Recorded at time: 1652617838.8237603 map Broadcaster: /slam gmapping Average rate: 20.204Buffer length: 4.9 Most recent transform: 1652617838.823 Oldest transform: 1652617833.923 odom Broadcaster: /differential odom Average rate: $10.20\overline{4}$ Buffer length: 4.802 Most recent transform: 1652617838.754 Oldest transform: 1652617833.952 base link Broadcaster: /base link to camera Average rate: $20.\overline{102}$ Buffer length: 4.925 Most recent transform: 1652617838.831 Oldest transform: 1652617833.906 camera link Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2 camera manager Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 $camera_depth_frame$ $camera_color_frame$ Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera depth optical frame camera color optical frame

view frames Result