Mid term revision

- A revision note
- Self study (implementing some algorithms)

Exam structure

- Answer Three from FIVE in paper CS2AO17, at least TWO from four algorithms question (70% of module marks)
- > Topics covered in Algorithm
 - □ Additional data structures*
 Tree, Heap, Graph, tree and graph traversals
 - □ Algorithms
 Divide and Conquer*
 - The greedy algorithms (Week 8-9)
 - Dynamic programming with Second revision (Week 10-11)
- *First Revision

Control abstraction

Define solutions of problems by Control abstraction

- Flow of control is un-ambiguous
- Primary operations are undefined (small combine, solve,....)

```
Algorithm D\&C(P)

if Small(P) return Solve(P)

else{

Divide P into smaller instances P_1, P_2, ..., P_k

Apply D\&C to each of these subproblems

return Combine(D\&C(P_1), D\&C(P_2), ..., D\&C(P_k))
}
```

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D&C Max-min

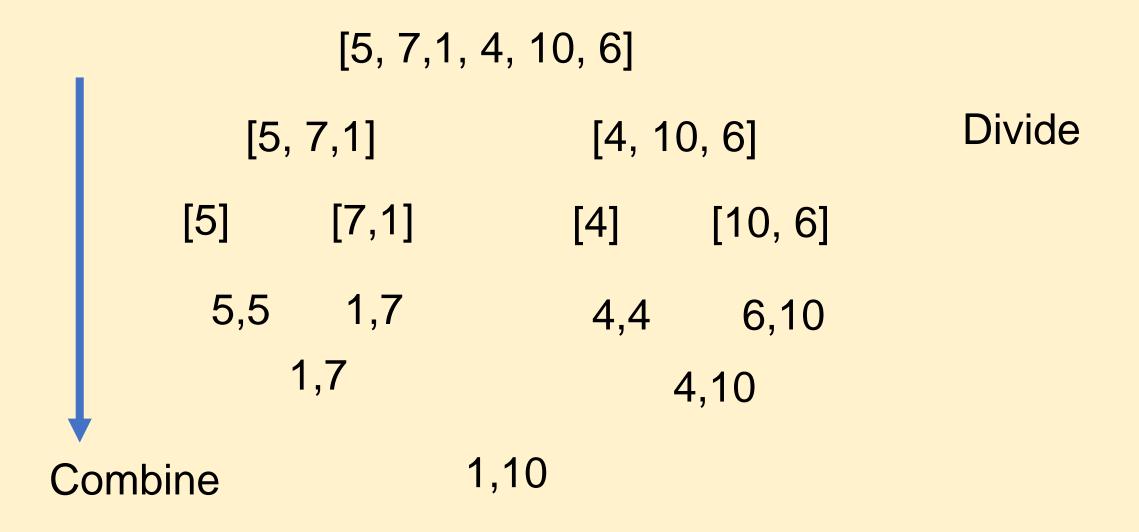
Redundant possibilities are eliminated as quickly as possible

- 1. Divide the list into small groups.
- 2. Then find max and min of each group.
- 3. The max/min of result must be one of maxs and mins of the groups.

e.g.
$$A = [5, 7, 1, 4, 10, 6]$$

$$A_1 = [5,7,1],$$
 $max(A_1) = 7,$ $min(A_1) = 1$
 $A_2 = [4,10,6],$ $max(A_2) = 10,$ $min(A_2) = 4$
So the min and max of A is $min(1,4)$ and $max(7,10)$, i.e. 1 and 10

Trace of recursive calls



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Selection -- Strategy

Choose a value in the list.

Partition the list so that the chosen value is in its final position if we are sorting.

lack Call this position j.

(i.e. all values to the left of j are smaller and all the elements to the right are larger).

- ♦ Since j is in correct place if j=k, we have found the kth smallest (if j=n-k, the k^{th} largest).
- If j > k then the k^{th} smallest is in the left sub-list otherwise in the right sub-list.

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Selection algorithm example

Find second smallest k=2

- **•** [5,7,4,1,10,6]
- [4,1,5,7,10,6] after partition -5 is the third smallest j=3
- ◆ [4,1,5] consider left sub-list A[1,2,3]
- ◆ [1,4,5] after partition –4 is the second smallest j =2 =k

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Heap and Graphs

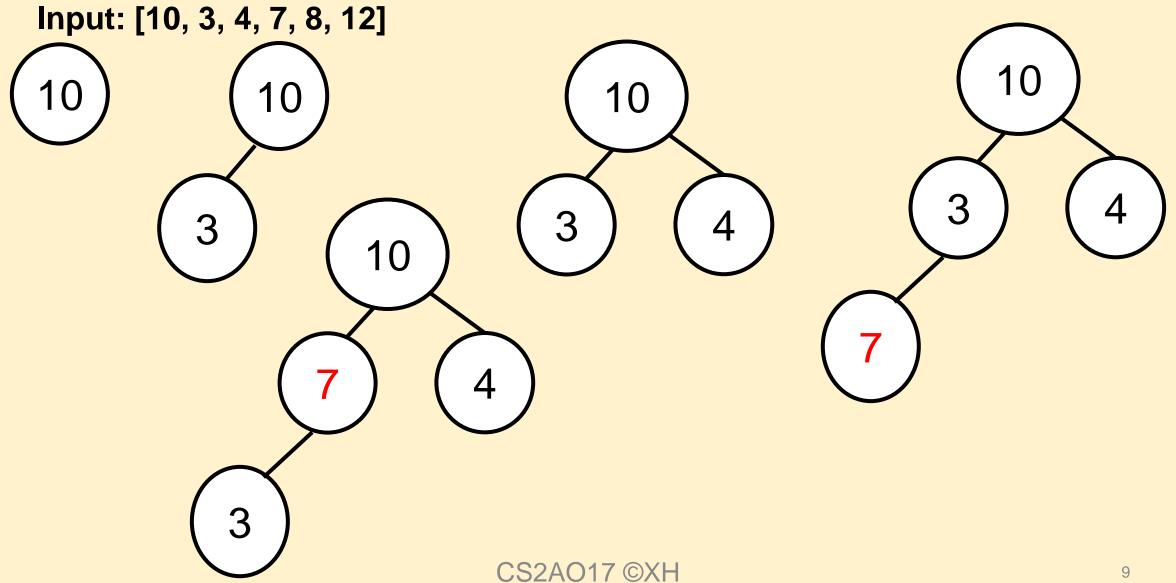
Main topics

- Heaps
 - Construction of Heap
 - Insertion (worst case O(nlogn))
 - bottom up (average O(n))
 - Heapsort

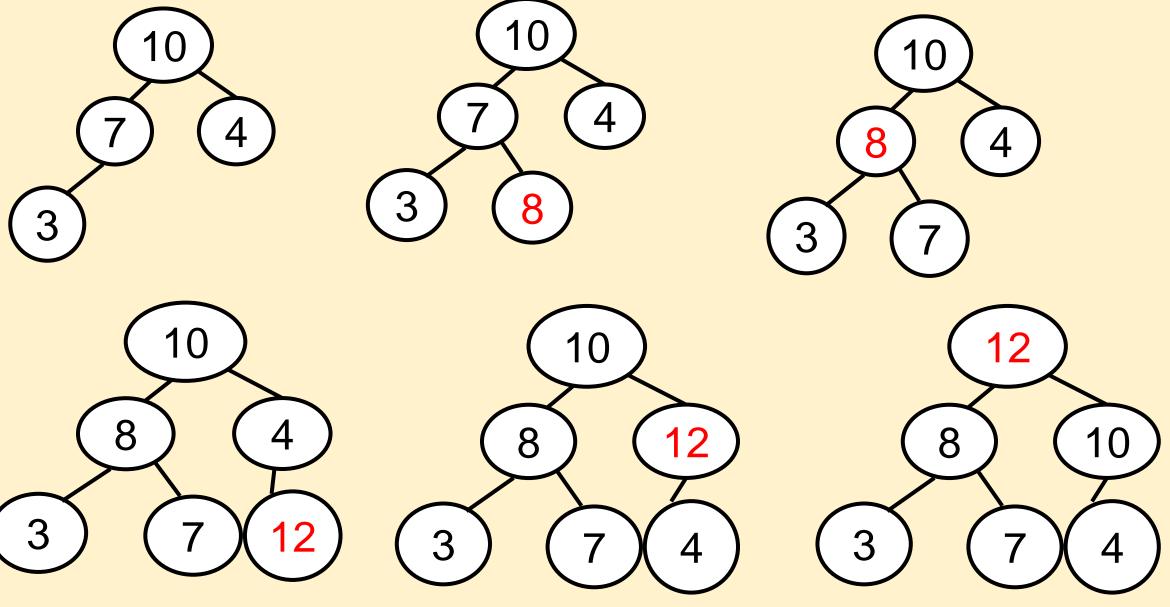
- Graphs
 - Representation
 - Adjacent list
 - Adjacent matrix
 - Traversals
 - BFS
 - DFS

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Making a Heap from n values

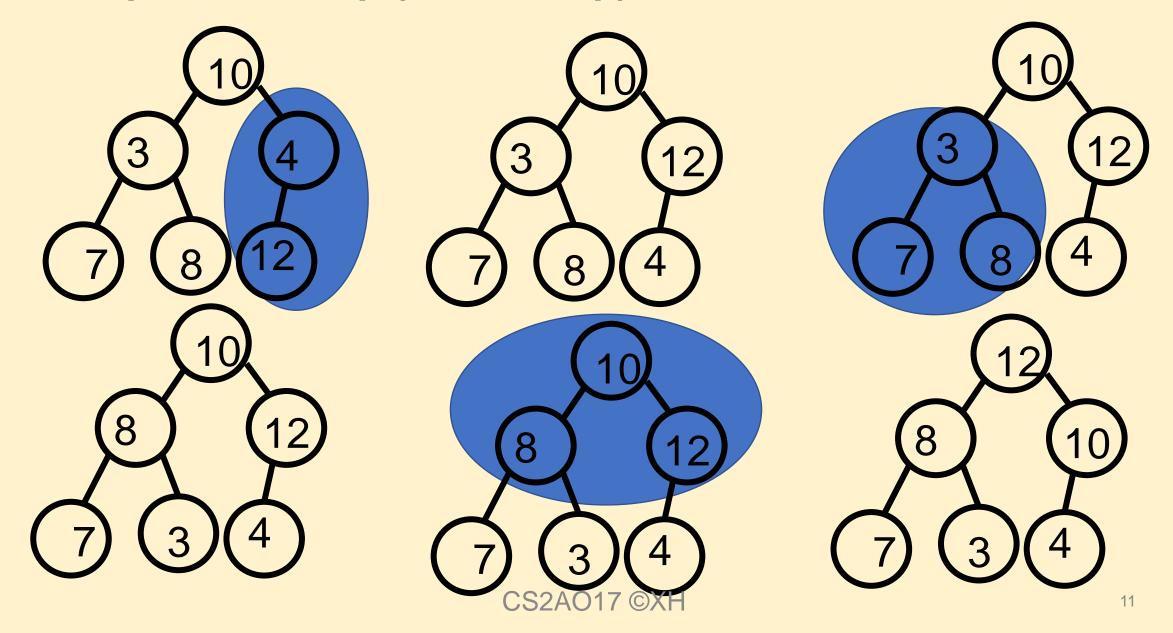


Input: [10, 3, 4, 7, 8, 12]



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Example Fast heap (Bottom up)



Definitions (Graph)

Graph

 a graph G(V, E) consists of a finite set V of vertices and a set of E of edges where each edge is a pair of a vertices (i, j)

Directed/undirected Graph

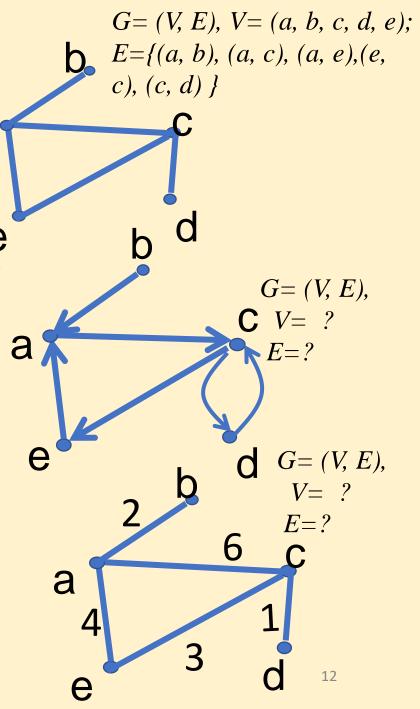
• a graph is undirected if (i, j) = (j, i), i.e., pair of vertices are unordered for all edges, otherwise directed

Weighted graph

 a weighted graph G(V; E) has a cost, a real number, attached to an edge.

Degree

- The degree of a vertex is the number of edges attached to it.
 - ✓ In-degree of vertex j is the number of edges ending at j.
 - ✓ Out-degree of vertex *j* is the number of edges leaving *j*.



Matrix representation

Undirected graph

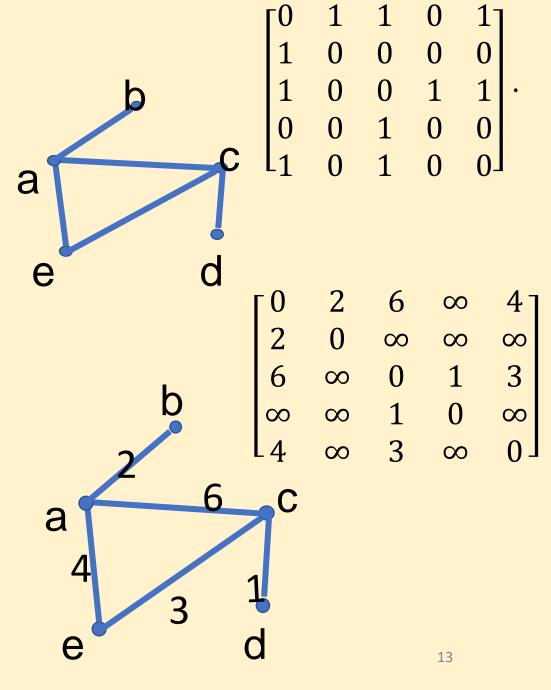
$$A[i, j] = \begin{cases} 1 & \text{if } edge\ (i, j) \text{ is in } E(G) \\ 0 & \text{otherwise} \end{cases}$$

Directed graph

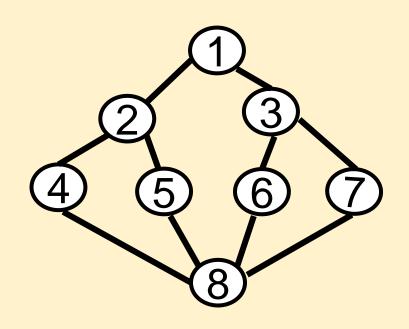
$$A[i, j] = \begin{cases} 1 & \text{if } edge < i, j > is in } E(G) \\ 0 & otherwise \end{cases}$$

Weighted graph

$$A[i, j] = \begin{cases} c & \text{if } edge < i, j > is in } E(G) \\ \infty & \text{otherwise} \end{cases}$$

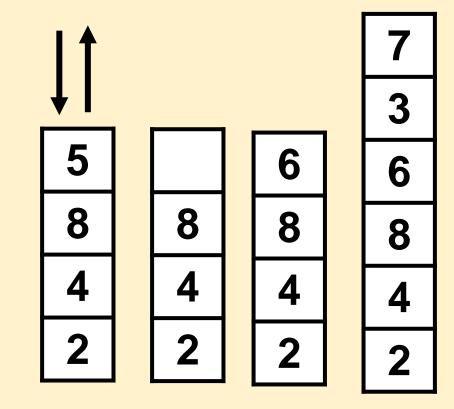


Example: Depth First Search from vertex 1



Vertices are visited vertices order 1,2,4,8,5,6,3,7

Stack of visited vertices from 1



Breath first search

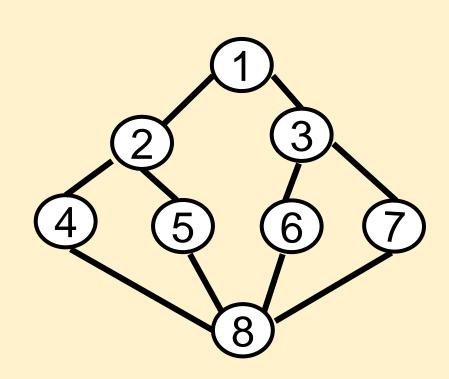
Theorem: Algorithm BFS visits all reachable vertices.

Algorithm:

- Start at a vertex v— mark it as reached
- The vertex v is, as yet, unexplored
- When all the vertices adjacent to it (connected by an edge) have been visited, v has been explored(reached).
- Collect all the unvisited vertices adjacent to v and add them to a list.
- Take a vertex from the list and repeat the process
- When there are no vertices left in the list they have all been explored (reached).
- This yields the set of vertices that are "reachable" from the start vertex

Breadth First Search from vertex 1

Queue for tracking visiting order



Vertices are visited vertices order: 1,2,3,4,5,6,7,8

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Applications of Graph traversal

Connected Components

- If G is connected undirected graph then all vertices of G are visited on first call of BFS. If G is not connected then we need at least two calls to BFS.
- An extension of BFS algorithm can be designed to find all the connected components.

Spanning Trees

- A graph G has a spanning tree if and only if G is connected.
- A slight modification of BFS can be made to compute a spanning tree.

Suggested problems

- ◆ Heap sort
- ◆ Convex hull
- ◆ D&C max-min

- Work with others together to solve as many as possible.
 e. g. two problems as a group two.
 or three problems as a group of four.
- ◆ If you work on your own, do at least one problem.
- ◆ For each problem (for your own reference)

Write a code or find a code from internet.
Write a A4 page to explain the method.
Implement the code (any language)
Report the results, attach to the method page.

- You are invited the share in blackboard forum.
- This work is unassessed to replace Week 7 lecture as self study, as part of revision.

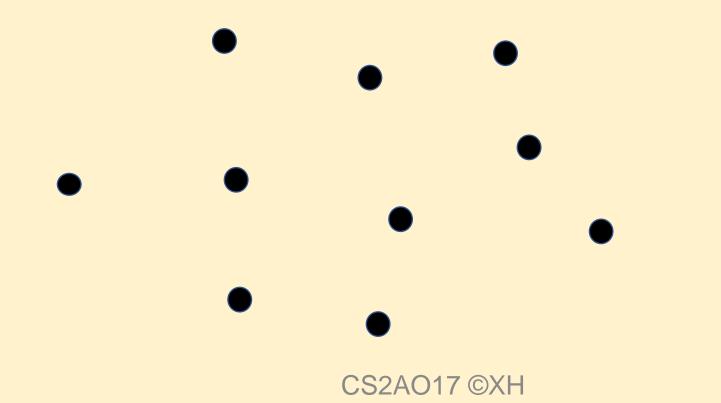
Heap sort

Sort out the following array using heapsort

[1, 6, 16, 13, 7, 3, 86, 30]

Convex hull

Create a convex hull of at least 10 points, e.g.



D&C Max-min

Find max-min using Divide and Conquer for

[1 2 3 4 5 6 7 8 9 10]