## coursework2

## **Problem 1:**

In Lecture we considered application of the classical and modified Gram-Schmidt algorithms to produce a QR factorisation the problem Lauchli matrix

$$A = egin{bmatrix} 1 & 1 & 1 \ \ell & 0 & 0 \ 0 & \ell & 0 \ 0 & 0 & \ell \end{bmatrix} = QR$$

In several application areas, it is important to compute the columns of Q so that their orthogonality is as strict as possible. For these cases, reorthogonalisation can vastly improve performance of the algorithm. Specically, the Gram-Schmidt orthogonalisation process is repeated p times. For the classical Gram-Schmidt algorithm, this modication results in:

```
Algorithm CGS
```

```
1: \mathbf{for} \ \mathbf{j} = 1 \ \mathbf{to} \ \mathbf{n} \ \mathbf{do}
2: u_j = a_j
3: \mathbf{for} \ \mathbf{i} = 1 \ \mathbf{to} \ \mathbf{j} - 1 \ \mathbf{do}
4: r_{ij} = q_i^* a_j
5: u_j = u_j - r_{ij} q_i
6: \mathbf{end} \ \mathbf{for}
7: r_{jj} = ||u_j||_2
8: q_j = u_j/r_{jj}
9: \mathbf{end} \ \mathbf{for}
```

 $\Rightarrow$ 

### Algorithm CGS with reorthogonalisation

```
1: \mathbf{for} \ \mathbf{j} = 1 \ \mathbf{to} \ \mathbf{n} \ \mathbf{do}
2: u_j = a_j
3: \mathbf{for} \ \mathbf{k} = 1 \ \mathbf{to} \ \mathbf{p} \ \mathbf{do}
4: \mathbf{for} \ \mathbf{i} = 1 \ \mathbf{to} \ \mathbf{j} - 1 \ \mathbf{do}
5: u_j = u_j - q_i^* u_j q_i
6: \mathbf{end} \ \mathbf{for}
7: \mathbf{end} \ \mathbf{for}
8: q_j = u_j / ||u_j||_2
9: \mathbf{end} \ \mathbf{for}
```

Notice that Algorithm 2 does not include the computation of the elements of R, since the projection step is repeated p times Base on the above

(a)

write the corresponding algorithm for the modified Gram-Schmidt (MGS) processs with reorthogonalisation, including with the computation of the elements of R

the original modified Gram Schmidt using orthogonal projectors is

#### **Algorithm** original MGS

```
1: for j = 1 to n do

2: u_j = a_j

3: end for

4: for j = 1 to n do

5: r_j j = ||u_j||_2

6: q_j = u_j/r_{jj}

7: for k = j+1 to n do

8: r_{jk} = q_j^* u_k

9: u_k = u_k - r_{jk} q_j

10: end for

11: end for
```

with reorthogonalisation

#### **Algorithm** MGS with Reorthogonalisation and Computation of R

```
1: for j = 1 to n do
 2: u_j = a_j
 3: end for
 4: for j = 1 to n do
 5: r_{jj} = ||u_j||_2
 6: q_j = u_j/r_{jj}
 7: \mathbf{for} \ \mathbf{i} = 1 \ \mathbf{to} \ \mathbf{p} \ \mathbf{do}
            for k = j + 1 to n do
 8:
 9:
               r_{jk}=q_{i}^{st}u_{k}
10:
               u_k = u_k - r_{jk}q_j
           end for
11:
       end for
12:
13: end for
```

# (b)

Apply CGS and MGS with one reorthogonalisation step (p = 2) to the Lauchi matrix A

we apply the conditions in the lecture, assuming  $\ell$  is small or

$$\begin{cases} 1+\ell=1\\ 1+\ell^2=1 \end{cases}$$

and from  $1+\ell^2=1,\,\ell^2=0,$  we can purge any  $\ell^2$ 

# In CGS with reorthogonalization

first we initialize U with A, and R with an empty matrix the size of U, in the Lauchi matrix, n = 3

$$oldsymbol{\cdot} j=1:u_1=egin{bmatrix}1\\ell\end{bmatrix} \ oldsymbol{0} \ oldsymbol{0} \end{bmatrix}$$

• since j - 1 = 0 < 1, the inner two loop do not execute

$$ullet q_1=rac{u_1}{||u_1||_2}=rac{u_1}{\sqrt{1+\ell^2}}=u_1=egin{bmatrix}1\\ell\0\0\end{bmatrix}$$

• 
$$j=2:u_2=egin{bmatrix}1\0\\ell\0\end{bmatrix}$$

$$egin{aligned} u_2 &= u_2 - q_1^* u_2 q_1 = egin{bmatrix} 0 \ -\ell \ 0 \end{bmatrix} &= egin{bmatrix} \ell^2 \ -\ell + \ell^3 \ 0 \end{bmatrix} &= egin{bmatrix} 0 \ -\ell \ 0 \end{bmatrix} &= egin{bm$$

$$ullet \ q_2 = rac{u_2}{||u_2||_2} = rac{u_2}{\sqrt{2\ell^2}} = rac{1}{\sqrt{2}\ell} u_2 = rac{1}{\sqrt{2}} egin{bmatrix} 0 \ -1 \ \end{pmatrix}$$

$$ullet j = 3: u_2 = egin{bmatrix} 1 \ 0 \ ldot \ ldot \end{bmatrix}$$

\_

$$egin{aligned} u_3 &= u_3 - q_1^* u_3 q_1 = egin{bmatrix} 0 \ -\ell \ 0 \end{bmatrix} &= egin{bmatrix} 0 \ -\ell \ 0 \end{bmatrix} &= egin{bmatrix} 1 \ \ell \ 0 \end{bmatrix} &= egin{bmatrix} 1 \ 0 \ \ell \end{bmatrix} &= egin{bmatrix} 1 \ 0 \ \ell \end{bmatrix} &= egin{bmatrix} 0 \ \ell \end{bmatrix} &= egin{bmatrix} 0 \ \ell \end{bmatrix} &= egin{bmatrix} 0 \ -\ell \ \ell \end{bmatrix} &$$

 $u_{3} = u_{3} - q_{2}^{*}u_{3}q_{2} = \begin{bmatrix} 0 \\ -\ell \\ 0 \\ \ell \end{bmatrix} - \frac{1}{2}[0 \quad -1 \quad 1 \quad 0] \begin{bmatrix} 0 \\ -\ell \end{bmatrix} \begin{bmatrix} 0 \\ -1 \end{bmatrix}$   $= \begin{bmatrix} 0 \\ -\ell \\ -\ell \end{bmatrix} - \frac{1}{2}\ell \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$   $= \begin{bmatrix} 0 \\ -\frac{1}{2}\ell \\ -\frac{1}{2}\ell \\ \ell \end{bmatrix}$ 

- k = 2 - i = 1

-

$$egin{aligned} u_3 &= u_3 - q_1^* u_3 q_1 = egin{aligned} -rac{1}{2}\ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} &- [1 \quad \ell \quad 0 \quad 0] egin{aligned} -rac{1}{2}\ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} egin{aligned} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix} &= egin{aligned} 0 \ -rac{1}{2}\ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} &- rac{1}{2}\ell^2 \ 0 \ 0 \end{bmatrix} \ &= egin{aligned} -rac{1}{2}\ell^2 \ -rac{1}{2}\ell \end{bmatrix} &= egin{aligned} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix} &= egin{aligned} 0 \ -rac{1$$

$$u_3 = u_3 - q_2^* u_3 q_2 = egin{bmatrix} 0 \ -rac{1}{2}\ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} - rac{1}{2}[0 \quad -1 \quad 1 \quad 0] egin{bmatrix} 0 \ -rac{1}{2}\ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} egin{bmatrix} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix} = egin{bmatrix} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix} = egin{bmatrix} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix} = egin{bmatrix} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix}$$

$$-\,q_3=rac{u_3}{||u_3||_2}=rac{u_3}{\sqrt{rac{1}{4}\ell^2+rac{1}{4}\ell^2+\ell^2}}=rac{u_3}{\sqrt{rac{3}{2}\ell}}=rac{1}{\sqrt{rac{3}{2}}}egin{bmatrix}0\-rac{1}{2}\1\end{bmatrix}$$

we can get the corresponding Q U, this algorithm does not calculate R

# In MGS with reorthogonalization:

first we initialize U with A, and R with an empty matrix the size of U, in the Lauchi matrix, n = 3

$$oldsymbol{i} j=1:u_1=egin{bmatrix} 1\ \ell\ 0\ 0 \end{bmatrix}, r_{11}=rac{1}{\sqrt{1+\ell^2}}=1, q_1=u_1/r_{11}=egin{bmatrix} 1\ \ell\ 0\ 0 \end{bmatrix}$$

- when i = 1,

$$- k = 2$$

$$egin{align*} oldsymbol{-} r_{12} &= q_1^* u_2 = egin{bmatrix} 1 \ \ell \ 0 \end{bmatrix} oldsymbol{-} oldsymbol{-} oldsymbol{0} \ 0 \end{bmatrix} oldsymbol{-} oldsymbol{0} \ oldsymbol{-} u_2 &= u_2 - 1 * q_1 = egin{bmatrix} 1 \ 0 \ 0 \end{bmatrix} - egin{bmatrix} 1 \ \ell \ 0 \end{bmatrix} = egin{bmatrix} 0 \ -\ell \ 0 \end{bmatrix} egin{bmatrix} 0 \ -\ell \ 0 \end{bmatrix}$$

$$oldsymbol{-} r_{13} = q_1^* u_3 = egin{bmatrix} egin{bmatrix} 1 \ \ell \end{bmatrix} & egin{bmatrix} 1 \ 0 \end{bmatrix} & egin{bmatrix} 0 \ 0 \end{bmatrix} & egin{bmatrix} 0 \ \ell \end{bmatrix} & = 1$$

$$ext{-} u_3 = u_3 - 1 * q_1 = egin{bmatrix} 1 \ 0 \ \ell \end{bmatrix} - egin{bmatrix} 1 \ \ell \end{bmatrix} = egin{bmatrix} 0 \ -\ell \end{bmatrix}$$

$$-i = 2$$

$$- k = 2$$

$$\begin{aligned} & \boldsymbol{\cdot} \boldsymbol{\cdot} \boldsymbol{r}_{12} = \boldsymbol{q}_1^* \boldsymbol{u}_2 = \begin{bmatrix} 1 \\ \ell \end{bmatrix} & \begin{bmatrix} 0 \\ -\ell \end{bmatrix} \\ & \begin{bmatrix} 0 \\ 0 \end{bmatrix} & = -\ell^2 \\ & \begin{bmatrix} 0 \\ 0 \end{bmatrix} & \begin{bmatrix} 1 \\ \ell \end{bmatrix} \\ & \begin{bmatrix} 1 \\ \ell \end{bmatrix} & \begin{bmatrix} \ell^2 \\ \ell(-1 + \ell^2) \end{bmatrix} & \begin{bmatrix} 0 \\ -\ell \end{bmatrix} \\ & \begin{bmatrix} \ell \end{bmatrix} & \begin{bmatrix} 0 \\ \ell \end{bmatrix} \\ & \begin{bmatrix} \ell \end{bmatrix} & \begin{bmatrix} 0 \\ \ell \end{bmatrix} \end{bmatrix} \end{aligned}$$

$$- k = 3$$

$$egin{align*} -r_{13} &= q_1^* u_3 = egin{align*} egin{align*} iggl[ egin{align*} 1 \ -\ell \ 0 \ 0 \ \end{bmatrix} &= -\ell^2 \ iggl[ egin{align*} 0 \ \ell \ \end{bmatrix} &= egin{align*} -\ell^2 \ iggl[ egin{align*} 0 \ -\ell \ \end{bmatrix} &= egin{align*} iggl[ egin$$

- when 
$$i = 1$$
,

$$-k = 3$$

$$egin{aligned} -r_{23} &= q_2^* u_3 = rac{1}{\sqrt{2}} egin{aligned} \ell & 0 & 0 & 0 \ -1 & 0 & 0 & 0 \ \ell & 0 & \ell & 0 \end{aligned} = rac{1}{\sqrt{2}} \ell \ -u_3 &= u_3 - rac{1}{\sqrt{2}} \ell * q_2 = egin{bmatrix} 0 & 0 & 0 & 0 \ -\ell & -\ell & 0 \ \ell & 0 & -rac{1}{2} \ell & 0 \end{bmatrix} = egin{bmatrix} 0 & 0 \ -rac{1}{2} \ell & 0 \ -rac{1}{2} \ell & \ell \end{bmatrix} \end{aligned}$$

$$-i = 2$$

$$-k = 3$$

$$egin{aligned} oldsymbol{-}r_{23} &= q_2^*u_3 = rac{1}{\sqrt{2}}egin{bmatrix} \ell \ -1 \ \ell \end{bmatrix}egin{bmatrix} \ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} &oldsymbol{-}rac{1}{2}\ell \ -rac{1}{2}\ell \ \ell \end{bmatrix} = 0 \end{aligned}$$

$$egin{align} egin{align*} egin{align*} egin{align*} egin{align*} egin{align*} -u_3 &= u_3 &= egin{align*} egin{align*} -rac{1}{2}\ell \ \ell \end{bmatrix} \ j &= 3, u_3 &= egin{bmatrix} 0 \ -rac{1}{2}\ell \ \ell \end{bmatrix}, r_{33} &= rac{1}{\sqrt{rac{3}{2}}\ell}, \ q_3 &= u_3/||u_3||_2 &= rac{1}{\sqrt{rac{3}{2}}} egin{bmatrix} 0 \ -rac{1}{2} \ 1 \end{bmatrix} \end{array}$$

we can get the corresponding Q U R

# (c)

in CGS

```
Algorithm CGS with reorthogonalisation
                                                                                                       \overline{//n} cycles
 1: for j = 1 to n do
 2:
      u_j = a_j
                                                                                                       //p cycles
 3:
      for k = 1 to p do
                                                                                          //1 + 2 + \cdots + n - 1
          for i = 1 to j - 1 do
 4:
             u_i = u_i - q_i^* u_i q_i
 5:
          end for
 6:
       end for
 7:
       q_j = u_j/||u_j||_2
 9: end for
```

assume  $U \in \mathbb{R}^{m imes n}$ 

in line 5, since  $q_i, u_j, q_i \in \mathbb{R}^m$  and  $q_i^*u_j$  is a scalar

therefore the flop operation in this line is m + m + m

the first for vector minus, the second for vector dot product and the last of multiplying a scalar with a vector

in line 8, the  $\ell_2$  norm of  $u_j$ , first calculates the sqaure of all elements, and the adds them together, do square root then do the division, this takes m + (m-1) + m + 1 = 3m

therefore the total flop operations is

$$n*(3m)+(\sum_{i=1}^{n-1}i*p*3m)=3mn(rac{p(n-1)}{2}+1)=3*4*3*3=108$$
 in MGS, this is similar,

#### Algorithm MGS with Reorthogonalisation and Computation of R

```
1: for j = 1 to n do
      u_i = a_j
 2:
 3: end for
 4: for j = 1 to n do
 5: r_{jj}=||u_j||_2
 6: q_j = u_j/r_{jj}
      for i = 1 to p do
         for k = j + 1 to n do
             r_{jk}=q_i^*u_k
 9:
             u_k = u_k - r_{jk}q_j
10:
         end for
11:
      end for
12:
13: end for
```

line 2 takes no flops

line 5 and line 6 take 3m (see CGS line 8)

line 9 and line 10 is similar to CGS line 5

so the flop in the is just the same as CGS, 108

### **Problem 2:**

Given the following matrix A, its inverse and a vector b:

$$A = egin{bmatrix} 5 & -1 & 1 \ -1 & 6 & -2 \ 1 & -2 & 6 \end{bmatrix} ext{ with } A^{-1} = rac{1}{152} egin{bmatrix} 32 & 4 & -4 \ 4 & 29 & 9 \ -4 & 9 & 29 \end{bmatrix}; b = egin{bmatrix} 5 \ -1 \ 2 \end{bmatrix}$$

(a)

Find the conditional number of A using both the  $\ell_1$  norm and the  $\ell_\infty$  norms

$$\kappa(A) = ||A|| \, ||A^{-1}|| \ = ||egin{bmatrix} 5 & -1 & 1 \ -1 & 6 & -2 \ 1 & -2 & 6 \end{bmatrix}|| \, ||rac{1}{152} egin{bmatrix} 32 & 4 & -4 \ 4 & 29 & 9 \ -4 & 9 & 29 \end{bmatrix}||$$

if using the  $\ell_1$  norm, or the maximum absolute column sum

then 
$$\kappa(A) = 9 * \frac{1}{152} 42 = \frac{210}{152} = \frac{189}{76}$$

if using the  $\ell_\infty,$  or the maximum absolute row sum

then 
$$\kappa(A) = 9 * \frac{1}{152} 42 = \frac{189}{76}$$

### Solve the equation Ax = b using an analytical method

since in edstem Any non-iterative method can be considered analytical.

$$x = A^{-1}b$$

$$= \frac{1}{152} \begin{bmatrix} 32 & 4 & -4 \\ 4 & 29 & 9 \\ -4 & 9 & 29 \end{bmatrix} \begin{bmatrix} 5 \\ -1 \\ 2 \end{bmatrix}$$

$$= \frac{1}{152} \begin{bmatrix} 148 \\ 9 \\ 29 \end{bmatrix}$$

## **Problem3**

In lecture, we examined the stability of multiplying vectors with vectors and triangular matrices. We now consider the problem of computing the general matrix product Ax=b, where  $A\in\mathbb{C}^{n\times n}$  and  $x,b\in\mathbb{C}^n$ . We use the following simple algorithm to compute b for given A, x

### Algorithm Matrix-Vector Multiplication

```
egin{aligned} 1: \mathbf{b} &= 0 \ 2: \mathbf{for} \ \mathbf{i} &= 1 \mathbf{to} \ \mathbf{n} \ \mathbf{do} \ 3: \quad \mathbf{for} \ \mathbf{j} &= 1 \mathbf{to} \ \mathbf{n} \ \mathbf{do} \ 4: \quad b_i &= b_i + A_{ij} x_j \ 5: \quad \mathbf{end} \ \mathbf{for} \ 6: \mathbf{end} \ \mathbf{for} \end{aligned}
```

Perform a backward stability analysis of this algorithm. You may assume the given data are floating-point numbers (errors are only introduce by arithmetic operations)

we assume the floating point precise of the machine that this algorithm will run on is  $\epsilon_{\rm machine}$ , and the floating point operations to be  $\oplus, \otimes$  for add ans multiply, and fl() for convert the numerical values to the real value used in the program

according to the question

- input data can be seen as x
- output is Ax

in order to check an algorithm is backwards stable, we need to check

$$egin{aligned} & ilde{f}(x) = f( ilde{x}) \ & ext{o} & rac{|| ilde{x} - x||}{||x||} = \mathcal{O}(\epsilon_{ ext{machine}}) \end{aligned}$$

for clarity

we first analyse the inner cycle, or line 3 to 5,

then the inner loop will iteratively increment  $b_i$  by  $A_{ij}x_j$ 

therefore, the inner loop does  $b_i = b_i \oplus (A_{ij} \otimes x_j)$  iteratively

Since

$$egin{aligned} fl(A_{ij})\otimes fl(x_j) &= A_{ij}\otimes x_j \ &= (1+\delta_1)A_{ij}x_j \end{aligned}$$

where, as the question states, we assume everything is floating point, or fl is the identity function.  $\delta_1$  is the error caused during multiplying floating point numbers and  $|\delta| \leq \epsilon_{\rm machine}$ 

therefore we can show that, the inner cycle will turn  $b_i$  to

$$b_i + \sum_{j=1}^n (1+\delta_1) A_{ij} x_j$$

combined with the outer loop, which does the same operation for each i, independently the program turns b (initially 0), to  $(1+\delta_1)Ax$ 

therefore 
$$ilde{f}(x) = (1+\delta_1)(1+\delta_2)Ax$$

where  $\delta_2$  is the error caused by  $\oplus$ 

to satisfy  $f(\tilde{x})$  which f(x) = Ax, we let  $\tilde{x} = (1 + \delta_1)(1 + \delta_2)x$ 

then

$$egin{aligned} rac{|| ilde{x}-x||}{||x||} &= rac{||(1+\delta_1)(1+\delta_2)x-x||}{||x||} \ &= rac{||(\delta_1+\delta_2+\delta_1\delta_2)x||}{||x||} \ &= \mathcal{O}(\epsilon_{ ext{machine}}) \end{aligned}$$

therefore, we can safely conclude that this algorithm is backward stable

## **Problem 4**

We defined the growth factor for Gaussian elimination of a matrix  $A \in \mathcal{L}^{m imes m}$  to be

$$ho = rac{\max_{i,j} |u_{i,j}|}{\max_{i,j} |a_{i,j}|}$$

where A=LU,  $a_{i,j}$  is the element A[i,j] and  $u_{i,j}$  is the element U[i,j]. Show that with partial pivoting this growth factor is bounded by  $\rho \leq 2^{m-1}$ 

we use induction to prove this

### base case:

m = 1, A is an 1 \* 1 matrix say [a]

then we dont need elimination for solving A = LU

A = U, or 
$$\rho = 1 = 2^0 = 2^{1-1} = 2^{m-1}$$

therefore when m = 1, the growth factor is bounded by  $2^{m-1}$ 

# **Induction hypothesis**

$$orall N \in \mathbb{R}^{(m-1) imes (m-1)}, 
ho_{(m-1)} \leq 2^{(m-1)-1} = 2^{m-2}$$

# **Inductive Step:**

take arbitrary matrix  $A \in \mathbb{C}^{m imes m}$ 

During the first step of Gaussian elimination, we look for the largest absolute value in the first column of the matrix to serve as the pivot.

Let  $M = \max_{1 \leq i \leq m} |a_{i1}|$  be the largest absolute value in the first column

Assume we a swap the first row containing M (the pivot row).

then we do the following operation on the remaining rows in Gaussian Elimination

$$u_{ij} := u_{ij} - rac{a_{i1}}{a_{11}} u_{ij}$$

(reminder: we assume the pivot is in the first row for clarity)

since  $a_{11}$  is the pivot, this limits  $|rac{a_{i1}}{a_{11}}| \leq 1$  since  $a_{11} \geq a_{i1} orall i$ 

therefore, after performing the elimination, the maximum absolute value of the entries in U can at most be doubled

this can happen when  $rac{a_{i1}}{a_{11}}=-1$ 

and since, by inductive hypothesis,  $ho_{m-1} \leq 2^{m-2}$ 

therefore  $ho_m \leq 2*2^{m-2}=2^{m-1}$ 

So in conclusion, we have shown that  $ho \leq 2^{m-1}$  if  $A \in \mathbb{C}^{m imes m}$