

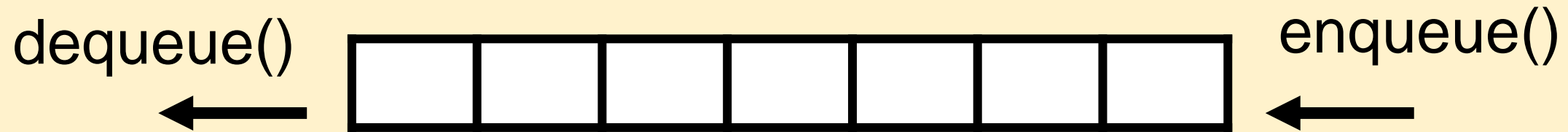
- ◆ **Additional data structure**
 - **Queue and Stack**
 - **Linked list**
- ◆ **Graph traversal**
 - **Depth first traversal**
 - **Breadth first traversal**

Queue and stack

- In computer science, a priority queue is an abstract data type.
- Each element has a priority associated with it.
e.g. in software systems, e.g. requests at a web server.
- Important to efficient algorithm design, especially for solving complex problems over graph.
- Since data structure is needed to organise data efficiently.
- Queue and stack are used for implementing priority queue.
- The queue in data structure is similar to queues which happen a lot in real life, e.g. checkout and banks.

Queue

- A queue is a linear data structure that stores items in First In First Out (FIFO) manner.
- Add and remove operations
 - Add is called enqueue, at the tail.
 - Remove is called dequeue, at the head
- Applications
 - serving incoming requests in stores
 - reservation services
 - operating systems for scheduling processes and disks
 - search algorithm



Queue head

Data Structure and Algorithms

Queue tail

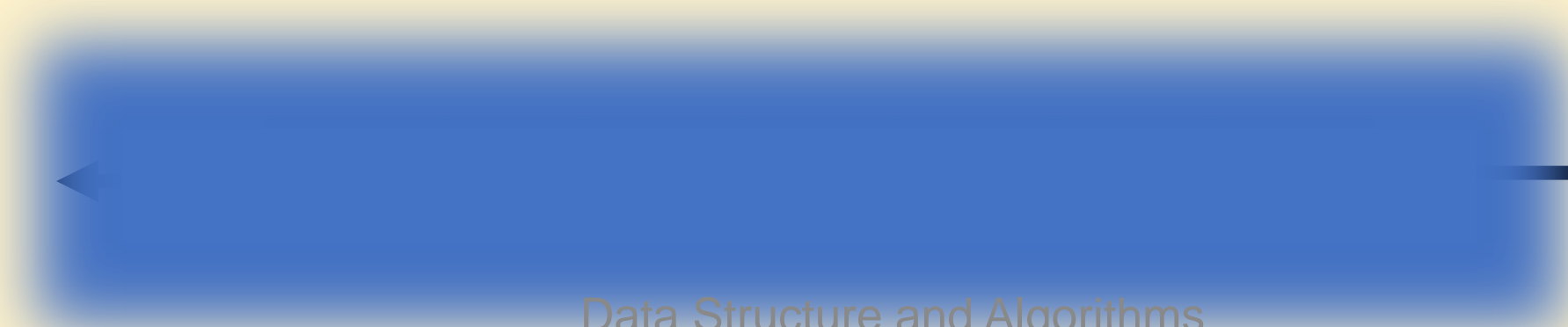
Example (queue)



1 = dequeue()

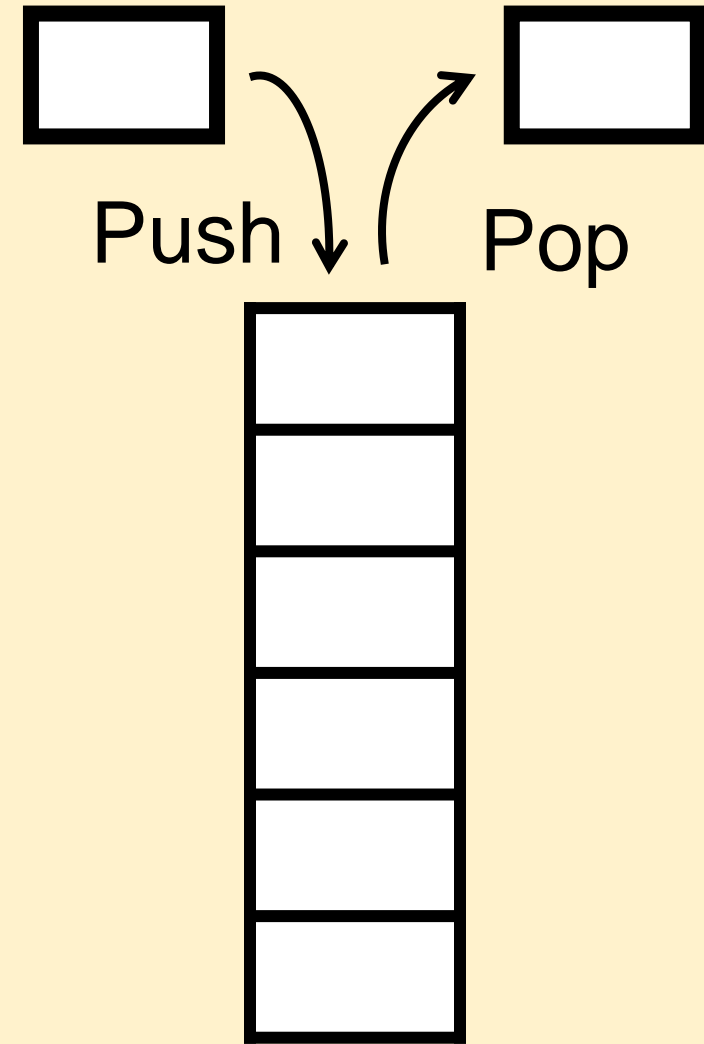


enqueue(8)



Stack

- A stack is a linear data structure that stores items in Last In First Out (LIFO) manner.
- Add and remove operations
 - Add is called push, at the top.
 - Remove is called pop, at the top
- Has applications
 - Evaluation of expression
 - Backtracking
 - Memory management



Example (stack)

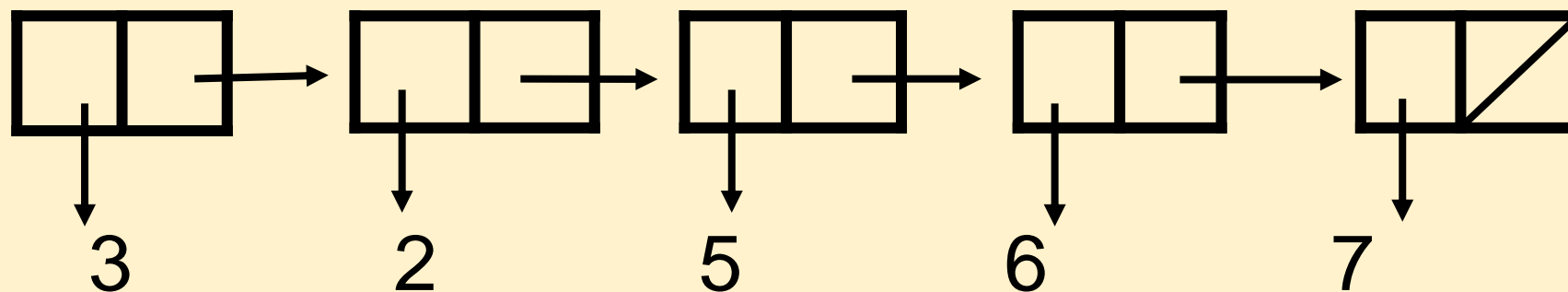


1 = pop()

push(8)

Linked list

- Linked list are used in many ways, e.g. in dynamic memory.
- Used for implementing queues and stacks.
- Examples of a list could be
[3,2,5 ,6,7] or [apple, carrots, milk, cheese]
- Non empty linked lists are represented by two cells.
- The first cell contains a pointer to a list element and the second cell contains a pointer to either the empty list or another two-cell.



Traversal Techniques for Tree and Graphs

- Trees and Graphs are models on which algorithmic solutions for many problems are constructed.
- Traversal: All nodes of a tree/graph are examined/evaluated
 - e.g Locate all the neighbours of a vertex V in a graph
- Binary Tree traversals
 - Inorder,
 - Postorder,
 - Preorder
- Trees are a special case of a graph
- General Tree has many children at each node

- Graph traversal is a generalization of tree traversal except we have to keep track of the visited vertices.
- Different from search: only a subset of vertices (nodes) are examined.
- Graph traversal techniques
 - Depth–first search (DFS)
 - Breadth–first search (BFS)
- Applications: Strongly connected components, topological sorting, critical path analysis
- They prove the basis of most simple, efficient graph algorithms.

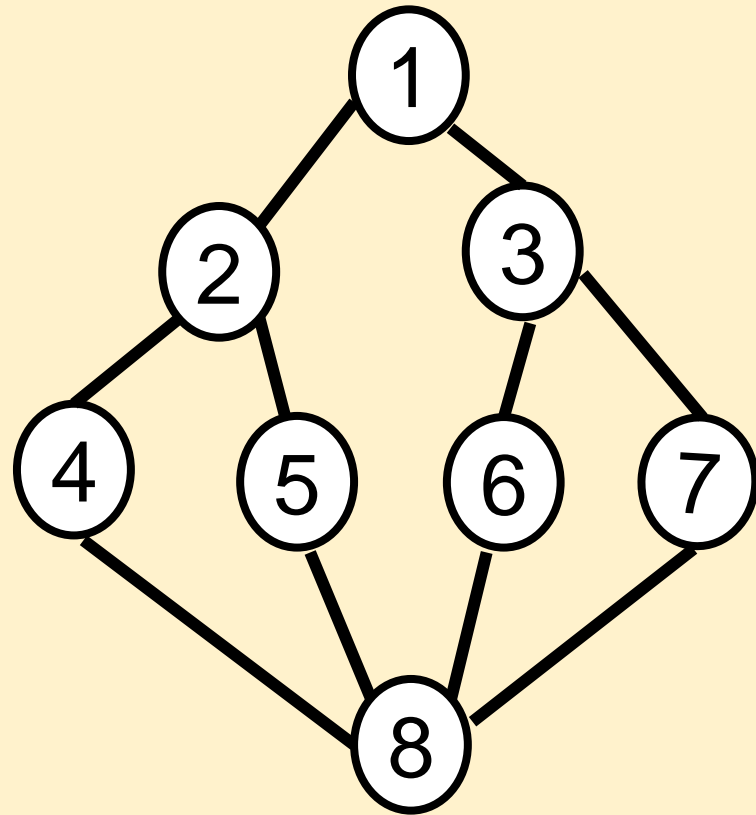
Depth first search (DFS)

- Depth-first search (DFS) is an algorithm for traversing or searching tree or graph data structures.
- starts at the root node
- Can select some arbitrary node as the root node in the case of a graph
- explores as far as possible along each branch before backtracking, after the branch is fully explored.
- This is expressed as a recursion.
- Can be implemented using a stack.

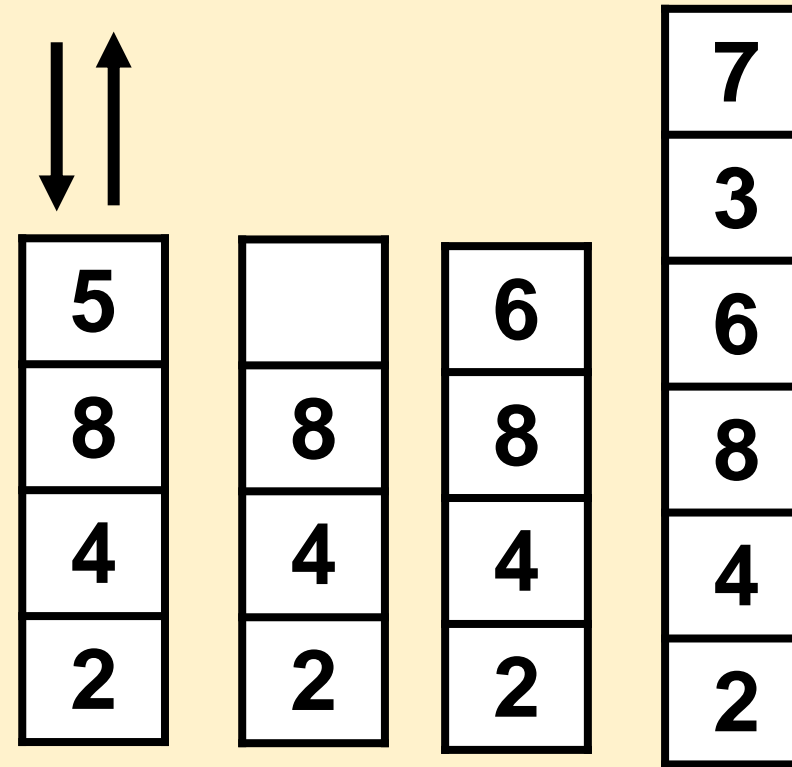
*Algorithm **DFS**(v : vertex; G :Graph)*
Visited[v] = 1;
for all vertices w adjacent to v {
if(Visited[w] = 0)
***DFS**(w ; G);*
}

- *The algorithm conduct a depth first search of G ;*
- *starting with vertex v*
- *a vertex i if visited is marked by setting $visited[i]=1$;*
- *initially all $visited[i] = 0$;*

Example: Depth First Search from vertex 1

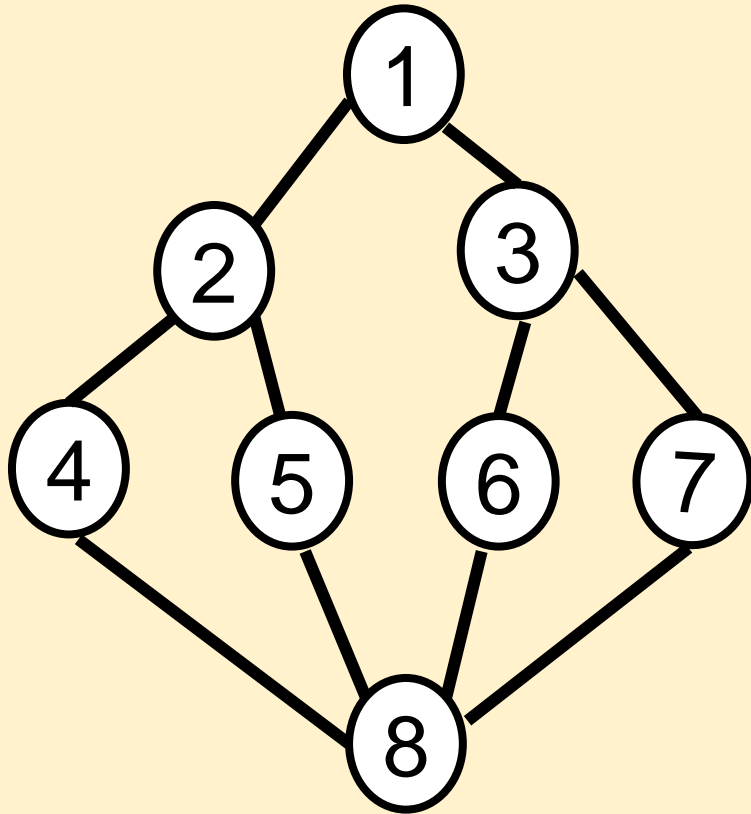


Stack of visited vertices from 1



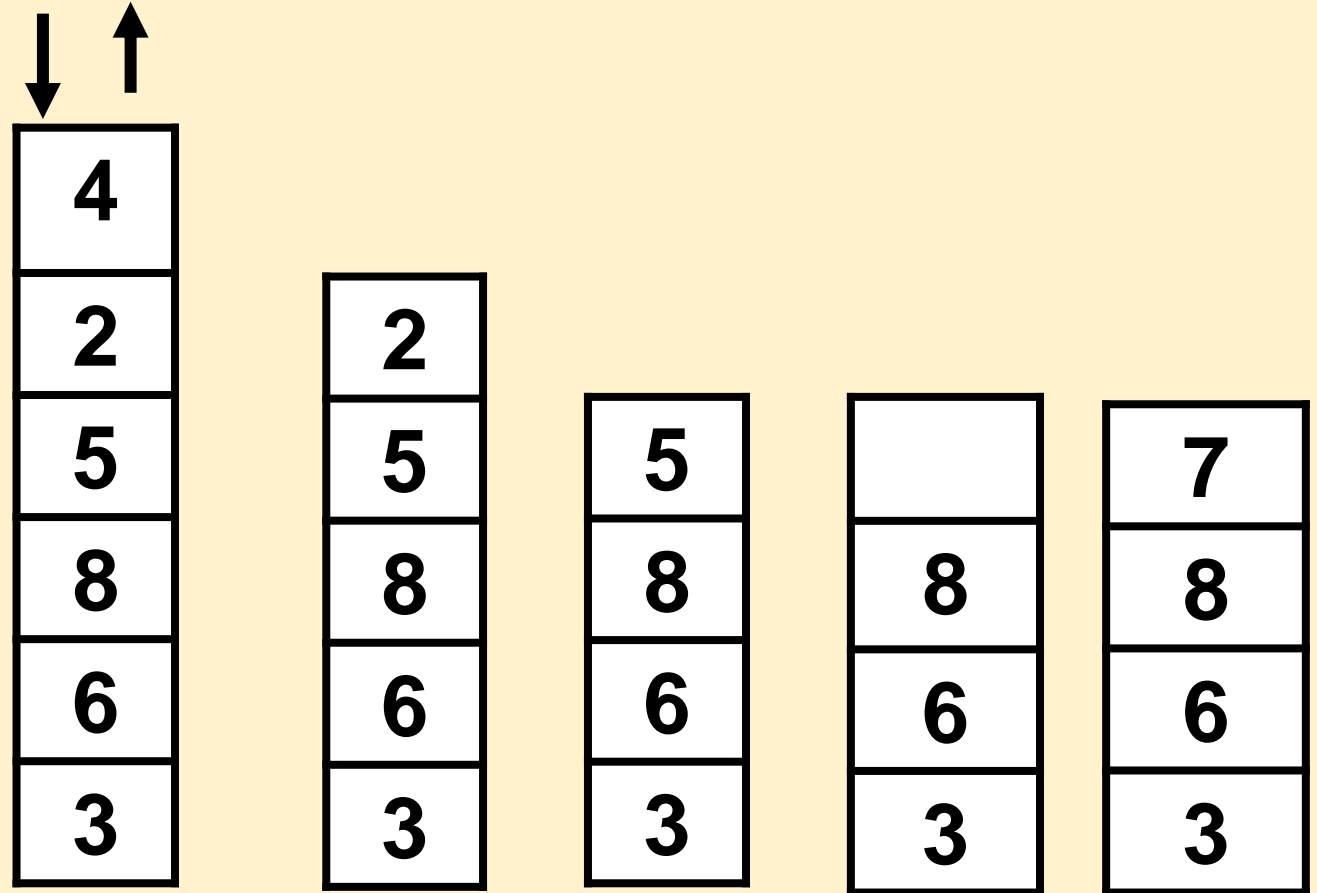
Vertices are visited vertices order 1,2,4,8,5,6,3, 7

Another possibility



Vertices are visited
vertices order:
1,3,6,8,5,2,4,7

Stack of visited vertices from 1



Breadth first search (BFS)

- Start at a vertex v — mark it as reached
- The vertex v is, as yet, unexplored
- When all the vertices adjacent to it (connected by an edge) have been visited, v has been explored(reached).
- Collect all the unvisited vertices adjacent to v and add them to a list.
- Take a vertex from the list and repeat the process
- When there are no vertices left in the list they have all been explored (reached).
- This yields the set of vertices that are “reach-able” from the start vertex v .

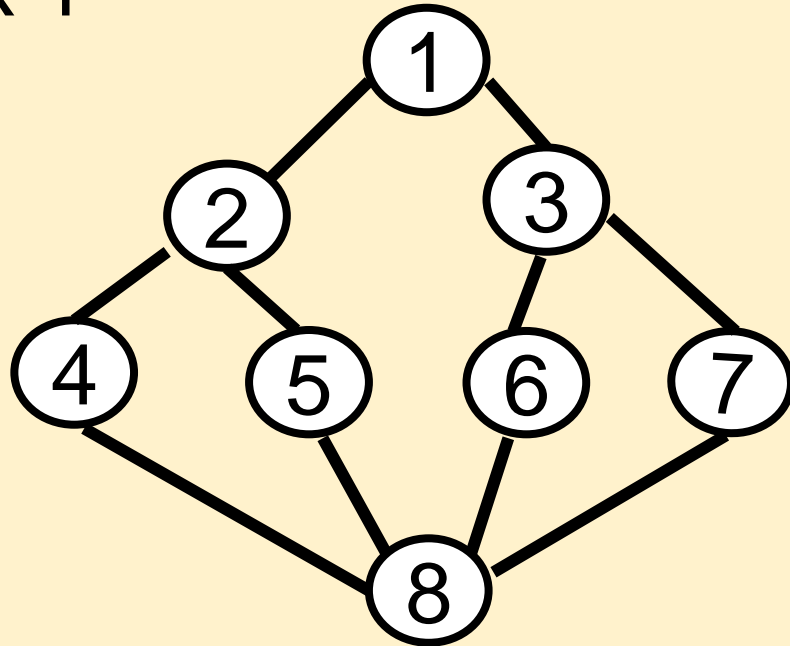
```

Algorithm BFS( $v$ : vertex;  $G$ : Graph) {
    visited[ $v$ ] = 1;
     $u = v$ ;
    MakeEmpty( $Q$ );
    Insert( $Q$ ;  $v$ );
    while(Not IsEmpty( $Q$ )) {
        for all vertices  $w$  adjacent to  $u$  {
            if(Visited[ $w$ ] == 0){
                Insert( $Q$ ;  $w$ ); visited[ $w$ ] = 1;
            }
        }
        if(IsEmpty( $Q$ ))  $u = Delete(Q)$ ;
    }
}

```

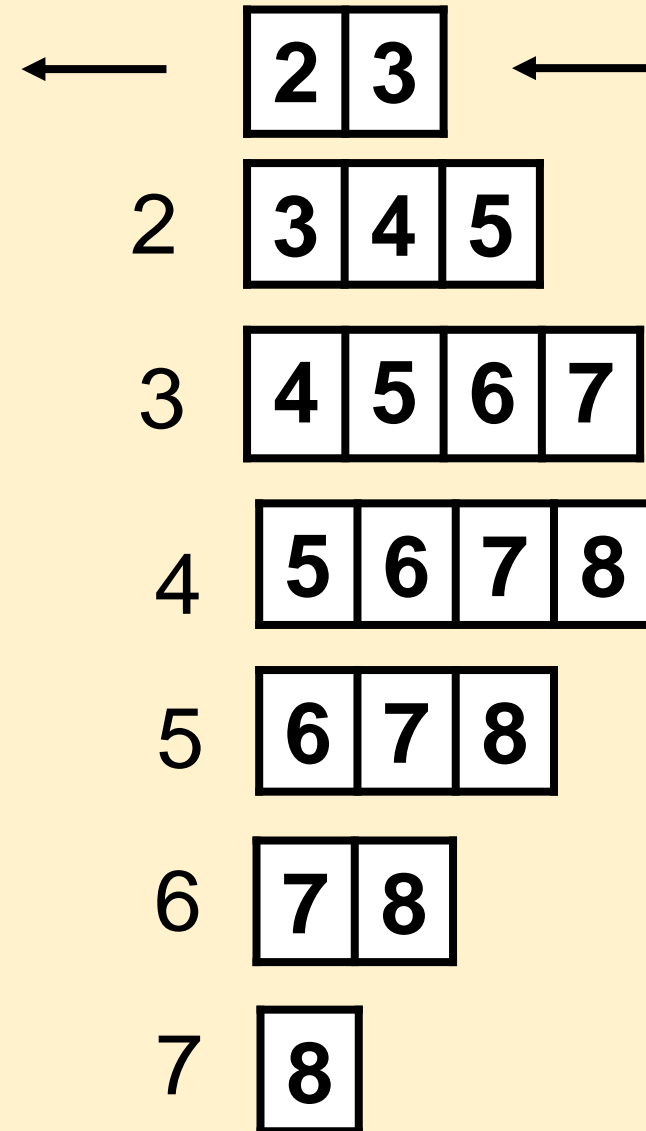
- *The algorithm conduct a breadth first search of G ;*
- *starting with vertex v*
- *a vertex i if visited is marked by setting*
visited[i]=1;
- *initially all visited[i] =0;*
- *Putting all adjacent nodes into a queue.*

Example: Breadth
First Search from
vertex 1



Vertices are visited vertices
order: 1,2,3,4,5,6,7,8

Queue for tracking visiting order



- ◆ **Graph traversal (continued)**
 - **Differences between DFS and BFS**
 - **Applications**
 - ✓ **Connected components**
 - ✓ **Spanning trees**
- ◆ **Analysis of BFS**

Difference between DFS and BFS

- Breadth first vs. Depth first
 - BFS : a node is fully explored before any other can begin.
 - DFS : exploration of a vertex v is suspended as soon as a new vertex u is reached.
 - ✓ exploration of the new vertex u begins.
 - ✓ exploration of v continues after u has been explored.
 - ✓ can be expressed as a recursive algorithm.
- Both are of $O(n)$ time complexity
- So which one to use and when ?
 - BFS is “better” at finding shortest path in a graph
 - DFS is “better” at answering connectivity queries
(Determining if every pair of vertices can be connected by two disjoint paths)

Applications

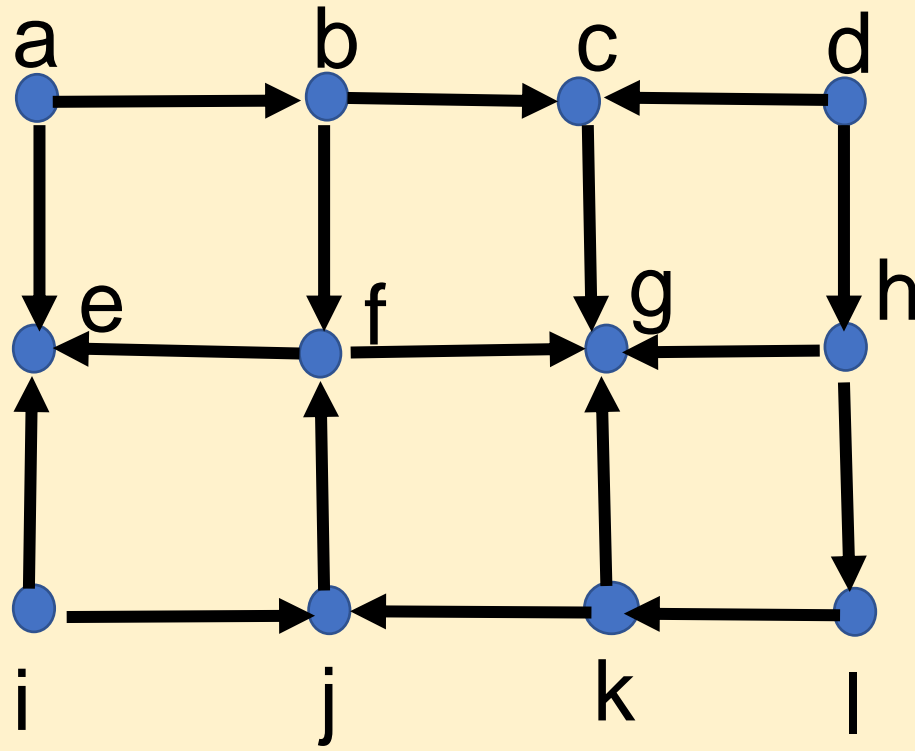
➤ IP Multicasting

- Efficiently transmit (same) data to multiple computers.
- requires that there are no loops in the network of computers and routers.
- Construct a spanning tree with routers and computers as nodes and links between routers as edges.

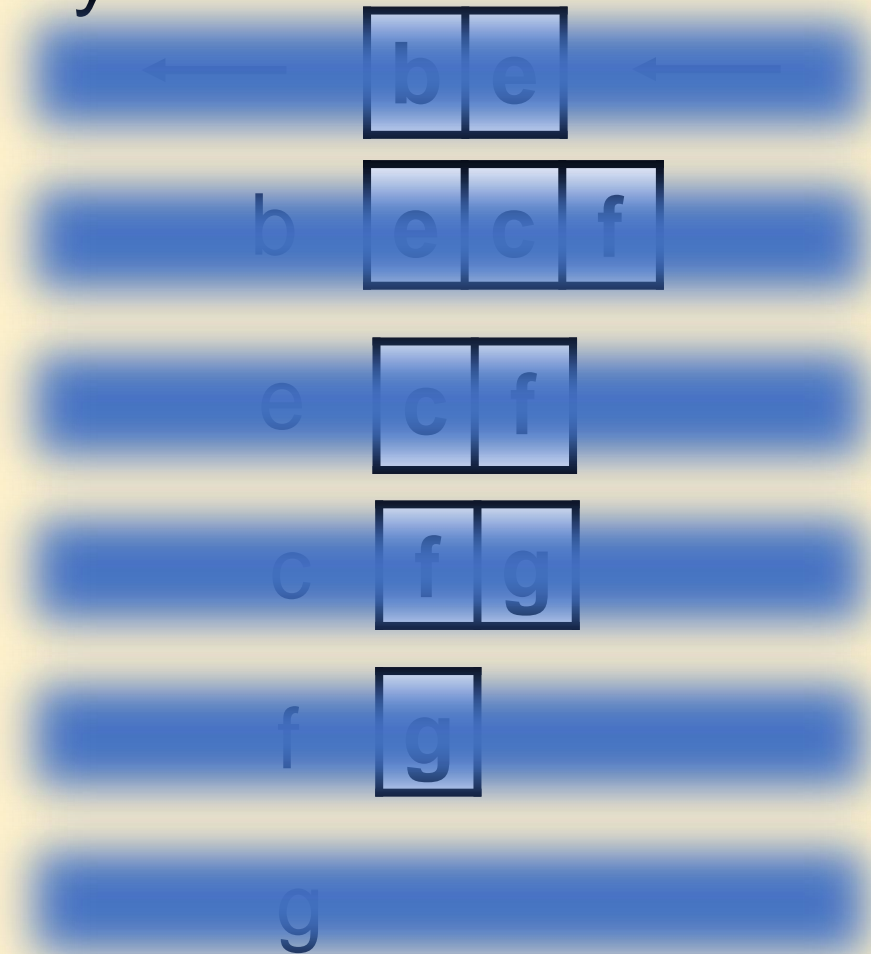
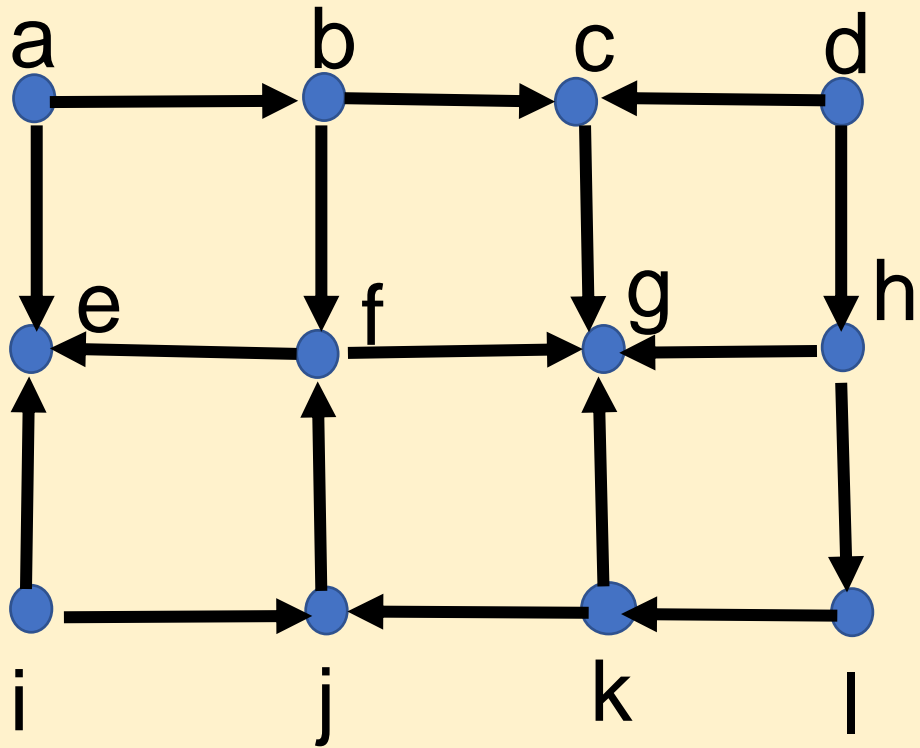
➤ Web Spiders

- Use a “web graph”
- A web page is a node.
- A (directed) edge between two nodes if there is a link in a web page pointing to another.
- Either DFS or BFS can be used to “crawl the web”
(Follow the links until no new links can be found.)

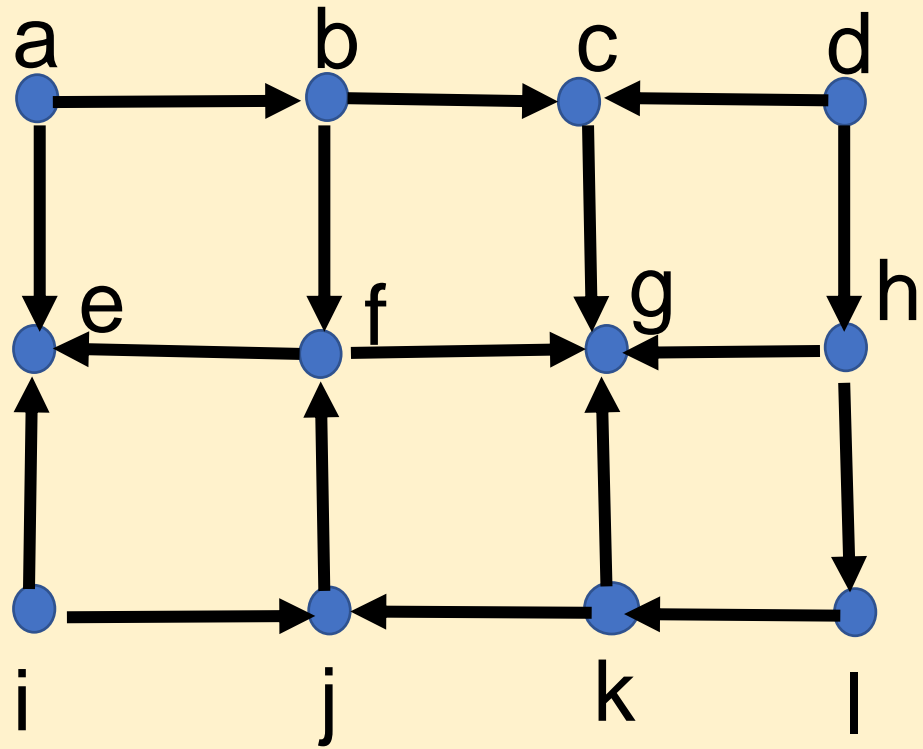
Example "Crawler": Trace the "crawl" for the following web graph based on DFS and BFS respectively
(exam question type)



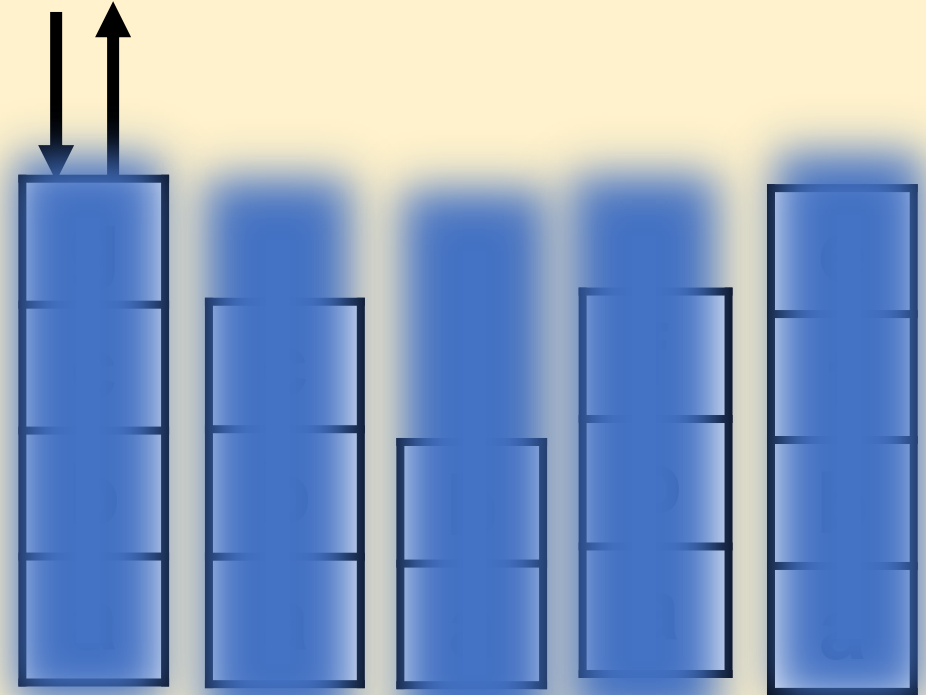
BFS: Pick a starting node, say it's 'a'



DFS: Pick a starting node, say it's 'a'



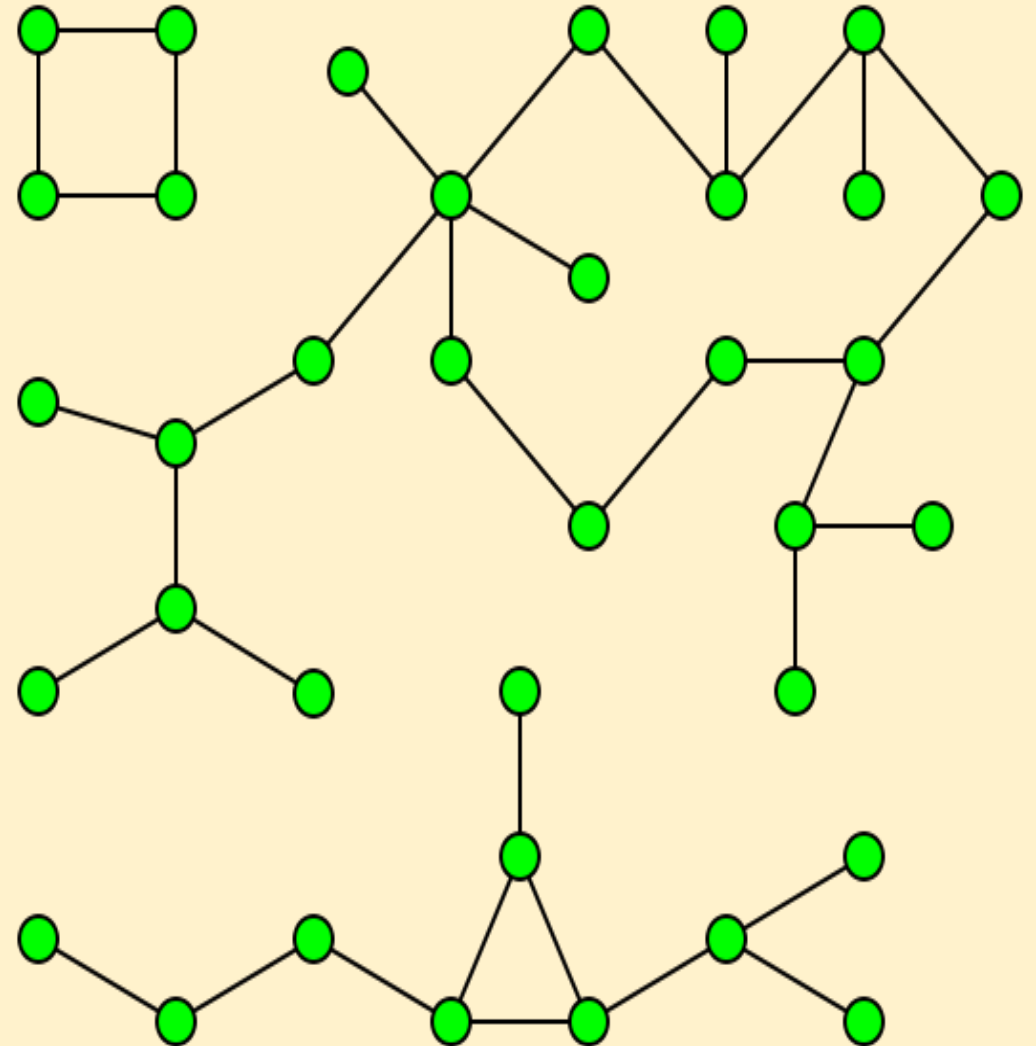
Stack of visited vertices from a



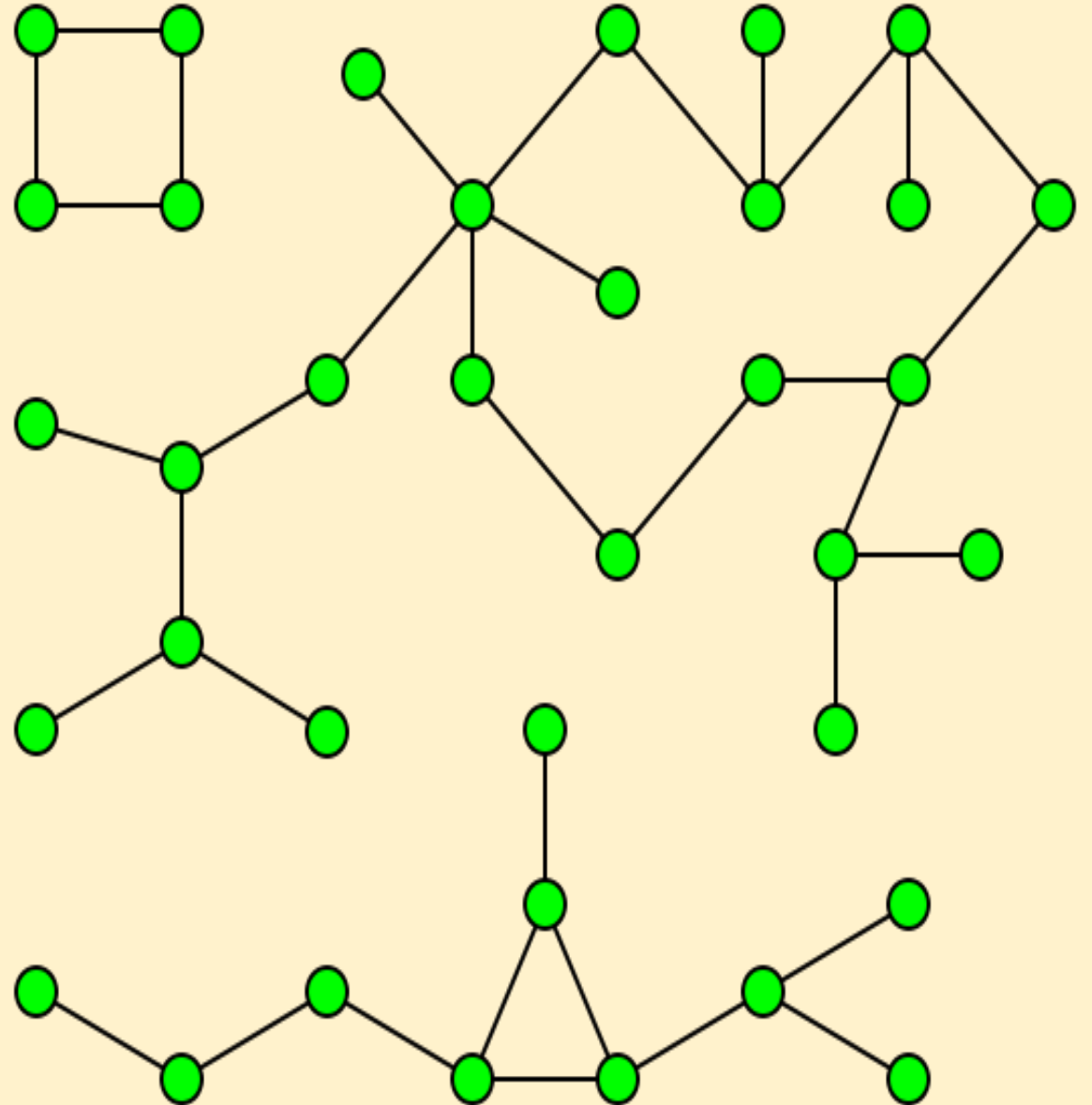
Applications

Connected components

- An undirected graph is connected if for every pair of vertices there exists a path between them.
- A connected component ' C ' is a maximal connected subgraph.



- If G is connected undirected graph, then all vertices of G are visited on first call of BFS.
- If G is not connected, then we need at least two calls of BFS.
- An extension of BFS algorithm can be designed to find all the connected components




```

Algorithm BFT(G:Graph; n:integer) {
    for(i= 1; i <=n; i++)
        Visited[i] = 1;
    for(i= 1; i <=n; i++)
        if(Visited[i] = 0) BFS(i, G);
}

```

- A complete traversal of an unconnected graph can be made by repeatedly calling BFS each time with an unvisited starting vertex.
- If *G* is connected then all vertices are visited in the first call of BFS.

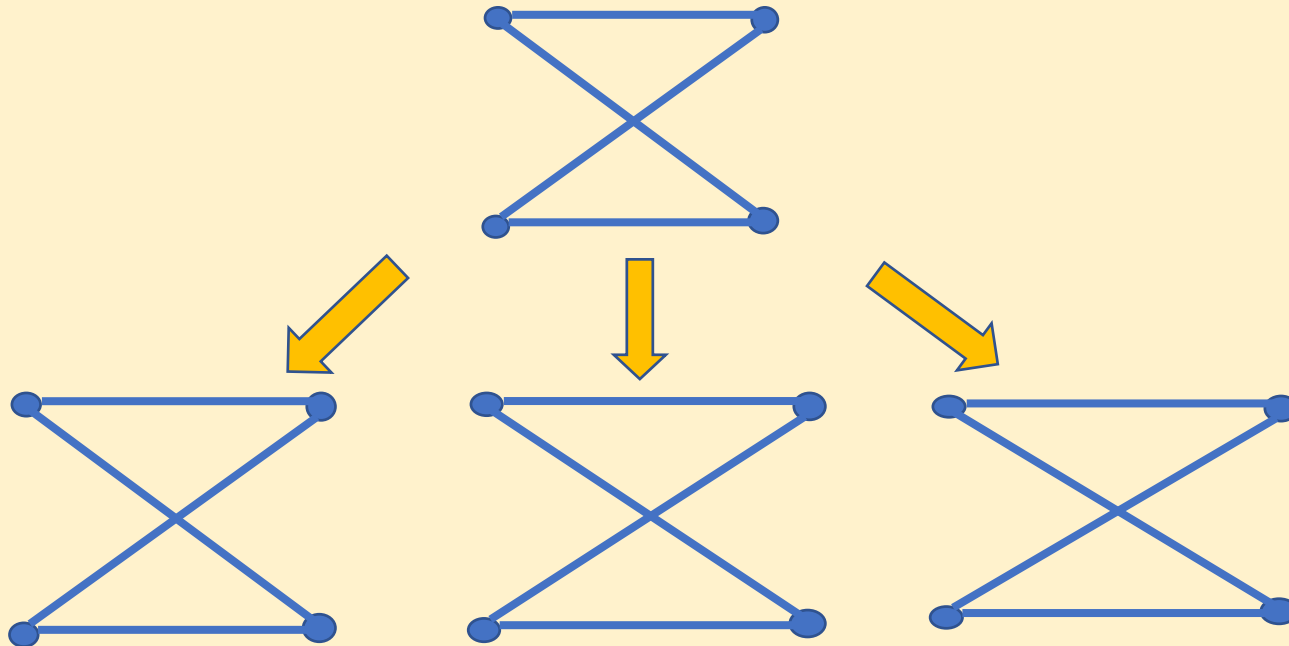
```

Algorithm BFS(v: vertex; G:Graph) {
    visited[v] = 1;
    u=v;
    MakeEmpty(Q);
    Insert(Q; v);
    while(Not IsEmpty(Q)) {
        for all vertices w adjacent to u {
            if(Visited[w] == 0) {
                Insert(Q; w); visited[w] = 1;
            }
        }
        if(Not IsEmpty(Q)) u=Delete(Q);
    }
}

```

Spanning tree

- A tree is a connected undirected graph with no cycles
- A spanning tree T of an undirected graph G is a subgraph that is a tree which includes all vertices of G , with a minimum possible number of edges.
- e.g. three spanning trees of G



- A graph G has a spanning tree if and only if G is connected.

```

Algorithm BFS-Span( $v$ : vertex;  $G$ : Graph)
{
    visited[ $v$ ] = 1;
     $u = v$ ;
    MakeEmpty( $Q$ );
    Insert( $Q$ ;  $v$ );  $t = \{\}$ ; //initially empty tree
    while(Not IsEmpty( $Q$ )) {
        for all vertices  $w$  adjacent to  $u$  {
            if(Visited[ $w$ ] == 0) {
                Insert( $Q$ ;  $w$ ); visited[ $w$ ] = 1;
                 $t = t \cup \{(u, w)\}$ ; //add forward edge
            }
        }
        if(Not IsEmpty( $Q$ ))  $u = \text{Delete}(Q)$ ;
    }
}

```

➤ A slight modification of BFS can be made to compute a spanning tree.

```

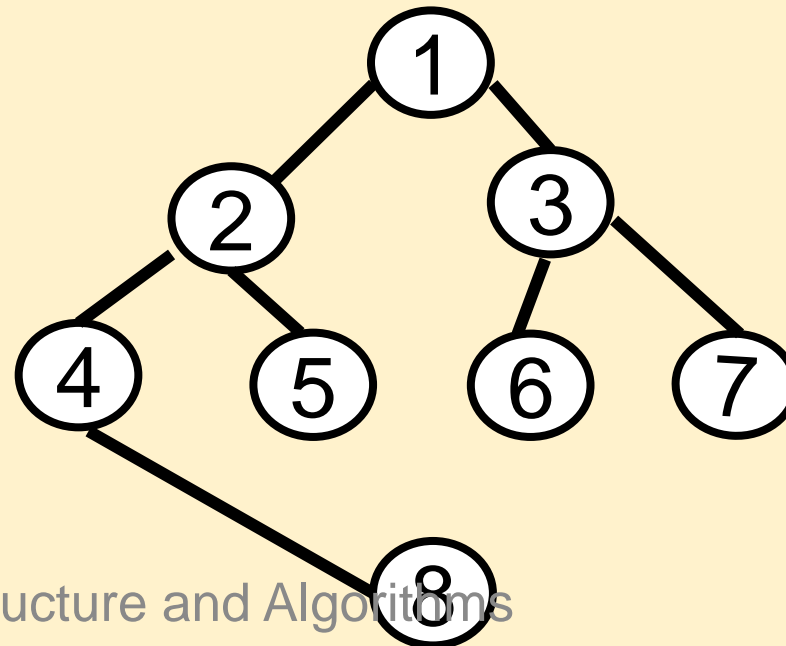
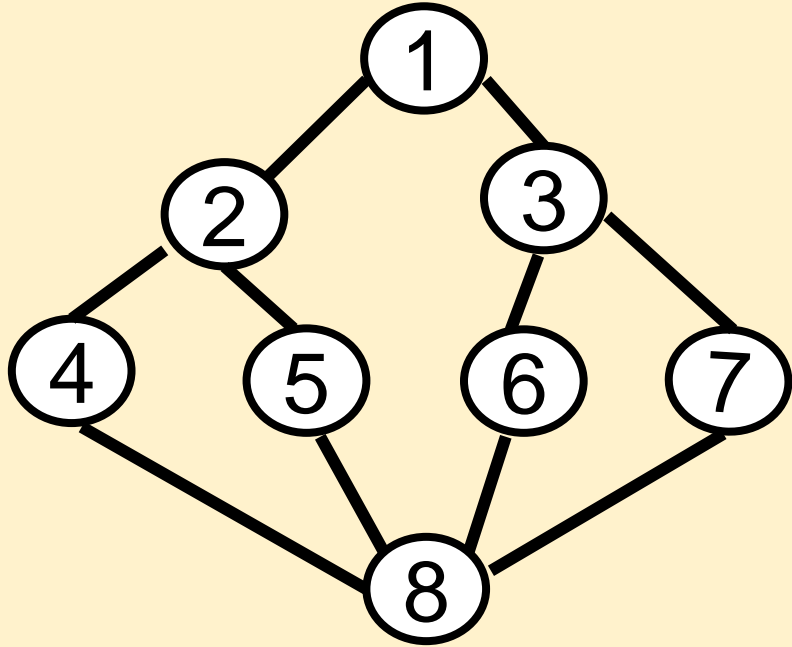
Algorithm BFS( $v$ : vertex;  $G$ : Graph) {
    visited[ $v$ ] = 1;
     $u = v$ ;
    MakeEmpty( $Q$ );
    Insert( $Q$ ;  $v$ );
    while(Not IsEmpty( $Q$ )) {
        for all vertices  $w$  adjacent to  $u$  {
            if(Visited[ $w$ ] == 0) {
                Insert( $Q$ ;  $w$ ); visited[ $w$ ] = 1;
            }
        }
        if(Not IsEmpty( $Q$ ))  $u = \text{Delete}(Q)$ ;
    }
}

```

Example: Breadth First Spanning tree from vertex 1

Vertices are visited vertices order:
1,2,3,4,5,6,7,8

Added forward edges:
 $\{1,2\}, \{1,3\}, \{2,4\}, \{2,5\}, \{3,6\}, \{3,7\}, \{4,8\}$



Extension: Modify DFS search to create a spanning tree algorithm

```
Algorithm DFS( $v$ : vertex;  
G: Graph)  
    Visited[ $v$ ] = 1;  
    for all vertices  $w$  adjacent  
    to  $v$  {  
        if(Visited[ $w$ ] = 0)  
            DFS( $w$ ; G);  
    }
```

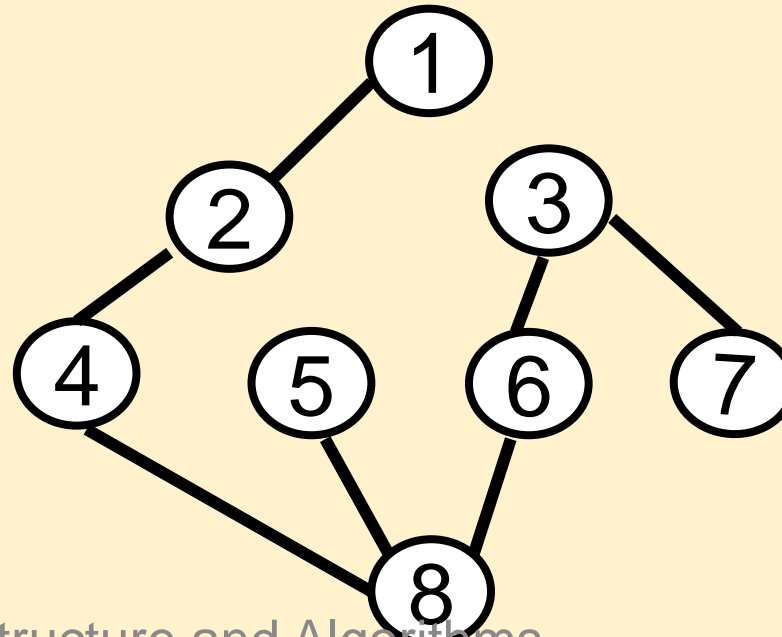
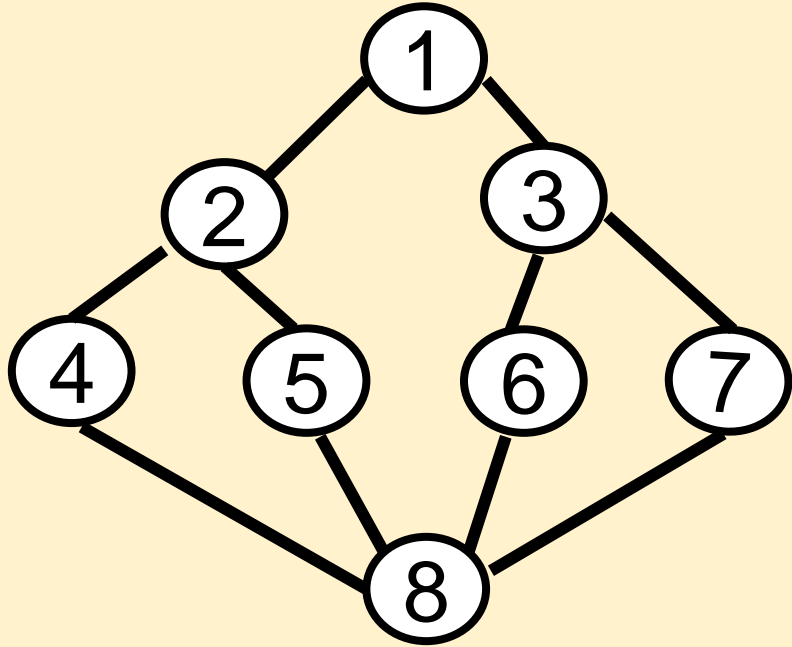
- A slight modification of DFS can be made to compute a spanning tree.

Example: Depth First Spanning tree from vertex 1

Vertices are visited vertices order
1,2,4,8,5,6,3, 7

Added forward edges:

$\{1,2\}, \{2,4\}, \{4,8\}, \{8,5\}, \{8,6\}, \{6,3\}, \{3,7\}$



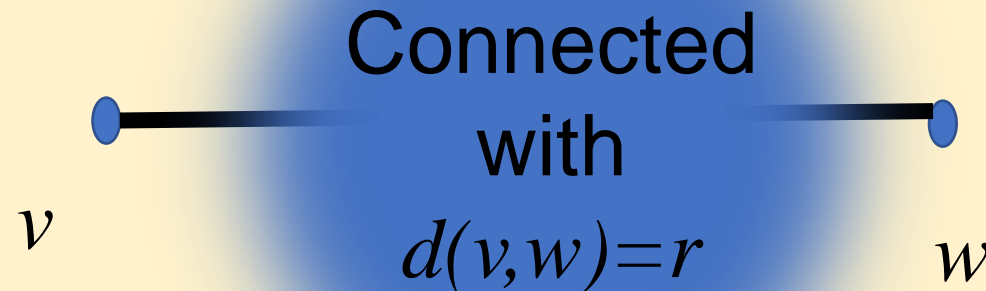
Analysis of BFS

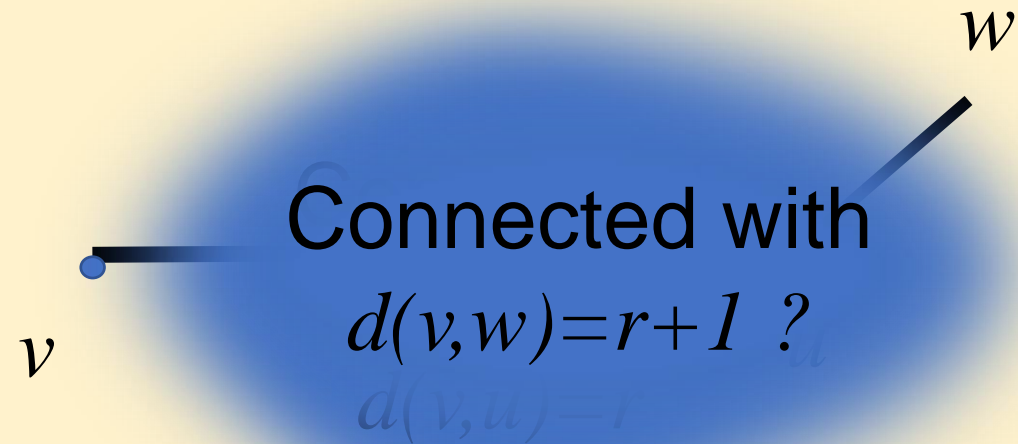
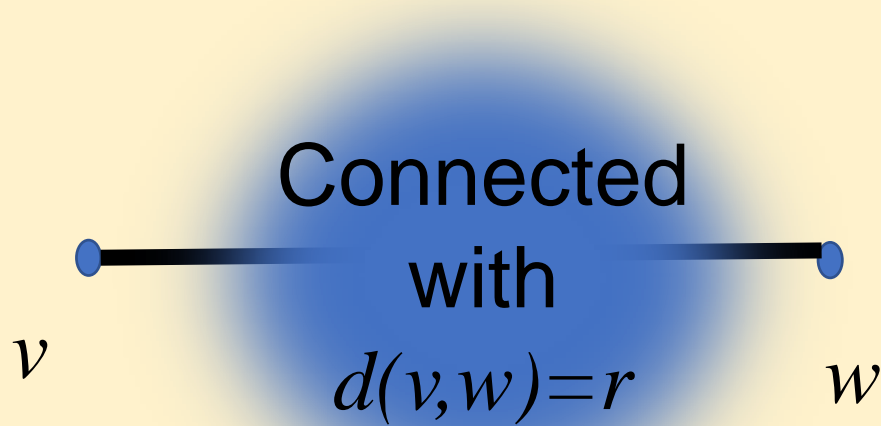
- The BFS algorithm:
 - Start at a vertex v — mark it as reached
 - The vertex v is, as yet, unexplored
 - When all the vertices adjacent to it (connected by an edge) have been visited, v has been explored(reached).
 - Collect all the unvisited vertices adjacent to v and add them to a list.
 - Take a vertex from the list and repeat the process
 - When there are no vertices left in the list they have all been explored (reached).
 - This yields the set of vertices that are “reach-able” from the start vertex v .
- Theorem: Algorithm BFS visits all reachable vertices.

- Mathematical Induction is a special way of proving things. It has only 2 steps:
Step 1. Show it is true for first case, usually $n=1$
Step 2. Show that if $n=k$ is true, then $n=k+1$ is also true
- Example:
 - Step 1. The first domino falls
 - Step 2. When any domino falls, the next domino falls
- So ... all dominos will fall!
- We will prove this theorem by method of induction.



- Proof is by induction based on the the distance of shortest path.
- Suppose $d(v, w)$ is the length (number of edges) of the shortest path from vertex v to a reachable vertex w .
- Basic step : Clearly, all w with $d(v; w) \leq 1$ are visited.
- Hypothesis : Assume all vertices w with $d(v; w) \leq r$ are visited.





- Inductive step : We now show that all w with $d(v; w) \leq r + 1$ are also visited.
- Suppose that $d(v, w) = r + 1$ for some w , and let u be a vertex adjacent to w , $u \neq v$ and $r \geq 1$.
 - Then $d(v, u) = r$ (**shortest path**) and immediately prior to u being visited by BFS, u is put on the Queue.
 - Since the algorithm only stops when the Queue is empty, at some stage u is taken off the Queue and is explored and thus visits w .
 - The only way for w not to be visited is if it is not reachable.