

# TI DSP, MCU, Xilinx Zynq FPGA Based Programming Expert Program

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Mov r0, r1, N

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r0,#0xff,8");
22
23     printf("r0 = 0x%x\n",r0);
24     return 0;
25 }
```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm11.c
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r0 = 0xff000000
```

lsl option

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r1,#7");
22     asm volatile("mov r2,#3");
23     asm volatile("add r0,r1,r2,lsl #7");
24
25     printf("r0 = %d\n",r0);
26     return 0;
27 }
```

```
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r0 = 391
```

asm15.c (~/HomeworkBackup/45th) - VIM

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r1,#2");
22     asm volatile("add r0,r1,r1,lsr #2");
23
24     printf("r0 = 0x%x\n",r0);
25     return 0;
26 }
```

```
howl@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r0 = 0xa
```

asr option

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 1;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r1,#32");
22     asm volatile("add r0,r1,asr #2");
23
24     printf("r0 = 0x%x\n",r0);
25     return 0;
26 }
```

```
howl@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm16.c
```

```
howl@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r0 = 0x9
```

mrs(Mov Register Statusregister)

```

1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r1,#32");
22     asm volatile("add r0,r1,asr #2");
23     asm volatile("mrs r0,cpsr");
24
25     show_reg(r0);
26     return 0;
27 }

```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm17.c  
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out  
0110000000000000000000000000000000000000
```

mul a, b, c

```

1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;){
7         printf("%d", (reg>>i--)&1);
8         printf("\n");
9     }
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r2,#3");
22     asm volatile("mov r3,#7");
23     asm volatile("mul r1,r2,r3");
24
25     printf("r1=%d\n",r1);
26     // show_reg(r0);
27     return 0;
28 }

```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm18.c
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r1=21
```

mula a, b, c, d (MuLtiply-Accumulate)

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r2,#3");
22     asm volatile("mov r3,#7");
23     asm volatile("mov r4,#33");
24     asm volatile("mula r1,r2,r3,r4");
25
26     printf("r1=%d\n",r1);
27 // show_reg(r0);
28     return 0;
29 }
```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm19.c
```

```
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r1=54
```

umull a, b, c, d

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11
12 int main(void){
13
14     register unsigned int r0 asm("r0") = 0;
15     register unsigned int r1 asm("r1") = 0;
16     register unsigned int r2 asm("r2") = 0;
17     register unsigned int r3 asm("r3") = 0;
18     register unsigned int r4 asm("r4") = 0;
19     register unsigned int r5 asm("r5") = 0;
20
21     asm volatile("mov r2,#0x44,8");
22     asm volatile("mov r3,#0x200");
23     asm volatile("umull r0,r1,r2,r3");
24
25     printf("r1r0=0x%x%08x\n",r1,r0);
26
27 // show_reg(r0);
28     return 0;
29 }
```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm20.c
```

```
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
r1r0=0x8800000000
```

umlal a, b, c, d

```
1 #include <stdio.h>
2
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11 int main(void){
12
13     register unsigned int r0 asm("r0") = 0;
14     register unsigned int r1 asm("r1") = 0;
15     register unsigned int r2 asm("r2") = 0;
16     register unsigned int r3 asm("r3") = 0;
17     register unsigned int r4 asm("r4") = 0;
18     register unsigned int r5 asm("r5") = 0;
19
20     asm volatile("mov r0,#0xf");
21     asm volatile("mov r1,#0x1");
22     asm volatile("mov r2,#0x44, 8");
23     asm volatile("mov r3,#0x200");
24     asm volatile("umlal r0,r1,r2,r3");
25
26     printf("r1r0=0x%x%x08x\n",r1,r0);
27
28 // show_reg(r0);
29     return 0;
30 }
```

howi@ubuntu:~/HomeworkBackup/45th\$ arm-linux-gnueabi-gcc -g asm21.c

howi@ubuntu:~/HomeworkBackup/45th\$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out  
r1r0=0x890000000f

ldr a, [b]

```
1 #include <stdio.h>
2 unsigned int arr[5] = {1, 2, 3, 4, 5};
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11 int main(void){
12
13     register unsigned int r0 asm("r0") = 0;
14     register unsigned int *r1 asm("r1") = NULL;
15     register unsigned int *r2 asm("r2") = NULL;
16     register unsigned int r3 asm("r3") = 0;
17     register unsigned int r4 asm("r4") = 0;
18     register unsigned int r5 asm("r5") = 0;
19
20     r1 = arr;
21
22     asm volatile("mov r2,#0x4");
23     asm volatile("ldr r0, [r1, #0x4]");
24
25     printf("r0=%u, r1=%u\n",r0, *r1);
26
27 // show_reg(r0);
28     return 0;
29 }
```

howi@ubuntu:~/HomeworkBackup/45th\$ arm-linux-gnueabi-gcc -g asm22.c

howi@ubuntu:~/HomeworkBackup/45th\$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out  
r0=2, r1=1

strb

```
1 #include <stdio.h>
2 char test[32] = "HelloARM";
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9 }
10
11 int main(void){
12
13     register unsigned int r0 asm("r0") = 0;
14     register char *r1 asm("r1") = NULL;
15     register unsigned int *r2 asm("r2") = NULL;
16     register unsigned int r3 asm("r3") = 0;
17     register unsigned int r4 asm("r4") = 0;
18     register unsigned int r5 asm("r5") = 0;
19
20     r1 = &test[5];
21
22     asm volatile("mov r0, #97");
23     asm volatile("strb r0,[r1]");
24
25     printf("test=%s\n",test);
26
27     // show_reg(r0);
28     return 0;
29 }
```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm24.c
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
test=HelloaRM
```

ldr a, [b, c]

```
1 #include <stdio.h>
2 char test[32] = "HelloARM";
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9 }
10
11 int main(void){
12
13     register char r0 asm("r0") = 0;
14     register char *r1 asm("r1") = NULL;
15     register unsigned int r2 asm("r2") = 0;
16     register unsigned int r3 asm("r3") = 0;
17     register unsigned int r4 asm("r4") = 0;
18     register unsigned int r5 asm("r5") = 0;
19
20     r1 = test;
21
22     asm volatile("mov r2, #0x5");
23     asm volatile("ldr r0,[r1,r2]");
24
25     printf("test=%s, r1=%s, r0=%c\n",test, r1, r0);
26
27     // show_reg(r0);
28     return 0;
29 }
```

```
howi@ubuntu:~/HomeworkBackup/45th$ arm-linux-gnueabi-gcc -g asm25.c
howi@ubuntu:~/HomeworkBackup/45th$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out
test=HelloARM, r1=HelloARM, r0=A
```

ldr a, [b], c

```
1 #include <stdio.h>
2 unsigned int arr[5] = {1, 2, 3, 4, 5};
3 void show_reg(unsigned int reg){
4     int i;
5
6     for(i=31;i>=0;)
7         printf("%d", (reg>>i--)&1);
8     printf("\n");
9
10 }
11 int main(void){
12
13     register unsigned int r0 asm("r0") = 0;
14     register unsigned int *r1 asm("r1") = NULL;
15     register unsigned int *r2 asm("r2") = NULL;
16     register unsigned int r3 asm("r3") = 0;
17     register unsigned int r4 asm("r4") = 0;
18     register unsigned int r5 asm("r5") = 0;
19
20     r1 = arr;
21
22     asm volatile("mov r2, #0x10");
23     asm volatile("ldr r0,[r1],r2");
24
25     printf("r0=%u,r1 = %u\n",r0,*r1);
26
27 // show_reg(r0);
28     return 0;
29 }
```

howi@ubuntu:~/HomeworkBackup/45th\$ arm-linux-gnueabi-gcc -g asm26.c

howi@ubuntu:~/HomeworkBackup/45th\$ qemu-arm-static -L /usr/arm-linux-gnueabi ./a.out  
r0=1,r1 = 5