

Research Plan

Title

Student Name

May, 2014

Doctoral Candidate

Supervisor

Abstract

Max. 1/2 page abstract ...

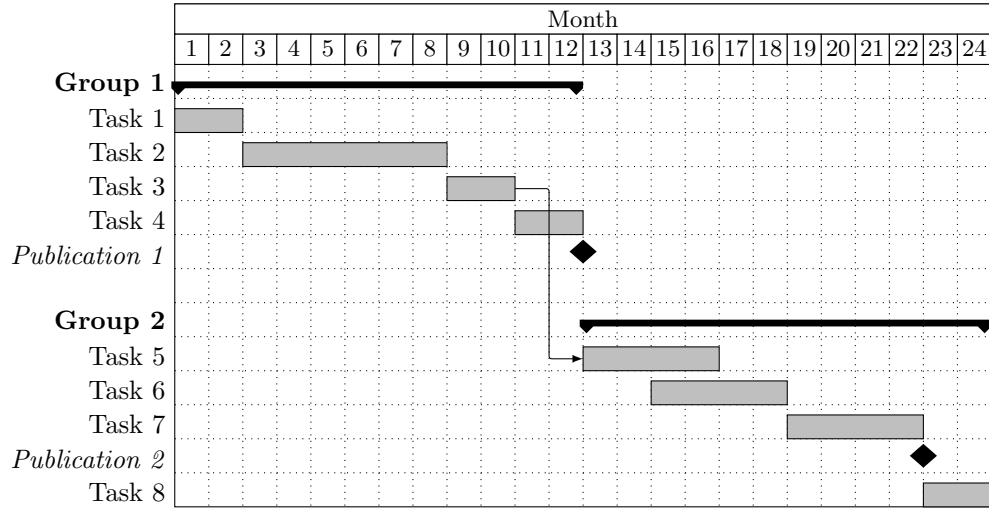


Figure 1: Gantt Chart

1 Motivation and Objectives

- *Motivation & relation to current work at ASL*
- *Objectives*

2 State of the Art

Example references in parentheses format [1, 2] or as textual format as in Pratt and Williamson [3].

3 Approach

- *Research tasks & approach*
- *Expected results*

4 Time Schedule and Planned Publications

- *Time schedule*
- *List of planned publications*

Example Gantt chart shown in fig. 1.

References

- [1] M. Raibert, *Legged Robots That Balance*. Cambridge, MA: MIT Press, 1986.
- [2] M. Vukobratović and B. Borovac, “Zero-moment point — thirty five years of its life,” *International Journal of Humanoid Robotics*, vol. 1, no. 01, pp. 157–173, 2004.

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- [3] G. A. Pratt and M. M. Williamson, “Series elastic actuators,” in *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 1995, pp. 3137–3181.