

Biostatistics 682: Applied Bayesian Inference

Lecture 10: Bayesian Linear Regression

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Bayesian linear regression

- Linear regression is the most common statistical model.
- The multiple linear regression model is

$$Y_i \sim N \left(\beta_0 + \sum_{j=1}^p X_{i,j} \beta_j, \sigma^2 \right),$$

for $i = 1, \dots, n$. Y_i are independently across the n observations.

- Bayesian and classical linear regression are similar if $n \gg p$ and the priors are uninformative

Review of least squares

- The least squares estimate of $\beta = (\beta_0, \beta_1, \dots, \beta_p)^T$ is

$$\hat{\beta}_{\text{OLS}} = \arg \min_{\beta} \sum_{i=1}^n (Y_i - \mu_i)^2,$$

where $\mu_i = \beta_0 + X_{i,1}\beta_1 + \dots + X_{i,p}\beta_p$.

- $\hat{\beta}_{\text{OLS}}$ is unbiased even if the errors are non-Gaussian.
- If the errors are Gaussian then the likelihood is proportional to

$$\prod_{i=1}^n \exp \left\{ -\frac{(Y_i - \mu_i)^2}{2\sigma^2} \right\} = \exp \left\{ -\frac{\sum_{i=1}^n (Y_i - \mu_i)^2}{2\sigma^2} \right\}.$$

- Therefore, if the errors are Gaussian $\hat{\beta}_{\text{OLS}}$ is also the MLE.

Review of least squares

- Linear regression is often simpler to describe using linear algebra notation.
- Let $\mathbf{Y} = (Y_1, \dots, Y_n)^T$ be the response vector and \mathbf{X} be the $n \times (p + 1)$ matrix of covariates.
- Then the mean of \mathbf{Y} is $\mathbf{X}\beta$ and the least squares solution is

$$\beta_{\text{OLS}} = \arg \min_{\beta} (\mathbf{Y} - \mathbf{X}\beta)^T (\mathbf{Y} - \mathbf{X}\beta) = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}.$$

- If the errors are Gaussian then the sampling distribution is

$$\hat{\beta}_{\text{OLS}} \sim N [\beta, \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1}].$$

- If the variance σ^2 is estimated using the mean squared residual error then the sampling distribution is multivariate t .

- The likelihood remains

$$Y_i \mid \boldsymbol{\beta}, \sigma^2 \sim N(\beta_0 + X_{i,1}\beta_1 + \dots + X_{i,p}\beta_p, \sigma^2)$$

independent for $i = 1, \dots, n$ observations.

- A Bayesian analysis also requires priors for $\boldsymbol{\beta}$ and σ .
- We will focus on prior specification since this piece is uniquely Bayesian.

- For the purpose of setting priors, it is helpful to standardize both the response and each covariate to have mean zero and variance one.
- Many priors for β have been considered:
 - Improper priors
 - Gaussian priors
 - Double exponential priors
 - Spike-and-Slab Priors

- The Jeffrey's prior is flat $\pi(\boldsymbol{\beta}) \propto 1$.
- This is improper, but the posterior is proper under the same conditions required by least squares.
- If σ is known then

$$\boldsymbol{\beta} \mid \mathbf{Y} \sim \text{N} \left[\hat{\boldsymbol{\beta}}_{\text{OLS}}, \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1} \right].$$

- How is this result different from the least squares?

- We rarely know σ^2 in practice.
- The Jeffreys prior for (β, σ^2) is

$$\pi(\beta, \sigma^2) \propto 1/\sigma^2,$$

which is the limit case of an inverse gamma distribution with shape and rate parameters approaching zero.

- Then the posterior of β follows a multivariate t centered on $\hat{\beta}_{\text{OLS}}$.

Multivariate normal prior

- Another common prior for is Zellner's g-prior

$$\boldsymbol{\beta} \mid \sigma^2 \sim N \left[0, \frac{\sigma^2}{g} (\mathbf{X}^T \mathbf{X})^{-1} \right].$$

- This prior is proper assuming \mathbf{X} is full rank.
- Then

$$\boldsymbol{\beta} \mid \sigma^2, \mathbf{Y}, \mathbf{X} \sim N \left[\frac{1}{1+g} \hat{\boldsymbol{\beta}}_{\text{OLS}}, \frac{1}{1+g} \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1} \right].$$

- This shrinks the least squares estimate towards zero.
- g controls the amount of shrinkage.
- $g = 1/n$ is common, and called the unit information prior.

Univariate Gaussian priors

- If there are many covariates or the covariates are collinear, then $\hat{\beta}_{\text{OLS}}$ is unstable.
- Independent priors can counteract collinearity

$$\beta_j \sim N(0, \sigma^2/g)$$

independent over j .

- The posterior mode is

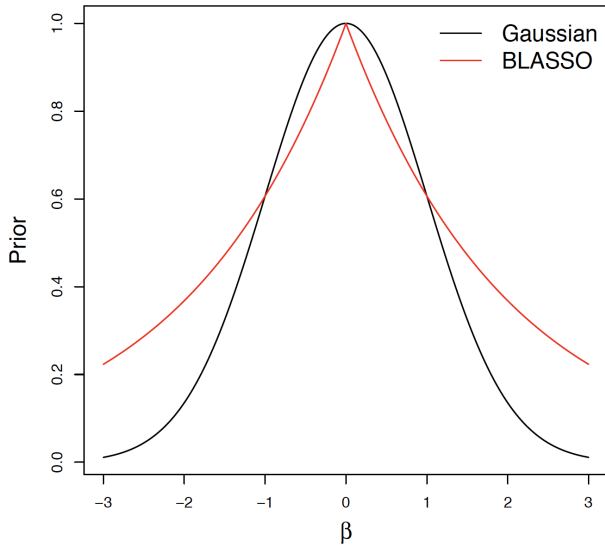
$$\arg \min_{\beta} \sum_{i=1}^n (Y_i - \mu_i)^2 + g \sum_{j=1}^p \beta_j^2.$$

- In classical statistics, this is known as the ridge regression solution and is used to stabilize the least squares solution.

- An increasingly-popular prior is the double exponential or Bayesian LASSO prior
- The prior is $\beta_j \sim \text{DE}(\tau^2)$ which has the probability density function

$$\pi(\beta_j) \propto \exp\left(-\frac{|\beta_j|}{\tau^2}\right).$$

- The square in the Gaussian prior is replaced with an absolute value
- The shape of the PDF is thus more peaked at zero
- The BLASSO prior favors settings where there are many β_j near zero and a few large β_j .
- That is, p is large but most of the covariates are noise.



- The posterior model is

$$\arg \min_{\beta} \sum_{i=1}^n (Y_i - \mu_i)^2 + \tau^{-2} \sum_{j=1}^p |\beta_j|.$$

- In classical statistics, this is known as the LASSO solution
- It is popular because it adds stability by shrinking estimates towards zero, and also sets some coefficient to zero
- Covariates with coefficients set to zero and can be excluded from the model.
- LASSO performs variable selection and estimation simultaneously.

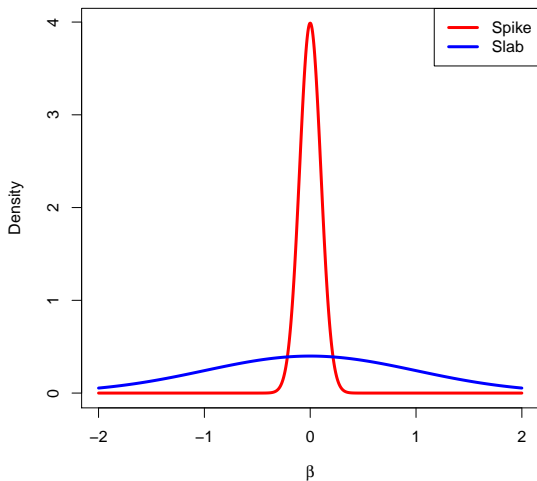
- Mixture Prior

$$\beta_j \mid \gamma_j \sim (1 - \gamma_j)\mathcal{N}(0, c_0^2) + \gamma_j\mathcal{N}(0, c_1^2).$$

$$\gamma_j \sim \text{Bernoulli}(\pi).$$

- The constant c_0^2 is small, so that if $\gamma_j = 0$, “ β_j could be safely estimated by 0”.
- The constant c_1^2 is large, so that if $\gamma_j = 1$, “a non-zero estimate of β_j should probably be included in the final model”.
- It works well for computing the marginal inclusion probability of each covariate and for model averaging
- This model is computationally convenient and extremely flexible

Spike and Slab Priors



Posterior computation for Bayesian linear model

- With flat or Gaussian (with fixed prior variance) priors the posterior is available in closed-form and Monte Carlo sampling is not needed
- With Gaussian priors all full conditionals are Gaussian or inverse gamma, and so Gibbs sampling is simple and fast
- With the BLASSO prior the full conditionals are more complicated
 - There is a trick to make all full conditional conjugate so that Gibbs sampling can be used
 - Metropolis sampling works fine too
- With the Spike Slab prior the full conditionals are available
- JAGS can handle all of them