

**TI DSP, MCU 및 Xilinx Zynq
FPGA
프로그래밍 전문가 과정**

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학생 – 문한나

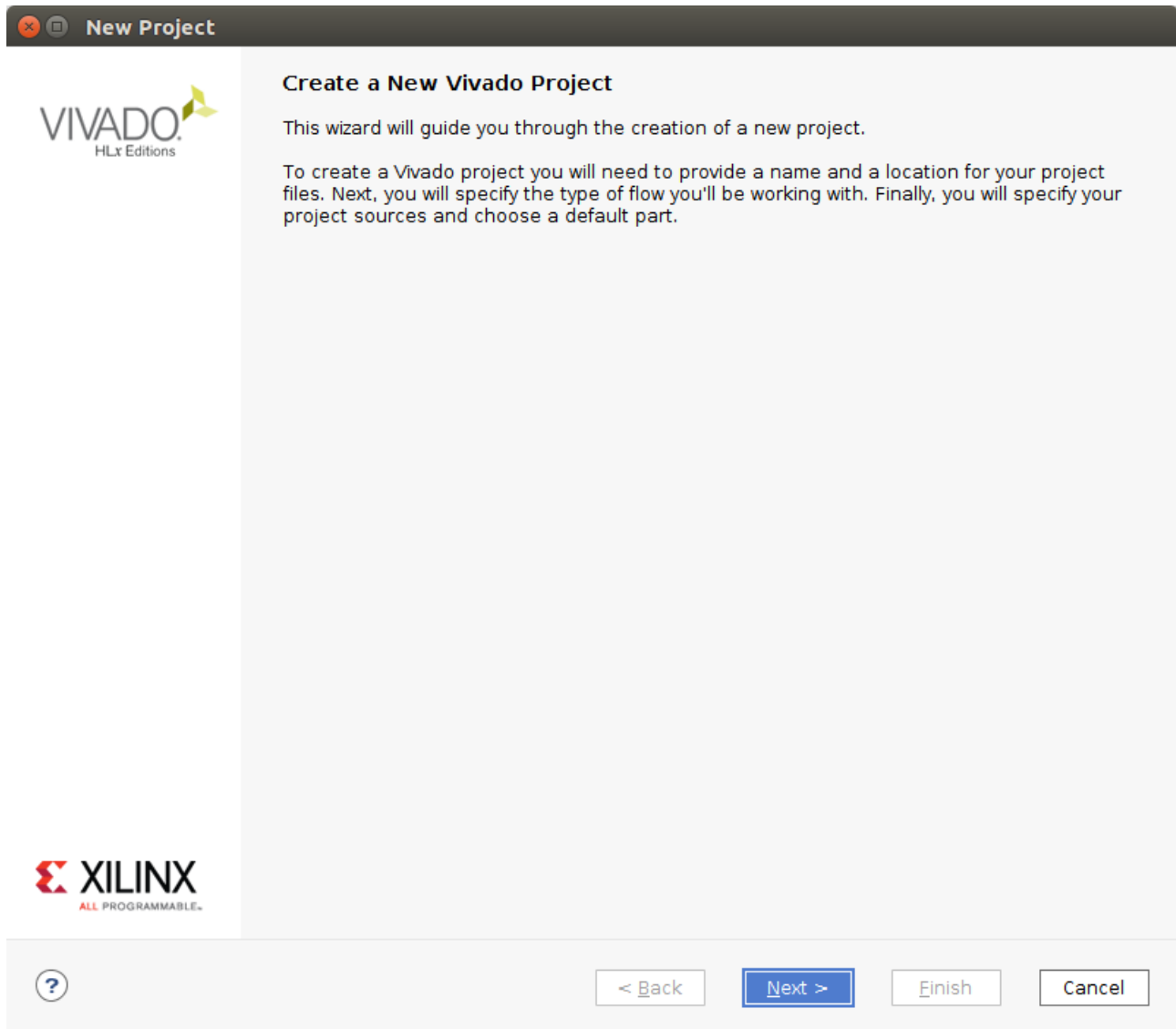
mhn97@naver.com

```
mkdir hw_sw_co_design2
```

```
cd hw_sw_co_design2
```

```
mkdir hardware
```

Vivado 실행



New Project

Project Name

Enter a name for your project and specify a directory where the project data files will be stored.



Project name:

Project location:

☐ Create project subdirectory

Project will be created at: /home/mhn/hw_sw_co_design2/hardware



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Finish

Cancel

Project Type

Specify the type of project to create.



- ☒ **RTL Project**
You will be able to add sources, create block designs in IP Integrator, generate IP, run RTL analysis, synthesis, implementation, design planning and analysis.
 - ☒ **Do not specify sources at this time**
- ☐ **Post-synthesis Project:** You will be able to add sources, view device resources, run design analysis, planning and implementation.
 - ☐ **Do not specify sources at this time**
- ☐ **I/O Planning Project**
Do not specify design sources. You will be able to view part/package resources.
- ☐ **Imported Project**
Create a Vivado project from a Synplify, XST or ISE Project File.
- ☐ **Example Project**
Create a new Vivado project from a predefined template.



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Finish

Cancel

Default Part

Choose a default Xilinx part or board for your project. This can be changed later.



Select:  Parts  Boards

Filter/ Preview













Vendor: All

Display Name: All

Board Rev: Latest

Reset All Filters

Search:

Display Name	Vendor	Board Rev	Part	I/O Pir
 Zybo Z7-20	digilentinc.com	B.2	 xc7z020clg400-1	400
 Zybo	digilentinc.com	B.3	 xc7z010clg400-1	400
 ZedBoard Zynq Evaluation and Development Kit	em.avnet.com	d	 xc7z020clg484-1	484
 Artix-7 AC701 Evaluation Platform	xilinx.com	1.1	 xc7a200tfbg676-2	676
 Kintex UltraScale+ KCU116 Evaluation Platform	xilinx.com	1.0	 xcku5p-ffvb676-2-e	676
 ZYNQ-7 ZC702 Evaluation Board	xilinx.com	1.0	 xc7z020clg484-1	484

No Board Connectors



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Finish

Cancel



New Project Summary

- i** A new RTL project named 'project_1' will be created.
- i** The default part and product family for the new project:
 - Default Board: Zybo
 - Default Part: xc7z010clg400-1
 - Product: Zynq-7000
 - Family: Zynq-7000
 - Package: clg400
 - Speed Grade: -1



To create the project, click Finish

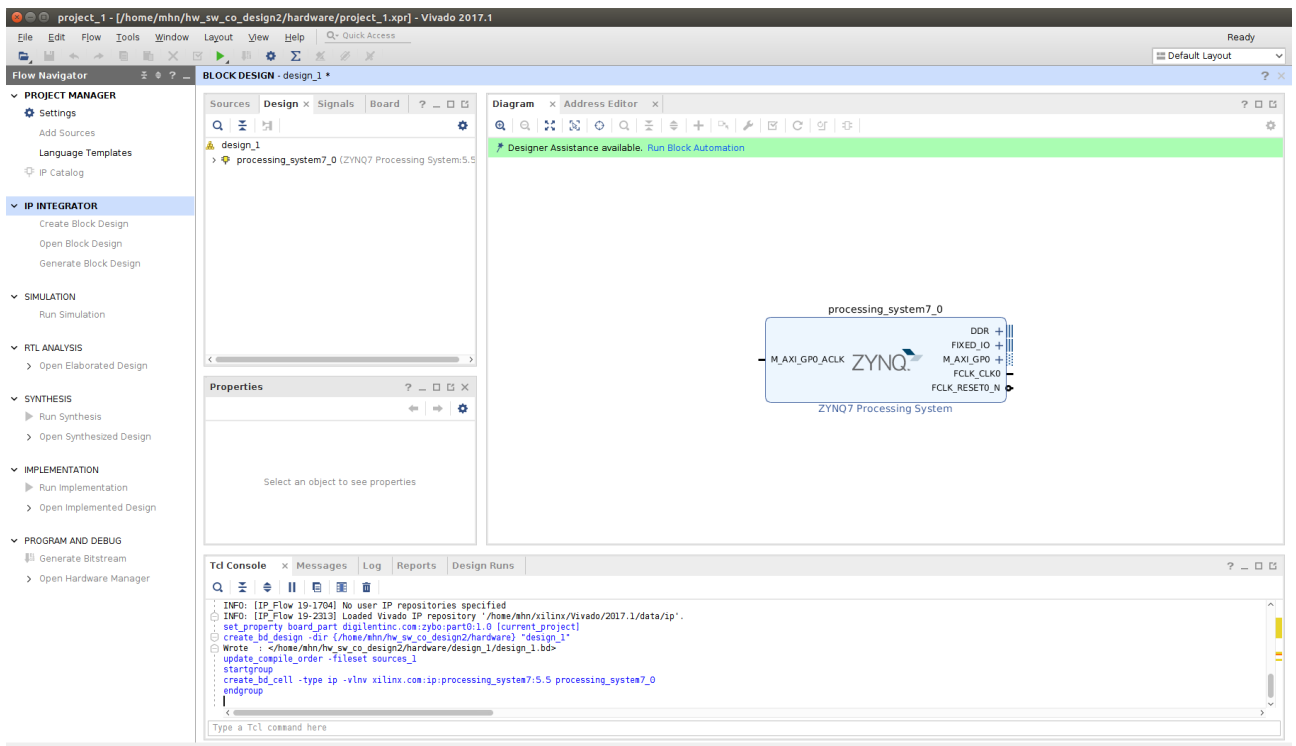
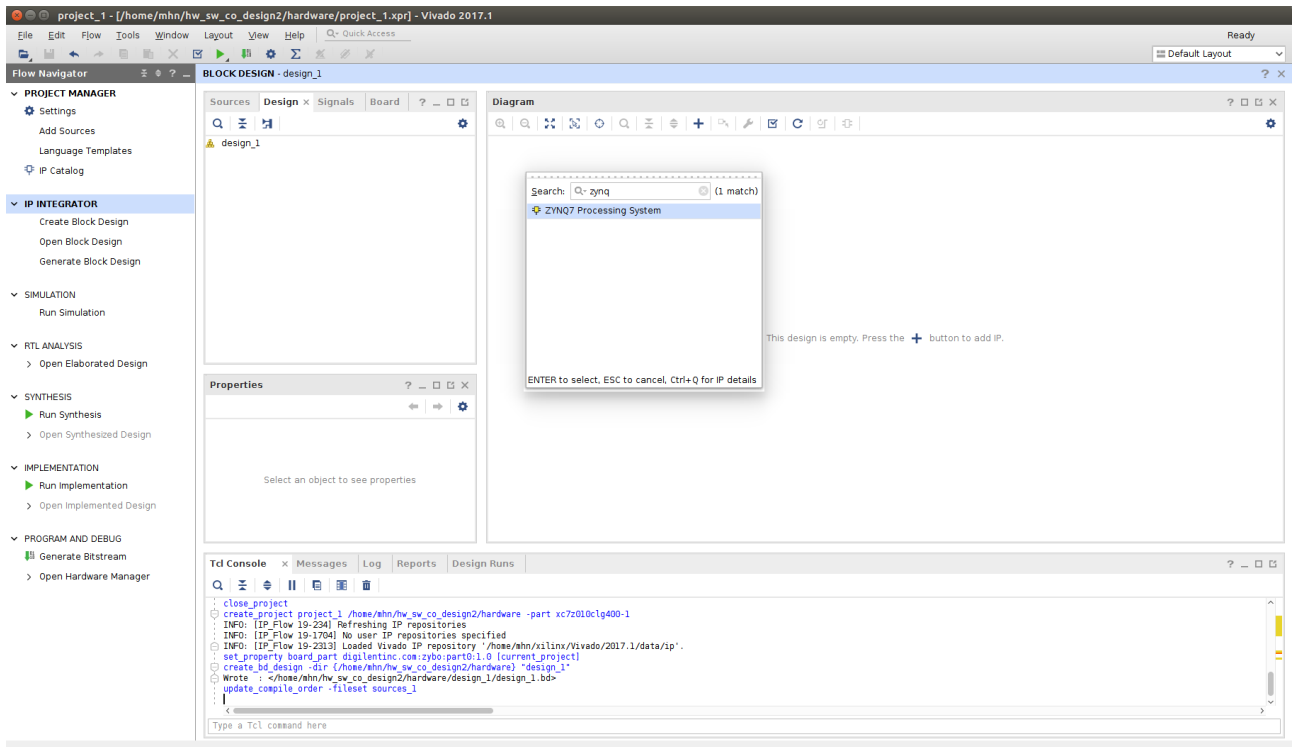


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Finish

Cancel



Run Block Automation

Automatically make connections in your design by checking the boxes of the blocks to connect. Select a block on the left to display its configuration options on the right.

?

🔍

⌵

⚙️

▼ ☒ All Automation (1 out of 1 selected)

☒ **processing_system7_0**

Description

This option sets the board preset on the Processing System. All current properties will be overwritten by the board preset. This action cannot be undone. Zynq7 block automation applies current board preset and generates external connections for FIXED_IO, Trigger and DDR interfaces.

NOTE: Apply Board Preset will discard existing IP configuration - please uncheck this box, if you wish to retain previous configuration.

Instance: /processing_system7_0

Options

Make Interface External: FIXED_IO, DDR

Apply Board Preset: ☒

Cross Trigger In:

Disable ▼

Cross Trigger Out:

Disable ▼

?

OK

Cancel

Re-customize IP

ZYNQ7 Processing System (5.5)

📄 Documentation ⚙️ Presets 📁 IP Location 🌐 Import XPS Settings

Page Navigator

Zynq Block Design

PS-PL Configuration

Peripheral I/O Pins

MIO Configuration

Clock Configuration

DDR Configuration

SMC Timing Calculation

Interrupts

MIO Configuration

Summary Report

⬅️ Bank 0 I/O Voltage

LVCMS 3.3V ▼

 Bank 1 I/O Voltage

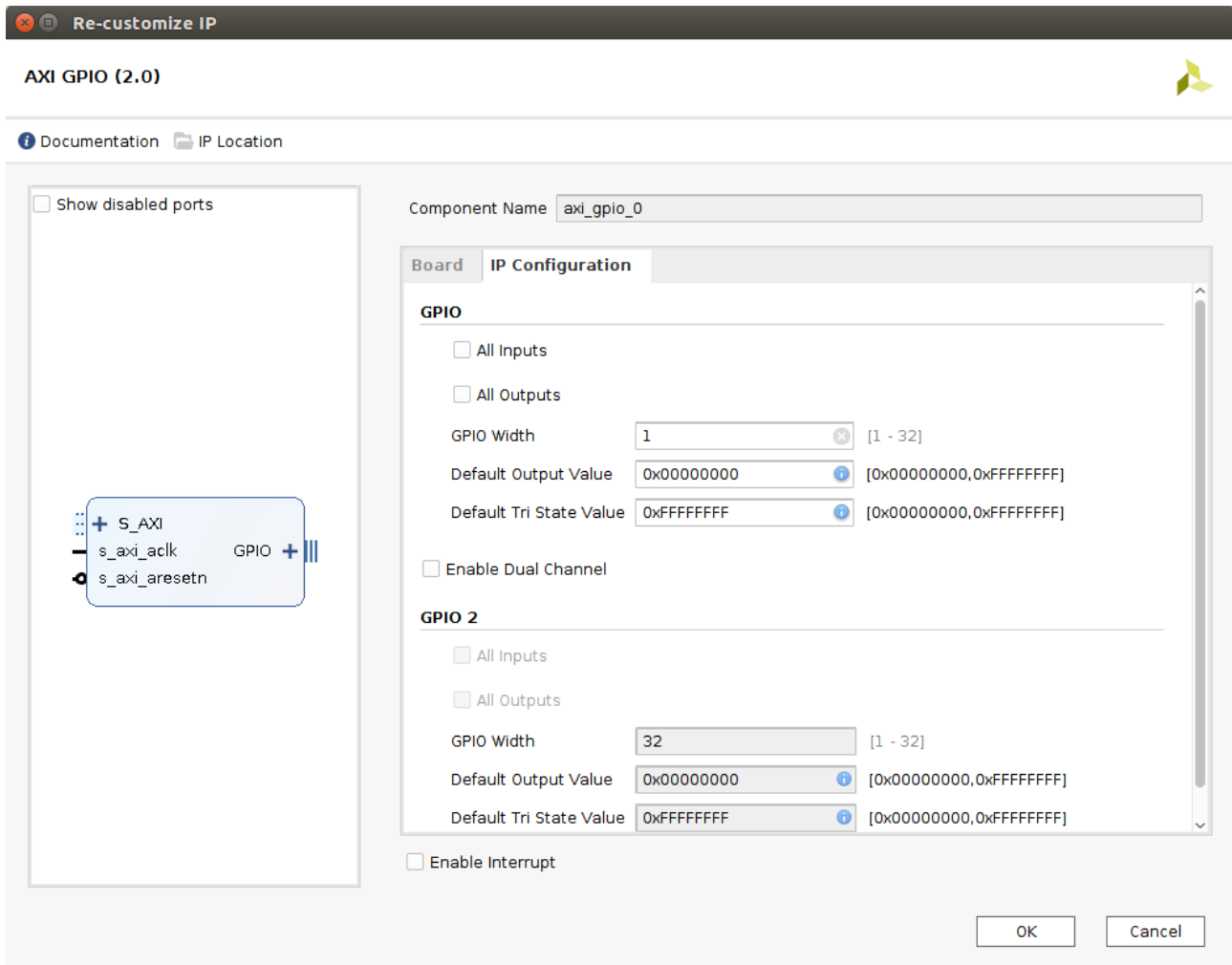
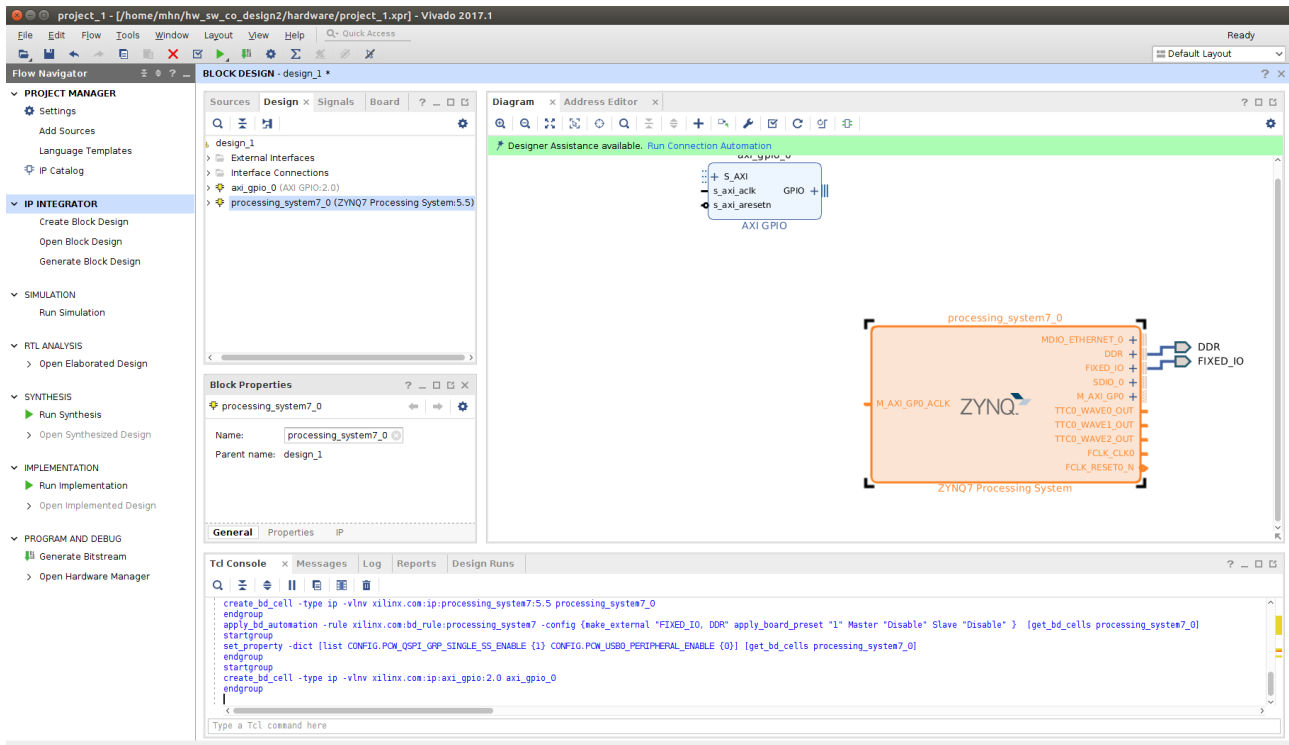
LVCMS 1.8V ▼

🔍 Search:

Peripheral	IO	Signal	IO Type	Speed	Pullup	Dir
Memory Interfaces						
I/O Peripherals						
▶ <input checked="" type="checkbox"/> ENET 0	<div>MIO 16 .. 27 ▼</div>					
▶ <input type="checkbox"/> ENET 1						
<input type="checkbox"/> USB 0						
<input type="checkbox"/> USB 1						
▶ <input checked="" type="checkbox"/> SD 0	<div>MIO 40 .. 45 ▼</div>					
▶ <input type="checkbox"/> SD 1						
▶ <input type="checkbox"/> UART 0						
▶ <input checked="" type="checkbox"/> UART 1	<div>MIO 48 .. 49 ▼</div>					
<input type="checkbox"/> I2C 0						
<input type="checkbox"/> I2C 1						
▶ <input type="checkbox"/> SPI 0						
▶ <input type="checkbox"/> SPI 1						
▶ <input type="checkbox"/> CAN 0						

OK

Cancel



Run Connection Automation

Automatically make connections in your design by checking the boxes of the interfaces to connect. Select an interface on the left to display its configuration options on the right.



All Automation (2 out of 2 selected)

axi_gpio_0

GPIO

S_AXI

Description

Connect Board Part Interface to IP interface.

Interface: /axi_gpio_0/GPIO

Options

Select Board Part Interface: Custom

OK

Cancel

project_1 - [/home/mhn/hw_sw_co_design2/hardware/project_1.xpi] - Vivado 2017.1

File Edit Flow Tools Window Layout View Help

Quick Access

Default Layout

Flow Navigator

BLOCK DESIGN - design_1

PROJECT MANAGER

Settings

Add Sources

Language Templates

IP Catalog

IP INTEGRATOR

Create Block Design

Open Block Design

Generate Block Design

SIMULATION

Run Simulation

RTL ANALYSIS

Open Elaborated Design

SYNTHESIS

Run Synthesis

Open Synthesized Design

IMPLEMENTATION

Run Implementation

Open Implemented Design

PROGRAM AND DEBUG

Generate Bitstream

Open Hardware Manager

Sources

Design

Signals

Board

?

design_1

External Interfaces

Interface Connections

Nets

axi_gpio_0 (AXI GPIO:2.0)

GPIO

S_AXI

S_AXI_ACLK

S_AXI_ARESETN

processing_system7_0 (ZYNQ7 Processing System:5.5)

ps7_0_axi_periph

rst_ps7_0_100M (Processor System Reset:5.0)

Block Interface Properties

GPIO

Name: GPIO

Mode: MASTER

Connection: axi_gpio_0_GPIO

Associated clock: None

General

Properties

Diagram

Address Editor

?

rst_ps7_0_100M

ps7_0_axi_periph

processing_system7_0

axi_gpio_0

gpio_rtl

DDR FIXED_IO

ZYNQ7 Processing System

Tcl Console

Messages

Log

Reports

Design Runs

?

</axi_gpio_0/S_AXI/Reg> is being mapped into </processing_system7_0/Data> at <0x41200000 [64K]>

apply_bd_automation -rule vivado.com:bd_rule_board_config -config {Board_Interface "Custom"} {get_bd_intf_pins axi_gpio_0/GPIO}

INFO: [board_rule 100-100] set_property CONFIG.USE_BOARD_FLOW true {get_bd_cells /axi_gpio_0}

INFO: [board_rule 100-100] set_property CONFIG.GPIO_BOARD_INTERFACE Custom {get_bd_cells /axi_gpio_0}

INFO: [board_rule 100-100] create_bd_intf_port -mode Master -vlnv vivado.com:interface_gpio_rtl:1.0 gpio_rtl

INFO: [board_rule 100-100] connect_bd_intf_net /gpio_rtl /axi_gpio_0/GPIO

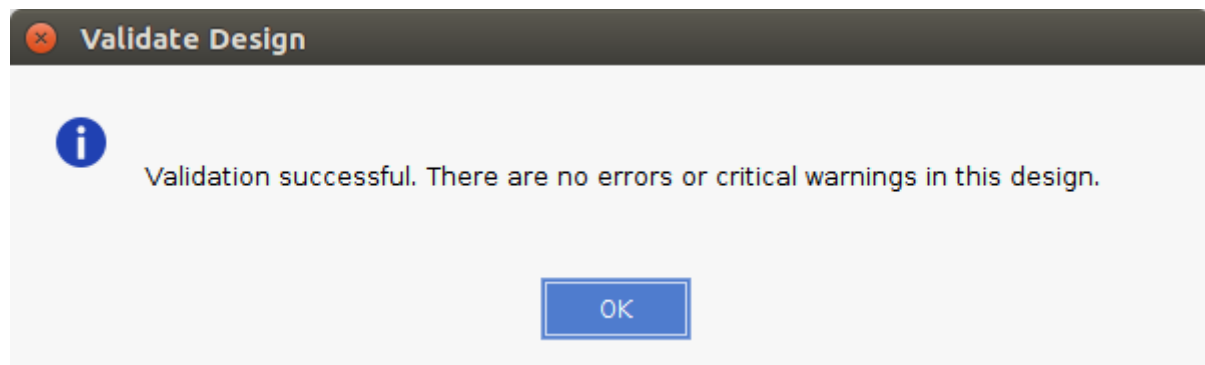
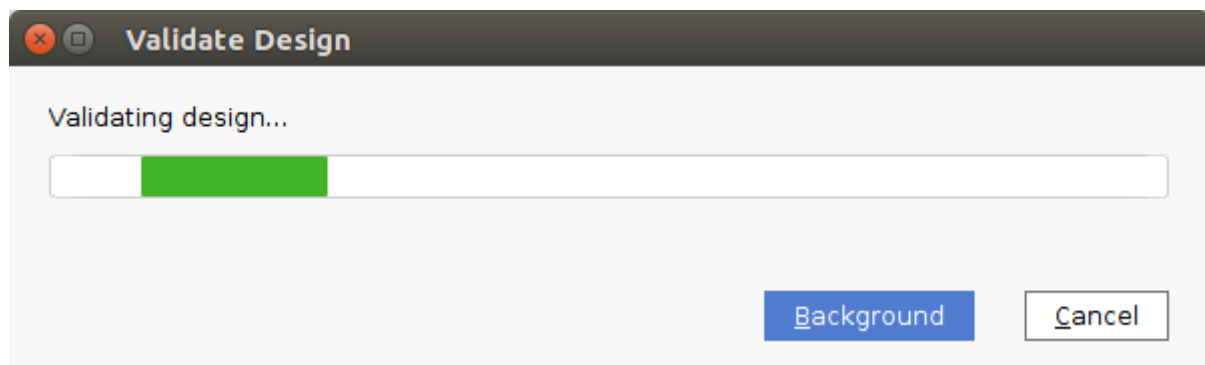
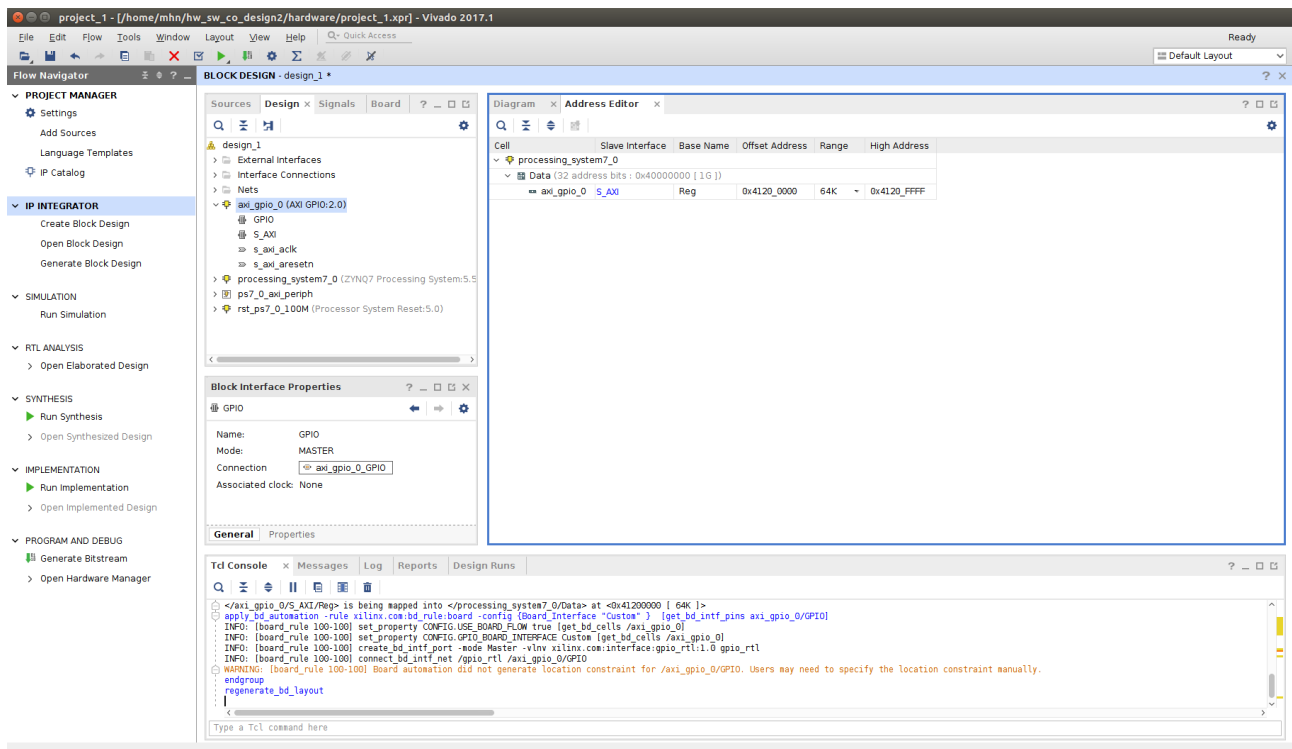
WARNING: [board_rule 100-100] Board automation did not generate location constraint for /axi_gpio_0/GPIO. Users may need to specify the location constraint manually.

endgroup

regenerate_bd_layout

Type a Tcl command here

System Net: processing_system7_0_FCLK_CLK0



Generate Output Products

The following output products will be generated.



Preview

design_1.bd (OOC per IP)

- Synthesis
- Implementation
- Simulation

Synthesis Options

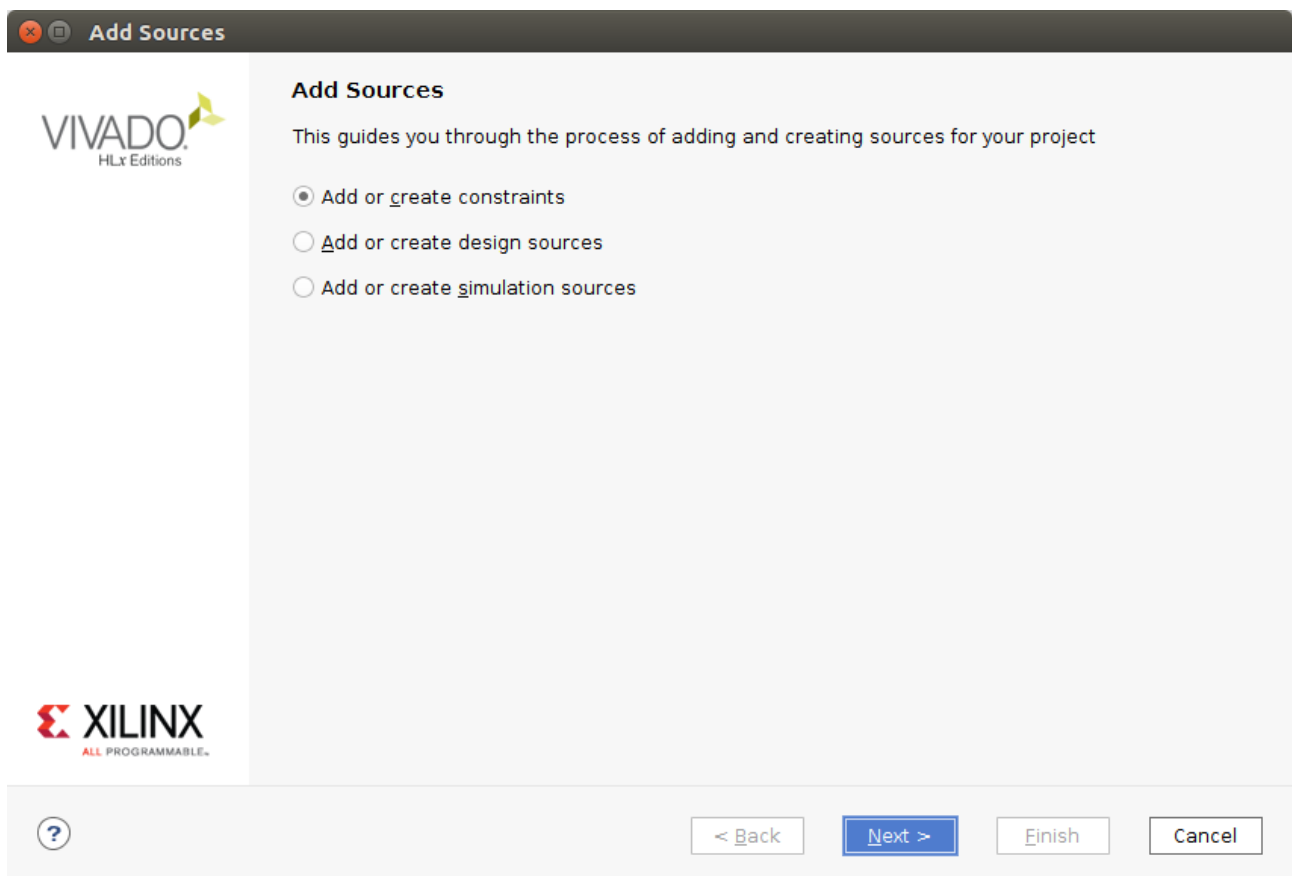
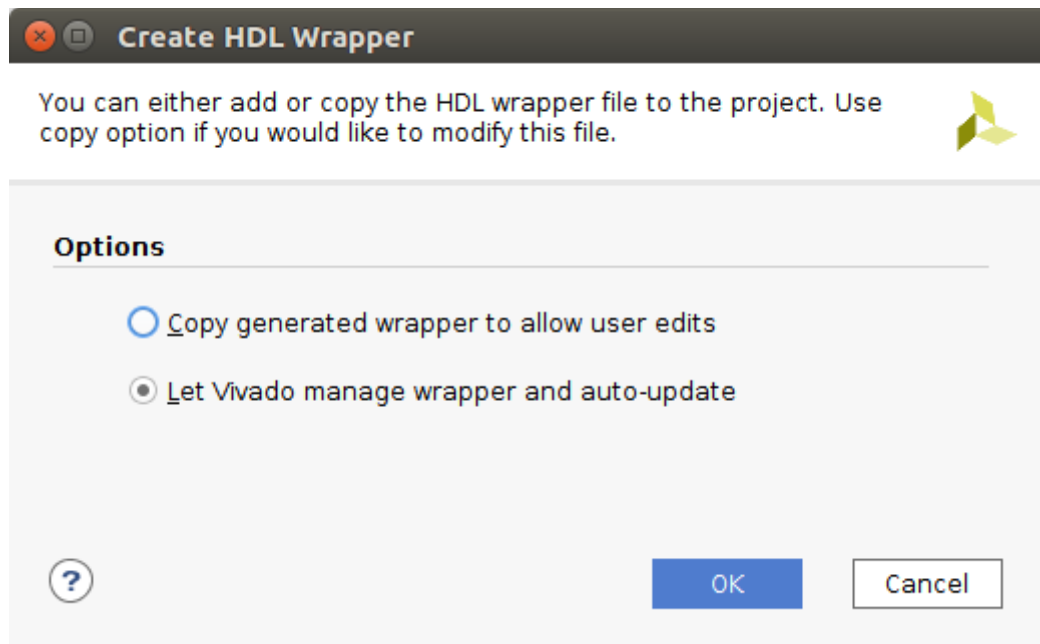
- ☒ Global
- ☐ Out of context per IP
- ☐ Out of context per Block Design

Run Settings

- ☒ On local host: Number of jobs: 2
- ☐ On remote hosts
- ☐ Use LSF:

Generate Output Products

Generation of output products completed successfully.



Add Sources

Add or Create Constraints

Specify or create constraint files for physical and timing constraint to add to your project.

Specify constraint set:

constrs_1 (active)

Create Constraints File

Create a new constraints file and add it to your project

File type:

XDC

File name:

driver

File location:

/home/mhn/hw_sw_co_d...

OK

Cancel

Copy constraints files into project

< Back

Next >

Finish

Cancel

Add Sources

Add or Create Constraints

Specify or create constraint files for physical and timing constraint to add to your project.

Specify constraint set:

constrs_1 (active)

Constraint File	Location
driver.xdc	/home/mhn/hw_sw_co_design2/hardware

Add Files

Create File

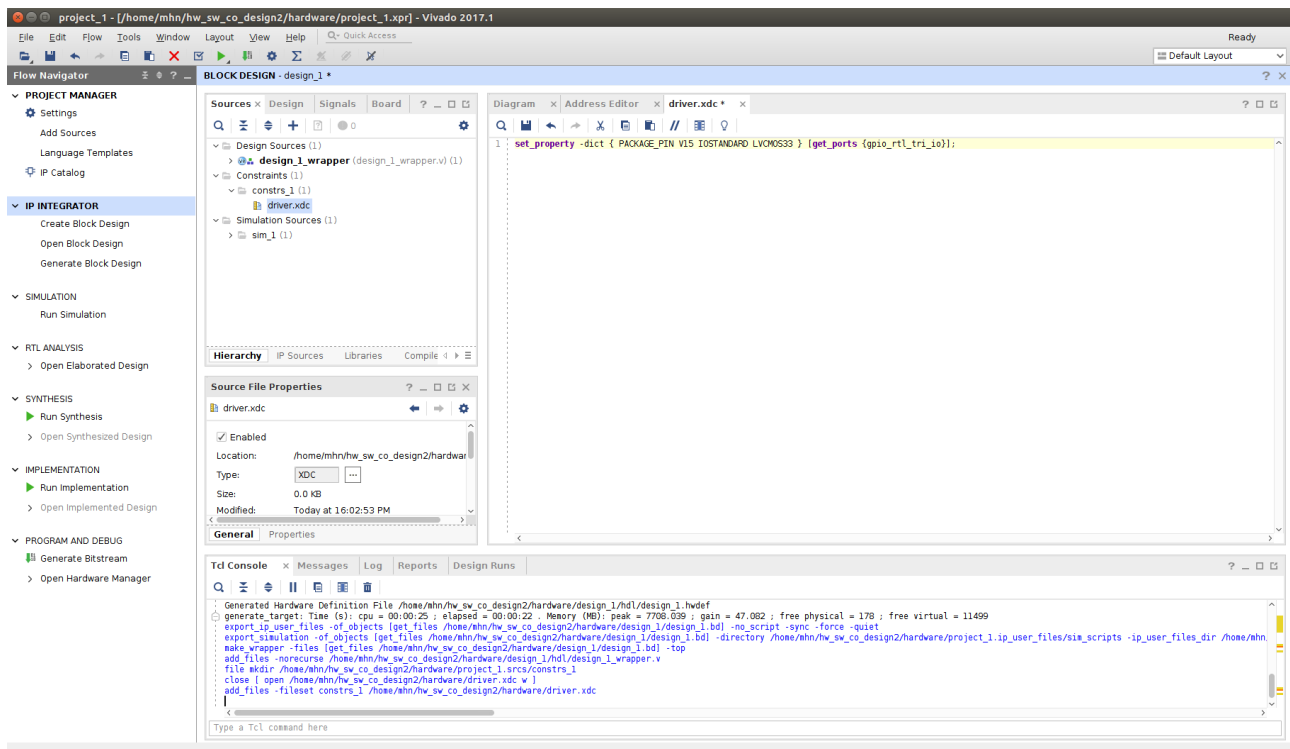
Copy constraints files into project

< Back

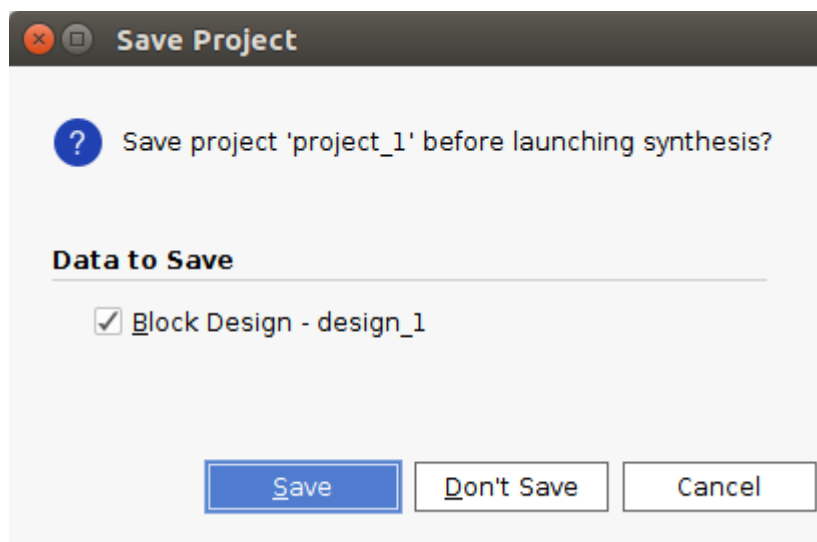
Next >

Finish

Cancel




- ▼ SYNTHESIS
- ▶ Run Synthesis
- > Open Synthesized Design



Launch Runs

Launch the selected synthesis or implementation runs.



Launch directory:

/home/mhn/hw_sw_co_design2/hardware

Options

☒ Launch runs on local host:

Number of jobs:

2

☐ Launch runs on remote hosts

Configure Hosts

☐ Launch runs using LSF


Configure LSF

☐ Generate scripts only

☐ Don't show this dialog again

OK

Cancel

Running synth_design [Cancel](#) 

Synthesis Completed

i

Project 'project_1' Synthesis successfully completed.

Next

☐ Run Implementation

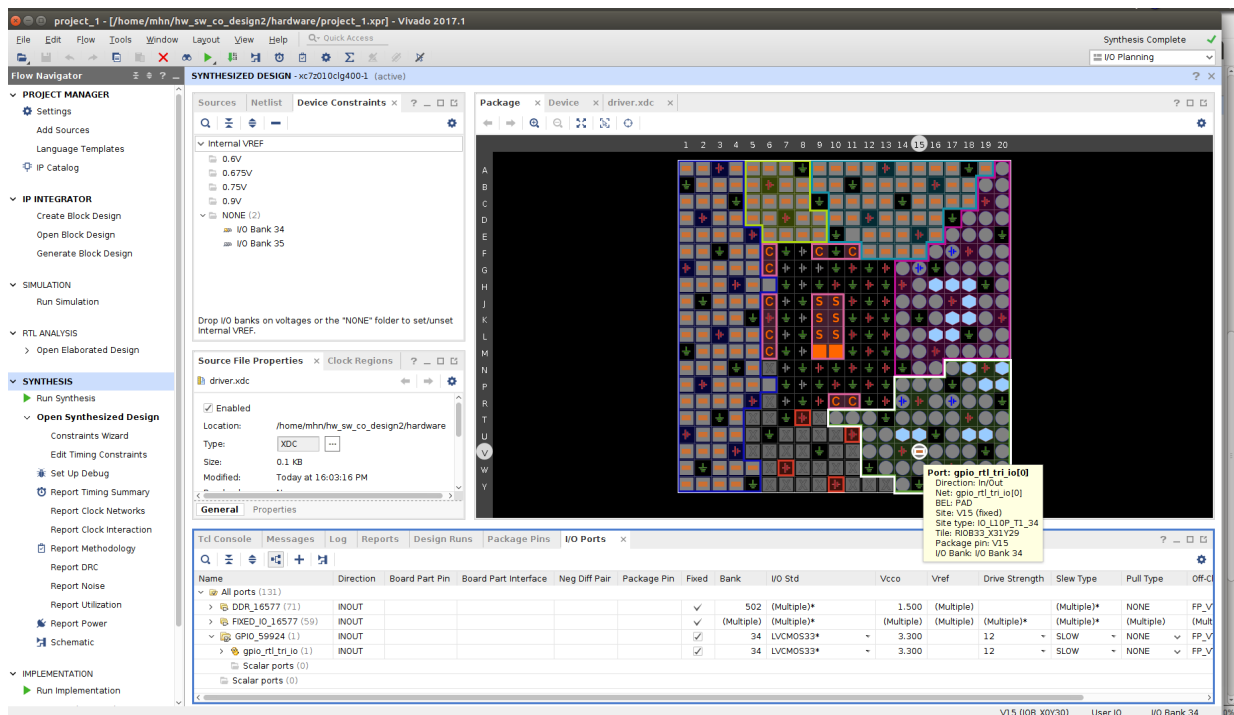
☒ Open Synthesized Design

☐ View Reports

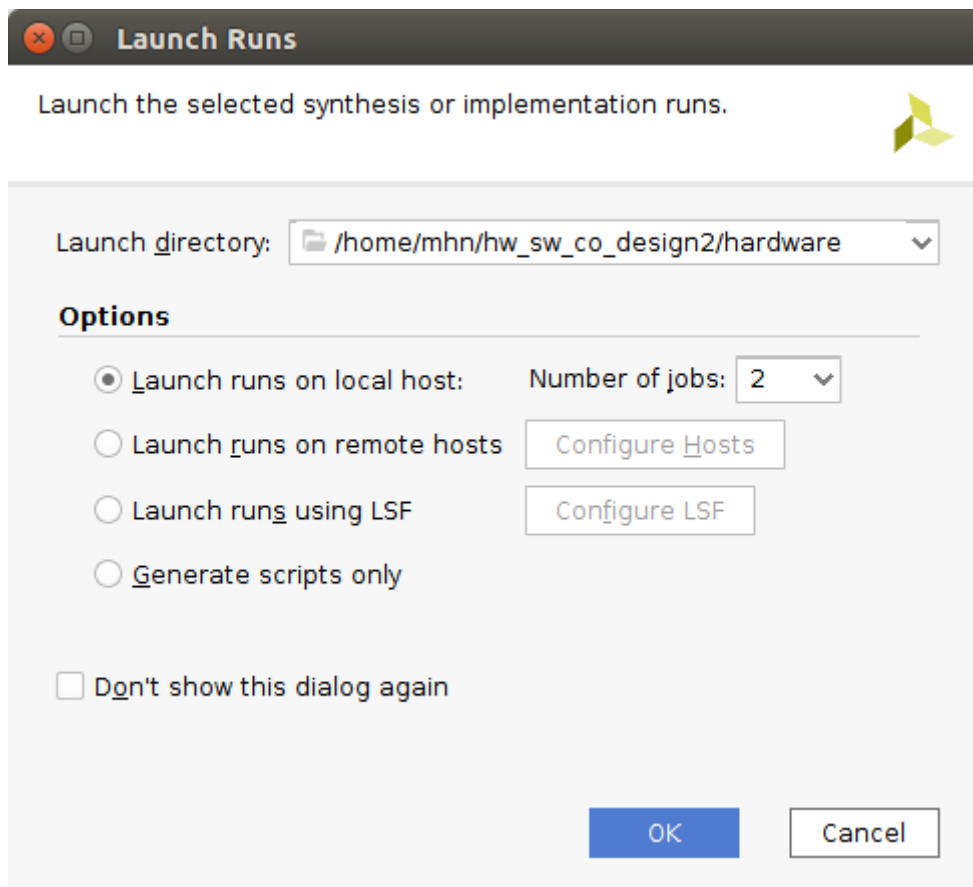
☐ Don't show this dialog again

OK

Cancel



Generate Bitstream



```
cd xilinx/Vivado/2017.1/data/xicom/cable_drivers/lin64/  
install_script/install_drivers/
```

```
sudo ./install_drivers
```

```
mhn@mhn-Z20NH-AS51B5U:~/xilinx/Vivado/2017.1/data/xicom/cable_drivers/lin64/install_script/install_drivers$ sudo ./install_drivers  
[sudo] password for mhn:  
INFO: Installing cable drivers.  
INFO: Script name = ./install_drivers  
INFO: HostName = mhn-Z20NH-AS51B5U  
INFO: Current working dir = /home/mhn/xilinx/Vivado/2017.1/data/xicom/cable_drivers/lin64/install_script/install_drivers  
INFO: Kernel version = 4.13.0-43-generic.  
INFO: Arch = x86_64.  
USB udev file exists and will not be updated.  
--File /etc/udev/rules.d/52-xilinx-ftdi-usb.rules exists.  
--File /etc/udev/rules.d/52-xilinx-ftdi-usb.rules version =  
--File 52-xilinx-ftdi-usb.rules exists.  
--File 52-xilinx-ftdi-usb.rules version =  
--File 52-xilinx-ftdi-usb.rules is newer than the destination file.  
--Updating rules file.  
--File /etc/udev/rules.d/52-xilinx-pcusb.rules exists.  
--File /etc/udev/rules.d/52-xilinx-pcusb.rules version = 0002  
--File 52-xilinx-pcusb.rules exists.  
--File 52-xilinx-pcusb.rules version = 0002  
--File 52-xilinx-pcusb.rules is already updated.  
  
INFO: Digilent Return code = 0  
INFO: Xilinx Return code = 0  
INFO: Xilinx FTDI Return code = 0  
INFO: Return code = 0  
INFO: Driver installation successful.  
CRITICAL WARNING: Cable(s) on the system must be unplugged then plugged back in order for the driver scripts to update the cables.
```

```
cd ../../../../../../
```

```
~/hw_sw_co_design$
```

```
petalinux-create -t project -n software --template zynq
```

```
~/hw_sw_co_design/hardware/driver_lab.sdk$
```

```
petalinux-config --get-hw-description -p ../../software/
```

```
mhn@mhn-Z20NH-AS51B5U:~/hw_sw_co_design/hardware/driver_lab.sdk$ petalinux-config --get-hw-description -p ../../software/  
INFO: Checking component...  
INFO: Getting hardware description...  
INFO: Rename design_1_wrapper.hdf to system.hdf  
  
***** hsi v2015.4 (64-bit)  
**** SW Build 1412921 on Wed Nov 18 09:44:32 MST 2015  
** Copyright 1986-2015 Xilinx, Inc. All Rights Reserved.  
  
source /home/mhn/hw_sw_co_design/software/build/linux/hw-description/hw-description.tcl -notrace  
INFO: [Common 17-206] Exiting hsi at Thu May 31 11:48:12 2018...  
INFO: Config linux  
[INFO ] config linux  
configuration written to /home/mhn/hw_sw_co_design/software/subsystems/linux/config  
  
*** End of the configuration.  
*** Execute 'make' to start the build or try 'make help'.  
  
[INFO ] generate DTS to /home/mhn/hw_sw_co_design/software/subsystems/linux/configs/device-tree  
INFO: [Hsi 55-1698] elapsed time for repository loading 3 seconds  
WARNING: ps7_ethernet_0: No reset found  
INFO: [Common 17-206] Exiting hsi at Thu May 31 11:48:32 2018...  
[INFO ] generate BSP for zynq_fsbl  
INFO: [Hsi 55-1698] elapsed time for repository loading 0 seconds  
INFO: [Common 17-206] Exiting hsi at Thu May 31 11:48:51 2018...  
INFO: Config linux/kernel  
[INFO ] oldconfig linux/kernel  
INFO: Config linux/rootfs  
[INFO ] oldconfig linux/rootfs  
INFO: Config linux/u-boot  
[INFO ] generate linux/u-boot configuration files  
[INFO ] generate linux/u-boot board header files  
INFO: [Hsi 55-1698] elapsed time for repository loading 1 seconds  
INFO: [Common 17-206] Exiting hsi at Thu May 31 11:49:10 2018...  
[INFO ] oldconfig linux/u-boot
```

```
~/hw_sw_co_design/software/components/bootloader/zynq_fsbl$ ls
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software/components/bootloader/zynq_fsbl$ ls
fsbl_debug.h      fsbl_hooks.h      main.c      nand.c      pcap.c      ps7_parameters.xml  rsa.h
fsbl.h            image_mover.c     Makefile    nand.h      pcap.h      qspl.c         sd.c
fsbl_handoff.S    image_mover.h     md5.c       nor.c       ps7_init.c  qspl.h         sd.h
fsbl_hooks.c      lscript.ld        md5.h       nor.h       ps7_init.h  rsa.c          zynq_fsbl_bsp
```

FPGA 베이스의 Cortex-A9 부트 코드를 볼 수 있다

```
~/hw_sw_co_design/software$ petalinux-config -c u-boot
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software$ petalinux-config -c u-boot
INFO: Checking component...
INFO: Config linux/u-boot
[INFO ] generate linux/u-boot configuration files
#
# configuration written to .config
#
[INFO ] config linux/u-boot

*** End of the configuration.
*** Execute 'make' to start the build or try 'make help'.
```

```
~/hw_sw_co_design/software$ petalinux-build
```

```
mhn@mhn-Z20NH-AS51B5U:~/hw_sw_co_design/software$ petalinux-build
INFO: Checking component...
INFO: Generating make files and build linux
INFO: Generating make files for the subcomponents of linux
INFO: Building linux
[INFO ] pre-build linux/rootfs/fwupgrade
[INFO ] pre-build linux/rootfs/peekpoke
[INFO ] build system.dtb
[INFO ] build linux/kernel
[INFO ] generate linux/u-boot configuration files
[INFO ] update linux/u-boot source
[INFO ] build linux/u-boot
[INFO ] build zynq_fsbl
[INFO ] build linux/rootfs/fwupgrade
[INFO ] build linux/rootfs/peekpoke
[INFO ] build kernel in-tree modules
[INFO ] modules linux/kernel
[INFO ] post-build linux/rootfs/fwupgrade
[INFO ] post-build linux/rootfs/peekpoke
[INFO ] pre-install linux/rootfs/fwupgrade
[INFO ] pre-install linux/rootfs/peekpoke
[INFO ] install system.dtb
[INFO ] install linux/kernel
[INFO ] generate linux/u-boot configuration files
[INFO ] update linux/u-boot source
[INFO ] build linux/u-boot
[INFO ] install linux/u-boot
[INFO ] install sys_init
[INFO ] install linux/rootfs/fwupgrade
[INFO ] install linux/rootfs/peekpoke
[INFO ] install kernel in-tree modules
[INFO ] modules_install linux/kernel
[INFO ] post-install linux/rootfs/fwupgrade
[INFO ] post-install linux/rootfs/peekpoke
[INFO ] package rootfs.cpio to /home/mhn/hw_sw_co_design/software/images/linux
[INFO ] Update and install vmlinux image
[INFO ] vmlinux linux/kernel
[INFO ] install linux/kernel
[INFO ] package zImage
[INFO ] zImage linux/kernel
[INFO ] install linux/kernel
[INFO ] Package HDF bitstream
[INFO ] Failed to copy images to TFTPBOOT /tftpboot
```

```
~/hw_sw_co_design/software$
```

```
petalinux-create -t apps -n device_driver -enable
```

```
mhn@mhn-Z20NH-AS51B5U:~/hw_sw_co_design/software$ petalinux-create -t apps -n device_driver --enable
INFO: Create apps: device_driver
INFO: New apps successfully created in /home/mhn/hw_sw_co_design/software/components/apps/device_driver
INFO: Enabling created component...
INFO: It has been enabled to linux/rootfs
```

```
~/hw_sw_co_design/software$
```

```
cd components/apps/device_driver/
```

```
~/hw_sw_co_design/software/components/apps/device_driver$  
vi device_driver.c
```

```
/*  
 * Placeholder PetaLinux user application.  
 *  
 * Replace this with your application code  
 */  
#include <stdio.h>  
#include <stdlib.h>  
#include <unistd.h>  
#include <sys/mman.h>  
#include <fcntl.h>  
  
#define IN          0  
#define OUT        1  
  
#define GPIO_MAP_SIZE      0x10000  
  
#define GPIO_DATA_OFFSET   0x00  
#define GPIO_TRI_OFFSET    0x04  
#define GPIO2_DATA_OFFSET  0x00  
#define GPIO2_TRI_OFFSET   0x04  
  
void usage(void){  
  
    printf("*argv[0] -d <UIO_DEV_FILE> -i | -o <VALUE>\n");  
    printf(" -d UIO device file - ex) /dev/uio0");  
    printf(" -i Input from GPIO\n");  
    printf(" -o <VALUE> Output to GPIO\n");  
  
}  
  
int main(int argc, char *argv[])  
{  
  
    int c, fd, value, direction = IN;  
    char *uiod;  
    void *ptr;  
  
    printf("GPIO UIO Test\n");  
  
    while( (c = getopt(argc, argv, "d:io:h")) != -1){  
  
        switch(c){  
            case 'd':  
                uiod = optarg;  
                break;  
            case 'i':  
                direction = IN;  
            case 'o':  
                direction = OUT;
```

```

        value = atoi(optarg);
        break;
    default :
        printf("Invalid Option: %c\n", (char)c);
        usage();
        return -1;
    }
}

fd = open(uiod, O_RDWR);

if(fd < 1){
    perror(argv[0]);
    printf("Onvalid UIO Device File: %s\n", uiod);
    usage();
    return -1;
}

ptr = mmap(NULL, GPIO_MAP_SIZE, PROT_READ|
PROT_WRITE,MAP_SHARED, fd, 0);

if(direction == IN){
    *((unsigned *)(ptr + GPIO_TRI_OFFSET)) == 255;
    printf("%s:Input: %08x\n", argv[0], value);
}else{
    *((unsigned *)(ptr + GPIO_TRI_OFFSET)) = 0;
    *((unsigned *)(ptr + GPIO_DATA_OFFSET)) = value;
}

munmap(ptr, GPIO_MAP_SIZE);

return 0;
}

```

/home/mhn/hw_sw_co_design/software/images/linux

여기에 부트 로더와 리눅스 이미지가 있는 것을 볼 수 있을 것이다.


```
~/hw_sw_co_design/software$ petalinux-config -c rootfs
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software$ petalinux-config -c rootfs
INFO: Checking component...
INFO: Config linux/rootfs
[INFO ] config linux/rootfs

*** End of the configuration.
*** Execute 'make' to start the build or try 'make help'.
```

```
~/hw_sw_co_design/software$ petalinux-config -c kernel
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software$ petalinux-config -c kernel
INFO: Checking component...
INFO: Config linux/kernel
[INFO ] config linux/kernel

*** End of the configuration.
*** Execute 'make' to start the build or try 'make help'.
```

```
~/hw_sw_co_design/software$ cd ../hardware/driver_lab.sdk
```

```
~/hw_sw_co_design/hardware/driver_lab.sdk$
```

```
petalinux-config --get-hw-description -p ../../software/
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/hardware/driver_lab.sdk$ petalinux-config --get-hw-description -p ../../software/
INFO: Checking component...
INFO: Getting hardware description...
INFO: Rename design_1_wrapper.hdf to system.hdf

***** hsi v2015.4 (64-bit)
**** SW Build 1412921 on Wed Nov 18 09:44:32 MST 2015
** Copyright 1986-2015 Xilinx, Inc. All Rights Reserved.

source /home/mhn/hw_sw_co_design/software/build/linux/hw-description/hw-description.tcl -notrace
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:26:31 2018...
INFO: Config linux
[INFO ] oldconfig linux
[INFO ] generate DTS to /home/mhn/hw_sw_co_design/software/subsystems/linux/configs/device-tree
INFO: [Hsi 55-1698] elapsed time for repository loading 0 seconds
WARNING: ps7_ethernet_0: No reset found
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:26:43 2018...
[INFO ] generate BSP for zynq_fsbl
INFO: [Hsi 55-1698] elapsed time for repository loading 0 seconds
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:27:01 2018...
INFO: Config linux/kernel
[INFO ] oldconfig linux/kernel
INFO: Config linux/rootfs
[INFO ] oldconfig linux/rootfs
INFO: Config linux/u-boot
[INFO ] generate linux/u-boot configuration files
[INFO ] generate linux/u-boot board header files
INFO: [Hsi 55-1698] elapsed time for repository loading 1 seconds
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:27:08 2018...
[INFO ] oldconfig linux/u-boot
```

```
~/hw_sw_co_design/hardware/driver_lab.sdk$ cd ../../software/
```

```
~/hw_sw_co_design/software$ petalinux-config
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software$ petalinux-config
INFO: Checking component...
INFO: Config linux
[INFO ] config linux

*** End of the configuration.
*** Execute 'make' to start the build or try 'make help'.

[INFO ] generate DTS to /home/mhn/hw_sw_co_design/software/subsystems/linux/configs/device-tree
INFO: [Hsi 55-1698] elapsed time for repository loading 0 seconds
WARNING: ps7_ethernet_0: No reset found
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:27:34 2018...
[INFO ] generate BSP for zynq_fsbl
INFO: [Hsi 55-1698] elapsed time for repository loading 0 seconds
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:27:53 2018...
INFO: Config linux/kernel
[INFO ] oldconfig linux/kernel
INFO: Config linux/rootfs
[INFO ] oldconfig linux/rootfs
INFO: Config linux/u-boot
[INFO ] generate linux/u-boot configuration files
[INFO ] generate linux/u-boot board header files
INFO: [Hsi 55-1698] elapsed time for repository loading 0 seconds
INFO: [Common 17-206] Exiting hsi at Thu May 31 14:27:59 2018...
[INFO ] oldconfig linux/u-boot
```

```
~/hw_sw_co_design/software$ petalinux-config -c kernel
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software$ petalinux-config -c kernel
INFO: Checking component...
INFO: Config linux/kernel
[INFO ] config linux/kernel

*** End of the configuration.
*** Execute 'make' to start the build or try 'make help'.
```

```
~/hw_sw_co_design/software$ petalinux-config -c rootfs
```

```
mhn@mhn-Z20NH-AS51BSU:~/hw_sw_co_design/software$ petalinux-config -c rootfs
INFO: Checking component...
INFO: Config linux/rootfs
[INFO ] config linux/rootfs

*** End of the configuration.
*** Execute 'make' to start the build or try 'make help'.
```

```
~/hw_sw_co_design/software/subsystems/linux/configs/device-tree$  
vi system-top.dts
```

```
/dts-v1/;  
/include/ "system-conf.dtsi"  
/ {  
};  
  
&clk {  
    ps-clk-frequency = <500000000>;  
};  
  
&flash0{  
    compatible = "s25fl128s1";  
};  
  
&usb0{  
    dr_mode = "otg";  
};  
  
&gem0{  
    phy-handle = <&phy0>;  
    mdio{  
  
        #address-cells = <1>;  
        #size-cells = <0>;  
        phy0: phy@1{  
            compatible = "realtek,RTL8211E";  
            device_type = "ethernet-phy";  
            reg = <1>;  
        };  
    };  
};  
  
&axi_gpio_0{  
    compatible = "generic-uio";  
};
```

~/hw_sw_co_design/software/images/linux\$ petalinux-build

mhn@mhn-Z20NH-ASS1B5U:~/hw_sw_co_design/software/images/linux\$ petalinux-build

```
INFO: Checking component...
INFO: Generating make files and build linux
INFO: Generating make files for the subcomponents of linux
INFO: Building linux
[INFO ] Cleaning packages
[INFO ] clean linux/rootfs/device_driver
[INFO ] clean linux/rootfs/fwupgrade
[INFO ] clean linux/rootfs/peekpoke
[INFO ] pre-build linux/rootfs/device_driver
[INFO ] pre-build linux/rootfs/fwupgrade
[INFO ] pre-build linux/rootfs/peekpoke
[INFO ] build system.dtb
[INFO ] build linux/kernel
[INFO ] generate linux/u-boot configuration files
[INFO ] update linux/u-boot source
[INFO ] build linux/u-boot
[INFO ] build zynq_fsbl
[INFO ] Setting up stage config
[INFO ] Setting up rootfs config
[INFO ] Updating for cortexa9-vfp-neon
[INFO ] Updating package manager
[INFO ] Expanding stagefs
[INFO ] build linux/rootfs/device_driver
[INFO ] build linux/rootfs/fwupgrade
[INFO ] build linux/rootfs/peekpoke
[INFO ] build kernel in-tree modules
[INFO ] modules linux/kernel
[INFO ] post-build linux/rootfs/device_driver
[INFO ] post-build linux/rootfs/fwupgrade
[INFO ] post-build linux/rootfs/peekpoke
[INFO ] pre-install linux/rootfs/device_driver
[INFO ] pre-install linux/rootfs/fwupgrade
[INFO ] pre-install linux/rootfs/peekpoke
[INFO ] install system.dtb
[INFO ] install linux/kernel
[INFO ] generate linux/u-boot configuration files
[INFO ] update linux/u-boot source
[INFO ] build linux/u-boot
[INFO ] install linux/u-boot
[INFO ] Expanding rootfs
[INFO ] install sys_init
[INFO ] install linux/rootfs/device_driver
[INFO ] install linux/rootfs/fwupgrade
[INFO ] install linux/rootfs/peekpoke
[INFO ] install kernel in-tree modules
[INFO ] modules_install linux/kernel
[INFO ] post-install linux/rootfs/device_driver
[INFO ] post-install linux/rootfs/fwupgrade
[INFO ] post-install linux/rootfs/peekpoke
[INFO ] package rootfs.cpio to /home/mhn/hw_sw_co_design/software/images/linux
[INFO ] Update and install vmlinux image
[INFO ] vmlinux linux/kernel
[INFO ] install linux/kernel
[INFO ] package zImage
[INFO ] zImage linux/kernel
[INFO ] install linux/kernel
[INFO ] Package HDF bitstream
[INFO ] Failed to copy images to TFTPBOOT /tftpboot
```

```
~/hw_sw_co_design/software/images/linux$  
petalinux-package --boot --fsbl zynq_fsbl.elf --fpga  
../../../../hardware/impl_1/design_1_wrapper.bit --uboot -force
```

```
mhn@mhn-Z20NH-A551BSU:~/hw_sw_co_design/software/images/linux$ petalinux-package --boot --fsbl zynq_fsbl.elf --fpga ../../../../../../hardware/impl_1/design_1_wrapper.bit --uboot --force  
INFO: File in BOOT BIN: "/home/mhn/hw_sw_co_design/software/images/linux/zynq_fsbl.elf"  
INFO: File in BOOT BIN: "/home/mhn/hw_sw_co_design/hardware/impl_1/design_1_wrapper.bit"  
INFO: File in BOOT BIN: "/home/mhn/hw_sw_co_design/software/images/linux/u-boot.elf"  
INFO: Generating zynq binary package BOOT.BIN...  
INFO: Binary is ready.  
WARNING: Unable to access the TFTPBOOT folder /tftpboot!!!  
WARNING: Skip file copy to TFTPBOOT folder!!!
```

```
if)
```

```
ERROR: This tool requires 'bootgen' and it is missing. Please source Xilinx Tools settings first
```

```
export PATH=$PATH:/home/mhn/xilinx/SDK/2017.1/bin/
```

수업중 제공한 문서를 기반으로 SD 카드에 부트 로더와 리눅스 이미지를 옮긴다.

(sd 카드 파티션 분할을 먼저 하자!)

FPGA 보드의 점퍼를 SD 카드 부팅으로 변경한다.

컴퓨터와 FPGA 보드를 USB 로 연결한다.

전원을 인가한다.

dmesg 를 통해 USB Device Driver 가 잘 잡히는지 확인한다.(노란불!)

sudo apt-get install putty

```
mhn@mhn-Z20NH-A551B5U:~/petalinux_zynq/petalinux-v2015.4-final/components/apps$ sudo apt-get install putty
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following packages were automatically installed and are no longer required:
  cabextract fonts-horai-umefont libasyns0:i386 libexif12:i386 libgpm2:i386
  libice6:i386 libieee1284-3:i386 libjpeg-turbo8:i386 libjson-c2:i386
  liblcms2-2:i386 libmspack0 libogg0:i386 libp11-kit-gnome-keyring:i386
  libsamplerate0:i386 libsm6:i386 libwrap0:i386 libx11-6:i386 libxau6:i386
  libxcb1:i386 libxcomposite1:i386 libxdamage1:i386 libxdmcp6:i386
  libxext6:i386 libxfixes3:i386 libxinerama1:i386 libxshmfence1:i386
  libxxf86vm1:i386 linux-headers-4.10.0-28 linux-headers-4.10.0-28-generic
  linux-headers-4.13.0-32 linux-headers-4.13.0-32-generic
  linux-headers-4.13.0-36 linux-headers-4.13.0-36-generic
  linux-headers-4.13.0-37 linux-headers-4.13.0-37-generic
  linux-headers-4.13.0-38 linux-headers-4.13.0-38-generic
  linux-headers-4.13.0-39 linux-headers-4.13.0-39-generic
  linux-image-4.10.0-28-generic linux-image-4.13.0-32-generic
  linux-image-4.13.0-36-generic linux-image-4.13.0-37-generic
  linux-image-4.13.0-38-generic linux-image-4.13.0-39-generic
  linux-image-extra-4.10.0-28-generic linux-image-extra-4.13.0-32-generic
  linux-image-extra-4.13.0-36-generic linux-image-extra-4.13.0-37-generic
  linux-image-extra-4.13.0-38-generic linux-image-extra-4.13.0-39-generic
  ttf-mscorefonts-installer
Use 'sudo apt autoremove' to remove them.
The following additional packages will be installed:
  putty-tools
Suggested packages:
  putty-doc
The following NEW packages will be installed:
  putty putty-tools
0 upgraded, 2 newly installed, 0 to remove and 24 not upgraded.
Need to get 662 kB of archives.
After this operation, 2,713 kB of additional disk space will be used.
Do you want to continue? [Y/n] y
Get:1 http://kr.archive.ubuntu.com/ubuntu xenial/universe amd64 putty-tools amd64 0.67-2 [342 kB]
Get:2 http://kr.archive.ubuntu.com/ubuntu xenial/universe amd64 putty amd64 0.67-2 [321 kB]
Fetched 662 kB in 0s (1,889 kB/s)
Selecting previously unselected package putty-tools.
(Reading database ... 431388 files and directories currently installed.)
Preparing to unpack .../putty-tools_0.67-2_amd64.deb ...
Unpacking putty-tools (0.67-2) ...
Selecting previously unselected package putty.
Preparing to unpack .../putty_0.67-2_amd64.deb ...
Unpacking putty (0.67-2) ...
Processing triggers for man-db (2.7.5-1) ...
Processing triggers for bamfdaemon (0.5.3~bZR0+16.04.20180209-0ubuntu1) ...
Rebuilding /usr/share/applications/bamf-2.index...
Processing triggers for gnome-menus (3.13.3-6ubuntu3.1) ...
Processing triggers for desktop-file-utils (0.22-1ubuntu5.1) ...
Processing triggers for mime-support (3.59ubuntu1) ...
Setting up putty-tools (0.67-2) ...
Setting up putty (0.67-2) ...
```

~/hw_sw_co_design/software\$ sudo chmod 666 /dev/ttyUSB1

~/hw_sw_co_design/software\$ putty

PuTTY Configuration

Category: **Basic options for your PuTTY session**

▼ Session

Logging

▼ Terminal

Keyboard

Bell

Features

▼ Window

Appearance

Behaviour

Translation

Selection

Colours

Fonts

▼ Connection

Data

Proxy

Telnet

Rlogin

► SSH

Specify the destination you want to connect to

Serial line: Speed:

Connection type:

☐ Raw ☐ Telnet ☐ Rlogin ☐ SSH ☒ Serial

Load, save or delete a stored session

Saved Sessions

Default Settings

Close window on exit:

☒ Always ☐ Never ☐ Only on clean exit

```

Sending discover...
Sending discover...
No lease, forking to background
done.

Built with PetaLinux v2015.4 (Yocto 1.8) software /dev/ttyPS0
software login: root
Password:
login[876]: root login on 'ttyPS0'
root@software:~#
root@software:~#
root@software:~# cd /dev
root@software:/dev# ;s
-sh: syntax error: unexpected ";"
root@software:/dev# ls
console          ram10            tty21            tty50
cpu_dma_latency ram11            tty22            tty51
flash           ram12            tty23            tty52
full            ram13            tty24            tty53
iio:device0     ram14            tty25            tty54
initctl         ram15            tty26            tty55
input           ram2             tty27            tty56
kmsg            ram3             tty28            tty57
loop-control    ram4             tty29            tty58
loop0           ram5             tty3             tty59
loop1           ram6             tty30            tty6
loop2           ram7             tty31            tty60
loop3           ram8             tty32            tty61
loop4           ram9             tty33            tty62
loop5           random          tty34            tty63
loop6           shm             tty35            tty7
loop7           snd             tty36            tty8
mem             tty             tty37            tty9
memory_bandwidth tty0            tty38            ttyPS0
mmcblk0         tty1            tty39            uio0
mmcblk0p1       tty10           tty4             urandom
mmcblk0p2       tty11           tty40            vcs
mtab            tty12           tty41            vcs1
network_latency tty13           tty42            vcsa
network_throughput tty14          tty43            vcsa1
null           tty15           tty44            vga_arbiter
port           tty16           tty45            watchdog
psaux          tty17           tty46            watchdog0
ptmx           tty18           tty47            xdevcfg
pts            tty19           tty48            zero
ram0           tty2            tty49
ram1           tty20           tty5
root@software:/dev# cd ../

```

uio0 이 잘 올라가 있는지 확인하자


```

root@software:/dev# cd ../
root@software:/# ls
bin    dev    home   lib    mnt    run    sys    usr
boot  etc    init   media  proc   sbin   tmp    var
root@software:/# cd bin
root@software:/bin# ls
ash                getopt            poke
busybox            grep              ps
busybox.nosuid     gunzip            pwd
busybox.suid       gzip              rm
cat                hostname          rmdir
chattr             kill              run-parts
chgrp              ln                sed
chmod              login             sh
chown              ls                sleep
cp                 mkdir             stat
cpio               mknod             stty
date               mktemp            su
dd                 more              sync
device_driver      mount             tar
df                 mountpoint        touch
dmesg              mountpoint.sysvinit true
dnsdomainname      mv                umount
dumpkmap            netstat           uname
echo                nice              upgrade-firmware
egrep              peek              usleep
false              pidof             vi
fatattr            pidof.sysvinit    watch
fgrep              ping              zcat
fwupgrade           ping6
root@software:/bin# cd ../
root@software:/# device_driver
.stage,apt/      etc/              mnt/              tmp/
.targetroot,apt/ home/             proc/             usr/
bin/              init              run/              var/
boot/             lib/              sbin/
dev/              media/            sys/
root@software:/# device_driver /dev/uio0 -o -0
GPIO UIO Test
device_driver: Bad address
Unvalid UIO Device File: (null)
*argv[0] -d <UIO_DEV_FILE> -i 1 -o <VALUE>
  -d UIO device file - ex) /dev/uio0 -i Input from GPIO
  -o <VALUE> Output to GPIO
root@software:/# device_driver -d /dev/uio0 -o -0
GPIO UIO Test
root@software:/# device_driver -d /dev/uio0 -o -1
GPIO UIO Test

```

bin 에 device_driver 가 잘 올라가 있는지 확인한 후
led 불을 켜다 켜다 해보자!

