

Research Plan

Title

Student Name

May, 2014

Doctoral Candidate

Supervisor

Abstract

Max. $\frac{1}{2}$ page abstract ...

1 Motivation and Objectives

- Motivation & relation to current work at ASL
- Objectives

2 State of the Art

- Example references: [1, 2, 3]

3 Approach

- Research tasks & approach
- Expected results

4 Time Schedule and Planned Publications

- Time schedule
- List of planned publications

References

- [1] M. Raibert, *Legged Robots That Balance*. Cambridge, MA: MIT Press, 1986.
- [2] M. Vukobratović and B. Borovac, “Zero-moment point — thirty five years of its life,” *International Journal of Humanoid Robotics*, vol. 1, no. 01, pp. 157–173, 2004.
- [3] G. A. Pratt and M. M. Williamson, “Series elastic actuators,” in *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, pp. 3137–3181, 1995.