

Last session of TA classes!

We will have a brief review of hard-core lie groups & algebs!

First, let's discuss the famous problem of non-matrix lie groups.

$$G = \mathbb{R} \times \mathbb{R} \times S^1 \text{ with } (x_1, y_1, u_1) \cdot (x_2, y_2, u_2) =$$

$$(x_1+x_2, y_1+y_2, e^{i(x_1y_2 - u_1u_2)})$$

Let H be the Heisenberg group $\left\{ \begin{pmatrix} 1 & a & b \\ & 1 & c \\ & & 1 \end{pmatrix} \mid a, b, c \in \mathbb{R} \right\}$

Consider $\Phi : H \rightarrow G$

$$\phi \begin{pmatrix} 1 & a & b \\ & 1 & c \\ & & 1 \end{pmatrix} = (a, c, e^{ib})$$

① Homomorphism :

$$\phi \begin{pmatrix} 1 & a_1 & b_1 \\ & 1 & c_1 \\ & & 1 \end{pmatrix} \phi \begin{pmatrix} 1 & a_2 & b_2 \\ & 1 & c_2 \\ & & 1 \end{pmatrix} = (a_1, c_1, e^{ib_1}) \cdot (a_2, c_2, e^{ib_2}) \\ = (a_1 + a_2, c_1 + c_2, e^{ia_1c_2 + i(b_1 + b_2)})$$

on the other hand: $(*)$ $\begin{pmatrix} 1 & a_1 & b_1 \\ & 1 & c_1 \\ & & 1 \end{pmatrix} \begin{pmatrix} 1 & a_2 & b_2 \\ & 1 & c_2 \\ & & 1 \end{pmatrix} = \begin{pmatrix} 1 & a_1+a_2 & b_2 + a_1c_2 + b_1 \\ & 0 & 1 \\ & \ddots & \ddots & 1 \end{pmatrix}$

$$\rightarrow \phi \begin{pmatrix} 1 & a_1+a_2 & b_1+b_2 + a_1c_2 \\ & 0 & 1 \\ & \ddots & \ddots & 1 \end{pmatrix} = (a_1+a_2, c_1+c_2, e^{ib_1+ib_2+i(a_1c_2)})$$

Let's find $\ker \phi = \{ M \in H \mid \phi(M) = e_{\mathbb{R} \times \mathbb{R} \times S^1} = (0, 0, 1) \}$

$$\text{since } \phi \begin{pmatrix} 1 & a & b \\ & 1 & c \\ & & 1 \end{pmatrix} = (a, c, e^{ib}) = (0, 0, 1)$$

$$\text{so } \ker \phi = \left\{ \begin{pmatrix} 1 & 0 & 2\pi n \\ & 1 & 0 \\ & & 1 \end{pmatrix} \mid n \in \mathbb{Z} \right\}$$

Now let Ψ be a finite-dim representation of G . (i.e.

a continuous map of G into some $GL(n, \mathbb{C})$)

so the associated representation (Σ) of H is given by

$$\Sigma = \Psi \circ \Phi$$

The kernel of such representation must include the kernel of Φ .

Let $Z(H)$ be the centre of H . By use of $*$ it is

$$Z(H) = \left\{ \begin{pmatrix} 1 & 0 & b \\ & 1 & 0 \\ & & 1 \end{pmatrix} \mid b \in \mathbb{R} \right\}$$

Corollary : For any finite-dimensional rep of H , If

$$\ker \Sigma \supset \ker \phi \implies \ker \Sigma \supset Z(H).$$

once this is established, we can conclude that there is no faithful finite-dimensional representations of G .

Since by above corollary, $\ker \Sigma$ will contain $\ker \phi$ (and $Z(H)$)

Thus:

$$\forall b \in \mathbb{R} : \Sigma \begin{pmatrix} 1 & b \\ & 1 \\ & & 1 \end{pmatrix} = \phi(0, 0, e^{ib})$$

which means that $\ker \phi$ contains $(0, 0, u)$ elements, so ϕ is not faithful! $\rightarrow G$ has no faithful finite-dim. representation.

so elements of G cannot be represented by a matrix, nevertheless
 G is a lie group (has manifold structure.)

It just remains to argue Corollary.

let σ be the associated representation of the lie-algebra \mathfrak{h} of H .

Basis elements of H are given by :

$$A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad B = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad C = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{with } [A, C] = B \quad [A, B] = [C, B] = 0$$

$$\text{so that } [\sigma(A), \sigma(C)] = \sigma(B) \quad [\sigma(A), \sigma(B)] = [\sigma(B), \sigma(C)] = 0$$

we claim that $\sigma(B)$ is nilpotent. In light of SN decomposition,
all its eigenvalues are zero.

Let λ be an eigenvalue for $\sigma(B)$ and V_λ its associated eigenspace.

so V_λ is invariant under $\sigma(B)$. since both $\sigma(A), \sigma(C)$ commute
with $\sigma(B)$, they also leave V_λ invariant.

The restriction of $\sigma(A), \sigma(B), \sigma(C)$ on V_λ also satisfies the same
commutation relations.

$$\text{By } [\sigma(A)|_{V_\lambda}, \sigma(C)|_{V_\lambda}] = \sigma(B)|_{V_\lambda} \implies \text{Tr}(\sigma(B)|_{V_\lambda}) = 0 .$$

on the other hand, V_λ is invariant subspace of $\sigma(B)|_{V_\lambda}$

$$\text{so } \sigma(B)|_{V_\lambda} = \lambda I$$

why? because $(\sigma(B) - \lambda I)|_{V_\lambda} \stackrel{(K)}{=} 0 \rightarrow$ on V_λ , $\sigma(B)|_{V_\lambda}$
acts like identity.

$$\rightarrow \text{Tr}(\sigma(B)|_{V_\lambda}) = \lambda \underbrace{\dim(V_\lambda)}_{\neq 0} \Rightarrow$$

$$\text{for } \text{Tr}(\sigma(B)|_{V_\lambda}) = 0 \rightarrow \boxed{\lambda = 0}$$

so zero is the only eigenvalue of $\sigma(B) \rightarrow \sigma(B)$ is nilpotent.

Corollary: If X is $\neq 0$ nilpotent matrix, for all $t \neq 0 \rightarrow e^{tX} \neq I$.

since X is nilpotent \rightarrow the expansion terminates.

Let $(e^{tX})_{k\ell} = P_{k\ell}(t)$ (polynomial depends on t)

suppose for $t \cdot \neq 0 \rightarrow e^{t \cdot X} = I \xrightarrow{(\cdot)^n} e^{nt \cdot X} = I \quad (\forall n)$

In terms of polynomials $\rightarrow P_{k\ell}(nt \cdot) = \delta_{k\ell}$

But a polynomial that has ∞ zeros, must be constant

\Rightarrow As long as there's an $t_0 \in \mathbb{R} - \{0\}$ that $e^{t_0 X} = I \rightarrow$

$$e^{t_0 X} = I$$

so that $X = \frac{1}{t_0} (\exp(tX))|_{t=0} = 0 \quad \times$

so if X is non-zero nilpotent $\rightarrow e^{tX}$ must $\neq I$. for all $t \neq 0$.

Now $\sigma(B)$ is nilpotent (non-zero) matrix. ($B^2 = 0 \rightarrow \sigma(B)^2 = 0$)

$$\text{and } e^{tB} = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

let Σ be rep of H and $\ker \Sigma \supset \ker \phi$

$$e^{2\pi n \sigma(B)} = \Sigma (e^{2\pi n B}) = I$$

since $\sigma(B)$ is nilpotent (according to the lemma) $\rightarrow \sigma(B)$ has to

be zero. $\rightarrow \forall t \in \mathbb{R}$

$$\sum(e^{tB}) = e^{t\text{tr}(B)} = I$$

$$\Rightarrow \ker \sum \supset Z(H)$$

Let's look at another technical example.

$SL(n, \mathbb{R})$ ($n > 2$) is not simply-connected

while

$SL(n, \mathbb{C})$ ($n > 2$) is simply-connected.

Universal cover of $\tilde{SL}(n, \mathbb{R})$ and

$\Phi: \tilde{SL}(n, \mathbb{R}) \rightarrow SL(n, \mathbb{R})$ is assumed!

asserted $\phi: \tilde{SL}(n, \mathbb{R}) \rightarrow SL(n, \mathbb{R})$ is isomorphism (lie-alg isomph.)

Theorem: There's no any faithful finite-dim representation of

$\tilde{SL}(n, \mathbb{R})$ \rightarrow $\tilde{SL}(n, \mathbb{R})$ is a non-metabelian Lie-group

If Π is any finite-dim rep of $\tilde{SL}(n, \mathbb{R})$, thus $\ker \Pi$ contains $\ker \Phi$ ($\Phi: \tilde{SL}(n, \mathbb{R}) \rightarrow SL(n, \mathbb{R})$)

By above, since $SL(n, \mathbb{R})$ is not simply-connected $\Rightarrow \Phi$ has non-trivial kernel $\Rightarrow \Pi$ is not faithful \rightarrow just like above.

The proof is beyond our knowledge and uses homological sequences!

I just wanted to introduce it as another non-matrix-lie grp.

The map of Lie groups & algebras:

matrix Lie groups

GL / SL / U / SU / O / SO / Sp / H / E / $p(n, l)$

their properties → Connected Homotopy groups
Compact Homology groups
dimension Their relationships , ...

Abstract definition → As a manifold.

Lie Algebra $\xrightarrow{\exp}$ Lie groups.

$T_e G$ is a vector space called Lie-Algebra.

(Naively, all matrixes A such that e^{tA} ($t \in \mathbb{R}$) is in liegrp, is an element of lie-algebra.)

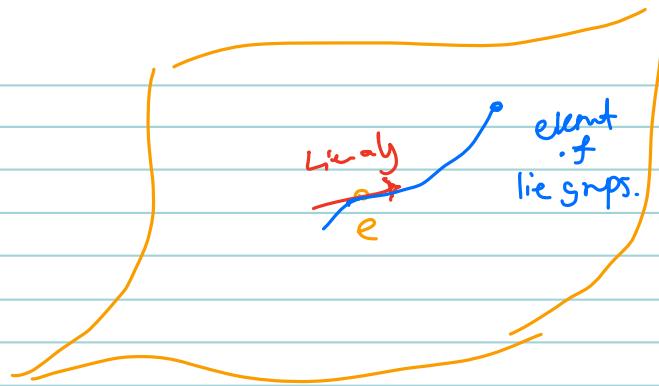
Technically $\mathfrak{g} = T_e G$.

It's a vector space of matrices.

Lie group homomorphism corresponds to lie-alg homomorph.

Exponential mapping:

$$\exp: \mathfrak{g} \rightarrow G$$



Lie alg. properties:

1. $[.,.]$ is linear

2. $[A, B] = -[B, A] \quad \forall A, B \in \mathfrak{g}$

3. $(A, [B, C]) + [B, [C, A]] + [C, [A, B]] = 0 \quad (\text{Jacobi})$

$$[x_i, x_j] = \underbrace{f_{ij}^k}_{\text{structure constants.}} x_k$$

There are so many topics about Lie-algebras.

- * Complexification
- * BCH lemma
- * \oplus and \otimes of them.
- * Real Lie algebras

with some basic knowledge of representation theory:

one can classify lie algebras according to:

C- {
 | simple
 | semi-simple

[exceptional lie algs. (g_2, f_4, e_6, e_7, e_8)]

$R \rightarrow \begin{cases} \text{simple} & \rightarrow \text{an invariant - sub algebra.} \\ \text{semi-simple} \end{cases}$

Then the classical path is to study their representations following ideas of Weyl, Vermas, Cartan, and find the root systems.

problems: show that the following is a lie-algebra.

vectors with \times product.

Sol:

(a) bilinearity : $(\lambda v + \mu w) \times u = \lambda v \times u + \mu w \times u$

$$u \times (\lambda v + \mu w) = \lambda u \times v + \mu u \times w$$

(b) $u \times w = -w \times u$ obviously (componentwise.)

(c) $\underbrace{(u \times v)}_{(u \cdot v)w - (u \cdot w)v} \times w + \underbrace{(v \times w)}_{(v \cdot w)u - (v \cdot u)w} \times u + \underbrace{(w \times u)}_{(w \cdot u)v - (w \cdot v)u} \times v = ?$

$$a \times (b \times c) = b(a \cdot c) - c(a \cdot b) \quad BAC - CAB$$

= zero

so it's a lie-algebra!

problem: (1) Determine Lie-algebra of H .
(2) prove \exp is diffeo from \mathfrak{h} to H .

(1) The bases are simply $\partial_{E_1}, \partial_{E_2}, \partial_{E_3}$ of $\begin{pmatrix} 1 & E_1 & E_2 \\ & 1 & E_3 \\ & & 1 \end{pmatrix}$

$$\rightarrow \mathfrak{h} = \left\langle \begin{pmatrix} 0 & 1 & 0 \\ & 0 & 0 \\ & & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \right\rangle$$

$$= \left\{ \begin{pmatrix} 0 & a & b \\ & 0 & c \\ & & 0 \end{pmatrix}; a, b, c \in \mathbb{R} \right\}$$

$$(2) \exp(\mathfrak{m}) = \sum_n \frac{\mathfrak{m}^n}{n!}$$

note that $\begin{pmatrix} a & b \\ & c \end{pmatrix}^3 = 0$

$$\exp\left(\begin{pmatrix} a & b \\ & c \end{pmatrix}\right) = I + \begin{pmatrix} a & b \\ & c \end{pmatrix} + \frac{1}{2} \begin{pmatrix} a & b \\ & c \end{pmatrix}^2$$

$$= \begin{pmatrix} 1 & a & b + \frac{ac}{2} \\ & 1 & c \\ & & 1 \end{pmatrix}$$

problem, prove that $\frac{o(n+1)}{o(n)}$ and $\frac{so(n+1)}{so(n)}$ are homogeneous spaces, which \mathfrak{g}' is diffeomorphic to them.

By means of the map

$$O(n) \longrightarrow O(n+1)$$

$$A \mapsto \begin{pmatrix} 1 & & & & \\ \vdots & A & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & & 1 \end{pmatrix}$$

To prove homogeneity :

- (i) a C^∞ action of $O(n+1)$ (or $SO(n+1)$) to S^n .
 - (ii) It's transitive action
 - (iii) Isotropy group H_p is isomorphic to $O(n)$ ($SO(n)$).
- (i) The action $GL(n+1, \mathbb{R})$ on \mathbb{R}^{n+1} by matrix product,
is C^∞ (why? It's just linear combination!)
- and since $O(n)$ is closed in $GL(n, \mathbb{R})$, Its restriction
to $O(n+1) \times \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$ is C^∞ .
- And since $O(n+1)$ preserves the length of vectors,
it takes $S^n \cong$ unit vectors in \mathbb{R}^{n+1} to itself.
 $\implies O(n+1)$ acts on S^n diffeomorphically.

- (ii) For any pair $p, q \in S^n$ there exists $A \in O(n+1)$
such that $Ap = q$.

There are actually infinitely many of them.
 one can define other elements of A arbitrarily,
 so the action is transitive.

(222) Take (WLOG) $p = (1, 0, \dots, 0)$

$$H_p = \{A \in O(n+1) \mid AP = P\}$$

so we have $A = (a_{ij})$ with $a_{ii} = 1$
 $a_{ij} = 0 \text{ for } i \neq j$.

$$\text{Since } A \in O(n+1) \rightarrow A^T A = A A^T = \mathbb{I}_{n+1}.$$

$$\text{so } \underbrace{A^T A}_P = P \rightarrow A^T P = P$$

by def
 $= P$

$$\rightarrow H_p = \left\{ \begin{pmatrix} 1 & 0 & \cdots & 0 \\ \vdots & & & \\ 0 & B \end{pmatrix} \in O(n+1) \right\}$$

$$\text{But } A^T A = \mathbb{I} \rightarrow B^T B = I \rightarrow B \in O(n)$$

$$\Rightarrow H_p \simeq O(n)$$

Hence the $S^n = \frac{O(n+1)}{O(n)}$ is established.

The similar arguments show us that $S^n = \frac{SO(n+1)}{SO(n)}$