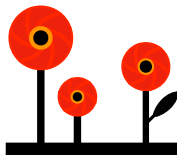


PoPPy: A Point Process PyTorch Toolbox

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Temporal Point Processes

- ▶ **Event sequence:** $S = \{(t_i, c_i)\}_{i=1}^I$, $c_i \in \mathcal{C}$.
- ▶ **Counting processes:** $N = \{N_c(t)\}_{c=1}^C$. $N_c(t)$ is the number of type- c events occurring till time t .
- ▶ **Intensity function:** The expected instantaneous happening rate of type- c events given the history.

$$\lambda_c(t) = \frac{\mathbb{E}[dN_c(t)|\mathcal{H}_t]}{dt}, \quad \mathcal{H}_t = \{(t_i, c_i) | t_i < t, c_i \in \mathcal{C}\}.$$

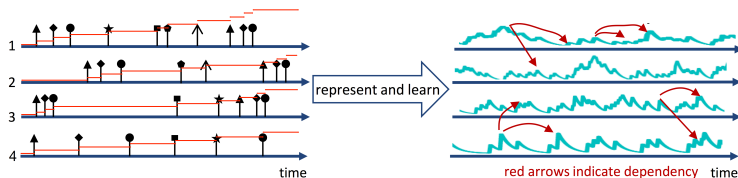


Figure 1: Event sequences and intensity functions.

Hawkes Processes

Hawkes Process has a particular form of intensity:

$$\begin{aligned}\lambda_c(t) &= \mu_c + \sum_{c'=1}^C \int_0^t \phi_{cc'}(t-s) dN_{c'}(s) \\ &= \mu_c + \sum_{(t_i, c_i) \in \mathcal{H}_t} \alpha_{cc_i} \kappa(-\delta_{cc_i}(t - t_i)).\end{aligned}\tag{1}$$

- ▶ $\mu = [\mu_c]$: the **exogenous intensity** of the system.
- ▶ $\Phi = [\phi_{cc'}(t)]$: the **endogenous impact** of the type- c events on the type- c' events.
- ▶ $\sum_{(t_i, c_i) \in \mathcal{H}_t} \phi_{cc_i}(t - t_i)$: the accumulated endogenous intensity caused by history.
- ▶ $\alpha_{cc'}$ is **infectivity**, and $\kappa(t)$ is **decay kernel**.

Motivations

Build a powerful point process toolbox...

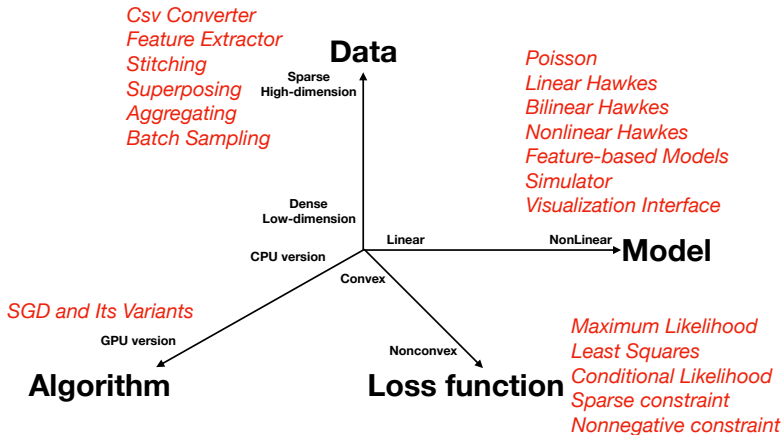
- ▶ Generalize Hawkes process to enhance the capacity of the model.
- ▶ Overcome the drawbacks of existing works.
- ▶ Fill the gap between stochastic process models and practical applications.
- ▶ Summarize my work in past 4 years.

Goals

The proposed toolbox should have the following features:

- ▶ **Rich Functionality:** data operations, learning, prediction, simulation, visualization, ...
- ▶ **Explicit Intrepretability:** Granger causality analysis, interpretable parameters, ...
- ▶ **High Flexibility:** modular design of model, multiple loss functions, regularizers, support numerical and categorical features, ...
- ▶ **High Speed:** low computational complexity, support GPU
- ▶ **High Scalability:** provide a general framework to design arbitrary PP models.

Current Stage: What can PoPPy do?



Data Structure

- ▶ Construct event sequences from csv files.
- ▶ Extract and vectorize numerical and/or categorical features from csv files.
- ▶ Each event contains $\{t, c, \mathbf{f}_c, \mathbf{f}_s\}$.

```
database = {'event_features': None or (C, De) float array of event's static features,  
           C is the number of event types.  
           'type2idx': a Dict = {'event_name': event_index}  
           'idx2type': a Dict = {'event_index': 'event_name'}  
           'seq2idx': a Dict = {'seq_name': seq_index}  
           'idx2seq': a Dict = {'seq_index': 'seq_name'}  
           'sequences': a List = {seq_1, seq_2, ..., seq_N}.  
        }
```

For the i -th sequence:

```
seq_i = {'times': (N,) float array of timestamps, N is the number of events.  
        'events': (N,) int array of event types.  
        'seq_feature': None or (Ds,) float array of sequence's static feature.  
        't_start': a float number indicating the start timestamp of the sequence.  
        't_stop': a float number indicating the stop timestamp of the sequence.  
        'label': None or int/float number indicating the labels of the sequence  
        }
```


Special Data Operations

Stitching (random or feature-based)



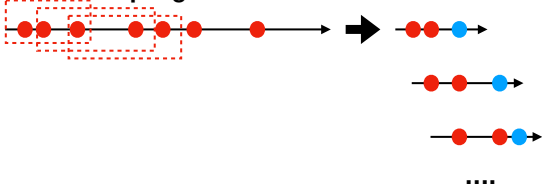
Superposing (random or feature-based)



Aggregating



Batch Sampling



Model

Intensity function:

$$\lambda_c(t) = g_\lambda \left(\mu(c, \mathbf{f}_c, \mathbf{f}_s) + \sum_{t_i < t} \phi(t, t_i, c, c_i, \mathbf{f}_c, \mathbf{f}_{c_i}) \right) \quad (2)$$

Exogenous Intensity:

$$\mu(c, \mathbf{f}_c, \mathbf{f}_s) = \begin{cases} g_\mu(\mu_c), \\ g_\mu(\mathbf{w}_c^\top \mathbf{f}_s), \\ g_\mu(\mathbf{f}_c^\top \mathbf{W} \mathbf{f}_s), \\ NN(c, \mathbf{f}_c, \mathbf{f}_s). \end{cases} \quad (3)$$

Model

Endogenous Impact

$$\phi(t, t_i, c, c_i, \mathbf{f}_c, \mathbf{f}_{c_i}) = \sum_{m=1}^M \alpha_m(c, c_i, \mathbf{f}_c, \mathbf{f}_{c_i}) \kappa_m(t - t_i). \quad (4)$$

Infectivity

$$\alpha_m(c, c_i, \mathbf{f}_c, \mathbf{f}_{c_i}) = \begin{cases} g_{\alpha}(\alpha_{cc_i m}), \\ g_{\alpha}(\mathbf{u}_{c,m}^{\top} \mathbf{v}_{c_i,m}), \\ g_{\alpha}(\mathbf{w}_{c,m}^{\top} \mathbf{f}_{c_i}), \\ g_{\alpha}(\mathbf{f}_c^{\top} \mathbf{W}_m \mathbf{f}_{c_i}), \\ NN(c, c_i, \mathbf{f}_c, \mathbf{f}_{c_i}). \end{cases} \quad (5)$$

Model

Decay Kernel

$$\kappa_m(t) = \begin{cases} \textit{Exp}, \\ \textit{Rayleigh}, \\ \textit{PowerLaw}, \\ \textit{Gate}, \\ \textit{Gaussian}, \\ \textit{GMM}. \end{cases} \quad (6)$$

Activation functions $g_\lambda, g_\mu, g_\alpha$ can be identity, ReLU, or softplus functions.

Loss Function

Maximum Likelihood Estimation

$$L(\theta) = - \sum_{i \in \mathcal{D}} \left(\log \lambda_{c_i}(t_i) - \sum_{c \in \mathcal{C}} \int_{t_{i-1}}^{t_i} \lambda_c(s) ds \right). \quad (7)$$

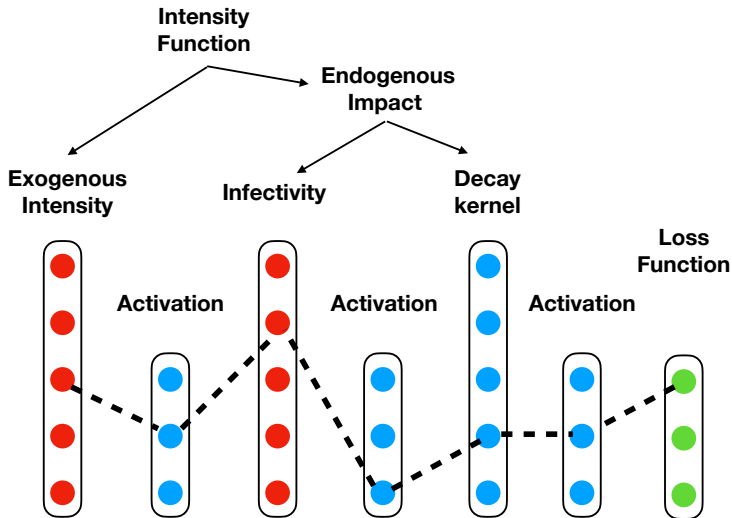
Least-Square Estimation

$$L(\theta) = \sum_{i \in \mathcal{D}} \left\| \int_{t_{i-1}}^{t_i} \lambda(s) ds - \mathbf{1}_{c_i} \right\|_2^2. \quad (8)$$

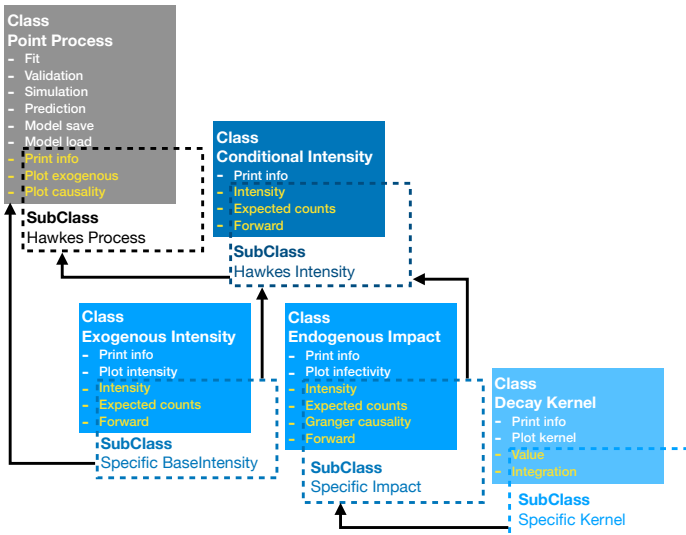
Conditional Likelihood Estimation

$$L(\theta) = - \sum_{i \in \mathcal{D}} \log p(c_i | t_i, \mathcal{H}_i) = - \sum_{i \in \mathcal{D}} \log \text{softmax} \left(\int_{t_{i-1}}^{t_i} \lambda(s) ds \right). \quad (9)$$

Possible Models



Code Framework



- Besides the models above, you can define your own models as long as the IO satisfies required format.

Algorithm

With the help of PyTorch...

- ▶ Most of SGD algorithms like Adam are applicable to learn the models defined above.
- ▶ Both CPU- and GPU-based computations are applicable
- ▶ Nonnegative and sparsity constraints can be imposed to the models.
- ▶ Tricks: although all optimizers are applicable, but generally Adam provides the most stable performance.

Future work

Short-term tasks in next 3 months

- ▶ Build attention-based point process model.
- ▶ Learn point process from aggregate observations.
- ▶ Integrate more my previous work, e.g., learning mixture model of point processes.
- ▶ Continue to do unit test.
- ▶ Documentation.
- ▶ Add more application examples, e.g., finance, healthcare, social network ...

Long-term tasks

- ▶ AutoML for Point Process: configure hyperparameters (i.e., the bandwidth and the number of decay kernel) automatically?
- ▶ Extend to spatial-temporal point process model?