

Spin1 build and installation Manual

Ok, you have the bare PCB, so this is what you need to do:

1. Get the BOM from **site**, its in csv format, so you can select what modules you want populated.

A few things to note:

- EGT circuit won't work, it has a 500°C limit.
- The usb connector is plain wrong. In the BOM you can choose to buy a cable to use this wrong (female-A) connector, or buy another usb connector and hack things to install it.
- You don't want the shutdown circuit, so its FETs aren't in the BOM. Don't worry about that.
- Don't populate all the injector drivers if you're not going to use them
- Thermistor circuits have pulldowns not suited for most of the sensors, and the bias resistor should be matched to the specific sensor you have.

Once you are decided about the BOM, go to digikey and place the order.

2. Cut the wrong traces:

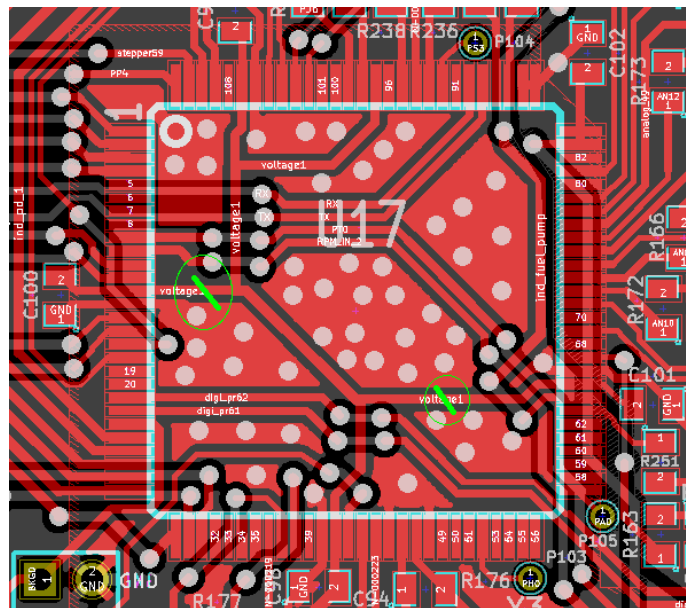
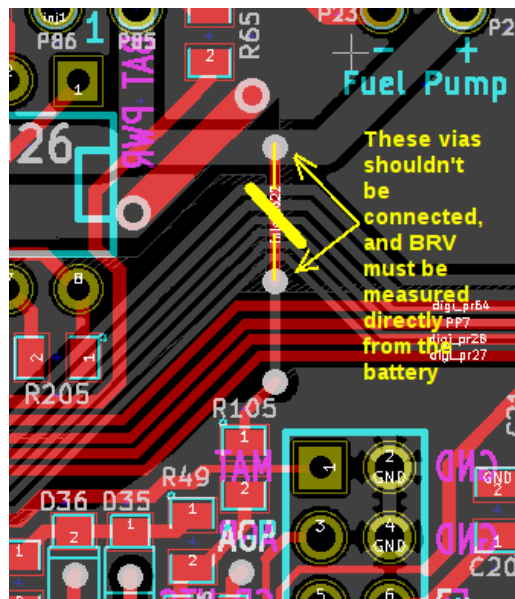
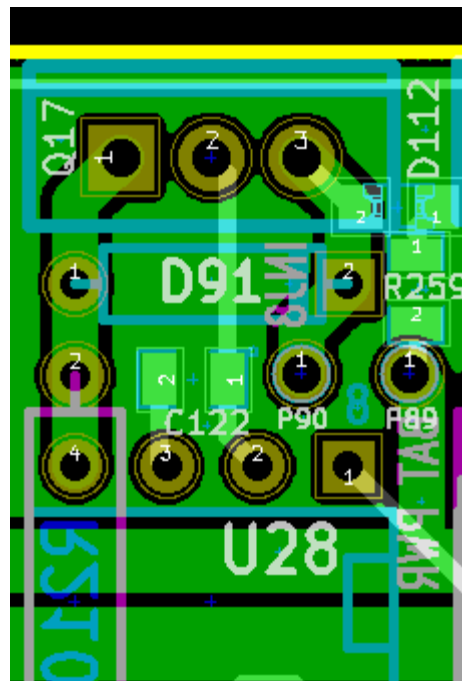
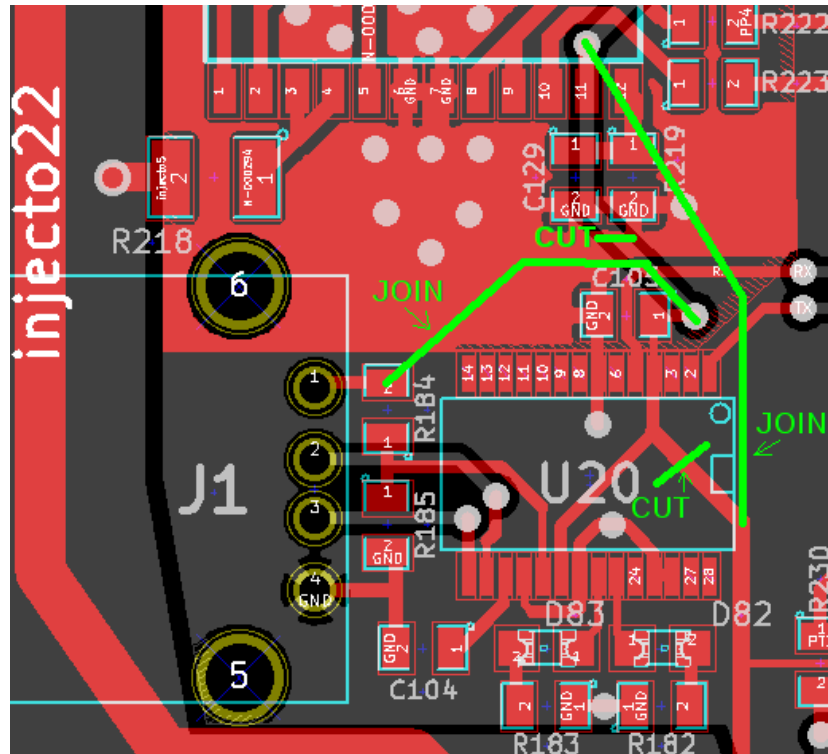


Illustration 1: There are wrong MCU VDD traces





3. You have the PCB + components, so get kicad and the files, or the pdf files from puma.freeems.org. PDFs aren't searchable so you may want to choose to install kicad until we workout that.

4. Start the assembly!

Just solder the components. If you ordered a board, you should know how to do it. An oven is a fast way to get it done.

Don't put too much paste for the small regulator, or it will get misaligned.

Components that shouldn't be populated:

- F1, F3 (Fuses)
- R226, R227, Q18, Q19, bridge pin 1 and 3 of Q19 (this is the shutdown circuit)
- R133 (bad pullup)
- R228 **OR** R229, using one of them defines whether the XOR negates or not its outputs.
- If you use VR inputs, R212, R213, R215, and R216 should be bigger, like $\frac{1}{4}$ or $\frac{1}{2}W$. 10Kohm to 20 kohm will be fine.
- U18, R186, R187, C107, D74, D75, C106 (thermocouple driver)
- D24 and D26 zeners aren't necessary, and there is a change the mess with the RPM input circuits.

Notes:

- To start correctly, MCU start must be delayed. In this spin it is done with a capacitor in the bdm header (2.2uF and 10uF worked consistently so far).
- If you are a hardcore developer, you might want to connect a switch in the load/run header.

5. Program the MCU using a BDM pod.

Install Codewarrior, open the programmer, go to File-> Load application, and select the .s12 (FreeEMS serial monitor). You have to bridge the load/run header in the board.

It should get connected, program it, verify, and never complain.

6. Load FreeEMS firmware, using seank's loader.

7. Install MTX and connect to the board to the PC to check that freeems is running.

8. Installation!

There are many things to consider:

- You can connect the power grounds from this places
- And the digital ground here
- And your sensors should get their grounds from here

The pinout in the board is the following (Fred's pinout)