

# TI DSP,MCU 및 Xilinx Zynq FPGA

## 프로그래밍 전문가 과정

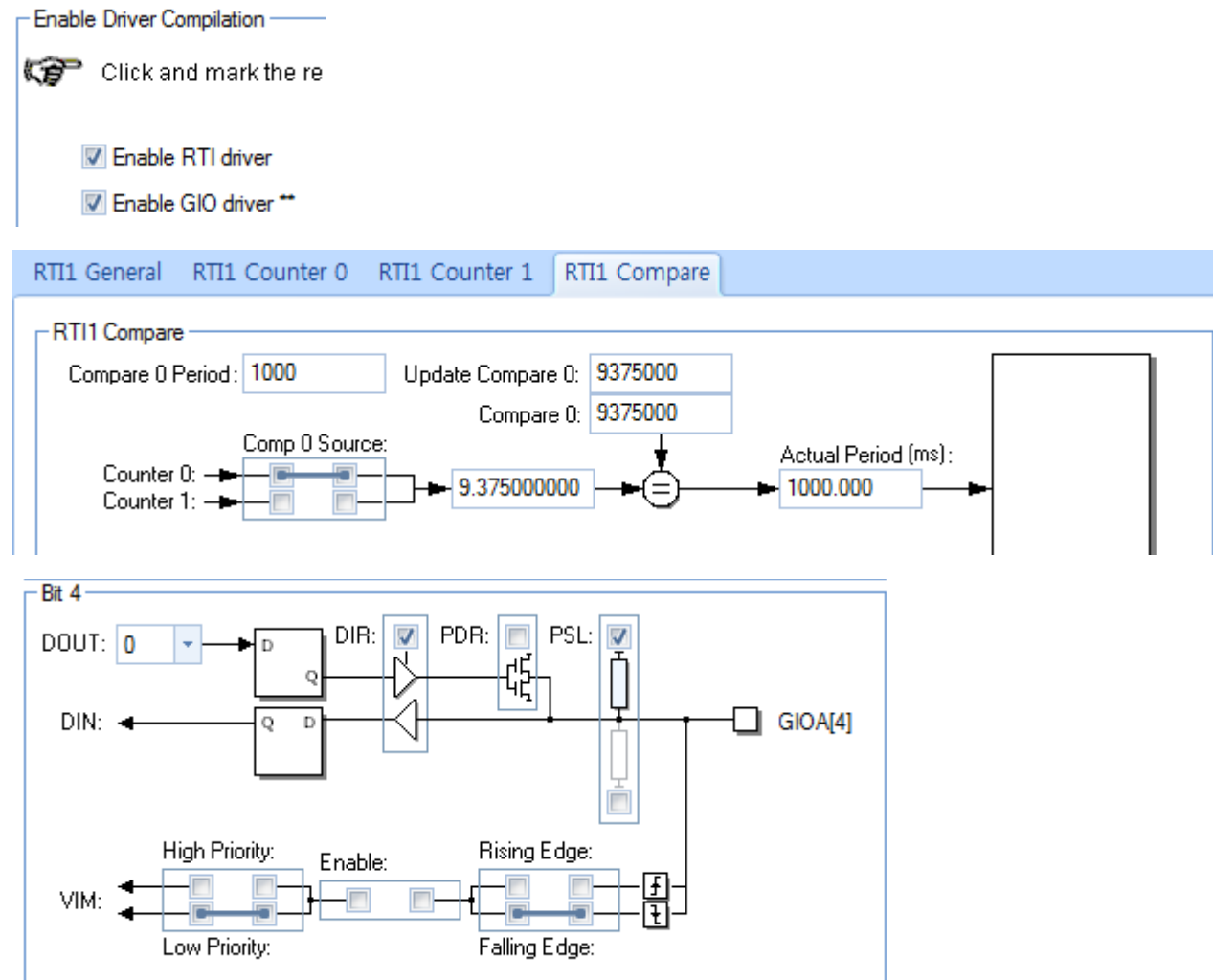
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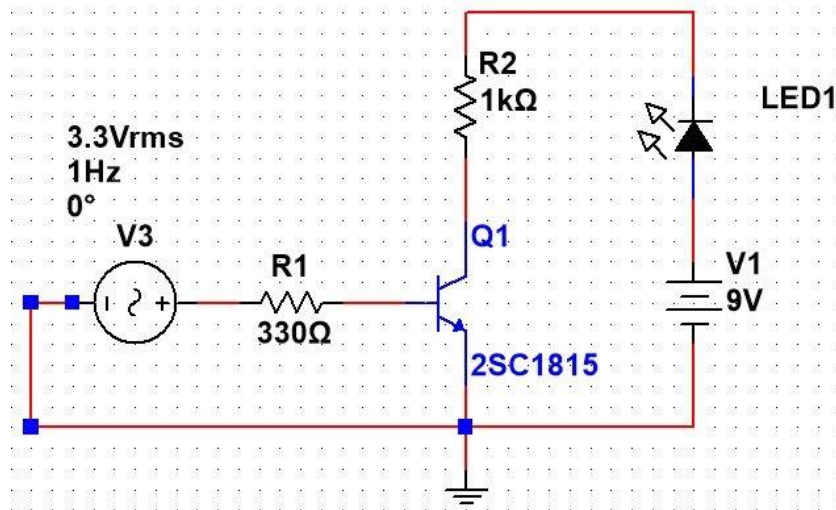
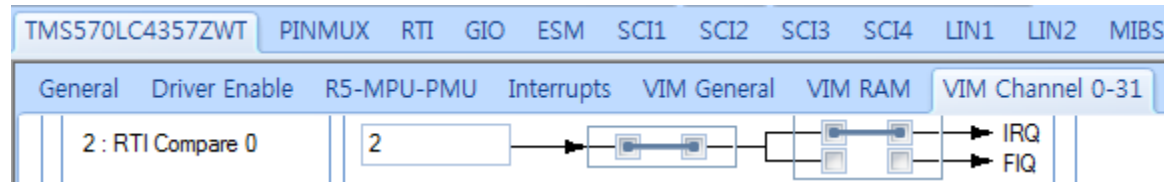
# 목차

1. OC\_circuit
2. ADC\_UART

# OC\_circuit

[HALcogen]설정





회로 구성

Open collector사용 이유

1. Open collector를 사용하지 않으면 항상 방전되어 소비전력이 커진다.
2. 유연한 인터럽트 동작을 위해, 하드웨어적으로만 회로를 구성하게 되면 정해진 동작밖에 하지 못하는데 소프트웨어적으로 인터럽트를
3. 두개의 전원으로 분리시킴

```
#include "HL_sys_common.h"
#include "HL_system.h"
```

```
#include "HL_sys_core.h"
#include "HL_mibspi.h"
#include "HL_esm.h"
#include "HL_rti.h"
#include "HL_gio.h"
#include "HL_het.h"
#include <stdlib.h>
#include <time.h>

unsigned int i = 0;
int t_flag = 0;

int main(void)
{
/* USER CODE BEGIN (3) */
    rtiInit();

    gioSetDirection(gioPORTA, 0xFFFFFFFF);

    rtiEnableNotification(rtiREG1, rtiNOTIFICATION_COMPARE0);

    _enable_IRQ_interrupt_();

    rtiStartCounter(rtiREG1, rtiCOUNTER_BLOCK0);
    srand(time(NULL));

    while(1);
/* USER CODE END */

    return 0;
}
```

```
void rtiNotification(rtiBASE_t *rtiREG, uint32 notification)
{
    unsigned int val = 0xAA060021;
    unsigned int val2= 0xFFFFFFFF;
    unsigned int a[9] = {0,5,25,18,29,27,17,31};

    /*i++;
    if(i>8)
    {i =0;
    }*/
    i = rand() % 9;

    if(t_flag == 0)
    {
        t_flag = 1;
        gioSetPort(hetPORT1, gioGetPort(hetPORT1) & ~(val));

    }
    else{
        gioSetPort(hetPORT1, gioGetPort(hetPORT1) | 1<<a[i]);
        t_flag = 0;
    }

}
```

# ADC\_UART

- ☒ Enable GIO driver \*\*
- ☒ Enable SCI drivers
  - ☐ Enable SCI3 driver \*\*
  - ☐ Enable SCI4 driver \*\*
- ☐ Enable LIN drivers
  - ☐ Enable LIN1 driver \*\* / ☒ Enable SCI1 driver \*\*
  - ☐ Enable LIN2 driver \*\* / ☐ Enable SCI2 driver \*\*
- ☒ Enable ADC drivers
  - ☒ Enable ADC1 driver \*\*
  - ☐ Enable ADC2 driver \*\*

ADC1 General   ADC1 Group Event   ADC1 Group 1   ADC1 Group 2   ADC1 Memory

ADC1 Configuration

Cycle Time (ns):

VCLK1 (MHz):  → Prescale:  → Actual Cycle Time (ns):

☐ RAM Parity enable

ADC1 General   ADC1 Group Event   ADC1 Group 1   ADC1 Group 2   ADC1 Memory   ADC1 F

ADC1 Group 1 Configuration

RiFo Size:    ☒ Enable Channel Id in Conversion Results

Data Resolution (Bit):    ☐ Enable Continuous Conversion

ADC1 Group 1 Trigger

Default Trigger:    Rising Edge   Hardware

Alternate Trigger:    Falling Edge   SW Trigger   Software

ADC1 Group 1 Sampling

Start: tScan → tDischarge → tSample → tConversion → End:

☐ Enable Sampling Capacitor Discharge   Discharge Time:

Discharge Prescaler:  → tDischarge (ns):

Cycle Time:  → Sample Time:

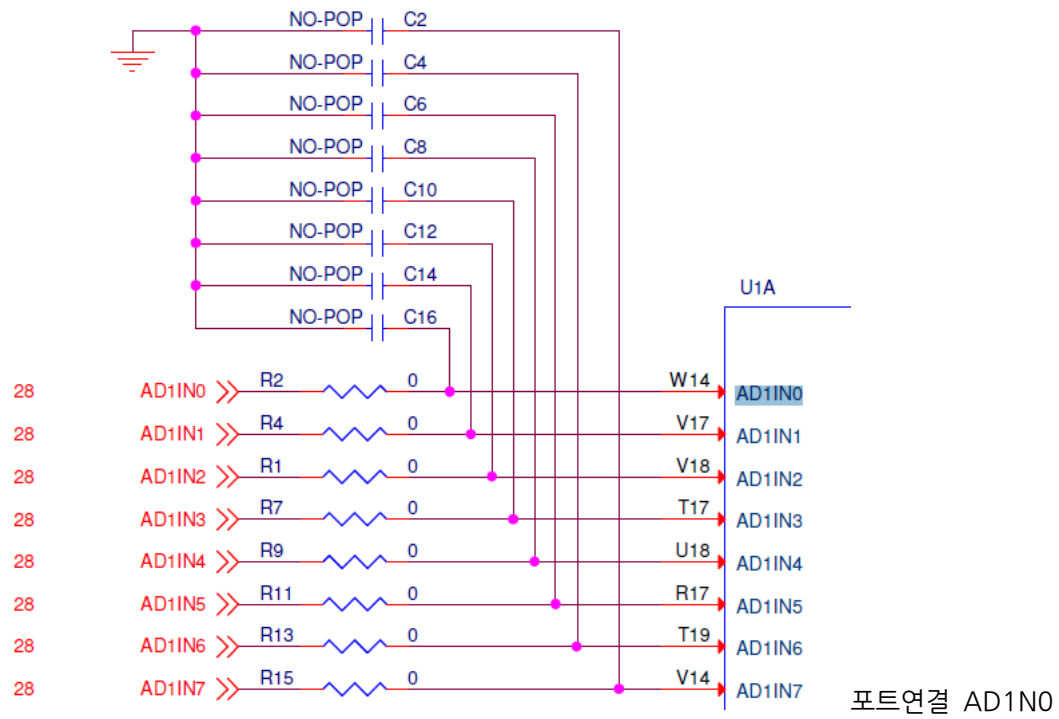
Sample Prescaler:  → tSample (ns):

tScanTotal (ns):    tExtended (ns):    tConversion (us):

tTotal (us):

ADC1 Group 1 Channel Selection

<input checked="" type="checkbox"/> Enable Pin 0	<input checked="" type="checkbox"/> Enable Pin 1	<input type="checkbox"/> Enable Pin 2	<input type="checkbox"/> Enable Pin 3
<input type="checkbox"/> Enable Pin 4	<input type="checkbox"/> Enable Pin 5	<input type="checkbox"/> Enable Pin 6	<input type="checkbox"/> Enable Pin 7
<input type="checkbox"/> Enable Pin 8	<input type="checkbox"/> Enable Pin 9	<input type="checkbox"/> Enable Pin 10	<input type="checkbox"/> Enable Pin 11
<input type="checkbox"/> Enable Pin 12	<input type="checkbox"/> Enable Pin 13	<input type="checkbox"/> Enable Pin 14	<input type="checkbox"/> Enable Pin 15
<input type="checkbox"/> Enable Pin 16	<input type="checkbox"/> Enable Pin 17	<input type="checkbox"/> Enable Pin 18	<input type="checkbox"/> Enable Pin 19
<input type="checkbox"/> Enable Pin 20	<input type="checkbox"/> Enable Pin 21	<input type="checkbox"/> Enable Pin 22	<input type="checkbox"/> Enable Pin 23
<input type="checkbox"/> Enable Pin 24	<input type="checkbox"/> Enable Pin 25	<input type="checkbox"/> Enable Pin 26	<input type="checkbox"/> Enable Pin 27
<input type="checkbox"/> Enable Pin 28	<input type="checkbox"/> Enable Pin 29	<input type="checkbox"/> Enable Pin 30	<input type="checkbox"/> Enable Pin 31



```
#include "HL_system.h"
#include "HL_sys_common.h"

#include "HL_esm.h"
#include "HL_adc.h"
#include "HL_sci.h"
#include "HL_gio.h"
```



```

#define TSIZE1  12
uint8 TEXT1[TSIZE1] = {'W', 'r', '\n', '|', 't', 'C', 'H', '.', '|', 'D', '=', '0', 'x'};
#define TSIZE2  9
uint8  TEXT2[TSIZE2] = {'W', 't', 'V', 'A', 'L', 'U', 'E', '=', '0', 'x'};

adcData_t adc_data[2];
void sciDisplayText(sciBASE_t *sci, uint8 *text, uint32 length);
void sciDisplayData(sciBASE_t *sci, uint8 *text, uint32 length);
void wait(uint32 time);

int main(void)
{
    uint32 ch_count = 0;
    uint32 id = 0;
    uint32 value = 0;

    gpioInit(); //HALcogen설정에 맞춘 gpio코드
    gpioSetDirection(gioPORTB, 1);

    sciInit(); //HALcogen설정에 맞춘 sci코드

    adcInit(); //HALcogen설정에 맞춘 adc코드
    adcStartConversion(adcREG1, adcGROUP1);

    for(;;)
    {
        gpioSetBit(gioPORTB, 0, 1); //시작
        while((adclIsConversionComplete(adcREG1, adcGROUP1)) == 0) //샘플링하는 구간
            ;
        ch_count = adcGetData(adcREG1, adcGROUP1, &adc_data[0]);
    }
}

```

```
id = adc_data[0].id; // 데이터 받은 핀  
value = adc_data[0].value; //샘플링 값
```

```
gioSetBit(gioPORTB, 0, 0); //샘플링 끝
```

```
sciDisplayText(sciREG1, &TEXT1[0], TSIZE1);  
sciDisplayData(sciREG1, (uint8 *)&id, 4);  
sciDisplayText(sciREG1, &TEXT2[0], TSIZE2);  
sciDisplayData(sciREG1, (uint8 *)&value, 4);
```

```
/* pin1은 사용하지 않으므로 주석처리  
id = adc_data[1].id;  
value = adc_data[1].value;
```

```
sciDisplayText(sciREG1, &TEXT1[0], TSIZE1);  
sciDisplayData(sciREG1, (uint8 *)&id, 4);  
sciDisplayText(sciREG1, &TEXT2[0], TSIZE2);  
sciDisplayData(sciREG1, (uint8 *)&value, 4);
```

```
wait(0xFFFFF);  
*/
```

```
}
```

```
return 0;
```

```
}
```

```
void sciDisplayData(sciBASE_t *sci, uint8 *text, uint32 length)
```

```
{
```

```
uint8 txt = 0;
```

```
uint8 txt1 = 0;
```

```

#if ((__little_endian__ == 1) || (__LITTLE_ENDIAN__ == 1))
    text = text + (length - 1);
#endif

    while(length--)
    {
#if((__little_endian__ == 1) || (__LITTLE_ENDIAN__ == 1))
        txt = *text--;
#else
        txt = *text++;
#endif
        txt1 = txt;

        txt &= ~(0xF0);
        txt1 &= ~(0x0F);
        txt1 = txt1 >> 4;

        if(txt <= 0x9)
        {
            txt += 0x30;
        }
        else if(txt > 0x9 && txt < 0xF)
        {
            txt = 0x37;
        }
        else
        {
            txt = 0x30;
        }
        if(txt1 <= 0x9)
        {
            txt1 += 0x30;

```

```

    }
    else if((txt1 > 0x9) && (txt1 <= 0xF))
    {
        txt += 0x37;
    }
    else
    {
        txt1 = 0x30;
    }

    while((sciREG1->FLR & 0x4) == 4)
        ;
    sciSendByte(sciREG1, txt1);

    while((sciREG1->FLR & 0x4) == 4)
        ;
    sciSendByte(sciREG1, txt);
}
}

void sciDisplayText(sciBASE_t *sci, uint8 *text, uint32 length)
{
    while(length--)
    {
        while((sciREG1->FLR & 0x4) == 4)
            ;
        sciSendByte(sciREG1, *text++);
    }
}

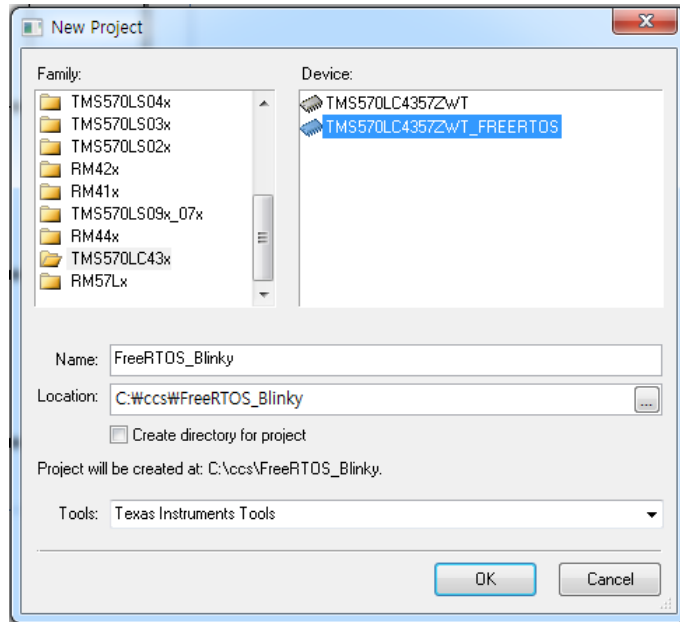
void wait(uint32 time)
{

```

```
while(time)
{
    time--;
}
}
```

# FreeRTOS\_Blinky

[HALcogen] 설정



project설정

## Enable Driver Compilation

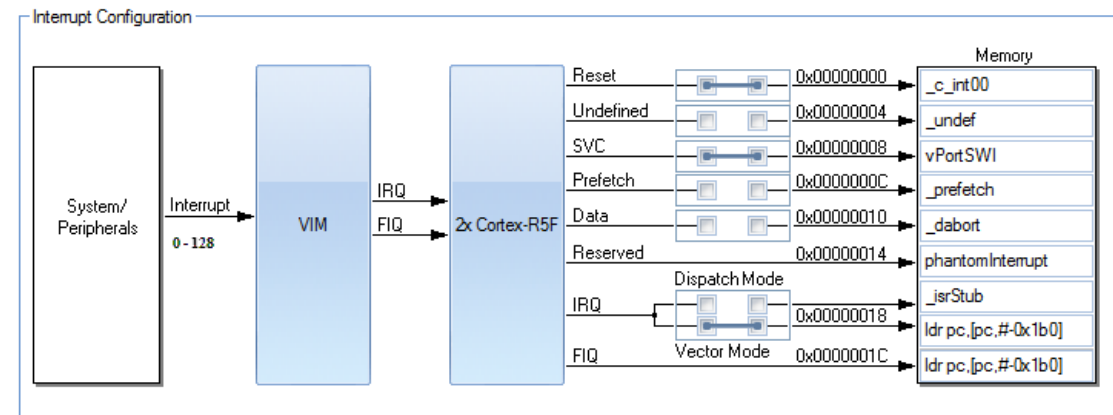


Click and mark the required modules for driver compilation from below:

☐ Enable RTI driver

☒ Enable GIO driver \*\*

☐ Mark/Unmark all drivers

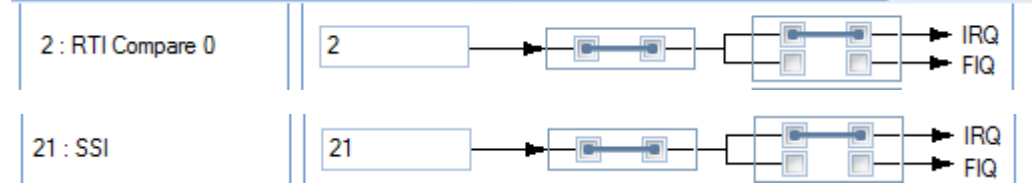


VIM RAM : ISR Assignments

Base Address: 0xFF82000 ☒ VIM RAM ECC enable

0x00000000:PH	phantomInterrupt	0x00000040:15	adc1Group1Interrupt	0x0000
0x00000004:00	esmHighInterrupt	0x00000044:16	can1HighLevelInterrupt	0x0000
0x00000008:01	phantomInterrupt	0x00000048:17	spi2HighLevelInterrupt	0x0000
0x0000000C:02	vPortPreemptiveTick	0x0000004C:18	phantomInterrupt	0x0000
0x00000010:03	phantomInterrupt	0x00000050:19	crcInterrupt	0x0000
0x00000014:04	phantomInterrupt	0x00000054:20	esmLowInterrupt	0x0000
0x00000018:05	phantomInterrupt	0x00000058:21	vPortYieldWithinAPI	0x0000
0x0000001C:06	phantomInterrupt	0x0000005C:22	phantomInterrupt	0x0000
0x00000020:07	phantomInterrupt	0x00000060:23	gioLowLevelInterrupt	0x0000
0x00000024:08	phantomInterrupt	0x00000064:24	het1LowLevelInterrupt	0x0000
0x00000028:09	gioHighLevelInterrupt	0x00000068:25	phantomInterrupt	0x0000
0x0000002C:10	het1HighLevelInterrupt	0x0000006C:26	mibspi1LowLevelInterrupt	0x0000
0x00000030:11	phantomInterrupt	0x00000070:27	lin1LowLevelInterrupt	0x0000
0x00000034:12	mibspi1HighLevelInterrupt	0x00000074:28	adc1Group2Interrupt	0x0000
0x00000038:13	lin1HighLevelInterrupt	0x00000078:29	can1LowLevelInterrupt	0x0000
0x0000003C:14	adc1Group0Interrupt	0x0000007C:30	mibspi2LowLevelInterrupt	0x0000

General Driver Enable R5-MPU-PMU Interrupts VIM General VIM RAM VIM Channel 0-31



TMS570LC4357ZWT\_FREERTOS OS PINMUX GIO ESM SCI1 SCI2 SCI3 SCI4 LIN

General

Configuration

Configuration options will set macros in FreeRTOSConfig.h

<input checked="" type="checkbox"/> Use Task Preemption	<input type="checkbox"/> Use Mutexes	<input checked="" type="checkbox"/> Use Verbose Stack Checking
<input type="checkbox"/> Use Idle Hook	<input type="checkbox"/> Use Recursive Mutexes	<input type="checkbox"/> Use Timers
<input type="checkbox"/> Use Tick Hook	<input type="checkbox"/> Use Counting Semaphores	<input type="checkbox"/> Generate Runtime Statistics
<input type="checkbox"/> Use Co-Routines	<input checked="" type="checkbox"/> Idle Task Should Yield	<input type="checkbox"/> Use Malloc Failed Hook
<input type="checkbox"/> Use Trace Facility	<input type="checkbox"/> Use Stack Overflow Hook	



```

#include "HL_sys_common.h"
#include "FreeRTOS.h"
#include "os_task.h"
#include "HL_het.h"
#include "HL_gio.h"

xTaskHandle xTask1Handle;

void vTask1(void *pvParameters) //태스크 생성 성공하면 자식 프로세스가 실행
{
    for(;;)
    {
        gioSetBit(hetPORT1, 17, gioGetBit(hetPORT1, 17) ^ 1 );
        vTaskDelay(100); //지연
    }
}

int main(void)
{
    gioSetDirection(hetPORT1, 0xFFFFFFFF); //hetPORT1사용

    if(xTaskCreate(vTask1, "Task1", configMINIMAL_STACK_SIZE, NULL, 1, &xTask1Handle) != pdTRUE) //태스크 생성 실패시 if문 만족
        /*RTOS의 태스크를 생성(fork와 같은것)
        Task1이라는 태스크가 생성됨.
        최소한의 스택 사이즈를 configMINIMAL_STACK_SIZE*/
    {
        while(1);
    }
    vTaskStartScheduler(); //태스크 생성 성공 시 부모 프로세스가 실행

    return 0;
}

```