

# TI DSP, MCU 및 Xilinx Zynq FPGA 프로그래밍 전문가 과정

- BMP280 -

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# 1. HALCOGEN 설정

TMS570LC4357ZWT PINMUX RTI GIO ESM SCI1 SCI2 SCI3 SCI4 LIN1

General Driver Enable R5-MPU-PMU Interrupts VIM General VIM RAM VIM C

Enable Driver Compilation

Click and mark the required modules for driver compilation from below:

☐ Enable RTI driver ☐ Mark/Unmark all drivers

☐ Enable GIO driver \*\*

☒ Enable SCI drivers

☐ Enable SCI3 driver \*\*

☐ Enable SCI4 driver \*\*

☐ Enable LIN drivers

☐ Enable LIN1 driver \*\*

☒ Enable SCI1 driver \*\*

☐ Enable LIN2 driver \*\*

☒ Enable SCI2 driver \*\*

☐ Enable MIBSPI drivers

☐ Enable MIBSPI1 driver \*\*

☐ Enable MIBSPI2 driver \*\*

☐ Enable MIBSPI3 driver \*\*

☐ Enable MIBSPI4 driver \*\*

☐ Enable MIBSPI5 driver \*\*

☐ Enable SPI1 driver \*\*

☐ Enable SPI2 driver \*\*

☐ Enable SPI3 driver \*\*

☐ Enable SPI4 driver \*\*

☐ Enable SPI5 driver \*\*

☐ Enable CAN drivers

☐ Enable CAN1 driver

☐ Enable CAN2 driver

☐ Enable CAN3 driver

☐ Enable CAN4 driver \*\*

☐ Enable ADC drivers

☐ Enable ADC1 driver \*\*

☐ Enable ADC2 driver \*\*

☐ Enable HET drivers

☐ Enable HET1 driver \*\*

☐ Enable HET2 driver \*\*

☒ Enable I2C driver \*\*

☐ Enable I2C1 driver \*\*

☒ Enable I2C2 driver \*\*

☐ Enable EMAC driver \*\*

Enable / Disable Peripherals

☐ HET1 ☐ GIOA ☐ MIBSPI2 ☐ MIBSPI1 ☐ SCI3 ☐ RMI

☐ HET2 ☐ GIOB ☐ MIBSPI4 ☐ MIBSPI3 ☐ SCI4 ☐ MII

☐ EMIF ☐ EQEP ☐ AD1EVT ☐ MIBSPI5 ☐ LIN2/SCI2 ☐ CAN4

☐ ETPWM ☐ ECAP ☐ AD2EVT ☐ I2C1 ☒ I2C2

Note  
GIO pins and alternate functions have RMI and Special

Ball Default Mux Mux Option 1 Mux Option 2 Mux Option 3

A4 N2HET1[16] NONE NONE ETPWM1SYNCR

TMS570LC4357ZWT PINMUX RTI GIO ESM SCI1 SCI2 SCI3 SCI4 LIN1 LIN2

I2C Global I2C Clocks I2C Port

Global Config

☒ Enable Master Mode Tx / Rx: TRANSMITTER

Add mode: 7BIT\_AMODE Bit Count: 8\_BIT Ignore NACK

Data Count: 8

☐ Enable Repeat Mode (Only in Master Mode) ☐ Enable Free Data Format ☐ Compatibility Mode

NOTE: Stop Condition is generated by the device.

Interrupts

TMS570LC4357ZWT PINMUX RTI GIO ESM SCI1 SCI2 SCI3 SCI4 LIN1 LIN2

I2C Global I2C Clocks I2C Port

Data Format

Baudrate: 400

Prescale: 8 Module Clock Frequency: 8

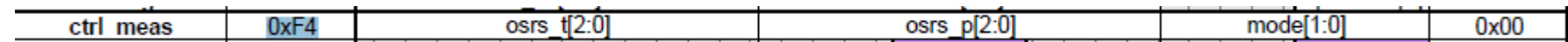
VCLK1 (MHz): 75.0

ICCH: 5

ICCL: 5

# 2. Register

```
BMP280_REGISTER_CONTROL, 0x3F, 0011 1111
```



## 3.6 Power modes

The BMP280 offers three power modes: sleep mode, forced mode and normal mode. These can be selected using the mode[1:0] bits in control register 0xF4.

Table 10: mode settings

mode[1:0]	Mode
00	Sleep mode
01 and 10	Forced mode
11	Normal mode

### 3.3.2 Temperature measurement

Temperature measurement can be enabled or skipped. Skipping the measurement could be useful to measure pressure extremely rapidly. When enabled, several oversampling options exist. Each oversampling step reduces noise and increases the output resolution by one bit, which is stored in the XLSB data register 0xFC. Enabling/disabling the temperature measurement and oversampling setting are selected through the osrs\_t[2:0] bits in control register 0xF4.

Table 5: osrs\_t settings

osrs_t[2:0]	Temperature oversampling	Typical temperature resolution
000	Skipped (output set to 0x80000)	–
001	×1	16 bit / 0.0050 °C
010	×2	17 bit / 0.0025 °C
011	×4	18 bit / 0.0012 °C
100	×8	19 bit / 0.0006 °C
101, 110, 111	×16	20 bit / 0.0003 °C

## 4.3.4 Register 0xF4 “ctrl\_meas”

The “ctrl\_meas” register sets the data acquisition options of the device.

Table 20: Register 0xF4 “ctrl\_meas”

Register 0xF4 “ctrl_meas”	Name	Description
Bit 7, 6, 5	osrs_t[2:0]	Controls oversampling of temperature data. See chapter 3.3.2 for details.
Bit 4, 3, 2	osrs_p[2:0]	Controls oversampling of pressure data. See chapter 3.3.1 for details.
Bit 1, 0	mode[1:0]	Controls the power mode of the device. See chapter 3.6 for details.

Table 21: register settings osrs\_p

osrs_p[2:0]	Pressure oversampling
000	Skipped (output set to 0x80000)
001	oversampling ×1
010	oversampling ×2
011	oversampling ×4
100	oversampling ×8
101, Others	oversampling ×16

### 3. CODE 1

```
void BMP280_Init(void){
    if (read8(BMP280_REGISTER_CHIPID) != 0x58){
        disp_set("Wrong chipId");
        while(1);
    }
    bmp280_readCoefficients();
    writeByte(BMP280_ADDRESS, BMP280_REGISTER_CONTROL, 0x3F); // 01 1111
}
```

temp_lsb	0xFB	temp_lsb<7:0>	0x00
temp_msb	0xFA	temp_msb<7:0>	0x80

```
void bmp280_readCoefficients(void)
{
    _bmp280_calib.dig_T1 = read16_LE(BMP280_REGISTER_DIG_T1);
    _bmp280_calib.dig_T2 = readS16_LE(BMP280_REGISTER_DIG_T2);
    _bmp280_calib.dig_T3 = readS16_LE(BMP280_REGISTER_DIG_T3);

    _bmp280_calib.dig_P1 = read16_LE(BMP280_REGISTER_DIG_P1);
    _bmp280_calib.dig_P2 = readS16_LE(BMP280_REGISTER_DIG_P2);
    _bmp280_calib.dig_P3 = readS16_LE(BMP280_REGISTER_DIG_P3);
    _bmp280_calib.dig_P4 = readS16_LE(BMP280_REGISTER_DIG_P4);
    _bmp280_calib.dig_P5 = readS16_LE(BMP280_REGISTER_DIG_P5);
    _bmp280_calib.dig_P6 = readS16_LE(BMP280_REGISTER_DIG_P6);
    _bmp280_calib.dig_P7 = readS16_LE(BMP280_REGISTER_DIG_P7);
    _bmp280_calib.dig_P8 = readS16_LE(BMP280_REGISTER_DIG_P8);
    _bmp280_calib.dig_P9 = readS16_LE(BMP280_REGISTER_DIG_P9);

    _bmp280_calib.dig_H1 = read8(BMP280_REGISTER_DIG_H1);
    _bmp280_calib.dig_H2 = readS16_LE(BMP280_REGISTER_DIG_H2);
    _bmp280_calib.dig_H3 = read8(BMP280_REGISTER_DIG_H3);
    _bmp280_calib.dig_H4 = (read8(BMP280_REGISTER_DIG_H4) << 4) | (read8(BMP280_REGISTER_DIG_H4+1) & 0xF);
    _bmp280_calib.dig_H5 = (read8(BMP280_REGISTER_DIG_H5+1) << 4) | (read8(BMP280_REGISTER_DIG_H5) >> 4);
    _bmp280_calib.dig_H6 = (int8_t)read8(BMP280_REGISTER_DIG_H6);
}
```

Table 17: Compensation parameter storage, naming and data type

Register Address LSB / MSB	Register content	Data type
0x88 / 0x89	dig_T1	unsigned short
0x8A / 0x8B	dig_T2	signed short
0x8C / 0x8D	dig_T3	signed short
0x8E / 0x8F	dig_P1	unsigned short
0x90 / 0x91	dig_P2	signed short
0x92 / 0x93	dig_P3	signed short
0x94 / 0x95	dig_P4	signed short
0x96 / 0x97	dig_P5	signed short
0x98 / 0x99	dig_P6	signed short
0x9A / 0x9B	dig_P7	signed short
0x9C / 0x9D	dig_P8	signed short
0x9E / 0x9F	dig_P9	signed short
0xA0 / 0xA1	reserved	reserved

- 1. Read8함수로 0xD0를 읽어 리셋값이 0x58이 나와야 한다.
- 2. Bmp280\_readCoefficients함수를 보면 little endian방식으로 2bytes 씩 읽어 온다.
- 3. 2bytes 씩 읽어오므로 왼쪽과 같이 레지스터를 맵핑한다.

### 3. CODE 2

```
void BMP280_Init(void){
    if (read8(BMP280_REGISTER_CHIPID) != 0x58){
        disp_set("Wrong chipId");
        while(1);
    }
    bmp280_readCoefficients();
    writeByte(BMP280_ADDRESS, BMP280_REGISTER_CONTROL, 0x3F); // 01 1111
}
```

1. writeByte를 이용하여 컨트롤 레지스터에 0x3F를 입력한다. 데이터시트를 참고하면 0x3F가 무인지를 파악하고 본인이 사용하고 싶은 용도에 맞게 변형하여 값을 넣으면 된다.

### 3. CODE 3

```
float bmp280_readTemperature(void)
{
    int32_t adc_T = read24(BMP280_REGISTER_TEMPDATA);

    int32_t var1, var2;

    adc_T >>= 4;

    var1 = (((((adc_T>>3) - ((int32_t)_bmp280_calib.dig_T1 <<1))) *
              ((int32_t)_bmp280_calib.dig_T2)) >> 11;

    var2 = ((((((adc_T>>4) - ((int32_t)_bmp280_calib.dig_T1)) *
              ((adc_T>>4) - ((int32_t)_bmp280_calib.dig_T1))) >> 12) *
              ((int32_t)_bmp280_calib.dig_T3)) >> 14;

    t_fine = var1 + var2;

    float T = (t_fine * 5 + 128) >> 8;

    return T/100;
}
```

1. 온도를 읽어오는 함수로 간단히 설명하자면 **3bytes**를 읽어온다.
2. 우리가 사용할 **bit**는 **20bits**이기 때문에 **4bit**는 옮겨버리고 **var1**과 **var2**에 **bit**를 나누어 셋팅한다.
3. **t\_fine** 변수에 **var1**과 **var2**를 넣어 온도 변환하는 수식을 넣고 값을 출력한다.

## 2. CODE

```
float bmp280_readPressure(void)
{
    int64_t var1, var2, p;

    // Must be done first to get the t_fine variable set up
    bmp280_readTemperature();

    int32_t adc_P = read24(BMP280_REGISTER_PRESSUREDATA);
    adc_P >>= 4;

    var1 = ((int64_t)t_fine) - 128000;
    var2 = var1 * var1 * (int64_t)_bmp280_calib.dig_P6;
    var2 = var2 + ((var1*(int64_t)_bmp280_calib.dig_P5)<<17);
    var2 = var2 + (((int64_t)_bmp280_calib.dig_P4)<<35);
    var1 = ((var1 * var1 * (int64_t)_bmp280_calib.dig_P3)>>8) +
        ((var1 * (int64_t)_bmp280_calib.dig_P2)<<12);
    var1 = (((((int64_t)1)<<47)+var1))*((int64_t)_bmp280_calib.dig_P1)>>33;

    if (var1 == 0) {
        return 0; // avoid exception caused by division by zero
    }
    p = 1048576 - adc_P;
    p = (((p<<31) - var2)*3125) / var1;
    var1 = (((int64_t)_bmp280_calib.dig_P9) * (p>>13) * (p>>13)) >> 25;
    var2 = (((int64_t)_bmp280_calib.dig_P8) * p) >> 19;

    p = ((p + var1 + var2) >> 8) + (((int64_t)_bmp280_calib.dig_P7)<<4);
    return (float)p/256;
}
```

```
float bmp280_readAltitude(float seaLevel)
{
    // Equation taken from BMP180 datasheet (page 16):
    // http://www.adafruit.com/datasheets/BST-BMP180-DS000-09.pdf

    // Note that using the equation from wikipedia can give bad results
    // at high altitude. See this thread for more information:
    // http://forums.adafruit.com/viewtopic.php?f=22&t=58064

    float atmospheric = bmp280_readPressure() / 100.0F;

    return 44330.0 * (1.0 - pow(atmospheric / seaLevel, 0.1903));
}
```

1. readPressure함수도 위의 온도함수와 마찬가지로이다.
2. readAltitude 함수는 해수면의 높이를 파라미터로 받아와 압력 값과 해수면값을 이용하여 고도를 구한다.



### 3. SIMULATION

```
altitude = 25.297636    pressure = 101021.937500    temperature = 31.520000
altitude = 25.333424    pressure = 101021.468750    temperature = 31.500000
altitude = 25.333424    pressure = 101021.468750    temperature = 31.500000
altitude = 25.103075    pressure = 101024.226563    temperature = 31.500000
altitude = 25.208923    pressure = 101022.968750    temperature = 31.480000
altitude = 25.277473    pressure = 101022.171875    temperature = 31.469999
altitude = 25.344009    pressure = 101021.375000    temperature = 31.469999
altitude = 25.410543    pressure = 101020.578125    temperature = 31.459999
altitude = 25.246727    pressure = 101022.507813    temperature = 31.459999
altitude = 25.313766    pressure = 101021.710938    temperature = 31.450001
altitude = 25.285540    pressure = 101022.078125    temperature = 31.440001
altitude = 25.258320    pressure = 101022.406250    temperature = 31.420000
altitude = 25.258320    pressure = 101022.406250    temperature = 31.420000
altitude = 25.324350    pressure = 101021.609375    temperature = 31.420000
altitude = 25.687271    pressure = 101017.234375    temperature = 31.410000
altitude = 25.593515    pressure = 101018.390625    temperature = 31.400000
altitude = 25.132814    pressure = 101023.906250    temperature = 31.400000
altitude = 25.496233    pressure = 101019.523438    temperature = 31.389999
altitude = 25.401470    pressure = 101020.687500    temperature = 31.379999
altitude = 25.534540    pressure = 101019.085938    temperature = 31.370001
altitude = 25.534540    pressure = 101019.085938    temperature = 31.370001
altitude = 25.437761    pressure = 101020.218750    temperature = 31.360001
altitude = 25.706427    pressure = 101017.000000    temperature = 31.340000
altitude = 25.410040    pressure = 101020.585938    temperature = 31.340000
altitude = 25.772964    pressure = 101016.203125    temperature = 31.330000
altitude = 25.284531    pressure = 101022.078125    temperature = 31.320000
altitude = 25.351570    pressure = 101024.007813    temperature = 31.320000
altitude = 25.418608    pressure = 101020.453125    temperature = 31.309999
altitude = 25.390381    pressure = 101020.820313    temperature = 31.299999
altitude = 25.523451    pressure = 101019.195313    temperature = 31.290001
altitude = 25.226566    pressure = 101022.750000    temperature = 31.290001
altitude = 25.293100    pressure = 101021.953125    temperature = 31.290001
altitude = 25.265377    pressure = 101022.312500    temperature = 31.270000
altitude = 25.398951    pressure = 101020.687500    temperature = 31.260000
altitude = 25.168600    pressure = 101023.445313    temperature = 31.260000
altitude = 25.398951    pressure = 101020.687500    temperature = 31.260000
altitude = 25.140375    pressure = 101023.812500    temperature = 31.250000
altitude = 25.209932    pressure = 101022.945313    temperature = 31.240000
altitude = 25.209932    pressure = 101022.945313    temperature = 31.240000
altitude = 25.209932    pressure = 101022.945313    temperature = 31.240000
altitude = 25.346529    pressure = 101021.351563    temperature = 31.230000
```

1. 데이터시트를 보면 압력값은 300-1100hPa까지 측정이 가능하다.
2. 압력 값이 101021.375000으로 정상적으로 나온다. 하지만, 우리가 보기에는 너무 큰 숫자이므로, 100을 나누어 스케일링을 해서 출력을 하면 된다.
3. 고도와 온도는 정상적으로 나오는 것을 확인할 수 있다.