

Q1.

$$\nabla_\beta g_{\alpha\sigma} \stackrel{?}{=} 0$$

By definition of Covariant derivative on forms:

$$\nabla_\beta g_{\alpha\sigma} = \partial_\beta g_{\alpha\sigma} - \Gamma_{\beta\alpha}^\lambda g_{\lambda\sigma} - \Gamma_{\beta\sigma}^\lambda g_{\alpha\lambda}$$

We find the second term, the third term is the same with  $\alpha \leftrightarrow \sigma$  exchange. since both  $\Gamma_{\mu\nu}^\rho$  and  $g_{\mu\nu}$  are symmetric under  $\mu \leftrightarrow \nu$ .

$$\Gamma_{\beta\alpha}^\lambda g_{\lambda\sigma} \stackrel{\text{By def}}{=} g_{\lambda\sigma} \times \frac{1}{2} g^{\lambda\rho} (\partial_\beta g_{\alpha\rho} + \partial_\alpha g_{\rho\beta} - \partial_\rho g_{\alpha\beta})$$

By  $g_{\lambda\sigma} g^{\lambda\rho} = g_{\sigma\lambda} g^{\lambda\rho} = \delta_\sigma^\rho$  identity  
(since  $g^{\mu\nu}$  is inverse of  $g_{\mu\nu}$  ...)

$$\Gamma_{\beta\alpha}^\lambda g_{\lambda\sigma} = \frac{1}{2} \delta_\sigma^\rho (\partial_\beta g_{\alpha\rho} + \partial_\alpha g_{\rho\beta} - \partial_\rho g_{\alpha\beta})$$

Now since  $\partial_\gamma (\delta^\alpha_\beta) = 0$  (since it's constant tensor) we can conclude that

$$\begin{aligned} \Gamma^\lambda_{\beta\alpha} g_{\lambda\sigma} &= \frac{1}{2} \left\{ \partial_\beta (\underbrace{\delta^\rho_\sigma}_{\text{by contraction}} g_{\alpha\rho}) + \partial_\alpha (\underbrace{\delta^\rho_\sigma}_{\text{by contraction}} g_{\rho\beta}) \right. \\ &\quad \left. - \underbrace{\delta^\rho_\sigma}_{\partial_\sigma} \partial_\rho (g_{\alpha\beta}) \right\} \\ &= \frac{1}{2} (\partial_\beta g_{\alpha\sigma} + \partial_\alpha g_{\sigma\beta} - \partial_\sigma g_{\alpha\beta}) \end{aligned}$$

Now  $\Gamma^\lambda_{\rho\sigma} g_{\alpha\lambda}$  is likewise (just  $\alpha \leftrightarrow \sigma$  exchange is necessary.)

$$\Gamma^\lambda_{\rho\sigma} g_{\alpha\lambda} = \frac{1}{2} (\partial_\rho g_{\sigma\alpha} + \partial_\sigma g_{\alpha\rho} - \partial_\alpha g_{\rho\sigma})$$

Adding them all results:

$$\nabla_\beta g_{\alpha\sigma} = \partial_\beta g_{\alpha\sigma}$$

$$\begin{aligned} & - \frac{1}{2} (\underbrace{\partial_\beta g_{\alpha\sigma}}_{(3)} + \underbrace{\partial_\alpha g_{\sigma\beta}}_{(1)} - \underbrace{\partial_\sigma g_{\alpha\beta}}_{(2)}) \\ & - \frac{1}{2} (\underbrace{\partial_\rho g_{\sigma\alpha}}_{(3)} + \underbrace{\partial_\sigma g_{\alpha\rho}}_{(2)} - \underbrace{\partial_\alpha g_{\rho\sigma}}_{(1)}) \end{aligned}$$

① since  $g_{\beta\sigma} = g_{\sigma\beta}$ , these terms cancel.

② similarly for these terms.

③ they add up to  $\partial_\beta g_{\alpha\sigma}$  which exactly  
cancels the first line  $\Rightarrow$

$$\nabla_\beta g_{\alpha\sigma} = 0 \quad \square$$

Q2. By transformation rules of vectors in  $T_p M$  and  $T_p^* M$  (according to Carroll's convention.)

$$e_\nu \longrightarrow e'_\nu = \frac{\partial x^\lambda}{\partial x'^\nu} e_\lambda$$

$$e^r \longrightarrow e'^r = \frac{\partial x'^r}{\partial x^p} e^p$$

$$\Gamma'^r_{\nu\sigma} = e'^r \cdot \frac{\partial}{\partial x'^\sigma} e'_\nu \longrightarrow ?$$

plug those relations into def of  $\Gamma$  - in terms of einbein (or tetrad):

$$\begin{aligned} & \left( \frac{\partial x'^r}{\partial x^p} e^p \right) \left( \frac{\partial}{\partial x'^\sigma} \right) \left( \frac{\partial x^\lambda}{\partial x'^\nu} e_\lambda \right) \\ &= \frac{\partial x'^r}{\partial x^p} e^p \left( \frac{\partial^2 x^\lambda}{\partial x'^\sigma \partial x'^\nu} e_\lambda + \underbrace{\frac{\partial e_\lambda}{\partial x'^\sigma}}_{\text{chain rule}} \times \frac{\partial x^\lambda}{\partial x'^\nu} \right) \\ &= \frac{\partial x'^r}{\partial x^p} e^p \left( \frac{\partial^2 x^\lambda}{\partial x'^\sigma \partial x'^\nu} e_\lambda + \frac{\partial x^\xi}{\partial x'^\sigma} \frac{\partial e_\lambda}{\partial x^\xi} \frac{\partial x^\lambda}{\partial x'^\nu} \right) \end{aligned}$$

$$\begin{aligned}
&= \frac{\partial x'^r}{\partial x^\rho} \frac{\partial x^\xi}{\partial x'^\sigma} \frac{\partial x^\lambda}{\partial x'^\nu} (e^\rho \partial_\xi e^\lambda) \\
&\quad \underbrace{\hspace{10em}}_{\text{This is } \Gamma_{\xi\lambda}^\rho} \\
&+ \frac{\partial x'^r}{\partial x^\rho} \frac{\partial^2 x^\lambda}{\partial x'^\sigma \partial x'^\nu} e^\rho e_\lambda
\end{aligned}$$

As you see the first term is the tensorial transformation of  $\Gamma_{\nu\sigma}^\rho$ , while the second part is the excessive part that doesn't vanish necessarily and prohibits  $\Gamma$  from being a tensor.

only for linear transformation when  $\frac{\partial^2 x^\lambda}{\partial x'^\sigma \partial x'^\nu} = 0$

$\Gamma$  is a tensor (since linear transformation

correspond to Poincaré group, so  $\Gamma$  is tensor

under Poincaré transformation.)  $\otimes$

Q3. Consider  $\begin{cases} x = u + v \\ y = u - v \\ z = 2uv - w \end{cases}$  in 3D flat space ( $\mathbb{R}^3$ ).

In usual Cartesian Coordinates, tangent vectors are  $\partial_x, \partial_y, \partial_z$ . By chain rule:

$$\partial_u = \frac{\partial}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial}{\partial y} \frac{\partial y}{\partial u} + \frac{\partial}{\partial z} \frac{\partial z}{\partial u}$$

$$\text{so } \frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{matrix} & \begin{matrix} x \downarrow & y \downarrow & z \downarrow \end{matrix} \\ \begin{matrix} u \\ v \\ w \end{matrix} & \begin{bmatrix} 1 & 1 & 2v \\ 1 & -1 & 2u \\ 0 & 0 & -1 \end{bmatrix} \end{matrix}$$

$$\Rightarrow \begin{cases} \partial_u = \partial_x + \partial_y + 2v \partial_z \\ \partial_v = \partial_x - \partial_y + 2u \partial_z \\ \partial_w = -\partial_z \end{cases}$$

Inverse transformation  $\begin{cases} u = \frac{1}{2}(x+y) \\ v = \frac{1}{2}(x-y) \end{cases}$

$$\Rightarrow \begin{cases} \partial u = \partial x + \partial y + (x-y) \partial z \\ \partial v = \partial x - \partial y + (x+y) \partial z \\ \partial w = -\partial z \end{cases}$$

Replace  $(\partial u, \partial v, \partial w)$  by  $(e_u, e_v, e_w)$   
and  $(\partial x, \partial y, \partial z)$  by  $(e_x, e_y, e_z)$   
to find the relation in the question's  
convention.

For dual basis :

$$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy + \frac{\partial u}{\partial z} dz$$

so we need inverse transformations ,

$$\text{As we saw } \begin{cases} u = \frac{1}{2}(x+y) \\ v = \frac{1}{2}(x-y) \end{cases}$$

$$\text{And } z = 2uv - w \Rightarrow$$

$$w = 2 \times \frac{1}{4} (x-y)(x+y) - z$$

$$\Rightarrow w(x, y, z) = \frac{1}{2}(x^2 - y^2) - z$$

$$\text{so } \frac{\partial(u,v,w)}{\partial(x,y,z)} = \begin{matrix} & \begin{matrix} u \downarrow & v \downarrow & w \downarrow \\ & & = u+v \end{matrix} \\ \begin{matrix} x \rightarrow \\ y \rightarrow \\ z \rightarrow \end{matrix} & \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & x \\ \frac{1}{2} & -\frac{1}{2} & -y \\ 0 & 0 & -1 \end{bmatrix} \end{matrix}$$

(v-u)

$$\Rightarrow \begin{cases} du = \frac{1}{2} (dx + dy) \\ dv = \frac{1}{2} (dx - dy) \\ dw = x dx - y dy - dz \end{cases}$$

you can check that  $du^\alpha (\partial_\beta) = \delta^\alpha_\beta$ .

when  $\alpha, \beta$  are in  $\{u, v, w\}$ , so the vectors & forms are normalized :).



Q4. use  $\Gamma^\beta_{\alpha\gamma} = \frac{1}{2} g^{\beta\alpha} (g_{\alpha\gamma, \nu} + g_{\alpha\nu, \gamma} - g_{\gamma\nu, \alpha})$

let's look at  $\Gamma^\theta_{ij} = \frac{1}{2} g^{\theta\alpha} (g_{\alpha i, j} + g_{\alpha j, i} - \partial_\alpha g_{ij})$

since the metric is diagonal  $\Rightarrow \alpha = \theta$

and since none of metric's components depend on  $\phi$  explicitly, the calculation is very easy!

$$\Gamma^\theta_{ij} = \frac{1}{2} \times \frac{g^{\theta\theta}}{1} \begin{cases} i=j=\theta \rightarrow \text{zero since all derivatives of } g_{\theta\theta}=1 \text{ vanish.} \\ i=j=\phi \rightarrow \text{just } -\partial_\theta g_{\phi\phi} = -2 \sin\theta \cos\theta \text{ survives} \\ i=\theta, j=\phi \rightarrow \text{zero since metric is diagonal and } \partial_\phi g_{\theta\theta} = 0 \text{ or vice versa} \end{cases}$$

$$(\Gamma^\theta)_{ij} = \begin{matrix} & \theta & \phi \\ \begin{matrix} \theta \\ \phi \end{matrix} & \begin{pmatrix} 0 & 0 \\ 0 & -\sin\theta \cos\theta \end{pmatrix} \end{matrix}$$

For  $\Gamma^\phi_{ij}$ , since  $g^{\phi\phi} = \frac{1}{\sin^2\theta}$

$$\Gamma^\phi_{ij} = \frac{1}{2} g^{\phi\alpha} (g_{\alpha i,j} + g_{\alpha j,i} - g_{ij,\alpha})$$

$$\Gamma^\phi_{ij} = \frac{1}{2} \sin^2 \theta \begin{cases} i=j=\theta \rightarrow \text{all terms vanish} \\ i=j=\phi \rightarrow \text{since all derivatives are w.r.t } \phi, \text{ they vanish.} \\ i=\theta, j=\phi \text{ or vice versa} \rightarrow \text{just } \partial_\theta g_{\phi\phi} = 2 \sin \theta \cos \theta \end{cases}$$

contributes

$$(\Gamma^\phi)_{ij} = \begin{matrix} & \theta & \phi \\ \theta & 0 & \cos \theta \\ \phi & \cos \theta & 0 \end{matrix}$$

$$\text{Geodesic eq : } \frac{d^2 x^r}{d\lambda^2} + \Gamma^r_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda} = 0$$

$$\text{Along } \theta \Rightarrow \frac{d^2 x^\theta}{d\lambda^2} - \sin \theta \cos \theta \left( \frac{dx^\phi}{d\lambda} \right)^2 = 0$$

$$\text{" } \phi \rightarrow \frac{d^2 x^\phi}{d\lambda^2} + 2 \cos \theta \frac{dx^\theta}{d\lambda} \frac{dx^\phi}{d\lambda} = 0$$

Notice that  $X^r = (X^\theta(\lambda), X^\phi(\lambda))$  are geodesics on the  $S^2$ -sphere.

(b) so simple!  $ds^2 = d\theta^2 + \sin^2 \theta d\phi^2$

$$S = \int_{\lambda_0}^{\lambda_1} d\lambda \left( \left( \frac{d\theta(\lambda)}{d\lambda} \right)^2 + \sin^2 \theta \left( \frac{d\phi(\lambda)}{d\lambda} \right)^2 \right)^{1/2}$$

when  $x'(\lambda) = (\theta(\lambda), \phi(\lambda))$  is a curve parametrized by  $\lambda \in (\lambda_0, \lambda_1)$ .

To extremize the length, we vary  $\theta(\lambda), \phi(\lambda)$  by

$$\begin{cases} \theta(\lambda) \rightarrow \theta(\lambda) + \delta\theta(\lambda) \\ \phi(\lambda) \rightarrow \phi(\lambda) + \delta\phi(\lambda) \end{cases} \quad \text{with} \quad \begin{cases} \delta\theta(\lambda)|_{\lambda_0, \lambda_1} = 0 \\ \delta\phi(\lambda)|_{\lambda_0, \lambda_1} = 0 \end{cases}$$

when at the end, the geodesic path results

from usual Euler-Lagrange equations.

$$\frac{d}{d\lambda} \frac{\partial \mathcal{L}}{\partial \left( \frac{d}{d\lambda} \begin{smallmatrix} \theta \\ \phi \end{smallmatrix} \right)} = \frac{\partial \mathcal{L}}{\partial \begin{smallmatrix} \theta \\ \phi \end{smallmatrix}} \quad \text{for both } \theta, \phi \text{ components.}$$

I elaborate  
on the  
reason  
why  
not  
taking  
its

$\left( \left( \frac{d\theta}{d\lambda} \right)^2 + \sin^2 \theta \left( \frac{d\phi}{d\lambda} \right)^2 \right)$  is like the Lagrangian,

and  $\lambda$  parameter is like time. So the situation

is quite similar to Classical Mechanics.

Square root into constant later at the end of this exercise.

$$\frac{d}{d\lambda} \frac{\partial L}{\partial \left(\frac{d}{d\lambda} \theta\right)} = \frac{d}{d\lambda} \left( 2 \frac{d\theta}{d\lambda} \right) = 2 \frac{d^2 \theta}{d\lambda^2}$$

$$\frac{\partial L}{\partial \theta} = 2 \sin \theta \cos \theta \left( \frac{d\phi}{d\lambda} \right)^2$$

$$\Rightarrow \frac{d^2 \theta(\lambda)}{d\lambda^2} - \sin \theta \cos \theta \left( \frac{d\phi(\lambda)}{d\lambda} \right)^2 = 0 \quad \square$$

For  $\phi$ -component of E-L equation:

$$\frac{d}{d\lambda} \frac{\partial L}{\partial \left(\frac{d}{d\lambda} \phi\right)} = 2 \frac{d}{d\lambda} \left( \sin^2 \theta \left( \frac{d\phi}{d\lambda} \right) \right)$$

since  $\frac{d}{d\lambda}$  is total derivative we have to be

CAREFUL, using chain rule:

$$\frac{d}{d\lambda} = \frac{\partial}{\partial \theta} \frac{d\theta}{d\lambda} + \frac{\partial}{\partial \phi} \frac{d\phi}{d\lambda}$$

$$\text{so } \frac{d}{d\lambda} \left( \frac{\partial L}{\partial \left(\frac{d\phi}{d\lambda}\right)} \right) = 2 \left( \frac{d}{d\lambda} \sin^2 \theta \right) \frac{d\phi}{d\lambda} +$$

$$2 \sin^2 \theta \frac{d^2 \phi}{d\lambda^2}$$

$$\text{when } \frac{d}{d\lambda} \sin^2 \theta = \frac{d\theta}{d\lambda} \frac{\partial}{\partial \theta} (\sin^2 \theta) + \cancel{\frac{d\phi}{d\lambda} \frac{\partial}{\partial \phi} (\sin^2 \theta)}$$

$$= 2 \sin \theta \cos \theta \times \frac{d\theta}{d\lambda}$$

$$\Rightarrow \frac{d}{d\lambda} \left( \frac{\partial L}{\partial \left( \frac{d\phi}{d\lambda} \right)} \right) = (4 \sin \theta \cos \theta) \frac{d\phi}{d\lambda} \frac{d\theta}{d\lambda} + 2 \sin^2 \theta \frac{d^2 \phi}{d\lambda^2}$$

And  $\frac{\partial L}{\partial \phi}$  also vanishes, therefore

$$4 \sin \theta \cos \theta \frac{d\phi}{d\lambda} \frac{d\theta}{d\lambda} + 2 \sin^2 \theta \frac{d^2 \phi}{d\lambda^2} = 0$$

Divide by  $2 \sin^2 \theta$  to get:

$$\frac{d^2 \phi}{d\lambda^2} + 2 \cot \theta \frac{d\phi}{d\lambda} \frac{d\theta}{d\lambda} = 0$$

Note: Lagrange was  $L = \left( \left( \frac{d\theta}{d\lambda} \right)^2 + \sin^2 \theta \left( \frac{d\phi}{d\lambda} \right)^2 \right)^{1/2}$

actually, but since zeros of  $\delta\sqrt{\#}$  are  
equal to zeros of  $\frac{\delta\#}{2\sqrt{\#}}$  so we doesn't

need to carry square root with surchs!