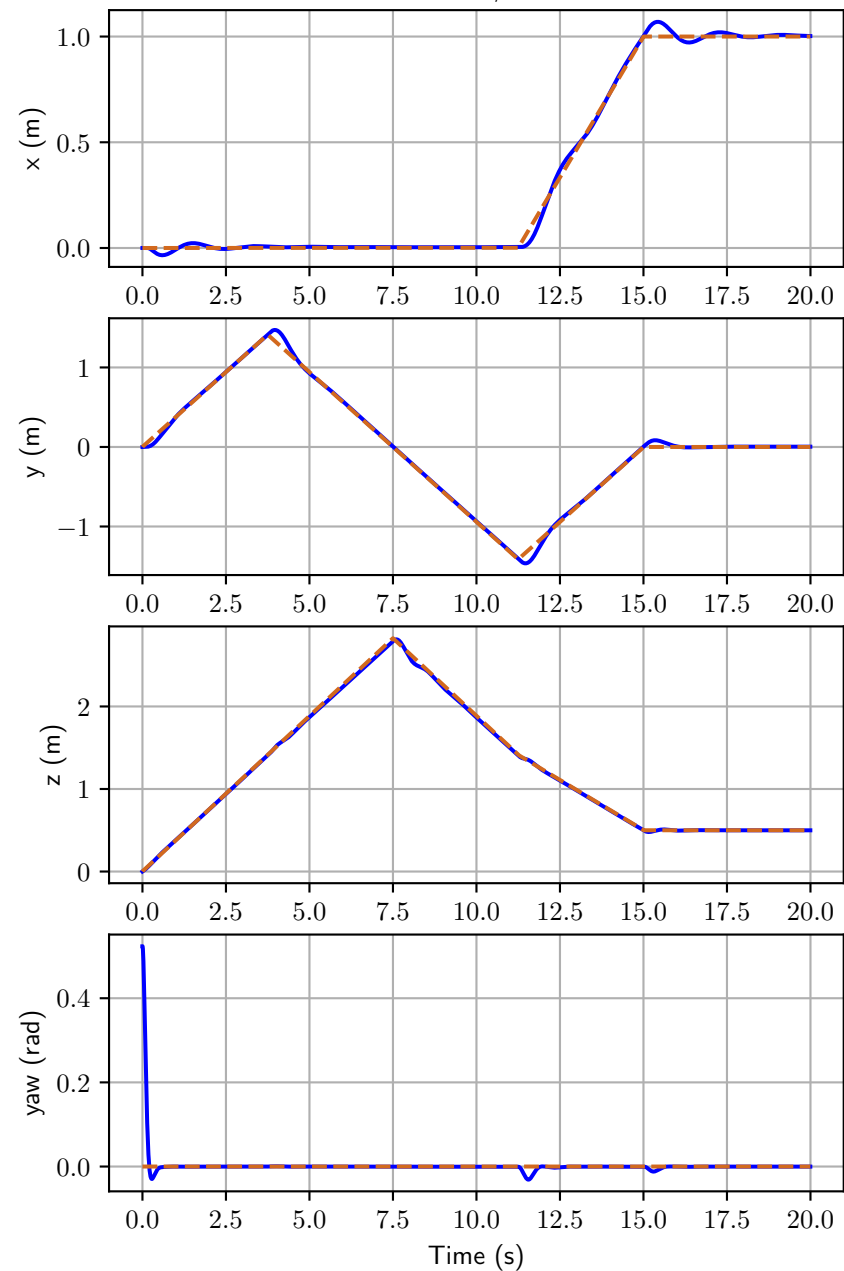
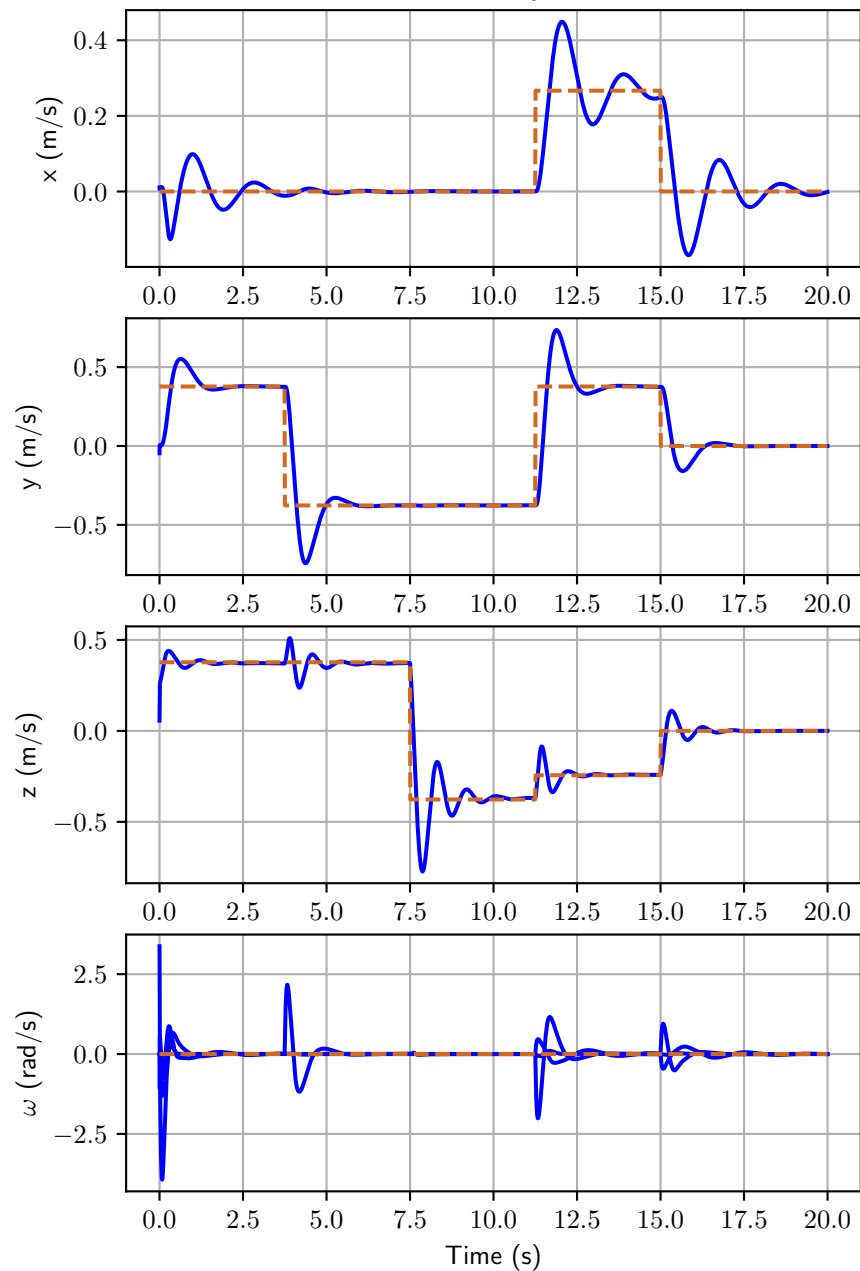


Position/Yaw



Velocity



— learned    - - - reference