


New CCS Project

CCS Project

Create a new CCS Project.



Target:


<select or type filter text>

RM57L8xx

Connection:

Texas Instruments XDS100v2 USB Debug Probe

Verify...

 Cortex R [ARM]

Project name:

FreeRTOS_Blinky

☒ Use default location

Location:

C:\WMCU\FreeRTOS_Blinky

Browse...

Compiler version:


TI v16.9.1.LTS


More...


▶ Advanced settings


▼ Project templates and examples


type filter text


 Empty Projects


 Empty Project

 Empty Project (with main.c)

 Empty Assembly-only Project


 Empty RTSC Project

 Basic Examples

 Hello World

Creates an empty project fully initialized for the selected device.

Open [Resource Explorer](#) to browse a wide selection of example projects...



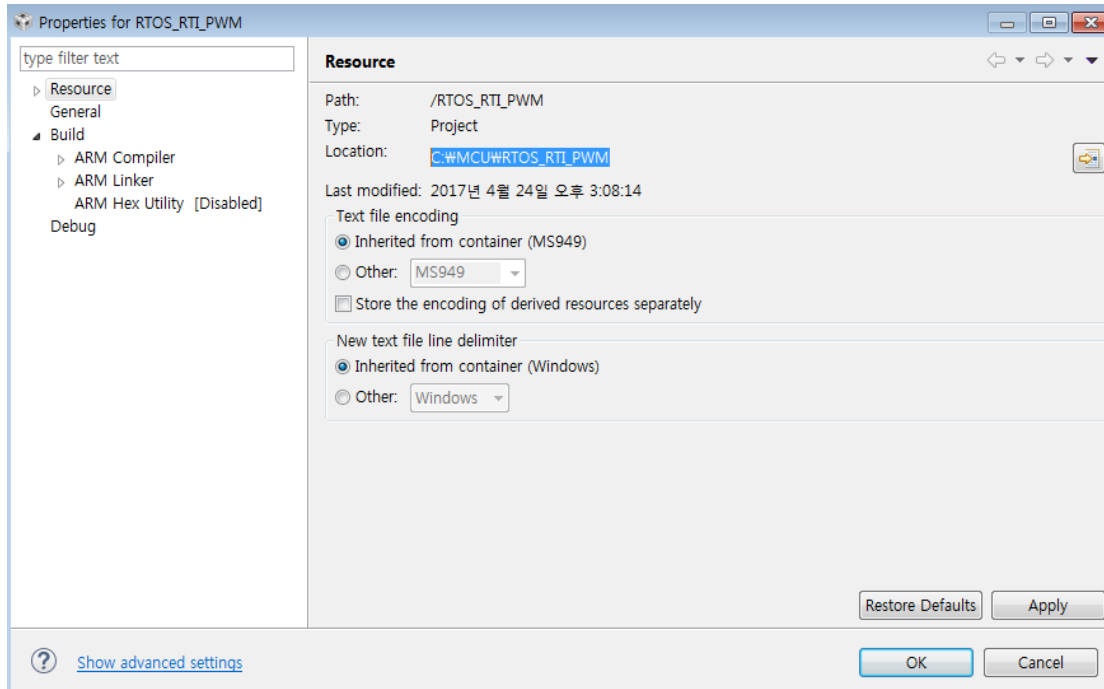
< Back

Next >

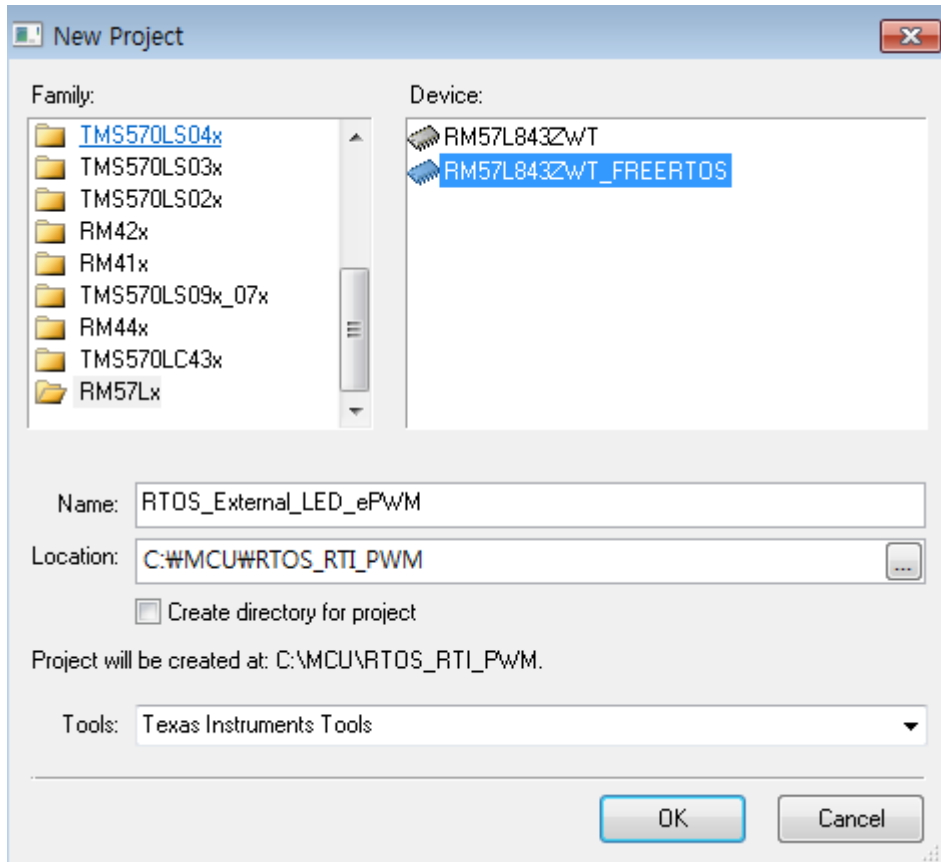
Finish

Cancel

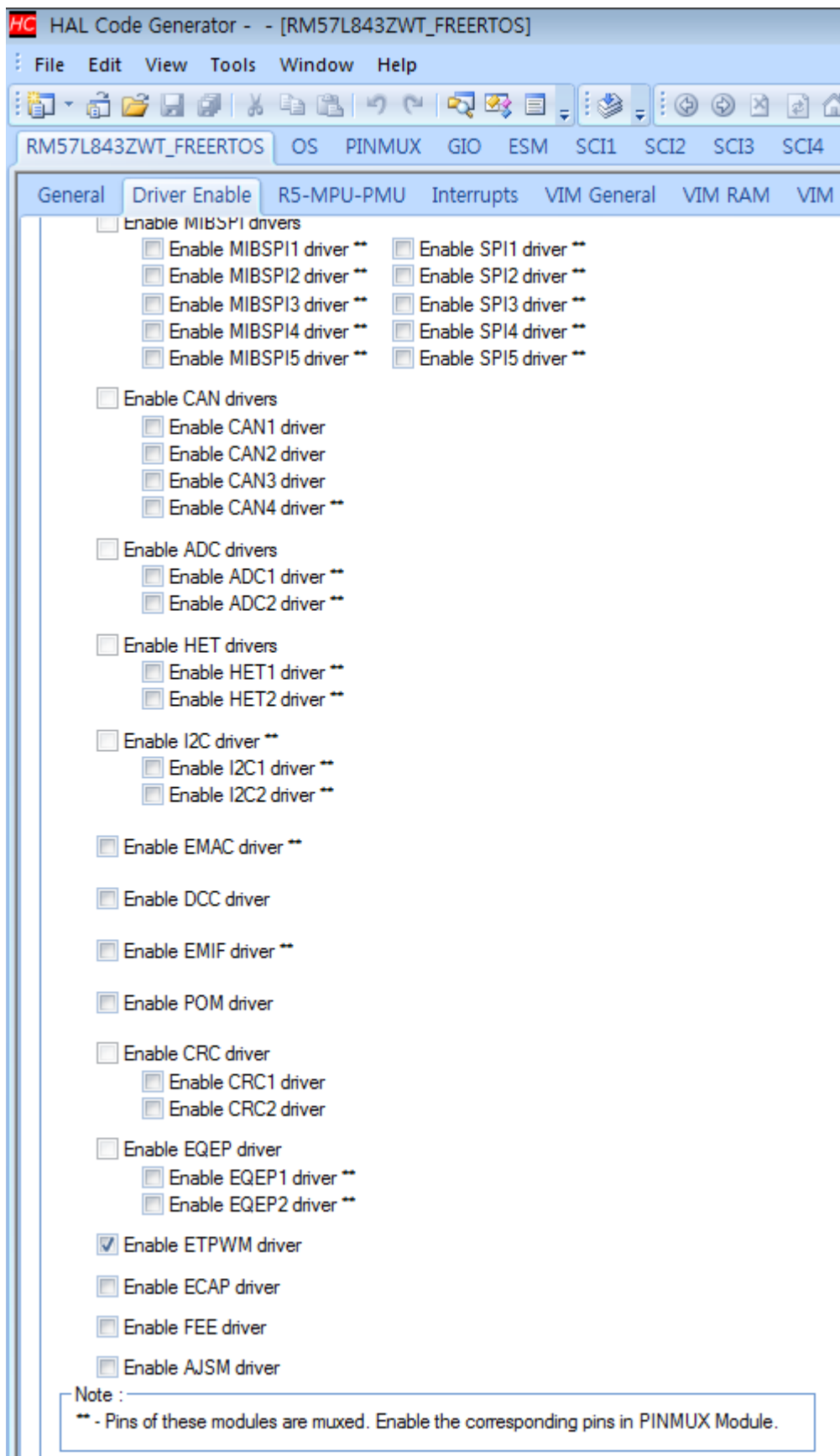
경로 복사



한코젠 커서 프로젝트 만든다.(여기서는 RM57L843ZWT_FREERTOS선택!)



Mark/Unmark all drivers 체크 풀고 GIO driver 선택



File Edit View Tools Window Help

Start Page RM57L843ZWT_FREERTOS OS PINMUX GIO ESM SCI1 SCI2 SCI3 SCI4 LIN1 LIN2 MIBSP1 MIBSP2 MIBSP3 MIBSP4 MIBSP5 SPI1 SPI2 SPI3

Pin Muxing	Input Pin Muxing	Special Pin Muxing					
G17	MIBSP1NENA	NONE	MIL_RXD[2]	N2HET1[23]	NONE	ECAP4	
G19							
H3	GIOA[6]	NONE	N2HET2[04]	NONE	NONE	eTPWM1B	
H4	N2HET1[21]	EMIF_nDQM[2]	NONE	NONE	NONE	NONE	
H16	MIBSP1SSOM[2]	DMM_DATA[14]	NONE	NONE	EXT_SEL[04]	NONE	
H17	MIBSP1SSIMO[2]	DMM_DATA[10]	NONE	NONE	EXT_SEL[01]	NONE	
H18	MIBSP1SNENA	DMM_DATA[07]	MIL_RXD[3]	NONE	NONE	ECAP5	
H19	MIBSP1SCLK	DMM_DATA[04]	MIL_TXEN	RMIL_TXEN	NONE	NONE	
J1	N2HET1[18]	EMIF_RNW	NONE	NONE	NONE	eTPWM6A	
J2	GIOB[6]	nERROR1	NONE	NONE	NONE	NONE	
J3	MIBSP1NCS[3]	NONE	NONE	N2HET1[21]	NONE	nTZ1_3	
J4	N2HET1[23]	EMIF_BA[0]	NONE	NONE	NONE	NONE	

Output

EQEP
FEE
AJSM
Code complete

For Help, press F1

Device Explorer

RM57L843ZWT

SYSTEM

- HL_hal_stdtypes.h
- HL_sys_common.h
- HL_reg_system.h
- HL_reg_flash.h
- HL_reg_l2ramw.h
- HL_reg_vim.h
- HL_reg_pbist.h
- HL_reg_stc.h
- HL_reg_efc.h
- HL_reg_pcr.h
- HL_reg_pmm.h
- HL_reg_dma.h
- HL_reg_ccmr5.h
- HL_sys_core.h
- HL_system.h
- HL_sys_vim.h
- HL_sys_mpu.h
- HL_sys_pmu.h
- HL_sys_pcr.h
- HL_sys_pmm.h
- HL_sys_dma.h
- HL_sys_core.asm
- HL_sys_intvecs.asm
- HL_sys_mpu.asm
- HL_sys_pmu.asm
- HL_sys_pcr.c
- HL_sys_pmm.c
- HL_sys_dma.c
- HL_system.c
- HL_sys_phantom.c
- HL_sys_startup.c
- HL_sys_vim.c
- HL_sys_main.c
- HL_notification.c
- HL_sys_link.cmd
- HL_reg_epc.h
- HL_reg_nmpu.h

Device Explorer File Explorer

Read CAP_OVS

File Edit View Tools Window Help

Start Page RM57L843ZWT_FREERTOS OS PINMUX GIO ESM SCI1 SCI2 SCI3 SCI4 LIN1 LIN2 MIBSP1 MIBSP2 MIBSP3 MIBSP4 MIBSP5 SPI1 SPI2 SPI3

Pin Muxing	Input Pin Muxing	Special Pin Muxing					
J3	MIBSP1TXD[2]	NONE	NONE	N2HET1[21]	NONE	NONE	
J4	N2HET1[23]	EMIF_BA[0]	NONE	NONE	NONE	NONE	
J18	MIBSP1SSOM[0]	DMM_DATA[12]	MIL_TXD[0]	RMIL_TXD[0]	NONE	NONE	
J19	MIBSP1SSIMO[0]	DMM_DATA[08]	MIL_TXD[1]	RMIL_TXD[1]	NONE	NONE	
K3	RESERVED	EMIF_CLK	ECLK2	NONE	NONE	NONE	
K5	ETMDATA[23]	EMIF_DATA[07]	NONE	NONE	NONE	NONE	
K15	ETMDATA[16]	EMIF_DATA[00]	NONE	NONE	NONE	NONE	
K17	EMIF_nCS[3]	RTP_DATA[14]	N2HET2[09]	NONE	NONE	NONE	
K18	N2HET1[00]	MIBSP1CLK	NONE	NONE	NONE	eTPWM2B	
K19	N2HET1[28]	NONE	MIL_RXCLK	RMIL_REFCLK	MIL_RX_AVCLK4	NONE	
L5	ETMDATA[24]	EMIF_DATA[08]	N2HET2[24]	MIBSP1NCS[4]	NONE	NONE	
L15	ETMDATA[17]	EMIF_DATA[01]	NONE	NONE	NONE	NONE	

Output

EQEP
FEE
AJSM
Code complete

For Help, press F1

Device Explorer

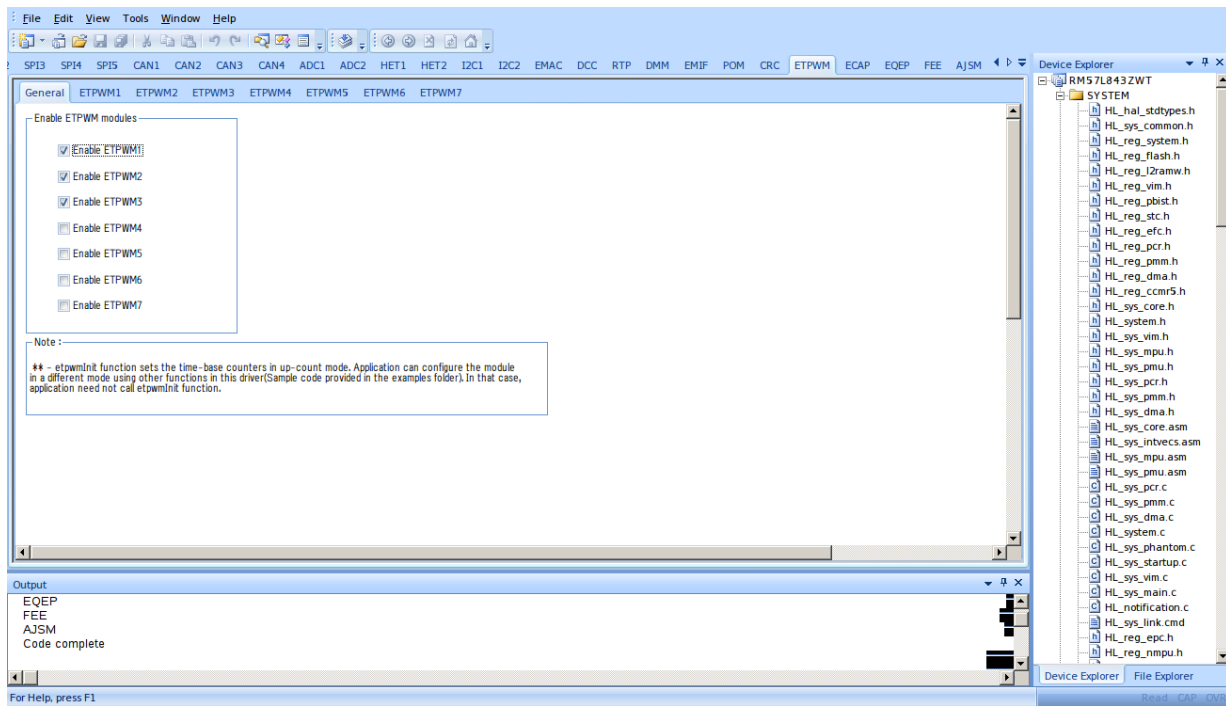
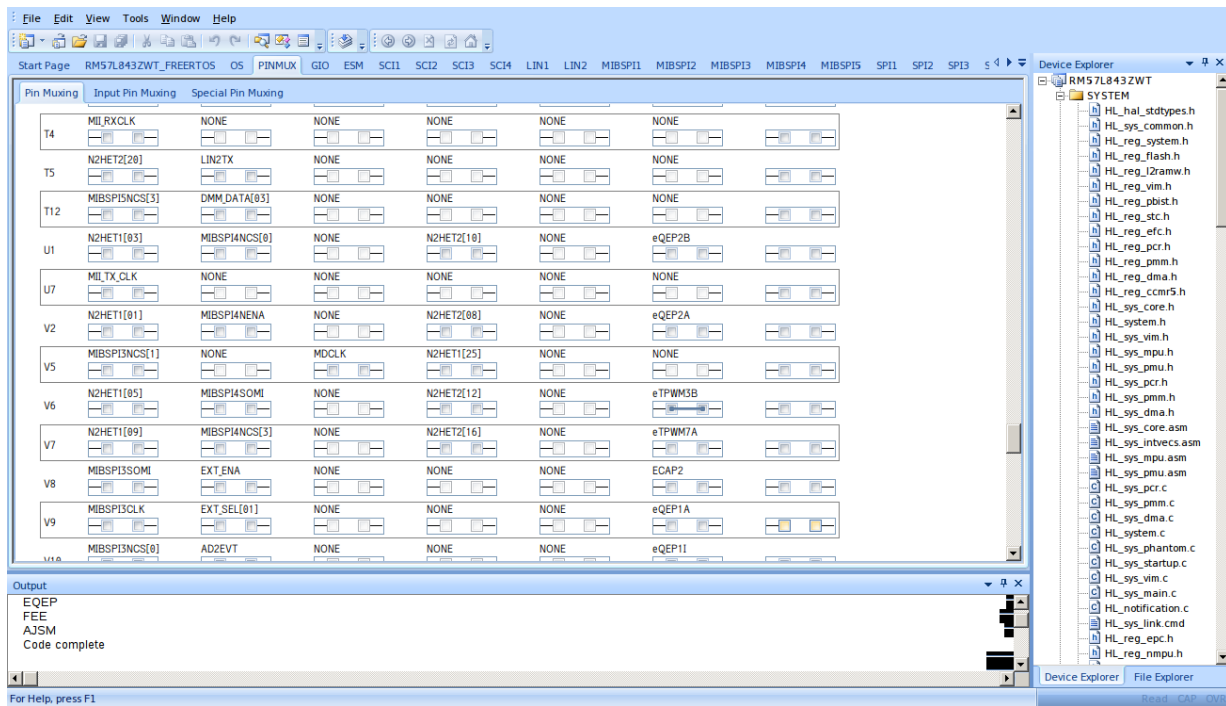
RM57L843ZWT

SYSTEM

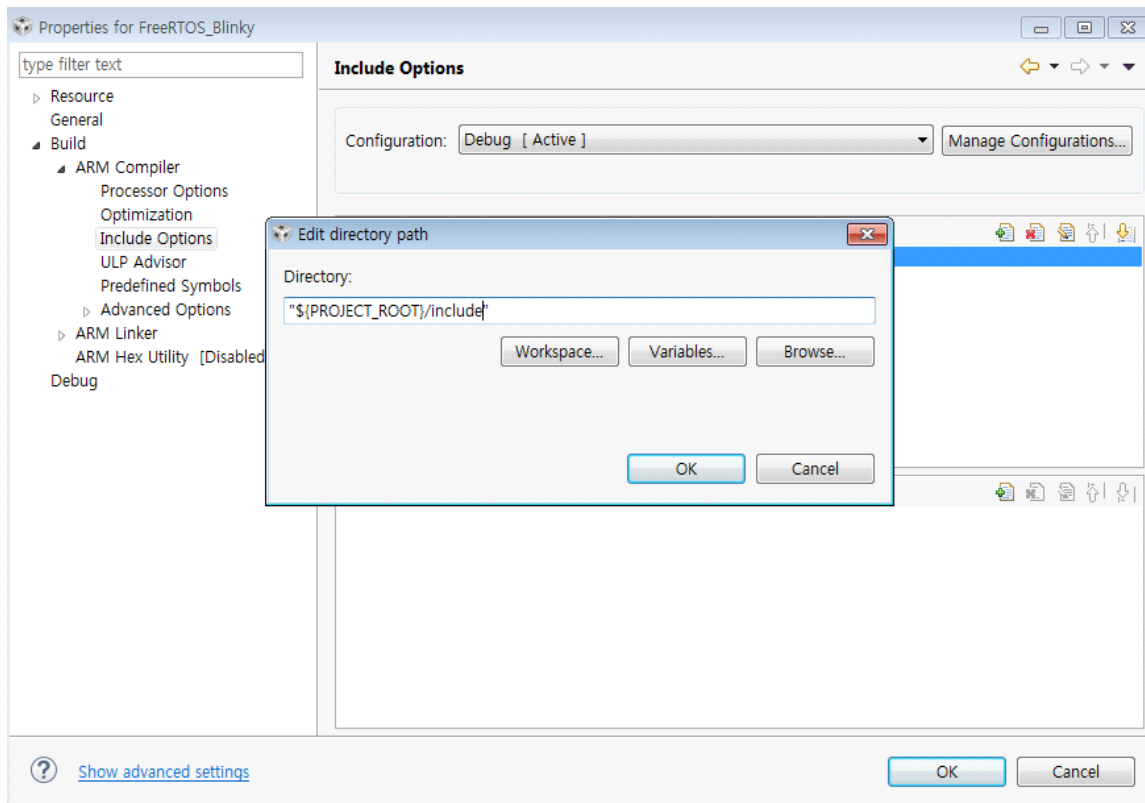
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- HL_reg_epc.h
- HL_reg_nmpu.h

Device Explorer File Explorer

Read CAP_OVS



Generate 후에 CCS로 간다.



Source안에 HL_sys_main.c안에 밑에 소스를 쓴다.

```
#include "HL_sys_common.h"
#include "FreeRTOS.h"
#include "os_task.h"
#include "HL_het.h"
#include <string.h>
#include "HL_system.h"
#include "HL_etpwm.h"

#define MAX 50

volatile int delay;
unsigned int ePWM1B=0,ePWM2B=0,ePWM3B=0;

int temp = MAX;

xTaskHandle xTask1Handle;

void vTask1(void *pvParameters)
{
    for(;;)
    {
        for(delay =0; delay < 100000; delay=delay+1)
            ;
    }
}
```

```

        if(ePWM1B >=(temp +50))
            ePWM1B = 0;
        else
            ePWM1B = ePWM1B + 1;

        etpwmSetCmpB(etpwmREG1, ePWM1B);
    }
}

void vTask2(void *pvParameters)
{
    for(;;)
    {
        for(delay =0; delay < 100000; delay=delay+1)
            ;
        if(ePWM2B >=(temp +50))
            ePWM2B = 0;
        else
            ePWM2B = ePWM2B + 1;

        etpwmSetCmpB(etpwmREG2, ePWM2B);
    }
}

void vTask3(void *pvParameters)
{
    for(;;)
    {
        for(delay =0; delay < 100000; delay=delay+1)
            ;
        if(ePWM3B >=(temp +50))
            ePWM3B = 0;
        else
            ePWM3B = ePWM3B + 1;

        etpwmSetCmpB(etpwmREG3, ePWM3B);
    }
}

void main(void)
{
    etpwmInit();
    etpwmStartTBCLK();

    /* Create Task 1 */
    if(xTaskCreate(vTask1, "Task1", configMINIMAL_STACK_SIZE, NULL, 1,
&xTask1Handle) != pdTRUE)
    {
        /*Task could not be create */
        while(1);
    }
    if(xTaskCreate(vTask2, "Task2", configMINIMAL_STACK_SIZE, NULL, 1,
&xTask1Handle) != pdTRUE)
    {
        /*Task could not be create */
        while(1);
    }
}

```



```

    }
    if(xTaskCreate(vTask3, "Task3", configMINIMAL_STACK_SIZE, NULL, 1,
&xTask1Handle) != pdTRUE)
    {
        /*Task could not be create */
        while(1);
    }

    /* Start Scheduler */
    vTaskStartScheduler();

    /* Run forever */
    while(1);
}

```

망치 쿵

회로 짠다

<회로참고>

PWM1B h3

MCU핀 : GPIOA[6]

PWM2B k18

MCU핀 : N2HET1[00]

PWM3B v6

MCU핀 : N2HET1[05]

벌레쿵

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