Xilinx Zynq FPGA, TI DSP, MCU 기반의 프로그래밍 및 회로 설계 전문가 과정

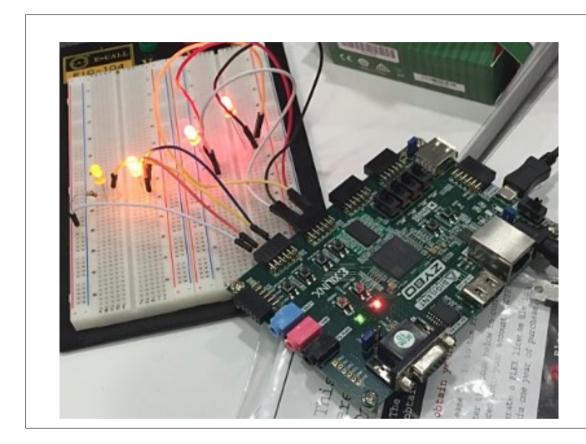
강사 – Innova Lee(이상훈)

gcccompil3r@gmail.com

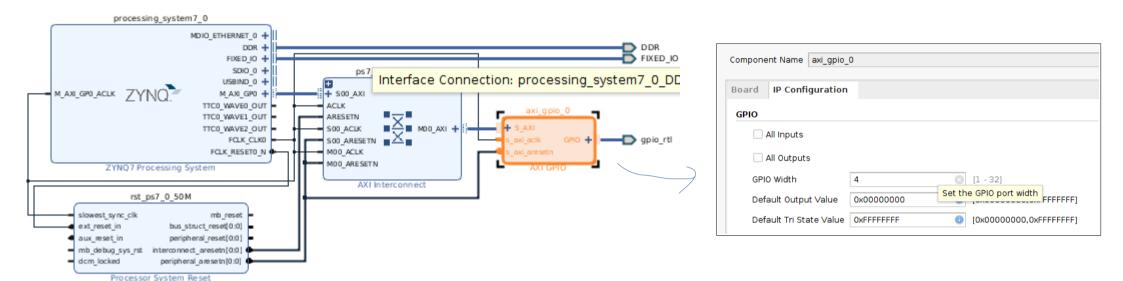
학생 – hoseong Lee(이호성)

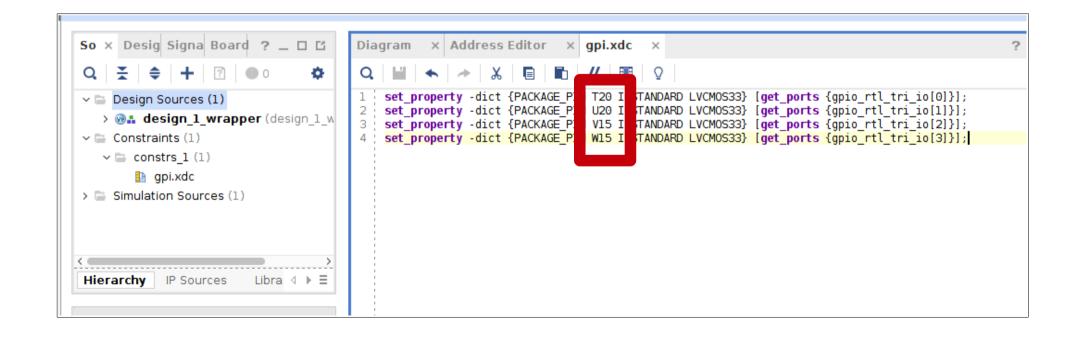
hslee00001@naver.com

1. FPGA, led 실습

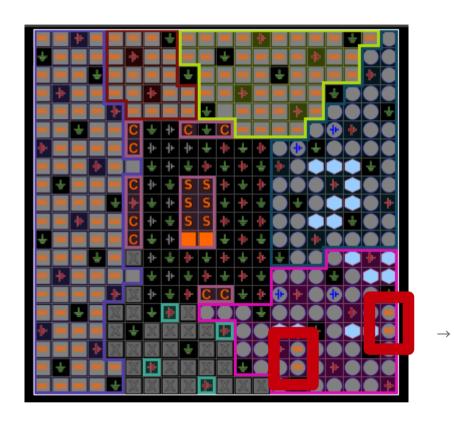


- shift 3

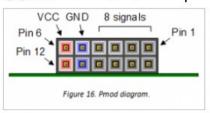




↓ Generate Bitstream

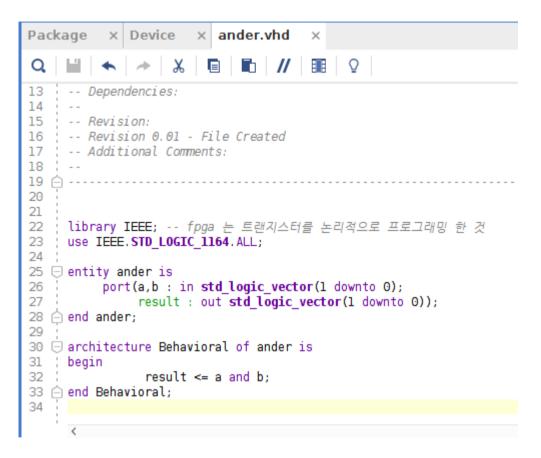


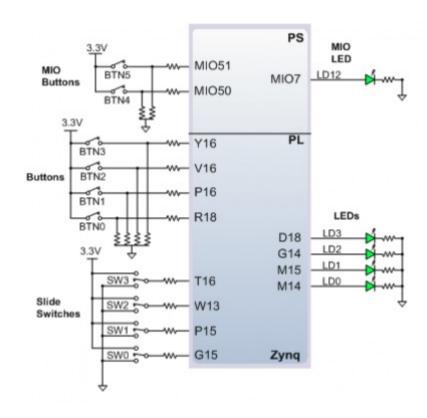
gpio 16 개의 포트



Pmod JA (XADC)	<u>Pmod JB</u> (고 속)	Pmod JC (고 속)	Pmod JD (고 속)	Pmod JE (고 속)	Pmod JF (MIO)	
JA1: N15	JB1: T20	JC1: V15	JD1: T14	JE1: V12	JF1 : MIO-13	
JA2 : L14	JB2 : U20	JC2: W15	JD2: T15	JE2: W16	JF2 : MIO-10	
JA3: K16	JB3: V20	JC3 : T11	JD3: P14	JE3: J15	JF3 : MIO-11	
JA4 : K14	JB4: W20	JC4: T10	JD4 : R14	JE4: H15	JF4 : MIQ-12	
JA7: N16	JB7: Y18	JC7: W14	JD7 : U14	JE7: V13	JF7 : MIO-0	
JA8: L15	JB8: Y19	JC8: Y14	JD8: U15	JE8 : U17	JF8 : MIO-9	
JA9 : J16	JB9: W18	JC9: T12	JD9: V17	JE9: T17	JF9 : MIO-14	
JA10: J14	JB10: W19	JC10: U12	JD10: V18	JE10: Y17	JF10 : MIO- 15	

```
#include <stdio.h>
 #include <xgpio.h>
 #include "xparameters.h"
 #include "sleep.h"
int main(void)
     int i=2;
     XGpio out;
     XGpio_Initialize(&out, XPAR_AXI_GPIO_0_DEVICE_ID);
     XGpio_SetDataDirection(&out,1,0x0);
     while(1)
         Xil_Out32(0x41200000, i);
         i= i<<1;
         if(i==16)
            i=1;
         sleep(1);
     return 0;
```





Name	Direction	Neg Diff Pair	Package Pi	n Fixed	Bank	I/O Std		Vcco	Vref	Drive Strength	Slew Type	Pull Type	Off-Chip
4 (2)	IN			✓	(Multiple)	LVCM0S33*	*	3.300				NONE ~	NONE
№ a[1]	IN		W13 -	/ /	34	LVCM0S33*	*	3.300				NONE ~	NONE
a[0]	IN		G15 ·	/	35	LVCM0S33*	*	3.300				NONE ~	NONE
🗸 👺 b (2)	IN			✓	34	LVCM0S33*	*	3.300				NONE ~	NONE
b[1]	IN		T16	/	34	LVCM0S33*	*	3.300				NONE ~	NONE
b[0]	IN		P15	/	34	LVCM0S33*	*	3.300				NONE ~	NONE
v 🔞 result (2)	OUT			✓	35	LVCM0S33*	*	3.300		12 🔻	SLOW ▼	NONE ~	FP_VTT_
√ result[1]	OUT		M15	/	35	LVCM0S33*	*	3.300		12 🔻	SLOW ▼	NONE ~	FP_VTT_
√ result[0]	OUT		M14	/	35	LVCM0S33*	*	3.300		12 🔻	SLOW ▼	NONE ~	FP_VTT_