

Divide and conquer (D&C) algorithms

- ◆ **General method**
- ◆ **Matrix multiplication**
- ◆ **Strassen matrix multiplication**

General method

- Given a function to compute on n inputs, the divide and conquer strategy suggests splitting the input into k distinct subsets, yielding k subproblems.
- These sub-problems must be solved, then a method must be found to combine sub-solutions into a solution of the whole.
- Often the subproblems are of the same type as the original problem. If the sub-problems are still large, apply D&C to the sub-problem (use recursion).
- Smaller and smaller subproblems are produced until the problem is small enough, which can be solved without splitting.

Algorithm **D&C**(P)

 if $Small(P)$ return $Solve(P)$

 else{

 Divide P into smaller instances P_1, P_2, \dots, P_k

 Apply **D&C** to each of these subproblems

 return $Combine(\mathbf{D\&C}(P_1), \mathbf{D\&C}(P_2), \dots, \mathbf{D\&C}(P_k))$

}

- $Small(P)$ is a Boolean valued function that determines whether the problem is small enough.
- If yes, the function $Solve(P)$ is invoked.
- otherwise, each of subproblems is solved by $D\&C$ algorithm.
- $Combine$ is a function that determines the solution of P using the solutions to k sub-problems.

Matrix multiplication
Strassen Matrix multiplication
Convex hull
Master theorem
Divide and Conquer
max-min **Selection**
Multiplication of two integers

Matrix multiplication

- Example: Calculate

$$C=AB= \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix}$$

$$= \begin{pmatrix} 1*5 + 2*7 & 1*6 + 2*8 \\ 3*5 + 4*7 & 3*6 + 4*8 \end{pmatrix} = \begin{pmatrix} 19 & 22 \\ 43 & 50 \end{pmatrix}$$

- How many multiplications?
- How many additions?
- If matrices are 4 by 4, how many multiplications and additions?
- If matrices are n by n, how many multiplications and additions?

➤ **Definition** If A is an $m \times n$ matrix and B is an $n \times p$ matrix,

$$A = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix}, \quad B = \begin{pmatrix} b_{11} & \cdots & b_{1p} \\ \vdots & \ddots & \vdots \\ b_{n1} & \cdots & b_{np} \end{pmatrix}$$

➤ The matrix product $C = AB$ is defined to be the $m \times p$ matrix

$$C = \begin{pmatrix} c_{11} & \cdots & c_{1p} \\ \vdots & \ddots & \vdots \\ c_{m1} & \cdots & c_{mp} \end{pmatrix}$$

➤ Such that $c_{ij} = a_{i1} b_{1j} + a_{i2} b_{2j} + \dots + a_{in} b_{nj}$

$$= \sum_{k=1}^n a_{ik} b_{kj}$$

➤ We will consider the case where $n=m=p$, for simplicity

Algorithm MatMult(A, B, C: matrix)

Input: matrices A; B

output: matrix C

for(i= 1; i <=n; i+ +) {

for(j= 1; j <=n; j+ +){

C[i; j] = 0;

for(k= 1; k <=n; k+ +){

*C[i, j] =C[i, j] +A[i, k]*B[k, j];*

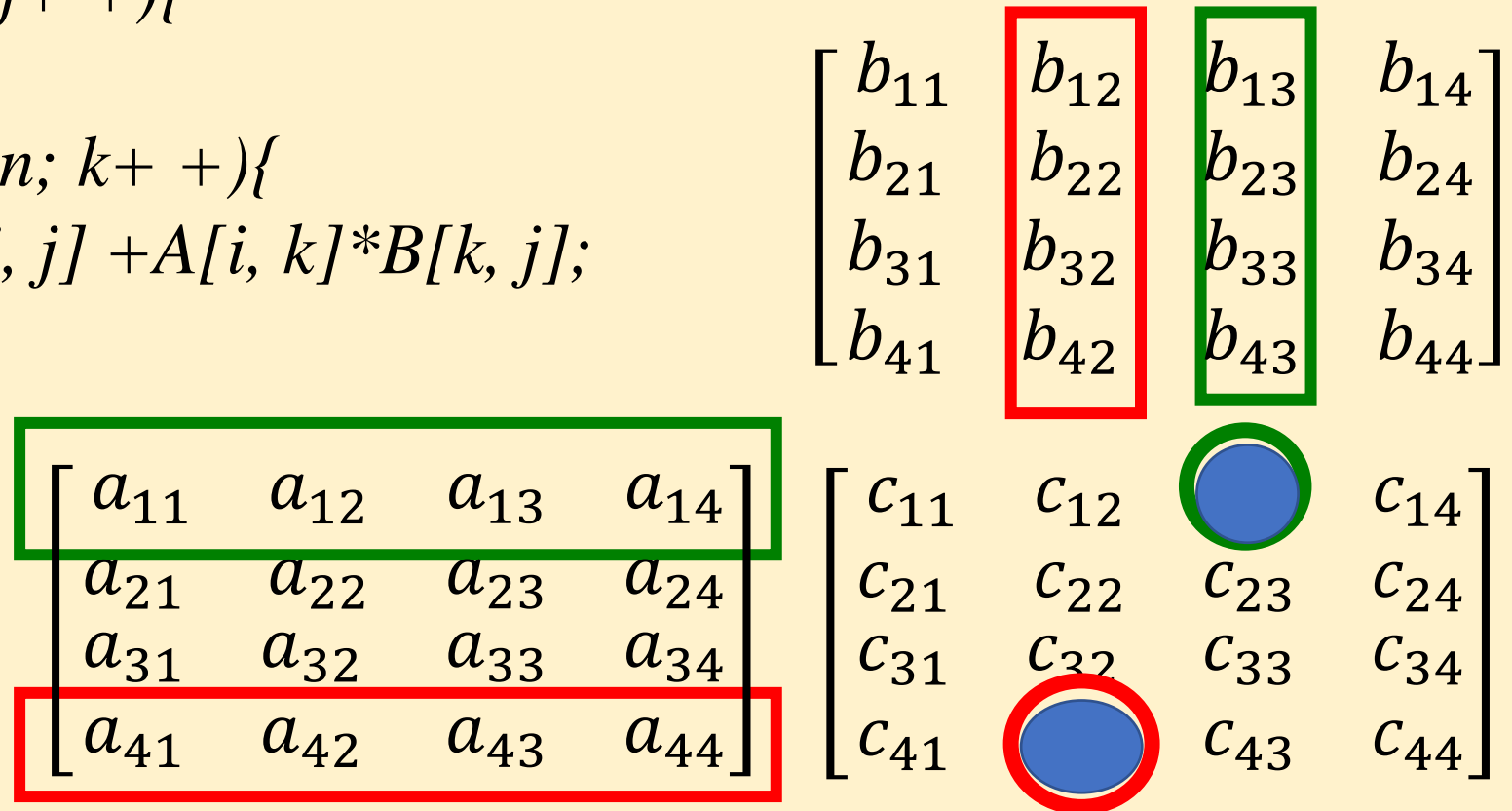
}

}

}

➤ Complexity: $T(n) = O(n^3)$

In which order Matrix C is filled?



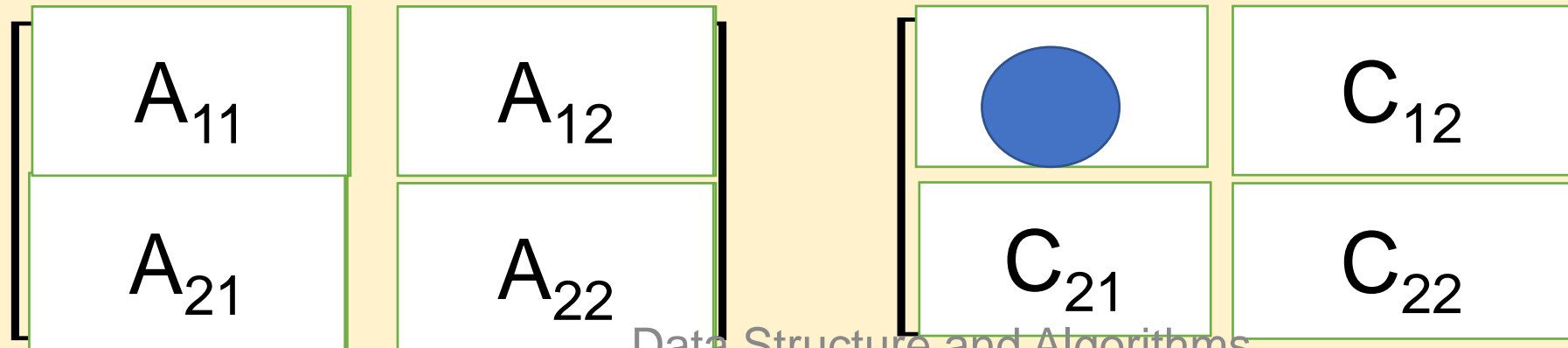
D & C Matrix Multiplication

$$n = \{2, 4, 8, 16, 32, 64 \dots\}$$

➤ Divide problem by partitioning $C=AB$ as

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

where each of A_{ij} , B_{ij} , C_{ij} is $\frac{n}{2}$ by $\frac{n}{2}$ matrices,



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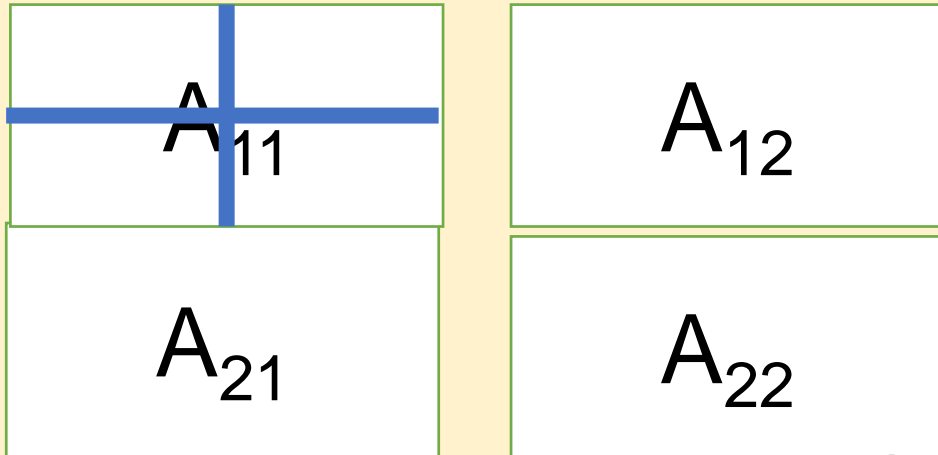
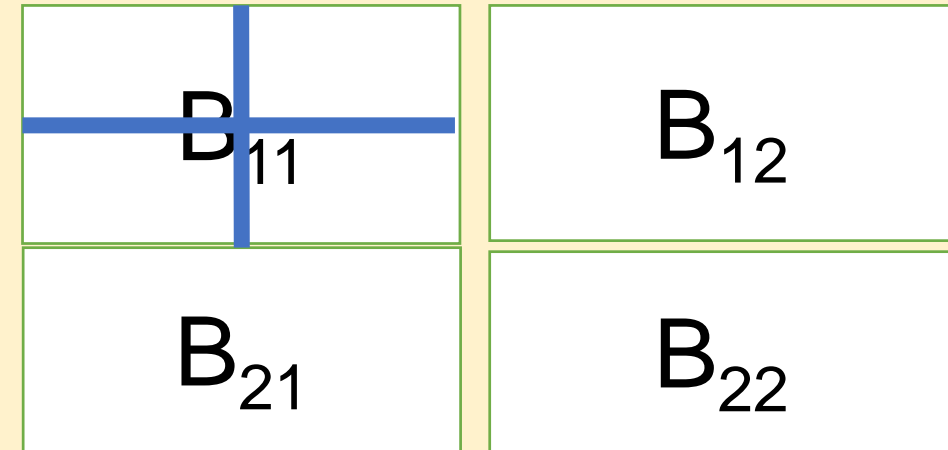
where each of A_{ij} , B_{ij} , C_{ij} is $\frac{n}{2}$ by $\frac{n}{2}$ matrices, with

- Combine solutions

$$\begin{aligned} C_{11} &= A_{11} B_{11} + A_{12} B_{21} \\ C_{12} &= A_{11} B_{12} + A_{12} B_{22} \\ C_{21} &= A_{21} B_{11} + A_{22} B_{21} \\ C_{22} &= A_{21} B_{12} + A_{22} B_{22} \end{aligned}$$

- For simplicity, we assume that $n = 2^k$, then each of the matrix products $A_{ij} B_{ij}$ can be recursively calculated using the same formula by D&C.

- $n=2^k$ divide into eight 2^{k-1} multiplications
- Each submatrix is divided in the same manner, recursively, until its size is $n=2$, so 2 by 2, which is direct solved



- *The algorithm Solve $C=AB$ by D&C*
- *Small(P) is true for $n \leq 2$: direct solve*
- *Divide into subproblems*
e.g $A_{11} B_{11} =$
 $D\&C\text{MatMul}(A_{11}, B_{11})$
- *Combine the solutions*

Algorithm *D&C*MatMult(A, B)

If ($n \leq 2$) return($C_{11}, C_{12}, C_{21}, C_{22}$);
 else{
 Recursively compute all combinations;

$$C_{11} = A_{11} B_{11} + A_{12} B_{21}$$

$$C_{12} = A_{11} B_{12} + A_{12} B_{22}$$

$$C_{21} = A_{21} B_{11} + A_{22} B_{21}$$

$$C_{22} = A_{21} B_{12} + A_{22} B_{22}$$

return($C_{11}, C_{12}, C_{21}, C_{22}$);

}

}

➤ eight multiplications of size $\frac{n}{2}$ by $\frac{n}{2}$ matrices.

➤ Four additions of $\frac{n}{2}$ by $\frac{n}{2}$ which is $O(n^2)$.

➤ So $T(n) = 8T(\frac{n}{2}) + c n^2$ for $n > 2$

Strassen Matrix Multiplication

- Matrix multiplication is more expensive than additions ($O(n^3)$ versus $O(n^2)$).
- Strassen's Matrix Multiplication approach is to reduce the number of multiplications at the expense in additions
- D&C Matrix Multiplication approach
 - 8 multiplications
 - 4 additions or subtractions
- Strassen's Matrix Multiplication approach
 - 7 multiplications
 - 18 additions or subtractions

1. Divide problem by partitioning $C=AB$ as

$$\begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}$$

2. Compute seven matrices as

$$P = (A_{11} + A_{22}) * (B_{11} + B_{22})$$

$$Q = (A_{21} + A_{22}) * B_{11}$$

$$R = A_{11} * (B_{12} - B_{22})$$

$$S = A_{22} * (B_{21} - B_{11})$$

$$T = (A_{11} + A_{12}) * B_{22}$$

$$U = (A_{21} - A_{11}) * (B_{11} + B_{12})$$

$$V = (A_{12} - A_{22}) * (B_{21} + B_{22})$$

3. Combine the solutions as

$$C_{11} = P + S - T + V$$

$$C_{21} = Q + S$$

$$C_{12} = R + T$$

$$C_{22} = P + R - Q + U$$

➤ 7 multiplications

➤ 18 additions or subtractions

➤ Checking if $C_{11} = P + S - T + V$ is correct

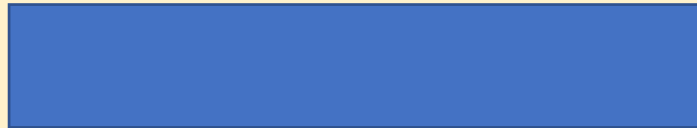
$$P = (A_{11} + A_{22}) * (B_{11} + B_{22}) =$$



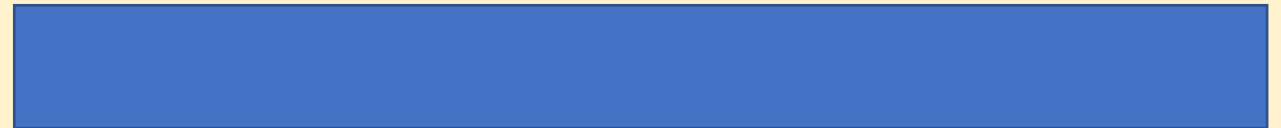
$$S = A_{22} * (B_{21} - B_{11}) =$$



$$-T = -(A_{11} + A_{12}) * B_{22} =$$



$$V = (A_{12} - A_{22}) * (B_{21} + B_{22})$$



$$\begin{aligned} P + S - T + V &= A_{11} B_{11} + A_{12} B_{21} \\ &= C_{11} \end{aligned}$$

Exercise: Checking if $C_{12} = R + T$ is correct

$$R = A_{11} * (B_{12} - B_{22})$$

$$T = (A_{11} + A_{12}) * B_{22}$$

$$R + T =$$

$$C_{12} =$$

Exercise: Checking if $C_{21} = Q + S$ is correct

$$Q = (A_{21} + A_{22}) * B_{11}$$

$$S = A_{22} * (B_{21} - B_{11})$$

$$Q + S =$$

$$C_{21} =$$

Exercise: Checking if $C_{22} = P + R - Q + U$ is correct

$$P = (A_{11} + A_{22}) * (B_{11} + B_{22}) =$$

$$-Q = -(A_{21} + A_{22}) * B_{11} =$$

$$R = A_{11} * (B_{12} - B_{22}) =$$

$$U = (A_{21} - A_{11}) * (B_{11} + B_{12})$$

$$P + R - Q + U =$$

$$C_{22} =$$

➤ Time complexity

$$T(n) = 7T\left(\frac{n}{2}\right) + an^2 \quad \text{for } n > 2$$

$$T(n) = 1 \quad \text{for } n \leq 2$$

➤ Solving recurrence

$$T(n) = a * n^2 \left(1 + \frac{7}{4} + \left(\frac{7}{4}\right)^2 + \dots + \left(\frac{7}{4}\right)^{k-1} \right) + 7^k T\left(\frac{n}{2^k}\right)$$
$$\leq cn^2 \left(\frac{7}{4}\right)^{\log n} + 7^{\log n}$$

(Where c is a constant)

$$= O(n^{\log 7}) = O(n^{2.81})$$

➤ In practice overhead of implementation outweighs benefit.

Divide and conquer (D&C) algorithms

- ◆ **General method**
- ◆ **Multiplication of two binary integers**
- ◆ **Convex hull**

General method

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Multiplication of two binary integers

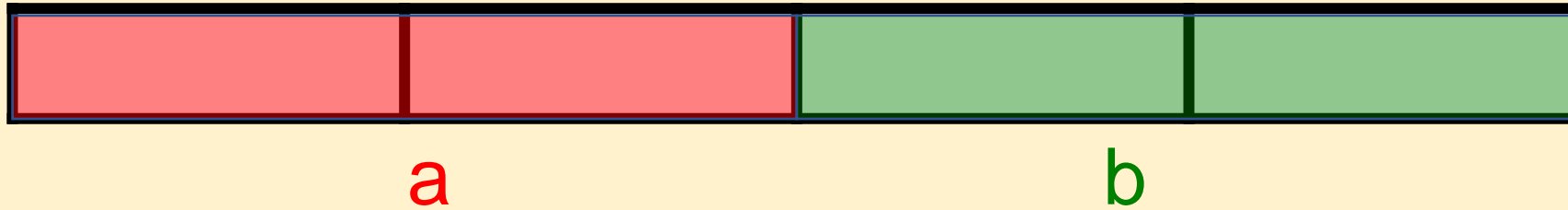
- For $12 \cdot 9 = 108$, if in binary arithmetic $1100_2 * 1001_2 = 1101100_2$
- For two n -bit numbers a and b , standard method requires $O(n^2)$ bit steps
- High-school approach to binary number multiplication result is at most $2n$ bits long, n^2 bit multiples, $2n$ -bit additions.

$$\begin{array}{r} 1100 \\ 1001 \\ \hline 1100 \\ 00000 \\ 000000 \\ 1100000 \\ \hline 1101100 \end{array}$$

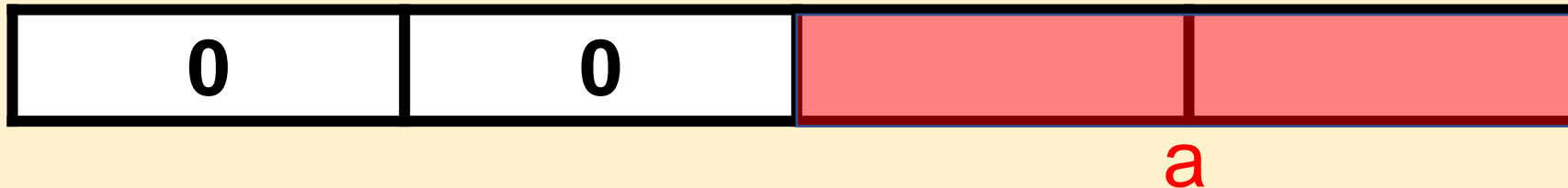
- Observe that a n -bit number can be expressed as

$$a * 2^{n/2} + b$$

e.g. $9 = 1001_2 = 1000_2 + 0001_2$
 $= 10_2 * 2^2 + 01_2$

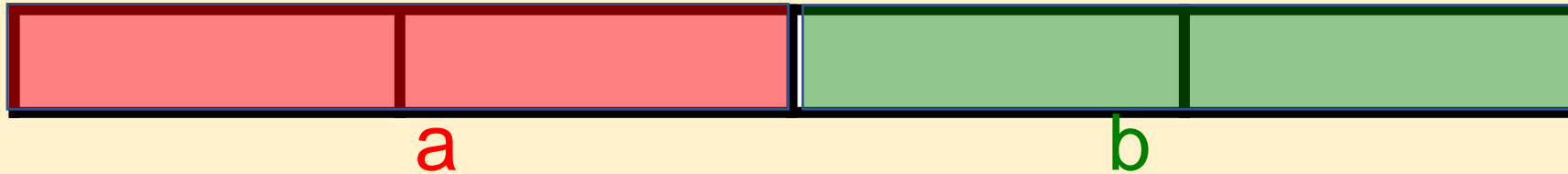


- To obtain **a**, shift right by 2 digits



- Since shift right one digit is divided by 2

$$a * 2^{n/2} + b$$



- To obtain **b** shift left by 2 digits, then shift right by two digits



- Since shift left one digit is to multiply by 2

➤ Also note the product uv for

$$u = a * 2^{\frac{n}{2}} + b$$

$$v = c * 2^{\frac{n}{2}} + d$$

is given by

$$\begin{aligned} uv &= \left(a * 2^{\frac{n}{2}} + b \right) \left(c * 2^{\frac{n}{2}} + d \right) \\ &= \textcircled{ac} * 2^n + (\textcircled{ad} + \textcircled{bc}) 2^{\frac{n}{2}} + \textcircled{bd} \end{aligned}$$

➤ Hence the problem is reduced to solving four $\frac{n}{2}$ bit multiplication instances.

$$T(n) = 4T\left(\frac{n}{2}\right) + cn$$

- But also observe that

$$ad+bc = (a+b)(c+d) - ac - bd$$

- Thus $(ad+bc)$ can be computed with one multiply, 2 additions, and 2 subtractions
(because ac and bd are already known)
- The cost of addition/subtraction is $O(n)$, hence

$$T(n) = 3T\left(\frac{n}{2}\right) + cn \quad \text{if } n > 1$$

- Time complexity is

$$O(n^{\log 3}) = O(n^{1.58})$$

- The algorithm solve n -bit multiplication between u and v by D&C
- Small(P), direct solve
- $\text{shiftright}(x,y)$ moves x by y bits to the left
- $\text{shiftright}(x,y)$ moves x by y bits to the right
- *Recursively solve, and combine solution*

Algorithm *multiply*($u, v, \text{word}; n: \text{integer}$)

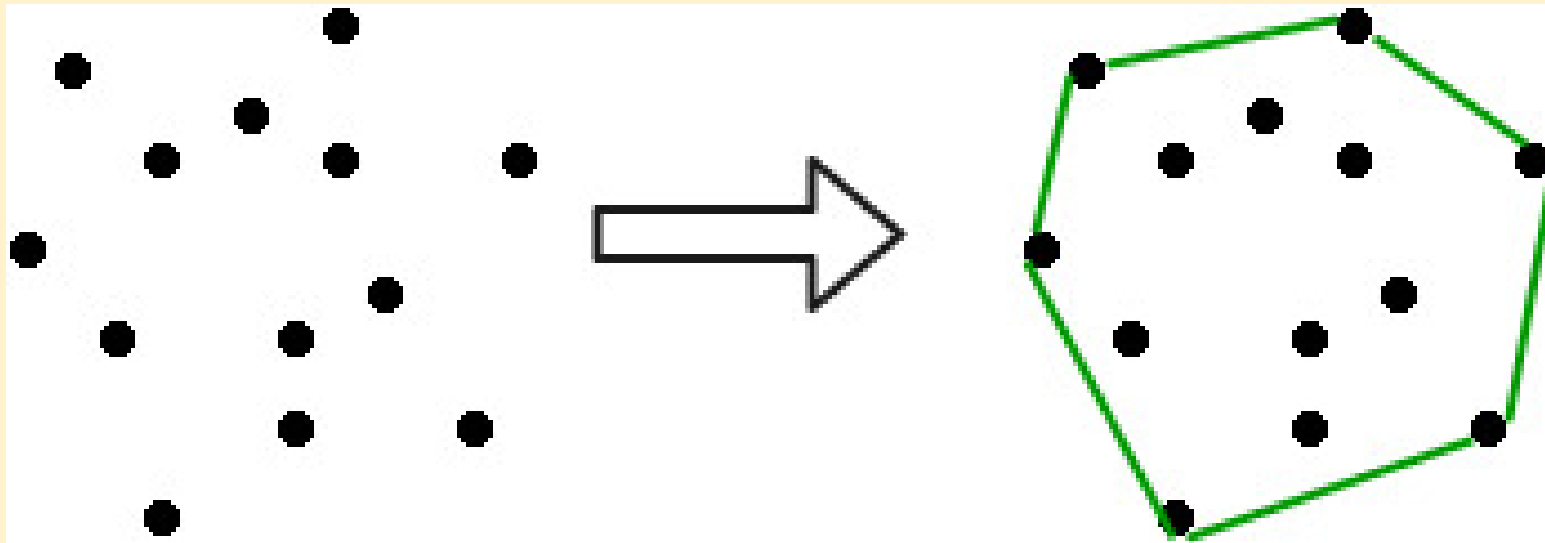
```

{ if( $n == 1$ ) return( $uv$ );
  else{
     $p = n$ ;
     $m = n/2$ ;
     $a = \text{shiftright}(u, m)$ ;
     $b = \text{shiftright}(\text{shiftright}(u; m); m)$ ;
     $c = \text{shiftright}(v; m)$ ;
     $d = \text{shiftright}(\text{shiftright}(v; m); m)$ ;
     $r1 = \text{multiply}(a, c, n/2)$ ;
     $r2 = \text{multiply}(b, d, n/2)$ ;
     $r3 = \text{multiply}(a, d, n/2)$ ;
     $r4 = \text{multiply}(b, c, n/2)$ ;
    return  $\text{shiftright}(r1, p) + \text{shiftright}(r3 + r4, m) + r2$ ;
  }

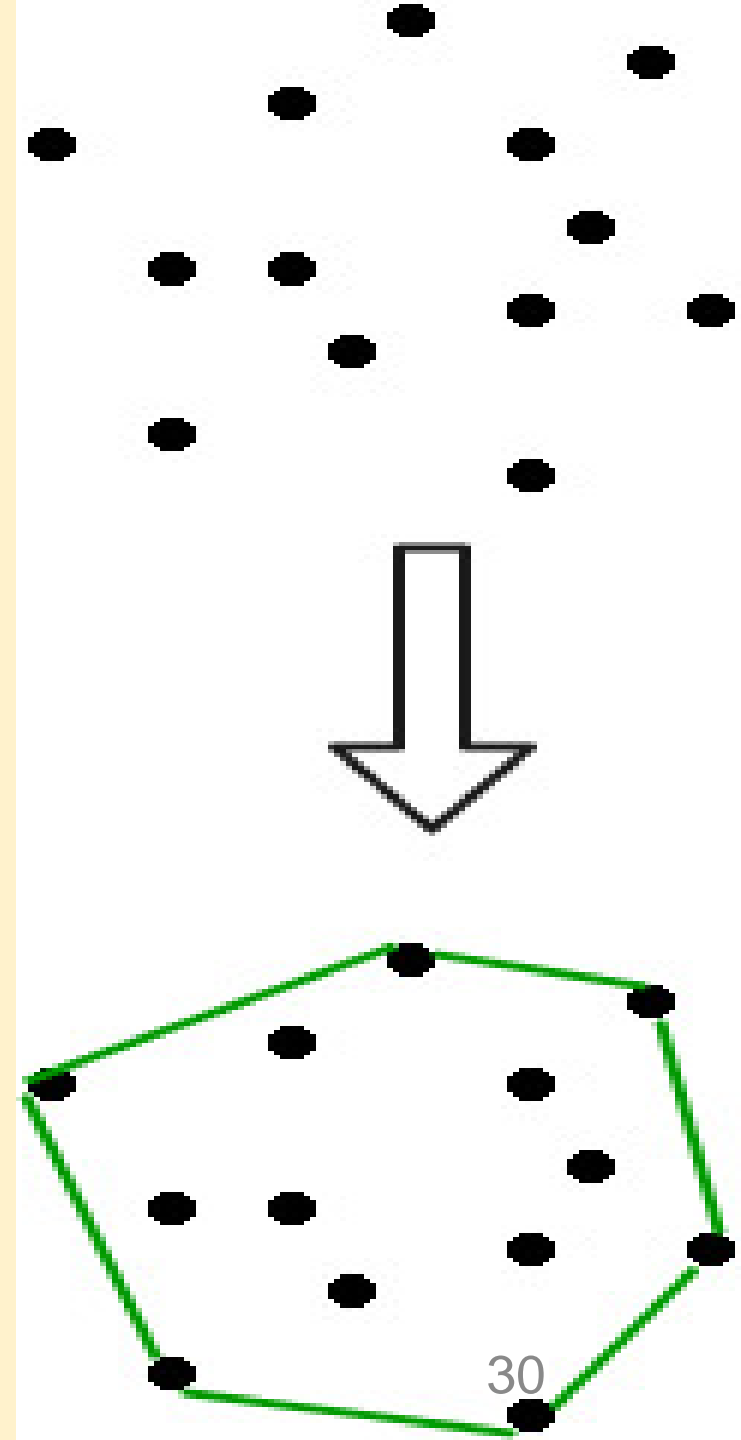
```

Convex Hull

- **Definition:** The smallest boundary of a convex set S of points in the plane is defined to be the smallest convex polygon containing all the points of S .



- Applications:
- Computer graphics (creating images and modeling scenes, creating realistic looking scenes taking light)
 - Robotics (design and use of robots, operating in a real 3-D world)
 - Geographic information systems (storage of physical systems such as mountains, vegetation, populations, roads)
 - CAD/CAM (design and manufacture of products)



Algorithm ConvexHull (P : set of points)

{

Sort the points by the x coordinate and place in list L ;

UpperHull(L);

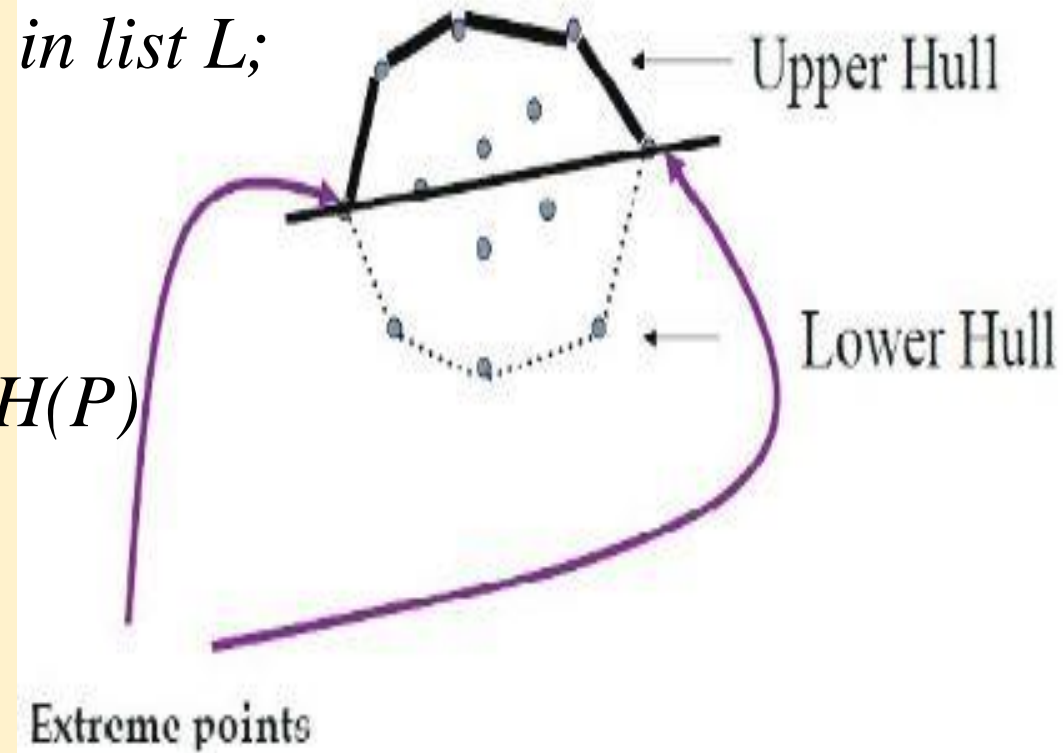
LowerHull(L);

Remove the first and last point from L lower

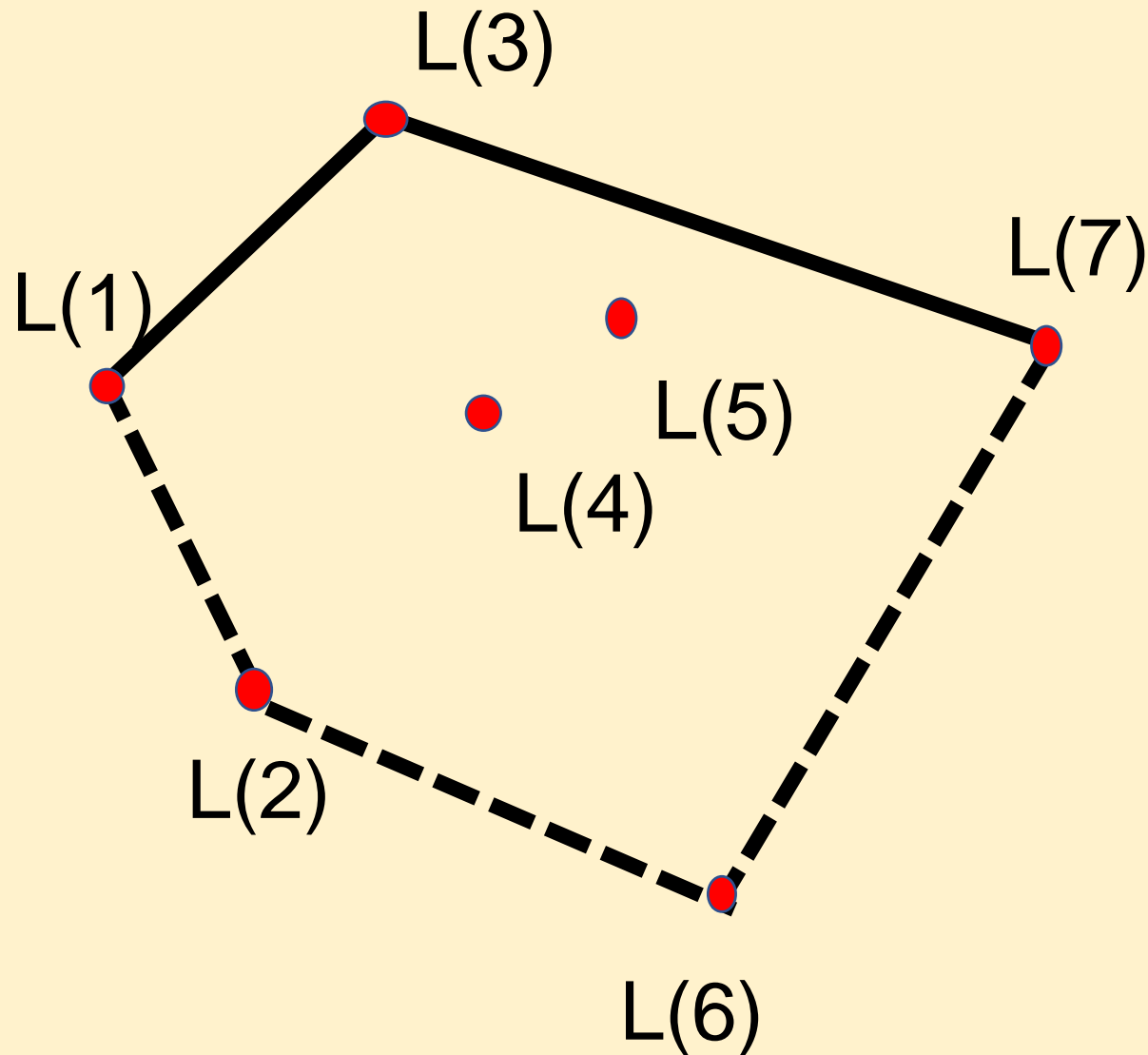
Return the union of L lower and L upper as $CH(P)$

}

- *The Algorithm constructs a convex hull*
- *Input: a set of points from 2D*
- *Output: a set of $CH(P)$ the vertices convex hull in clockwise order*
- *L upper is the list for upper hull*
- *L lower is the list for lower hull*
- *Combine the two hulls*

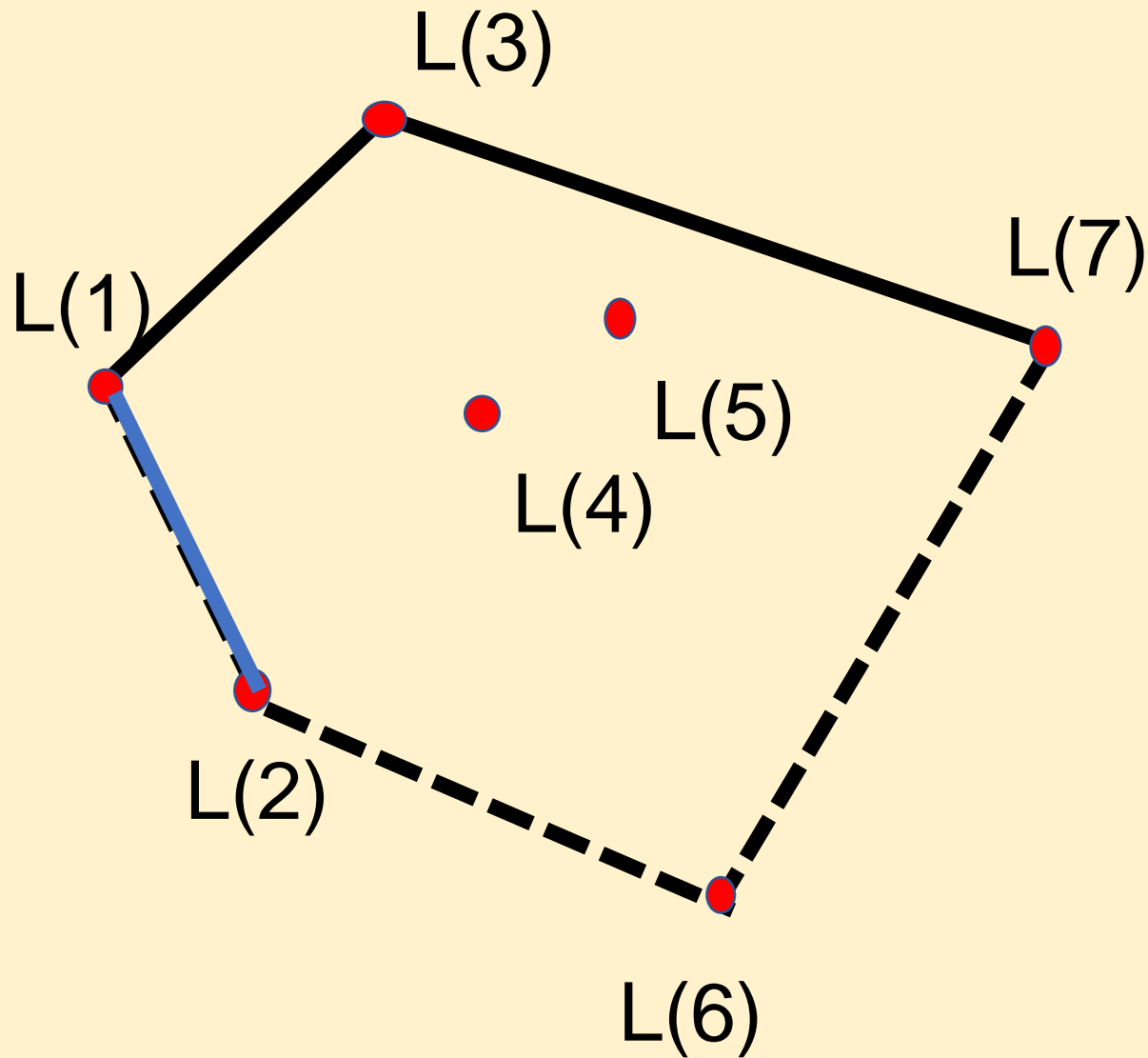


Example



```
Algorithm UpperHull( $P$ : set of points)
{
    Put points  $L(1)$  and  $L(2)$  into a list
     $Lupper$ ;
    for( $i = 3; i \leq n; i++$ ) { add  $L(i)$  to  $Lupper$ 
    while  $Lupper$  contains more than two
    points AND the last three points do not
    make right turn {
        Delete the middle of the last three
        points from  $Lupper$ 
    }
    return  $Lupper$ ;
}
```

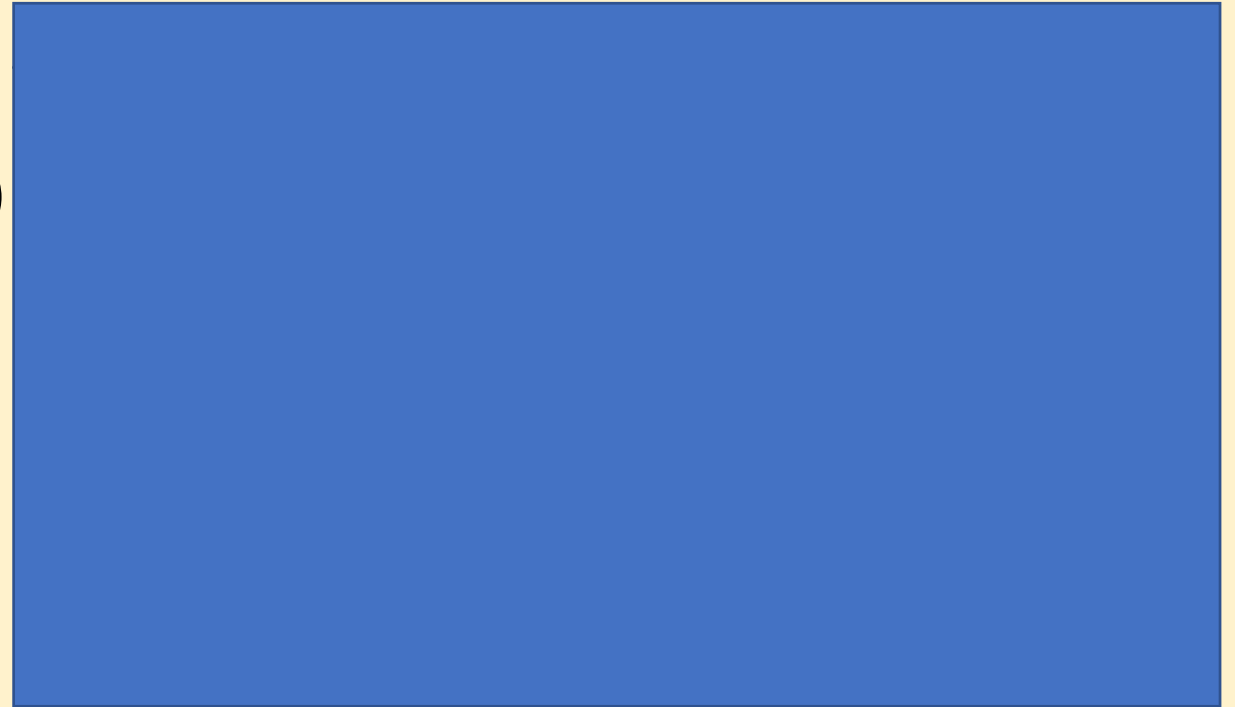

Example



Algorithm UpperHull(P : set of points)

{

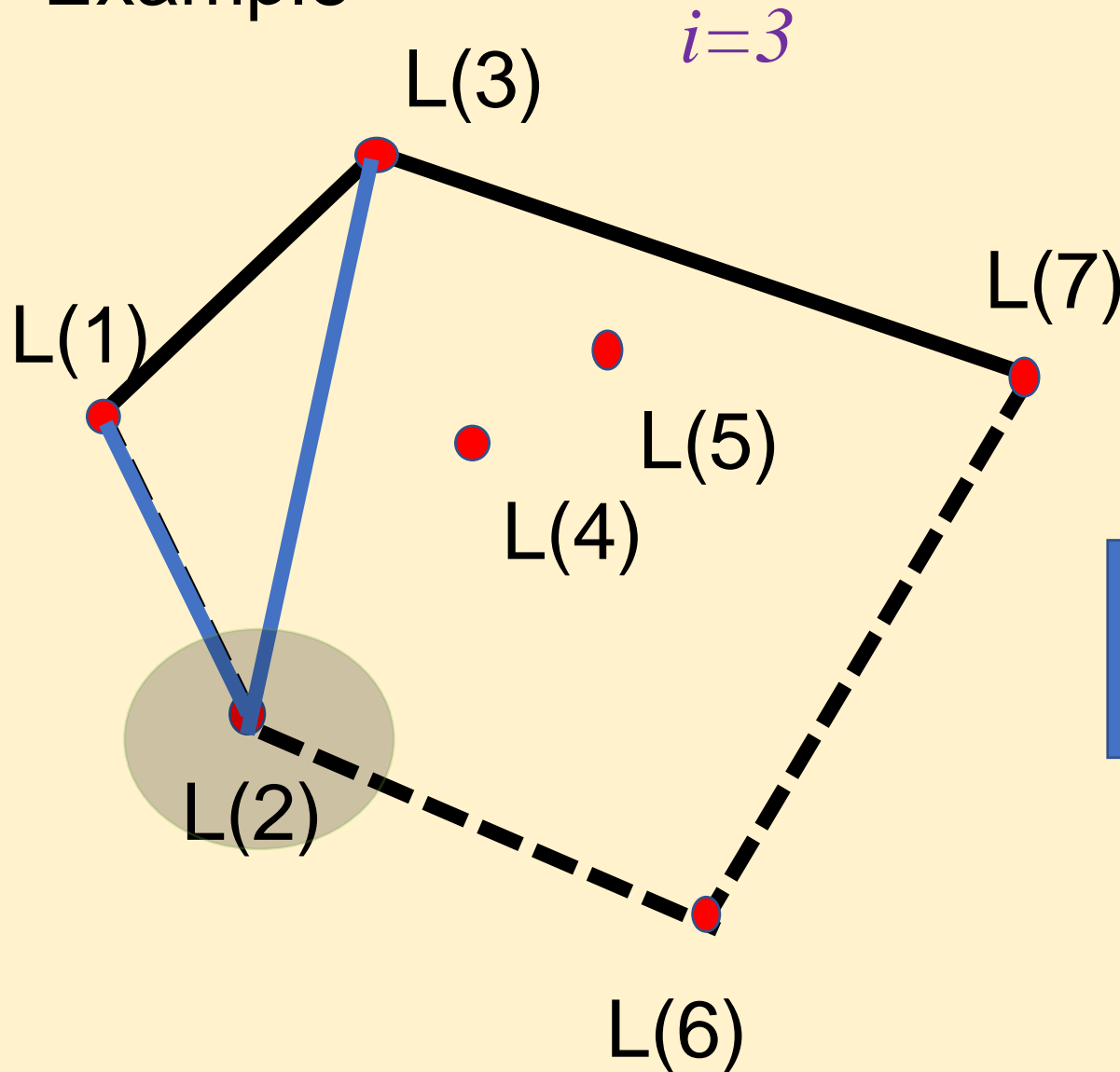
Put points $L(1)$ and $L(2)$ into a list $Lupper$;



$Lupper$:

- $L(1)$, $L(2)$

Example

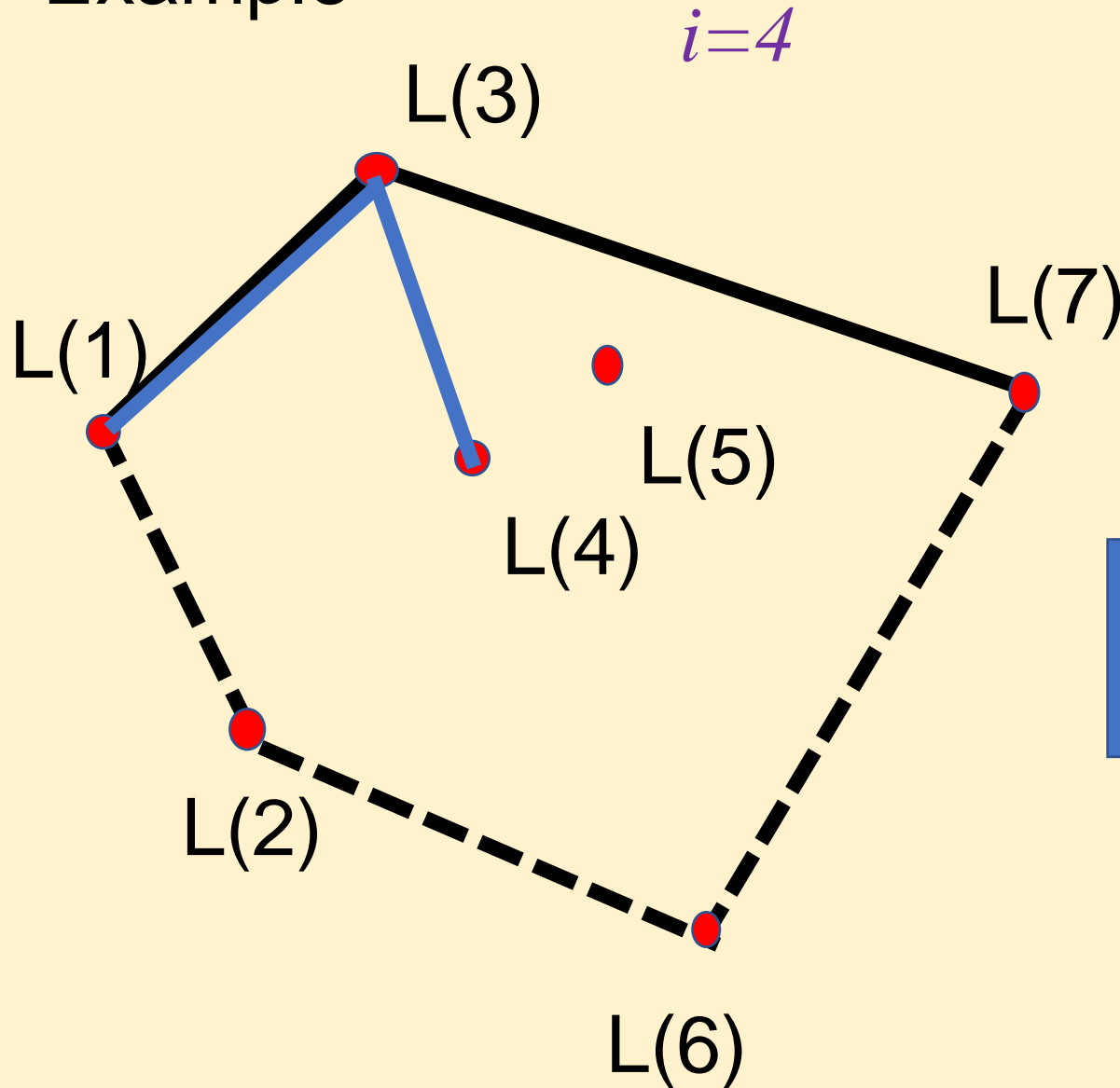


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 turn {
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 points from $Lupper$ }
}

Lupper:

- $L(1), L(2)$
- $L(1), L(2), L(3)$

Example

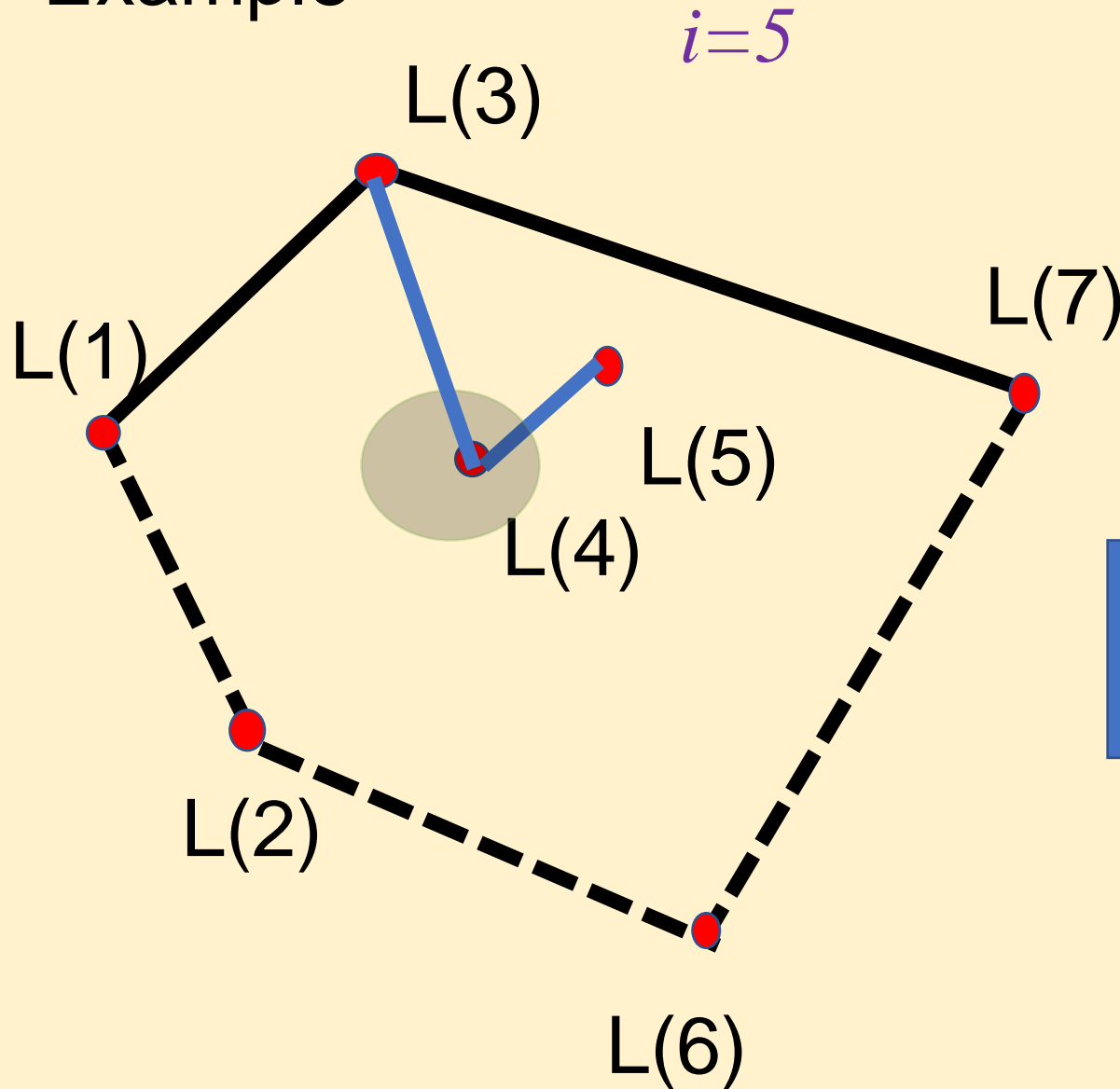


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 points from $Lupper$ }
}

Lupper:

- $L(1), L(3)$
- $L(1), L(3), L(4)$

Example

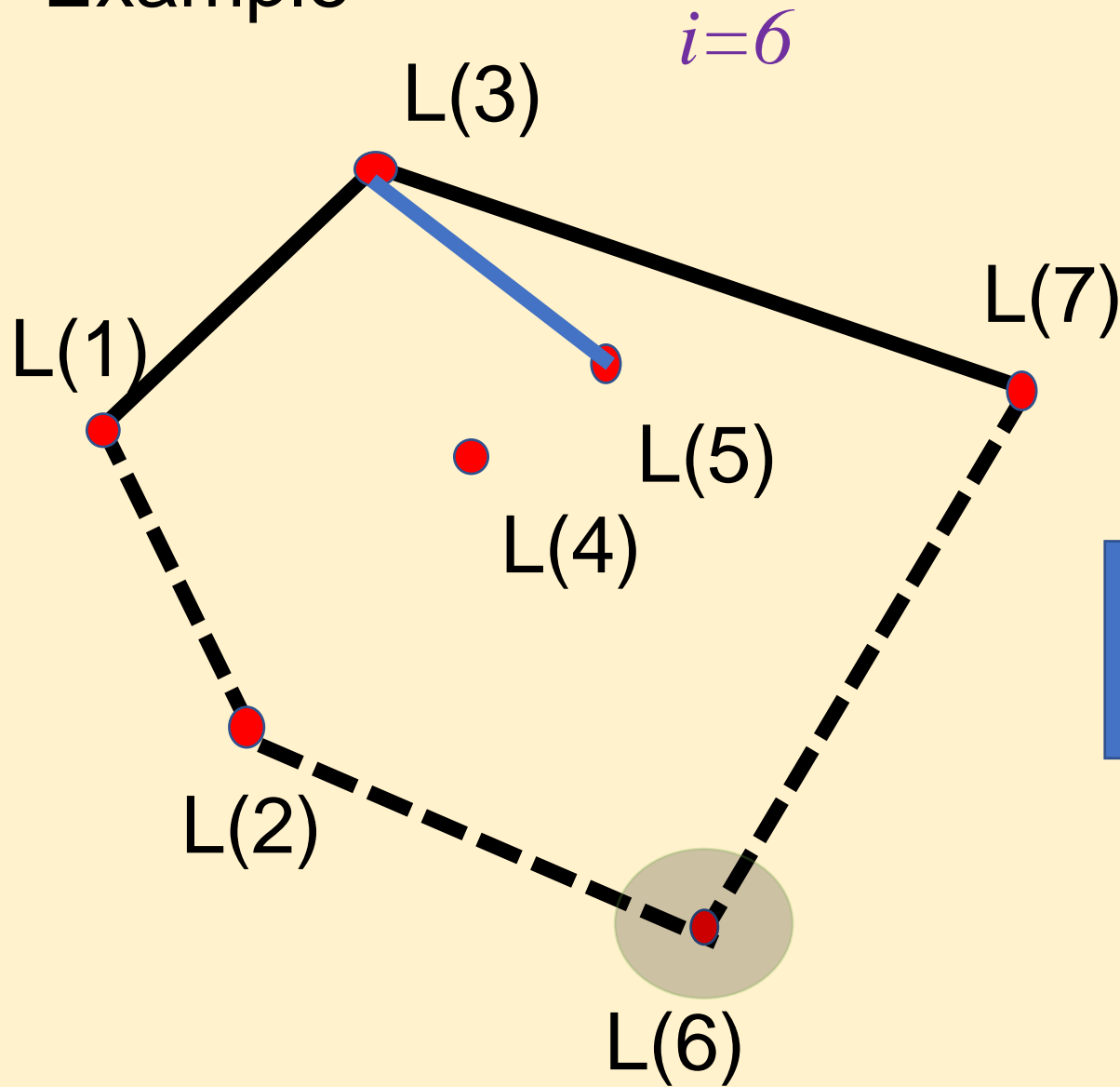


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 while $Lupper$ contains more than two points
 AND the last three points do not make right
 turn {
 Delete the middle of the last three
 points from $Lupper$ }
}

Lupper:

- $L(1), L(3), L(4)$
- $L(1), L(3), \cancel{L(4)}, L(5)$

Example

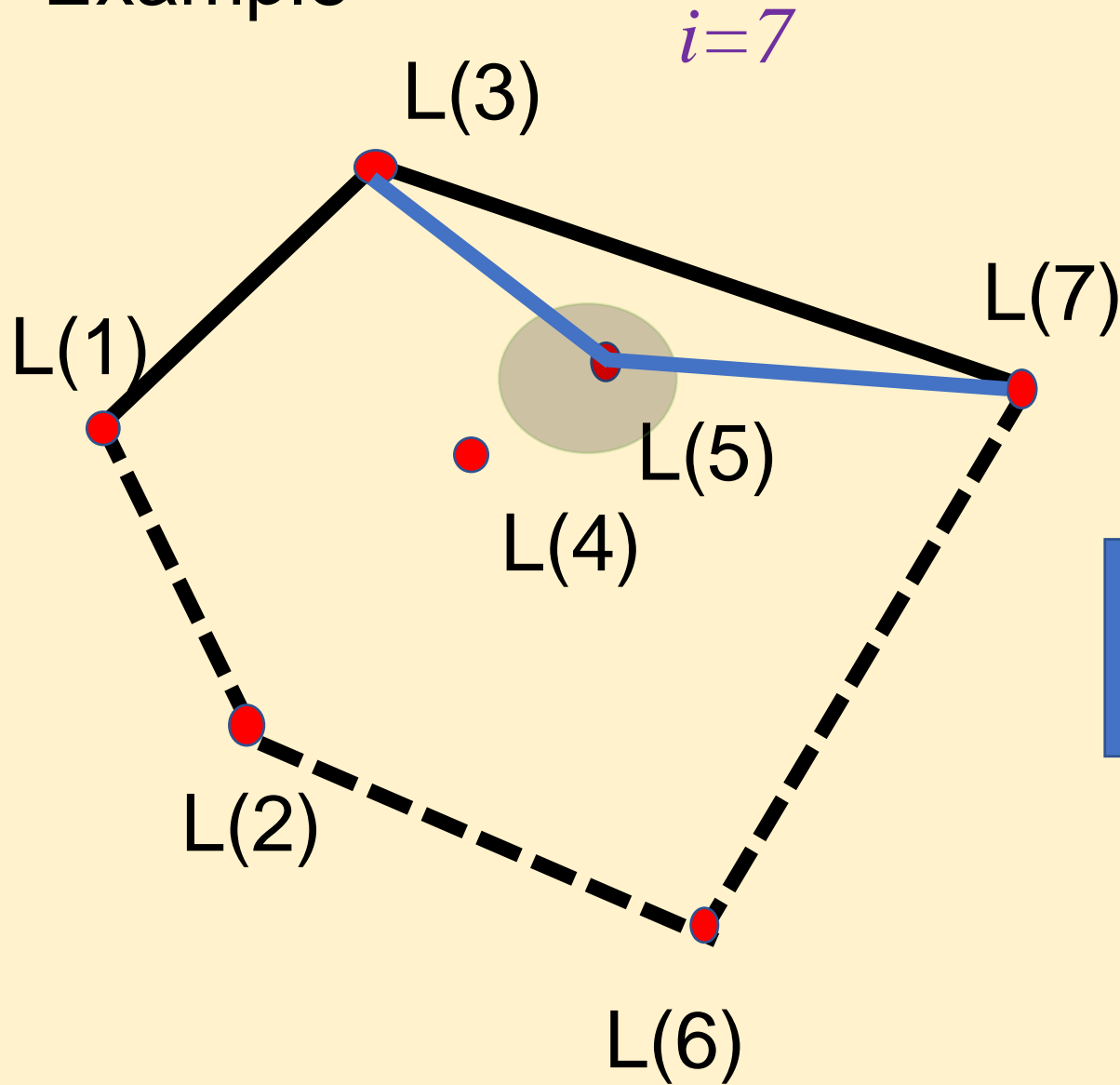


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Lupper:

- $L(1), L(3), L(5)$
- $L(1), L(3), L(5)$

Example

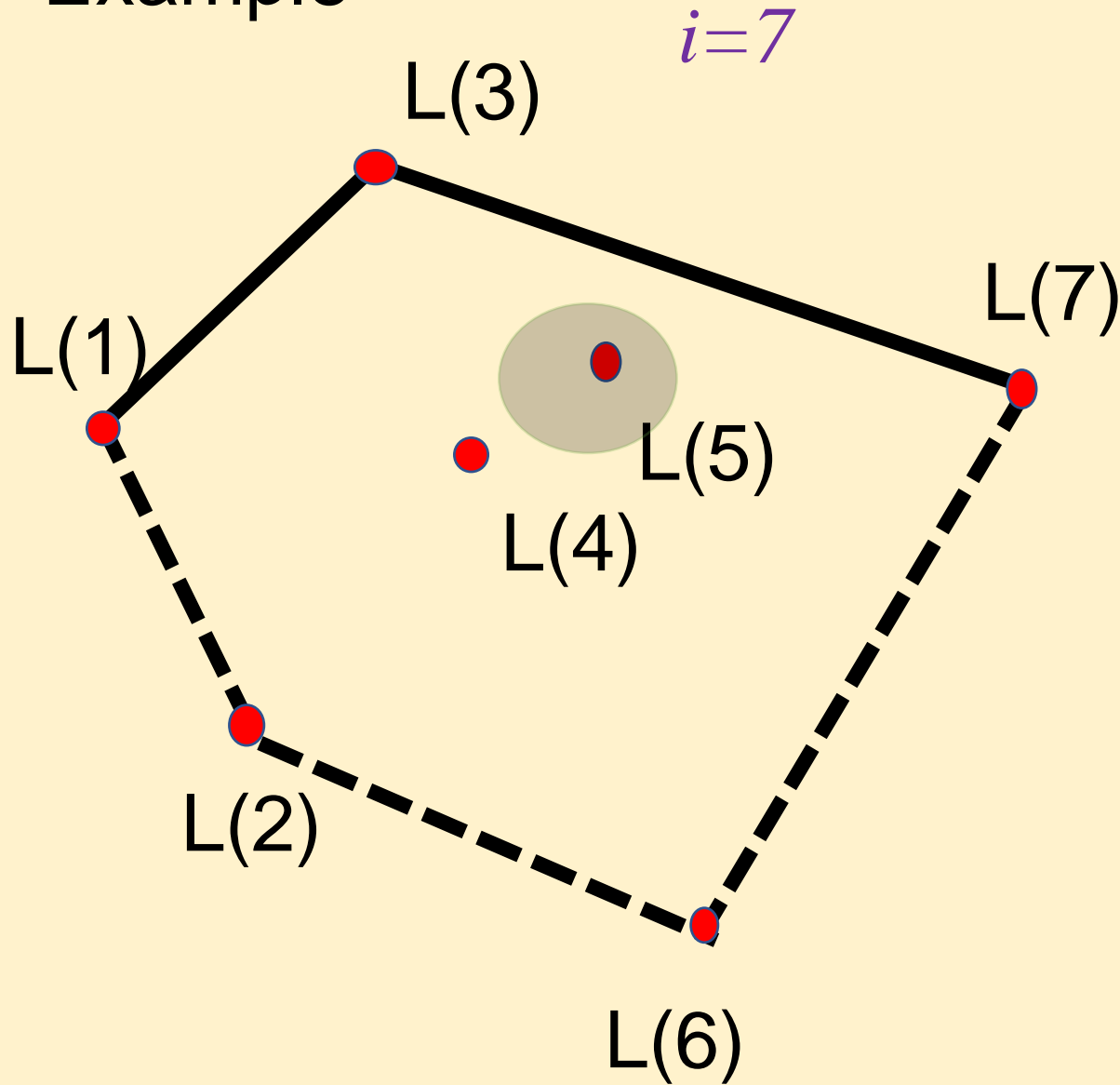


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}

Lupper:

- $L(1), L(3), L(5)$
- $L(1), L(3), \cancel{L(5)}, L(7)$

Example



Algorithm UpperHull(P : set of points)

```

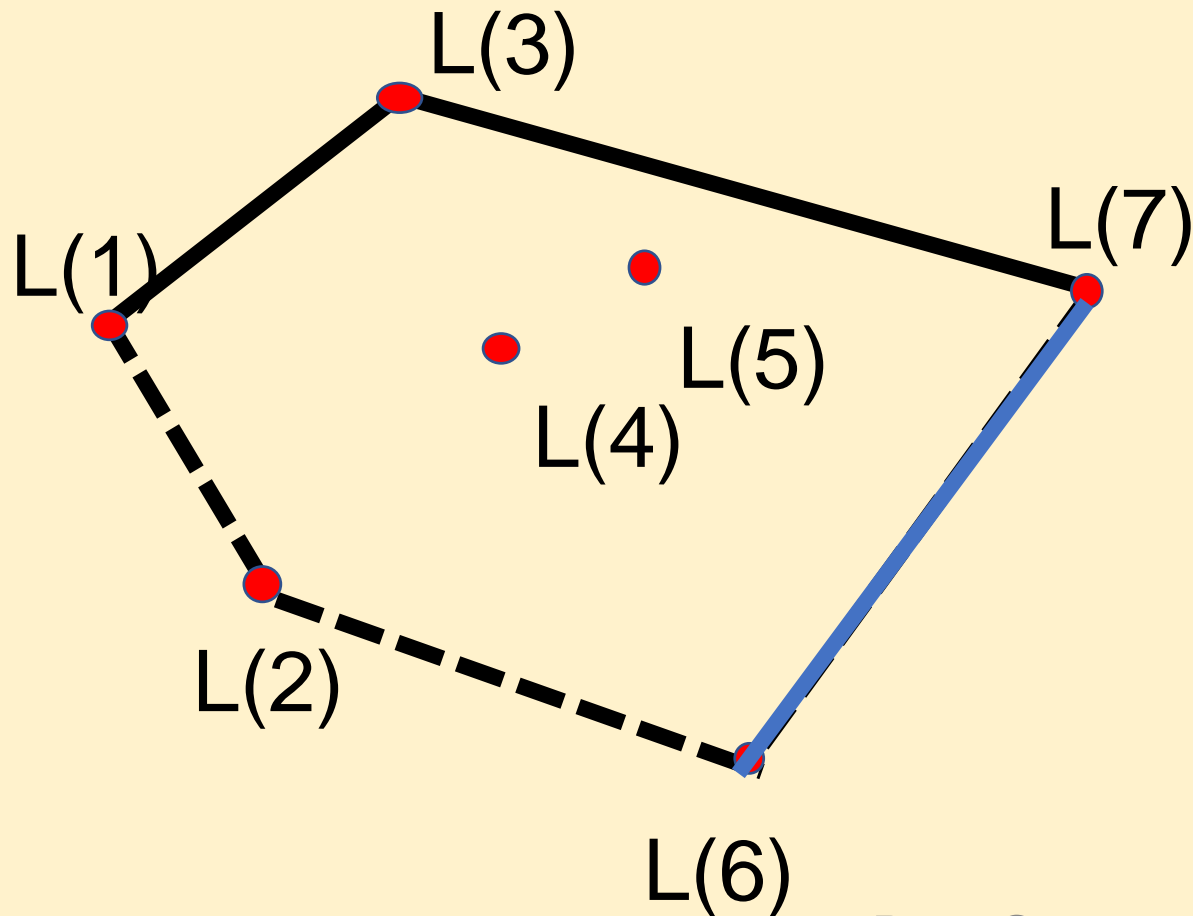
{
    Put points  $L(1)$  and  $L(2)$  into a list  $Lupper$ ;
    for( $i=3$ ;  $i \leq n$ ;  $i++$ ) { add  $L(i)$  to  $Lupper$ 
        while  $Lupper$  contains more than two points
        AND the last three points do not make right
        turn {
            Delete the middle of the last three
            points from  $Lupper$ 
        }
    }
    return  $Lupper$ ;
}

```

$Lupper$:

- $L(1)$, $L(3)$, $L(7)$

In class exercise: Find the sequence of Lower hull

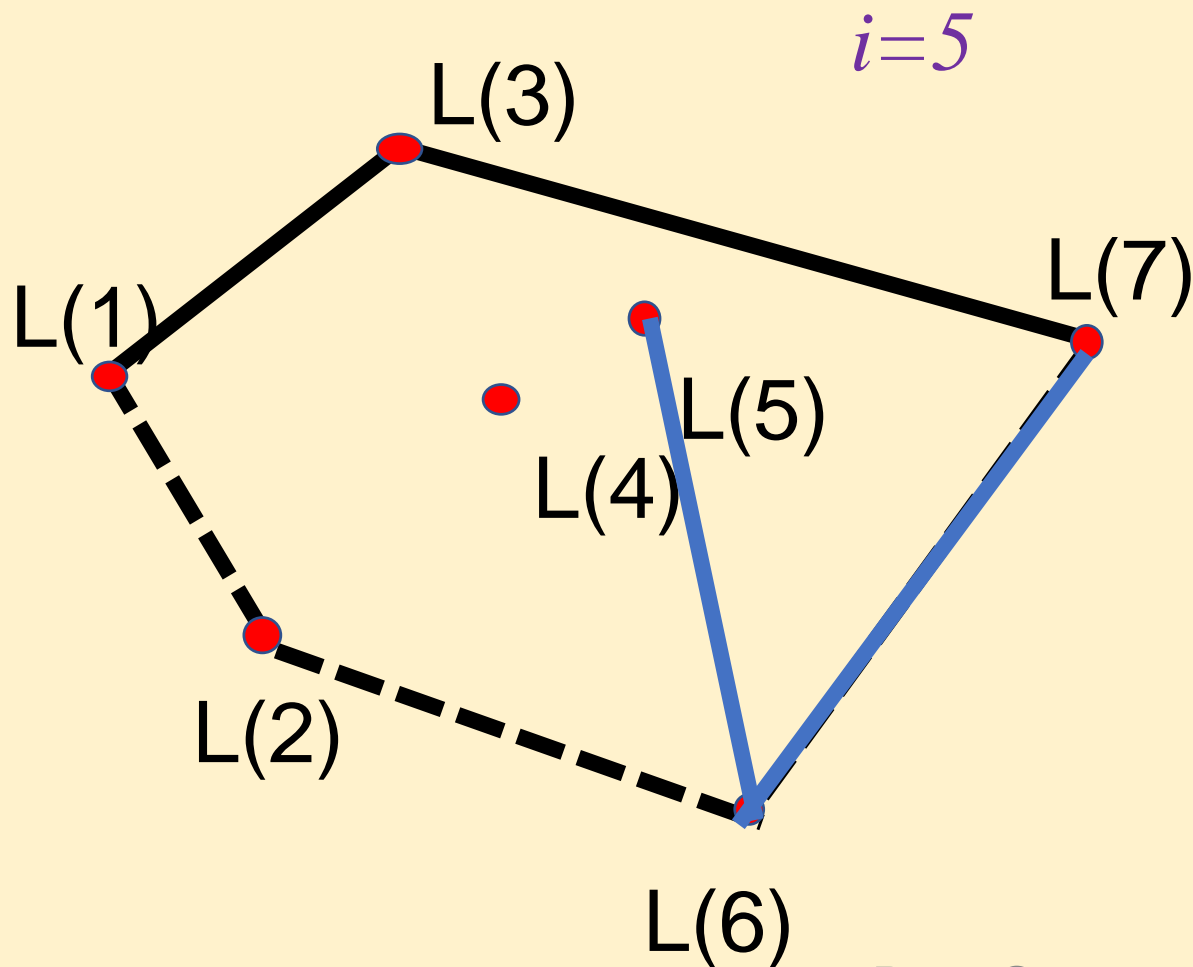


```
Algorithm LowerHull( $P$ : set of points)
{
    Put points  $L(n)$  and  $L(n-1)$  into a list  $Llower$ ;
    for( $i = n-2; i \geq 1; i--$ ) { add  $L(i)$  to  $Llower$ 
        while  $Llower$  contains more than two
        points AND the last three points do not
        make right turn {
            Delete the middle of the last three
            points from  $Llower$ 
        }
    }
    return  $Llower$ ;
}
```

$Llower$:

- $L(7), L(6)$

In class exercise: Find the sequence of Lower hull



```
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    for( $i = n-2; i \geq 1; i--$ ) { add  $L(i)$  to  $Llower$ 
        while  $Llower$  contains more than two
        points AND the last three points do not
        make right turn {
            Delete the middle of the last three
            points from  $Llower$ 
        }
    }
    return  $Llower$ ;
}
```

$Llower$:

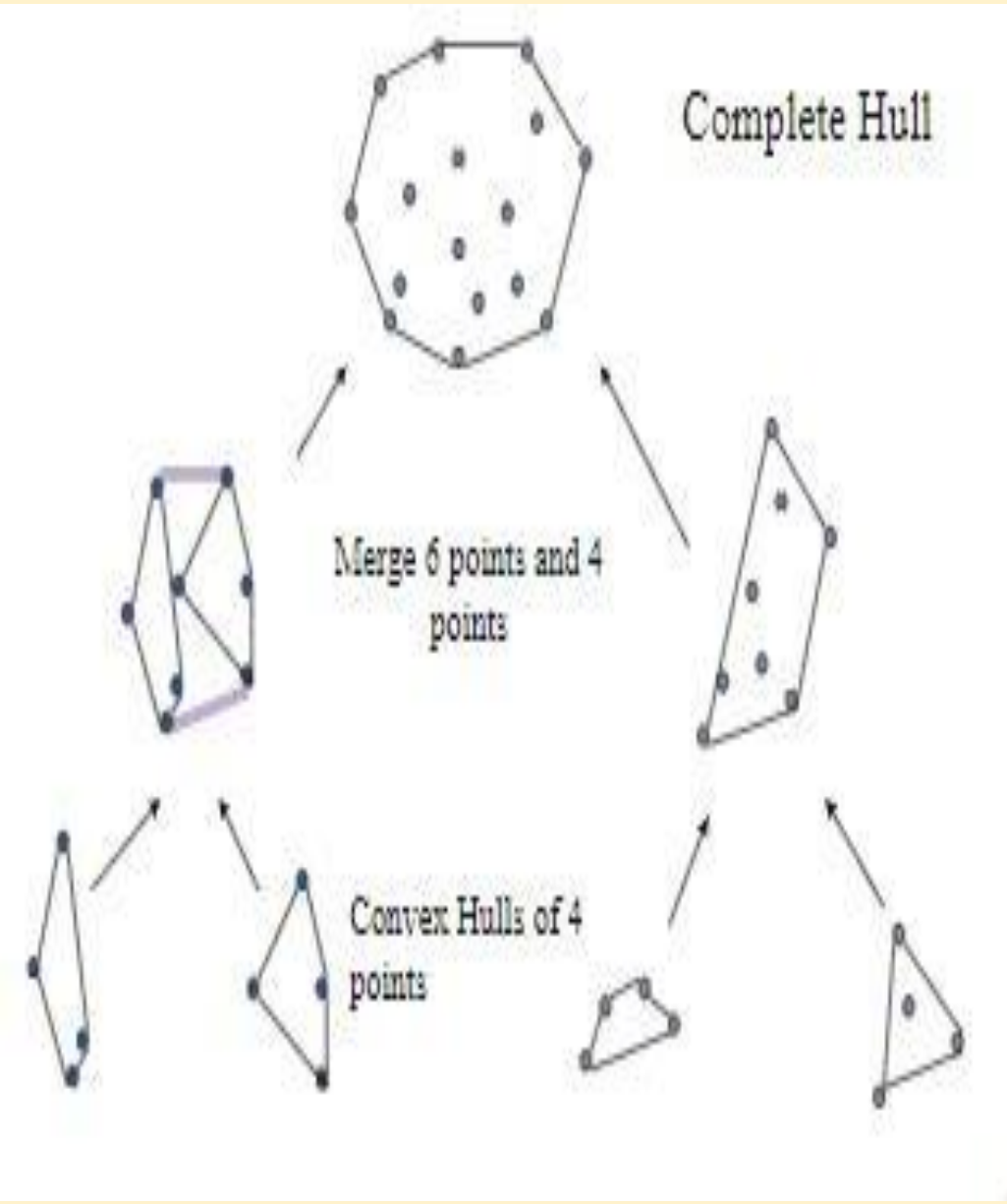
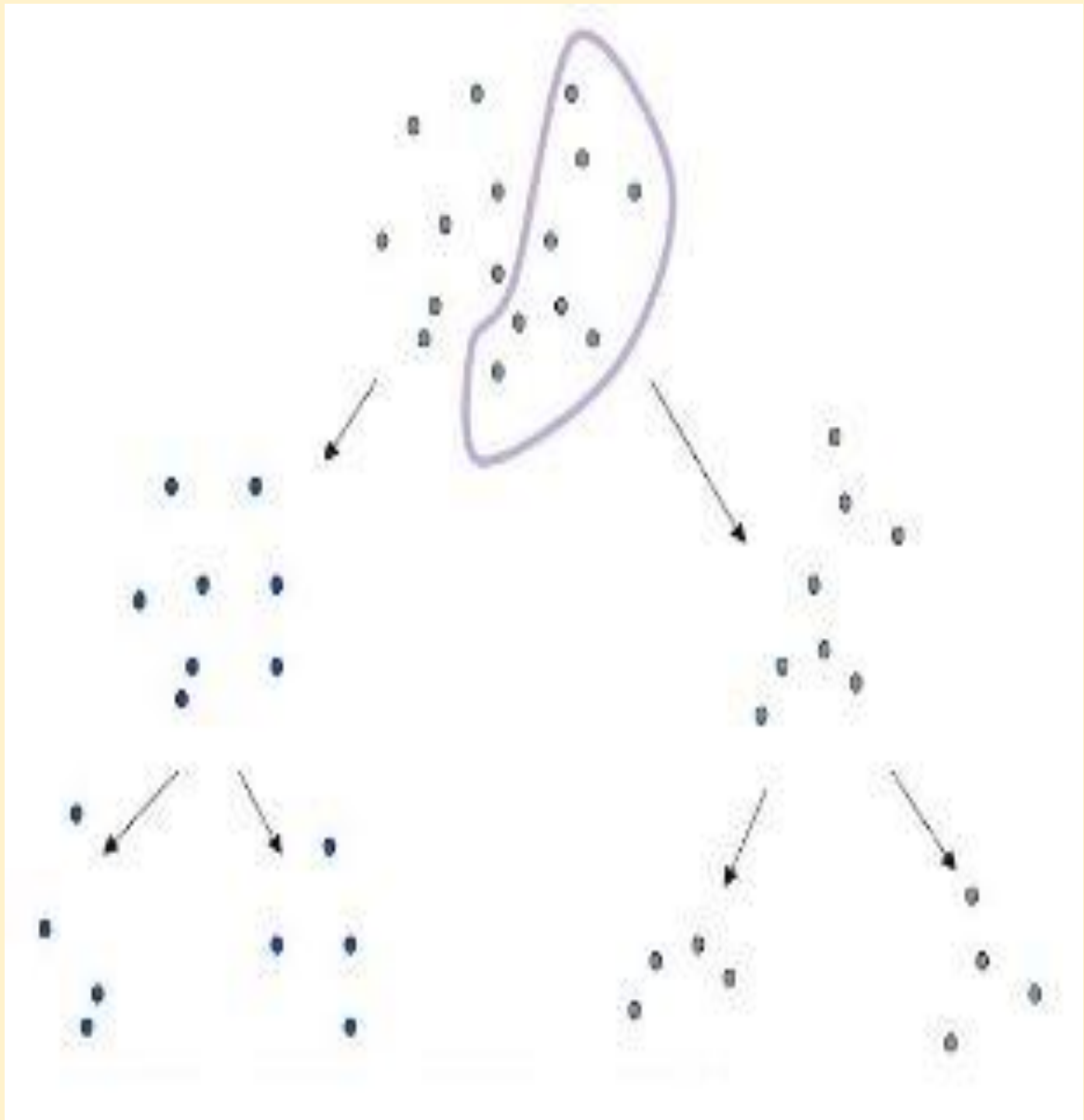
- $L(7), L(6)$
- $L(7), L(6), L(5)$

D&C convex hull:

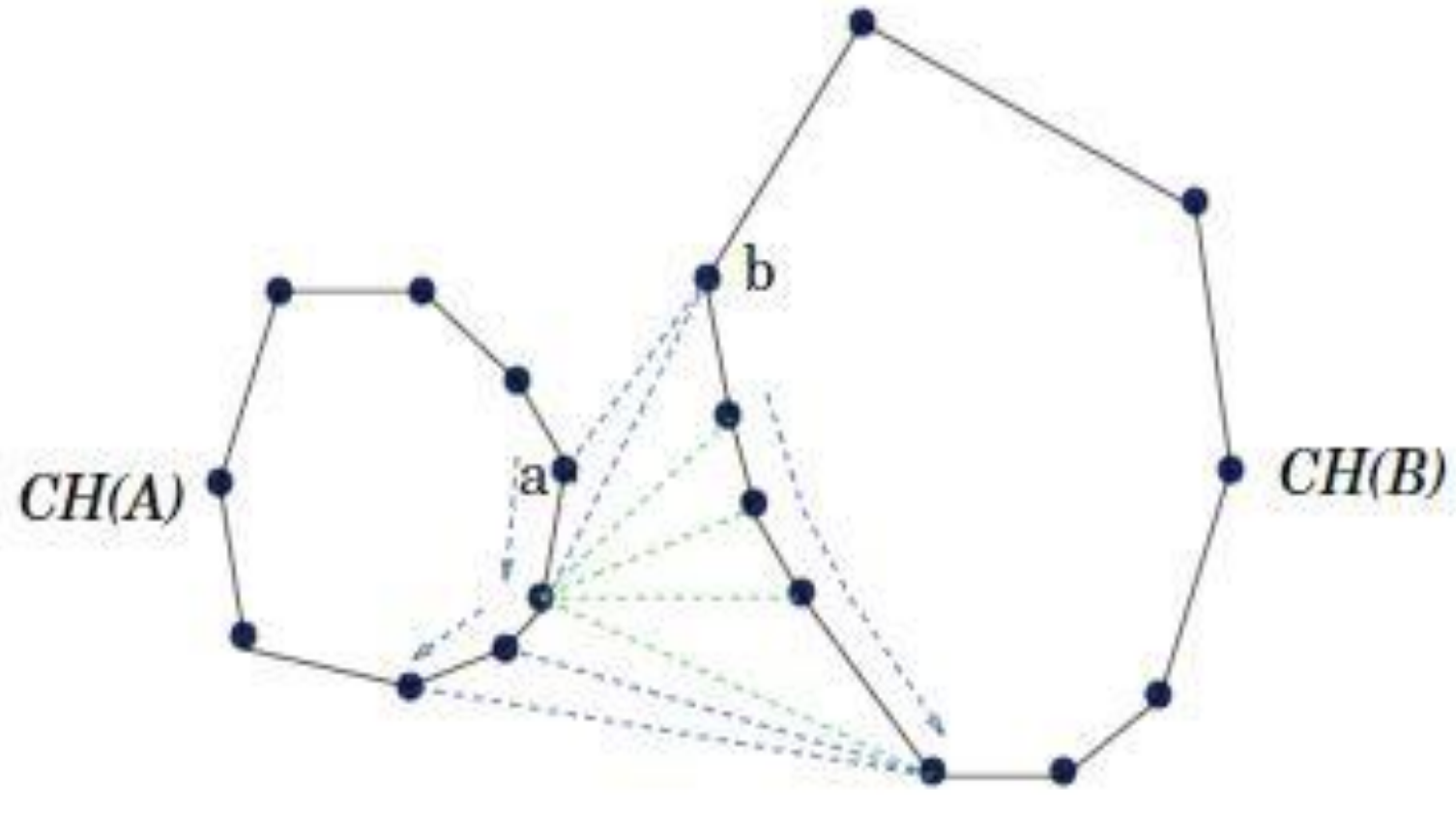
```
Algorithm DCHull( $P$ :set of points)
{
    if( $\text{size}(P) < \text{minsize}$ )
        return ConvexHull( $P$ )
    else{
        split( $P, L_1, L_2$ );
        //divide P into two Lists L1, L2
        return Merge(DCHull( $L_1$ ); DCHull( $L_2$ ))
    }
}
```

- Eliminate as many point as possible before doing a hull.
- How the list is split is crucial to efficiency.
- Merge: throws away points inside the two hulls form L_1, L_2

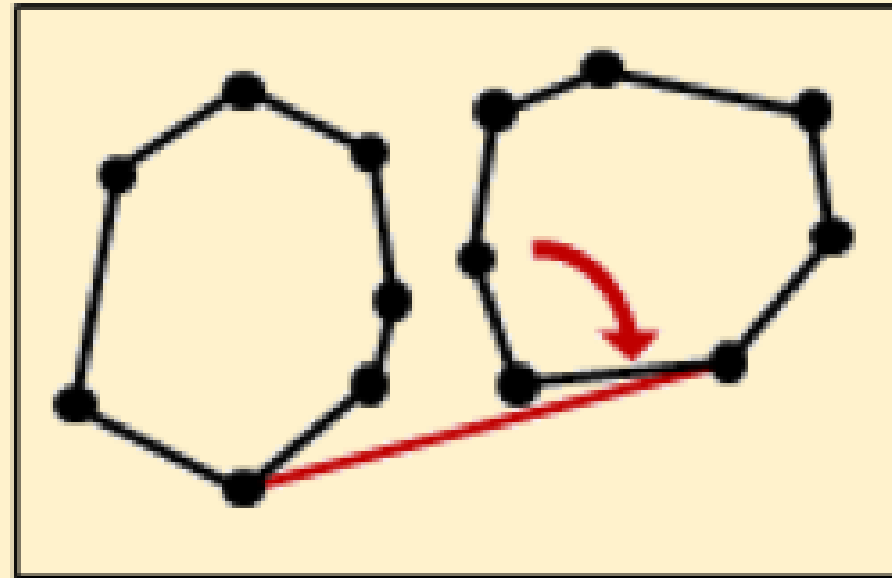
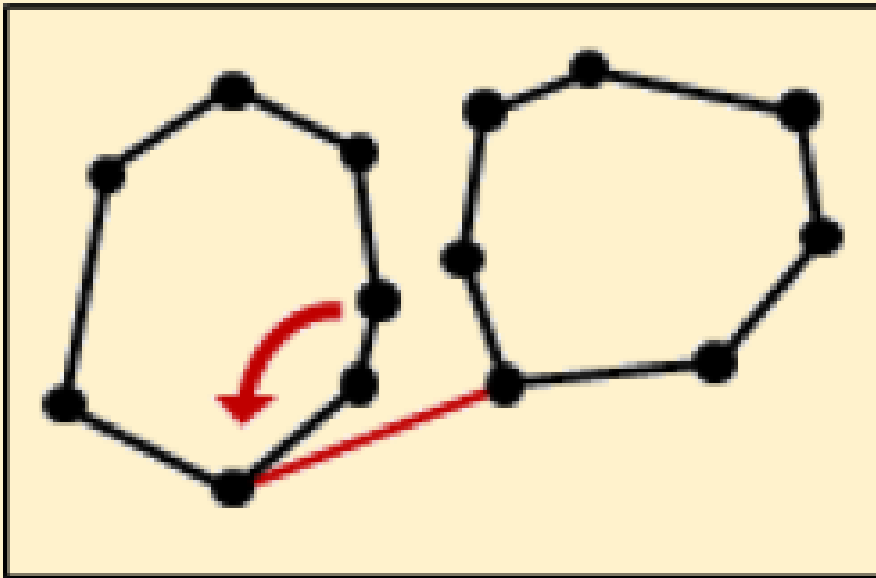
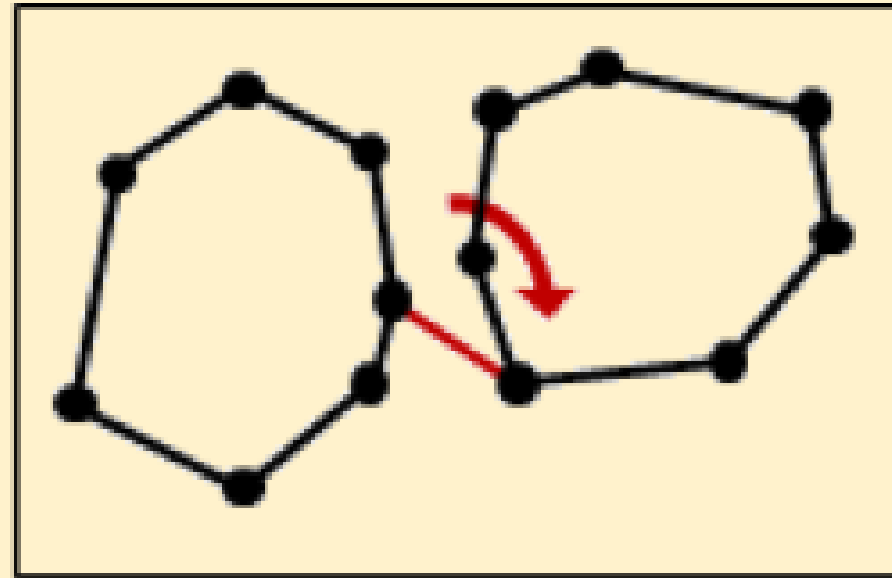
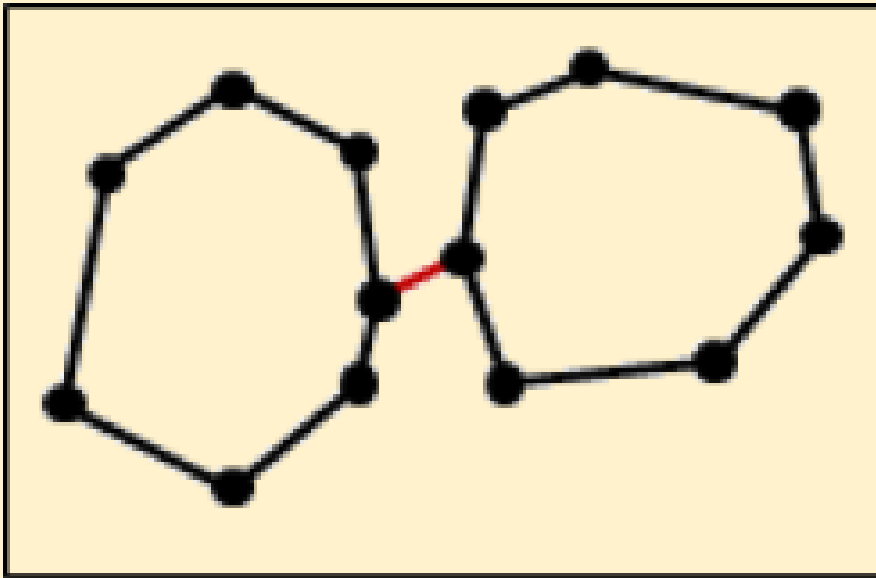
Let minsize = 4



- To merge two convex hulls, the lower and higher tangent lines are found.



- All other points are on one side of the tangent lines.
- For example, search the lower tangent line, move **a** clockwise and **b** counter clockwise, until **ab** is lower tangent.
- Points between two tangent lines are dropped.



Complexity of DCHull

- Dividing the points into left and right half each containing $\frac{n}{2}$ points
 - Sort the points ($O(n \log n)$)
 - take the median
- Find the convex hull of each recursively and stitch the hulls together
 - $T(n) = 2T(\frac{n}{2}) + cn$
 - $O(n \log n)$

D&C complexity summary

Problem	Algorithm	Time Complexity
Max-min	Direct	$O(n)$
	D&C	$O(n)$
Selection	Selection	$O(n^2)$
	Fast	$O(n)$
Convex Hull	Incremental	$O(n^2)$
	DCHull	$O(n \log n)$
Matrix Multiplication	D&C	$O(n^3)$
	Strassen's	$O(n^{2.81})$

Matrix multiplication
Strassen Matrix multiplication

Convex hull

Master theorem

Divide and Conquer

max-min

Selection

Multiplication of two
integers