Problem

We consider the transient heat equation in a two-dimensional (2D) unit square $\Omega := (0,1) \times (0,1)$. The boundary of the domain Γ can be decomposed into

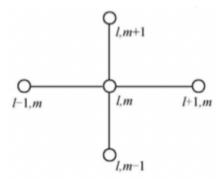
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the bottom face \Gamma_b := \{(x,y) : x \in (0,1), y = 0\};
the top face \Gamma_t := \{(x,y) : x \in (0,1), y = 1\};
the left face \Gamma_l := \{(x,y) : x = 0, y \in (0,1)\};
the right face \Gamma_r := \{(x,y) : x = 1, y \in (0,1)\}.
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Let f be the heat supply per unit volume, u be the temperature, ρ be the density, c be the heat capacity, u_0 be the initial temperature, κ be the conductivity, n_x and n_y be the Cartesian components of the unit outward normal vector. The boundary data involves the prescribed temperature g on Γ_g and heat flux h on Γ_h . The boundary Γ admits a non-overlapping decomposition: $\Gamma = \overline{\Gamma_g \cup \Gamma_h}$ and $\emptyset = \Gamma_g \cap \Gamma_h$. The transient heat equation may be stated as follows.

$$\begin{split} \rho c \frac{\partial u}{\partial t} - \kappa \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) &= f &\quad \text{on } \Omega \times (0,T) \\ u &= g &\quad \text{on } \Gamma_g \times (0,T) \\ \kappa \frac{\partial u}{\partial x} n_x + \kappa \frac{\partial u}{\partial y} n_y &= h &\quad \text{on } \Gamma_h \times (0,T) \\ u|_{t=0} &= u_0 &\quad \text{in } \Omega. \end{split}$$

Solutions

We learned the solution methods from the videos on bilibili and the books from class MAE5032-HPC by Ju-LIU



 $\boldsymbol{u}_{l,m}^{t}$ is denoted as temperature u in node l,m at time t.

(1) For each internal node, the $u_{l,m}^{t+1}$ should be depended on five data at time t (i.e., $u_{l,m}^t$, u_{l-1}^t , u_{l-1}^t , $u_{l,m-1}^t$, $u_{l,m-1}^t$) spatially and temporally.

The basic equation should be

$$\rho c \Delta x \Delta y (u_{l,m}^{t+1} - u_{l,m}^t) = \kappa ((\frac{\partial u}{\partial x})_{l+1,m}^{t \to t+1} - (\frac{\partial u}{\partial x})_{l-1,m}^{t \to t+1}) \Delta y \Delta t + \kappa ((\frac{\partial u}{\partial y})_{l,m+1}^{t \to t+1} - (\frac{\partial u}{\partial y})_{l,m-1}^{t \to t+1}) \Delta x \Delta t$$

In explicit format, the relationship can be decribed by the following.

$$\frac{\rho c \Delta x \Delta y}{\Delta t} (u_{l,m}^{t+1} - u_{l,m}^t) = \kappa (\frac{u_{l+1,m}^t - u_{l,m}^t}{\delta x_{l+1}} - \frac{u_{l,m}^t - u_{l-1,m}^t}{\delta x_{l-1}}) \Delta y + \kappa (\frac{u_{l,m+1}^t - u_{l,m}^t}{\delta y_{m+1}} - \frac{u_{l,m}^t - u_{l,m-1}^t}{\delta y_{m+1}}) \Delta x$$

$$a_{l,m}^{t+1} u_{l,m}^{t+1} = a_{l+1,m}^t u_{l+1,m}^t + a_{l-1,m}^t u_{l-1,m}^t + a_{l,m+1}^t u_{l,m+1}^t + a_{l,m-1}^t u_{l,m-1}^t + a_{l,m}^t u_{l,m}^t$$

where

$$\begin{split} a_{l+1,m}^t &= \frac{\kappa \Delta y}{\delta x_{l+1}} = \frac{\kappa \Delta y}{\Delta x} = a_{l-1,m}^t = \frac{\kappa \Delta y}{\delta x_{l-1}} \\ a_{l,m+1}^t &= \frac{\kappa \Delta x}{\delta y_{m+1}} = \frac{\kappa \Delta x}{\Delta y} = a_{l,m-1}^t = \frac{\kappa \Delta x}{\delta y_{m-1}} \\ a_{l,m}^t &= \frac{\rho c \Delta x \Delta y}{\Delta t} - \frac{\kappa \Delta y}{\delta x_{l+1}} - \frac{\kappa \Delta y}{\delta x_{l-1}} - \frac{\kappa \Delta x}{\delta y_{m+1}} - \frac{\kappa \Delta x}{\delta y_{m-1}} \\ &= \frac{\rho c \Delta x \Delta y}{\Delta t} - 2 \frac{\kappa \Delta y}{\Delta x} - 2 \frac{\kappa \Delta x}{\Delta y} \\ a_{l,m}^{t+1} &= \frac{\rho c \Delta x \Delta y}{\Delta t} = 2 a_{l+1,m}^t + 2 a_{l,m+1}^t + a_{l,m}^t \end{split}$$

Note that δ is actually the same as Δ for internal nodes.

In implicit format, the relationship can be decribed by the following.

$$\frac{\rho c \Delta x \Delta y}{\Delta t} (u_{l,m}^{t+1} - u_{l,m}^{t}) = \kappa (\frac{u_{l+1,m}^{t+1} - u_{l,m}^{t+1}}{\delta x_{l+1}} - \frac{u_{l,m}^{t+1} - u_{l-1,m}^{t+1}}{\delta x_{l-1}}) \Delta y + \kappa (\frac{u_{l,m+1}^{t+1} - u_{l,m}^{t+1}}{\delta y_{m+1}} - \frac{u_{l,m}^{t+1} - u_{l,m-1}^{t+1}}{\delta x_{m-1}}) \Delta x$$

$$a_{l,m}^{t+1} u_{l,m}^{t+1} - a_{l+1,m}^{t+1} u_{l+1,m}^{t+1} - a_{l-1,m}^{t+1} u_{l-1,m}^{t+1} - a_{l,m+1}^{t+1} u_{l,m+1}^{t+1} - a_{l,m-1}^{t+1} u_{l,m-1}^{t+1} = a_{l,m}^{t} u_{l,m}^{t}$$

where

$$\begin{split} a_{l+1,m}^{t+1} &= \frac{\kappa \Delta y}{\delta x_{l+1}} = \frac{\kappa \Delta y}{\Delta x} \\ a_{l-1,m}^{t+1} &= \frac{\kappa \Delta y}{\delta x_{l-1}} = \frac{\kappa \Delta y}{\Delta x} \\ a_{l,m+1}^{t+1} &= \frac{\kappa \Delta x}{\delta y_{m+1}} = \frac{\kappa \Delta x}{\Delta y} \\ a_{l,m-1}^{t+1} &= \frac{\kappa \Delta x}{\delta y_{m-1}} = \frac{\kappa \Delta x}{\Delta y} \\ a_{l,m-1}^{t+1} &= \frac{\kappa \Delta x}{\delta y_{m-1}} = \frac{\kappa \Delta x}{\Delta y} \\ a_{l,m}^{t} &= \frac{\rho c \Delta x \Delta y}{\Delta t} \\ a_{l,m}^{t+1} &= a_{l+1,m}^{t+1} + a_{l-1,m}^{t+1} + a_{l,m+1}^{t+1} + a_{l,m-1}^{t} + a_{l,m-1}^{t} \end{split}$$

(2) Considering the boundary condition

When $l,m\in \Gamma$, data are given that u=g or $\kappa rac{\partial u}{\partial x}n_x+\kappa rac{\partial u}{\partial y}n_y=h.$

Starting from only considering h from the left and down sides, the basic equation can be decribed as the following.

$$\rho c \Delta x \Delta y (u_{l,m}^{t+1} - u_{l,m}^t) = (\kappa (\frac{\partial u}{\partial x})_{l+1,m}^{t \to t+1} + h_{l-1,m}^{t \to t+1}) \Delta y \Delta t + (\kappa (\frac{\partial u}{\partial y})_{l,m+1}^{t \to t+1} + h_{l,m-1}^{t \to t+1}) \Delta x \Delta t$$

In explicit format,

$$\begin{split} \rho c \Delta x \Delta y (u_{l,m}^{t+1} - u_{l,m}^t) &= \kappa (\frac{u_{l+1,m}^t - u_{l,m}^t}{\delta x_{l+1}} + h_{l-1,m}^t) \Delta y \Delta t + \kappa (\frac{u_{l,m+1}^t - u_{l,m}^t}{\delta y_{m+1}} + h_{l,m-1}^t) \Delta x \Delta t \\ \frac{\rho c \Delta x \Delta y (u_{l,m}^{t+1} - u_{l,m}^t)}{\Delta t} &= \kappa (\frac{u_{l+1,m}^t - u_{l,m}^t}{\delta x_{l+1}} + h_{l-1,m}^t) \Delta y + \kappa (\frac{u_{l,m+1}^t - u_{l,m}^t}{\delta y_{m+1}} + h_{l,m-1}^t) \Delta x \\ a_{l,m}^{t+1} u_{l,m}^{t+1} &= a_{l+1,m}^t u_{l+1,m}^t + \kappa h_{l-1,m}^t \Delta y + a_{l,m+1}^t u_{l,m+1}^t + \kappa h_{l,m-1}^t \Delta x + a_{l,m}^t u_{l,m}^t \end{split}$$

We described this in general format.

$$\begin{aligned} a_{l,m}^{t+1}u_{l,m}^{t+1} &= a_{l+1,m}^{t}u_{l+1,m}^{t} + a_{l-1,m}^{t}u_{l-1,m}^{t} + a_{l,m+1}^{t}u_{l,m+1}^{t} + a_{l,m-1}^{t}u_{l,m-1}^{t} \\ &+ \kappa h_{l+1,m}^{t}\Delta y + \kappa h_{l-1,m}^{t}\Delta y + \kappa h_{l,m+1}^{t}\Delta x + \kappa h_{l,m-1}^{t}\Delta x + a_{l,m}^{t}u_{l,m}^{t} \end{aligned}$$

In implicit format, similarly we get that

$$\begin{aligned} a_{l,m}^{t+1}u_{l,m}^{t+1} &= a_{l+1,m}^{t+1}u_{l+1,m}^{t+1} + a_{l-1,m}^{t+1}u_{l-1,m}^{t+1} + a_{l,m+1}^{t+1}u_{l,m+1}^{t+1} + a_{l,m-1}^{t+1}u_{l,m-1}^{t+1} \\ &+ \kappa h_{l+1,m}^{t+1}\Delta y + \kappa h_{l-1,m}^{t+1}\Delta y + \kappa h_{l,m+1}^{t+1}\Delta x + \kappa h_{l,m-1}^{t+1}\Delta x + a_{l,m}^{t}u_{l,m}^{t} \end{aligned}$$

(a) If prescribed u=g for the boundary nodes in Ω

$$h_{l+1,m} = h_{l-1,m} = h_{l,m+1} = h_{l,m-1} = 0;$$

when
$$l + \Delta x = 1$$
, $u_{l+1,m} = g$;

when
$$l - \Delta x = 0$$
, $u_{l-1} = q$;

when
$$m+\Delta y=0$$
, $u_{l,m+1}=g$;

when
$$m-\Delta y=0$$
, $u_{l,m-1}=g$

(b) If prescribed $\kappa rac{\partial u}{\partial x} n_x + \kappa rac{\partial u}{\partial y} n_y = h$ for the boundary nodes in Ω

when
$$l+1=1$$
 , $h_{l+1,m}=-h$ and $a_{l+1,m}=h_{l-1,m}=h_{l,m+1}=h_{l,m-1}=0$;

when
$$l-1=0$$
 , $h_{l-1,m}=h$ and $a_{l-1,m}=h_{l+1,m}=h_{l,m+1}=h_{l,m-1}=0$;

when
$$m+1=1$$
, $h_{l,m+1}=-h$ and $a_{l,m+1}=h_{l+1,m}=h_{l-1,m}=h_{l,m-1}=0$;

when
$$m-1=0$$
, $h_{l,m-1}=h$ and $a_{l,m-1}=h_{l+1,m}=h_{l-1,m}=h_{l,m+1}=0$.

Targets (Course Video 15)

编写程序

□ 程序可以重启(需要hfd5来帮我们)
□ 防御性写法,能处理异常,有断言,有详细的注释
□ 编译的时候不能有任何warning
□ 有makfile或者cmake,可以在太乙上直接编译
□ 有profiling,程序的哪里耗时最多
□ 利用github进行版本控制和团队合作
□ 用开源软件可视化,二维的话需要用VTK或者Paraview
□ 技术性的报告,最好包括LaTex的使用
测试
□ 方法的稳定性
□ 误差分析
□ 并行效率(强可扩展性、弱可扩展性、Petsc不同求解器的影响)