

$$\mathfrak{s}(\delta_{c2})$$

$$\mathfrak{s}(\delta_{c3})$$

$$\mathfrak{s}(\delta_{r1})$$

$$A \overset{x}{\dashrightarrow} B \overset{y}{\dashrightarrow} C$$

$$\parallel$$

$$\overset{a}{\downarrow}$$

$$\overset{r}{\downarrow}$$

$$\mathfrak{s}(\delta_{r2})$$

$$A \overset{p}{\longrightarrow} D \overset{q}{\longrightarrow} F$$

$$\overset{b}{\downarrow}$$

$$\overset{s}{\downarrow}$$

$$E \overset{=}{=} E$$