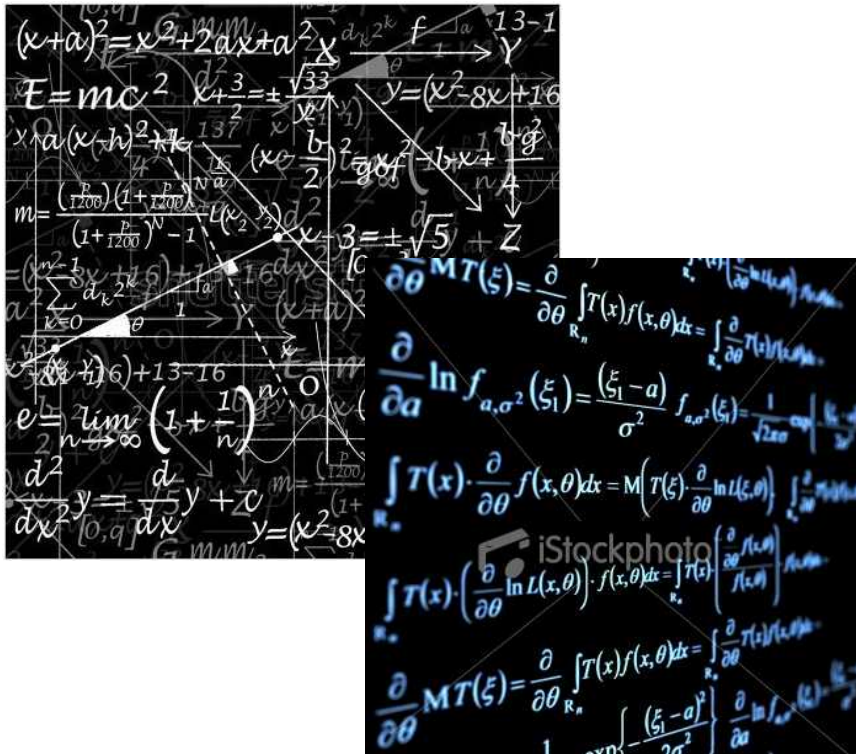


# 수치해석(Numerical Methods)



# 1

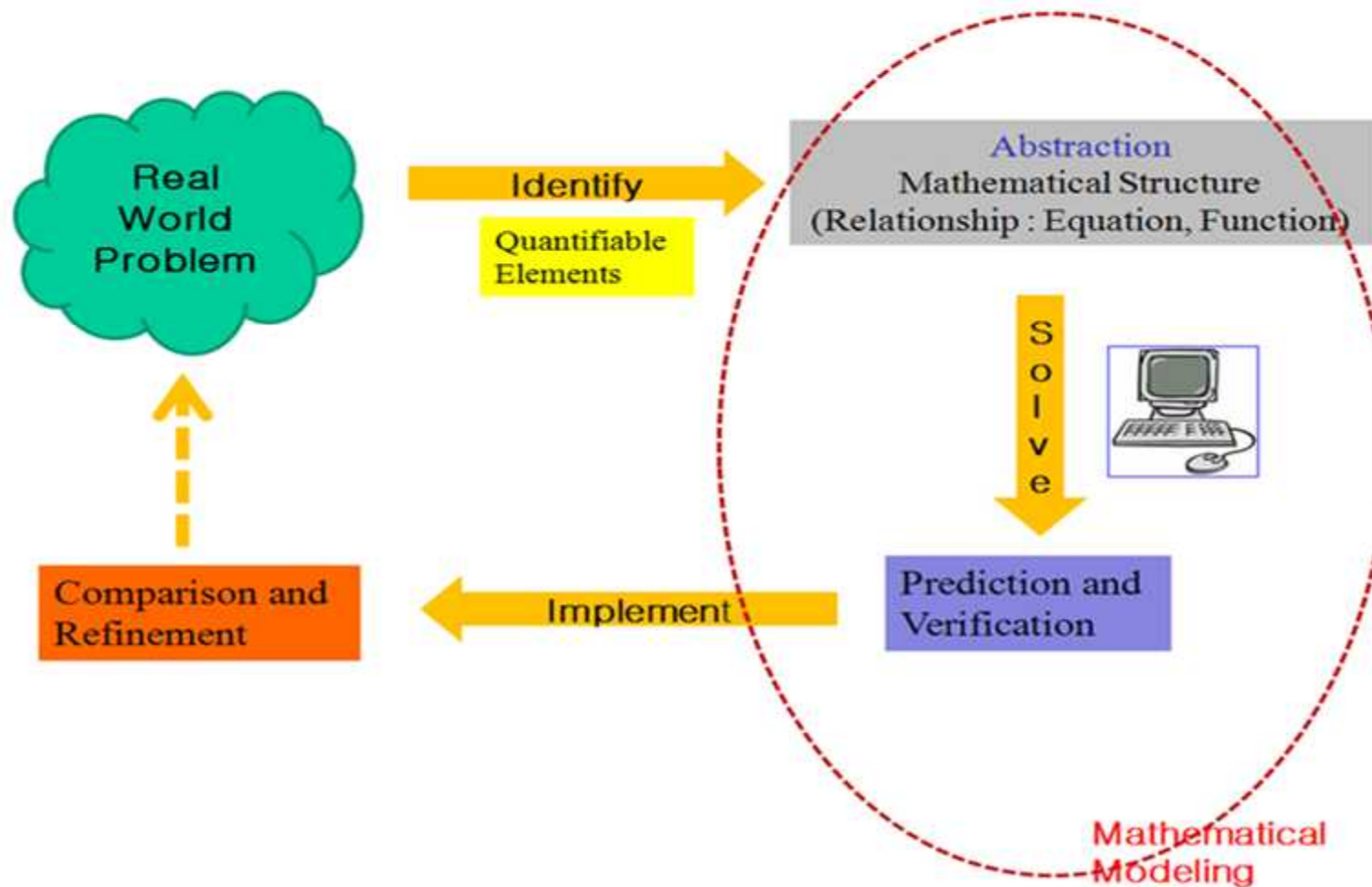
## Mathematical Modeling, Numerical Methods, and Problem Solving

### CHAPTER OBJECTIVES

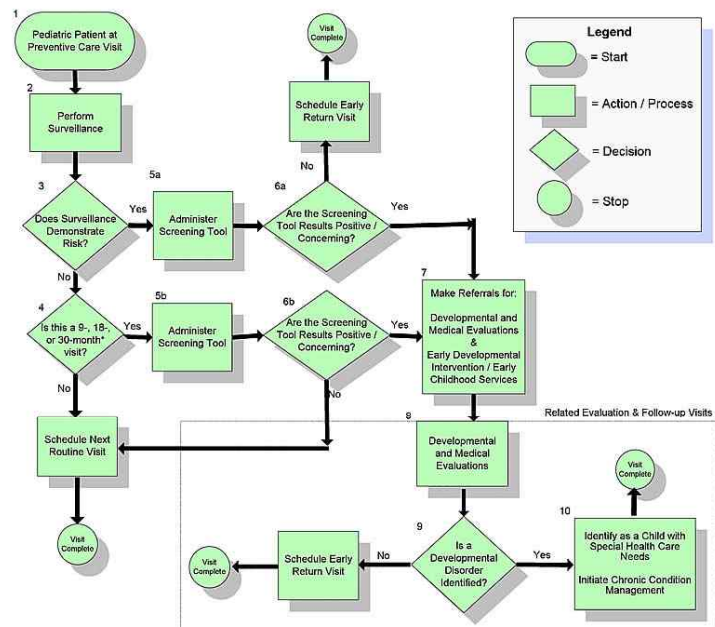
The primary objective of this chapter is to provide you with a concrete idea of what numerical methods are and how they relate to engineering and scientific problem solving. Specific objectives and topics covered are

- Learning how mathematical models can be formulated on the basis of scientific principles to simulate the behavior of a simple physical system.
- Understanding how numerical methods afford a means to generate solutions in a manner that can be implemented on a digital computer.
- Understanding the different types of conservation laws that lie beneath the models used in the various engineering disciplines and appreciating the difference between steady-state and dynamic solutions of these models.
- Learning about the different types of numerical methods we will be covering in this book.

# Modeling



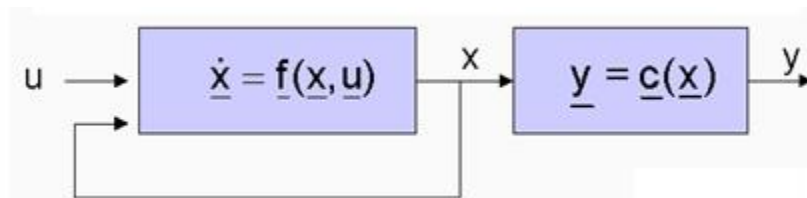
# Abstraction



```

*
C      CALCULATE STATISTICS ON DATA FROM LOW SPEED READER
SIM=0
SIMSQ=0
TYPE 100
FORMAT("ENTER THE NUMBER OF VALUES TO CALCULATE STATISTICS ON",/)
ACCEPT 10,N
FORMAT(I)
DO 200 I=1,N
READ 1,110,V
FORMAT(E)
SIM=SIM + V
SIMSQ=SIMSQ + V*V
TYPE 120,I,V
FORMAT("VALUE",I,"IS",E,/)
120 CONTINUE
SAMP=N
AVRG=SIM/SAMP
STD=SQRT(SIMSQ/SAMP - AVRG**2)
TYPE 300,N,AVRG,STD
FORMAT("NUMBER OF VALUES",I,"MEAN",E,"STANDARD DEVIATION",E,/)
END

*
R FORT
?
    
```



$$a^x + b^y = c^z$$

# Characteristics of mathematical models

- It **describes** a natural process (or system) in mathematical terms
- It represents an idealization and **simplification of reality**
- Finally, it **yields reproducible results**,
  - consequently, can be used for predictive purposes.

The time rate change of momentum of a body is equal to the resulting force acting on it.



$F$ ,  $m$ ,  $a$

$$F = m * a$$

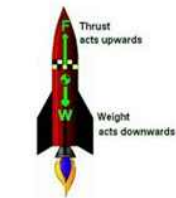
Newton's second law of motion

where

$F$  = net force acting on the body (N)

$m$  = mass of the object (kg)

$a$  = its acceleration ( $\text{m/s}^2$ )



# Building Blocks of Mathematical Model

- Variables of the mathematical model
  - Decision (independent) variables
  - State (dependent) variables
    - represents system state and/or output variables
  - Exogenous variables
    - parameters or constants.

$$\begin{array}{ll}\text{Maximize} & P = p_1 x_1 + p_2 x_2 + \cdots + p_k x_k \\ \text{Subject to:} & a_{11} x_1 + a_{12} x_2 + \cdots + a_{1k} x_k \leq q_1 \\ & a_{21} x_1 + a_{22} x_2 + \cdots + a_{2k} x_k \leq q_2 \\ & \vdots \\ & a_{n1} x_1 + a_{n2} x_2 + \cdots + a_{nk} x_k \leq q_n \\ & x_1, x_2, \cdots, x_k \geq 0\end{array}$$



- You need to buy some filing cabinets.

## Real World Problem

- Cabinet X costs \$10 per unit, requires 6 square feet of floor space, and holds 8 cubic feet of files.
- Cabinet Y costs \$20 per unit, requires 8 square feet of floor space, and holds 12 cubic feet of files.
- You have been given \$140 for this purchase, though you don't have to spend that much.
- The office has room for no more than 72 square feet of cabinets.
- How many of which model should you buy, in order to maximize storage volume?

- Decision variables

## Mathematical Modeling

- $x$ : number of model X cabinets purchased ( $x \geq 0$ )
- $y$ : number of model Y cabinets purchased ( $y \geq 0$ )

- State variable

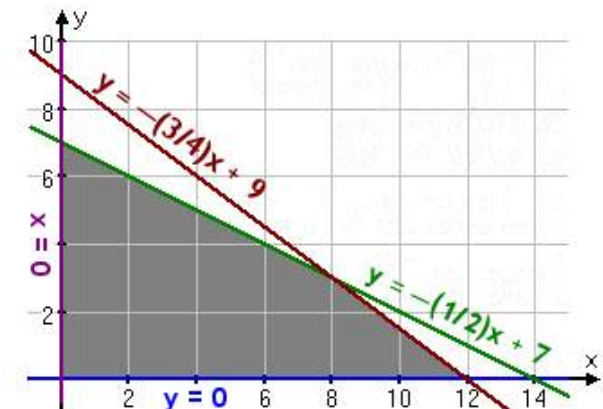
- Maximize Volume( $V$ ) =  $8x + 12y$

- Parameters

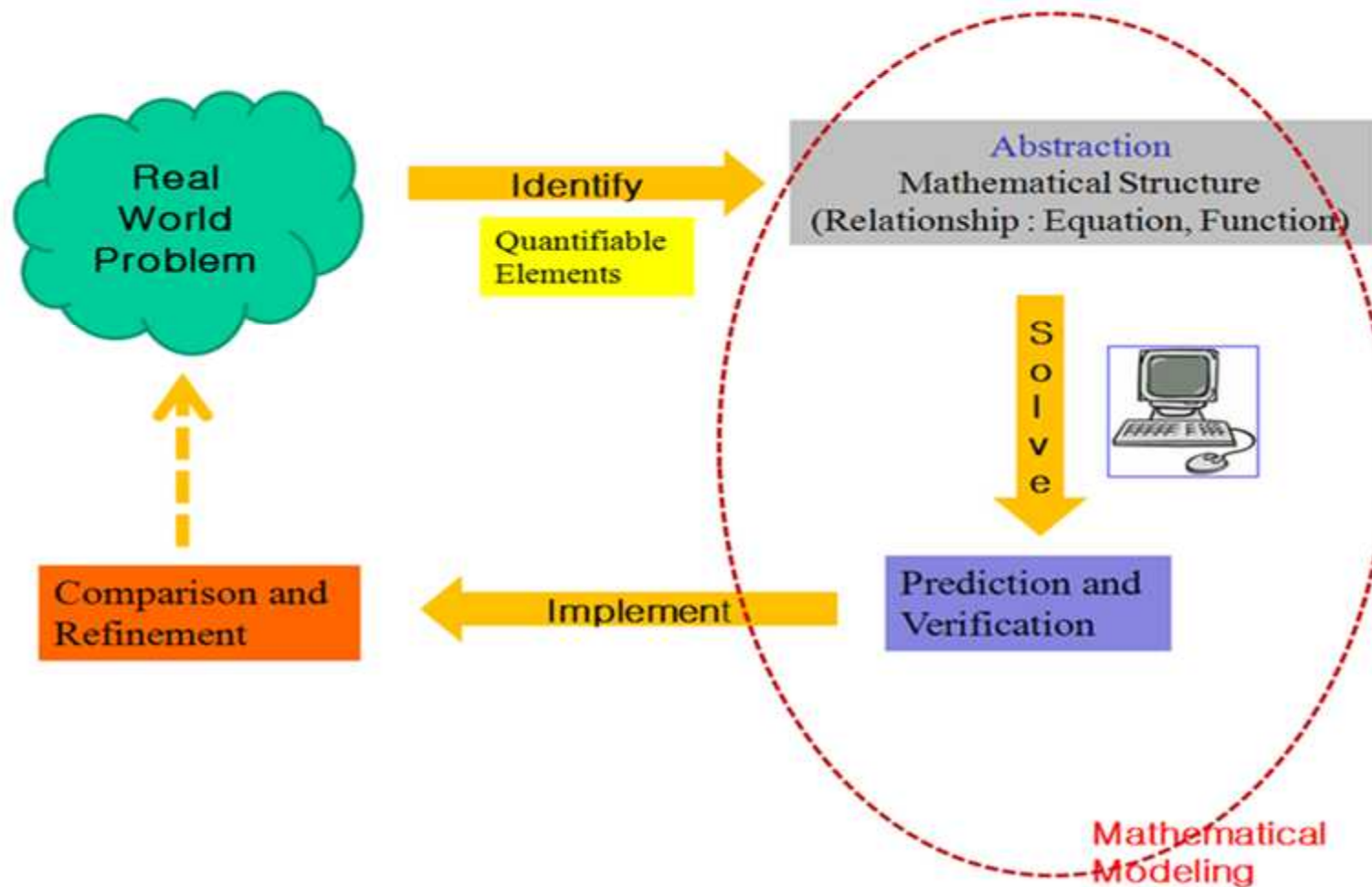
- Cost :  $10x + 20y \leq 140 \rightarrow y \leq -0.5x + 7$
- Space :  $6x + 8y \leq 72 \rightarrow y \leq -0.75x + 9$

- Optimal solution

- Test the corner points at (8, 3), (0, 7), and (12, 0),
- Maximal volume of 100 cubic feet at (8,3)



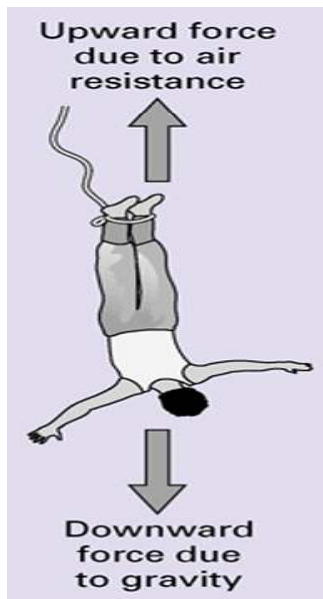
# Mathematical Modeling





# Bungee Jumper Problem

- Develop the mathematical model for the rate of change of velocity with respect to time



$F_U$  = Force due to air resistance  
( $c$  = drag coefficient)  
 $F_D$  = Force due to gravity

$$F = ma$$

$$a = \frac{F}{m}$$

$$\frac{dv}{dt} = \frac{F}{m}$$

$$F = F_D + F_U$$

$$F_D = mg$$

$$F_U = -cv^2$$

$$\frac{dv}{dt} = \frac{mg - cv^2}{m}$$

# Analytical methods

$$v(t) = \sqrt{\frac{gm}{c_d}} \tanh\left(\sqrt{\frac{gc_d}{m}} t\right)$$

$$\int_{T=1}^T \left[ \sum_{j=1}^n \left( \frac{W_j}{R} \right) \right] dt$$

$$c = a + b + d$$

$$c = (\pi \cdot 8 \cdot (2 \cdot 10^3) + 3\pi + 2 \cdot 3 \ln 11)^2$$

$$c = (\pi \cdot 8 \cdot \log \frac{1}{8+2} + 3\pi + 6 \ln 11)^2$$

$$c = \left[ \int_{x_1}^{x_2} \sum_{i=1}^n \alpha_i dx + \frac{3[(3+7x)^2 + 6+3\pi]}{(5+y)(8+z)+1} + 6 \ln 11 \right]^2$$

$$c = \left[ \int_{x_1}^{x_2} \sum_{i=1}^n \frac{(3+7x)(1+6+3\pi)}{(5+y)(8+z)+1} dx + \frac{3[(3+7x)^2 + 6+3\pi]}{(5+y)(8+z)+1} + 6 \ln 11 \right]^2$$

$$c = \left[ \int_{x_1}^{x_2} \sum_{i=1}^n \frac{(3+7x)^2 + (\beta - 180^\circ) + 3\pi}{(5+y)(8+z)+1} dx + \frac{3[(3+7x)^2 + (\beta - 180^\circ) + 3\pi]}{(5+y)(8+z)+1} + 6 \ln 11 \right]^2$$

$$c = \left[ \int_{x_1}^{x_2} \sum_{i=1}^n \frac{\sqrt{3+7x} + (\beta - 180^\circ) + 3\pi}{(5+y)(8+z) + \log 8} dx + \frac{3[\sqrt{3+7x} + (\beta - 180^\circ) + 3\pi]}{(5+y)(8+z) + \log 8} + 6 \ln 11 \right]^2$$

$$c = \sqrt{\left[ \int_{x_1}^{x_2} \sum_{i=1}^n \alpha_i dx + \frac{30 \pi^2 [\sqrt{3+7x} + (\beta - 180^\circ) + 3\pi]}{(5+y)(8+z) + \log 8} + 6 \ln 11 \right]^2}$$

$$c = \sqrt{\left[ \int_{x_1}^{x_2} \sum_{i=1}^n \alpha_i dx + \frac{30 \pi^2 [\sqrt{3+7x} + (\beta - 180^\circ) + 3\pi]}{(5+y)(8+z) + \log 8} + 6 \ln 11 \right]^2}$$

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# Numerical methods

- Numerical methods are those in which the mathematical problem is reformulated so it can be
- Solved by arithmetic operations.

$$\frac{dv}{dt} = \frac{mg - cv^2}{m}$$

$$\frac{dv}{dt} = g - \frac{c_d}{m} v^2$$



$$\frac{dv}{dt} \approx \frac{\Delta v}{\Delta t} = \frac{v(t_{i+1}) - v(t_i)}{t_{i+1} - t_i}$$

# Parachutist Problem



$F_U$  = Force due to air resistance  
( $c$ =drag coefficient)

$F_D$  = Force due to gravity

When Drag( $F_U$ ) is equal to Weight( $F_D$ ), acceleration is zero.  
Velocity becomes constant (terminal velocity).

$$\frac{dv}{dt} = \frac{F}{m}$$

$$F = F_D + F_U$$

$$F_D = mg$$

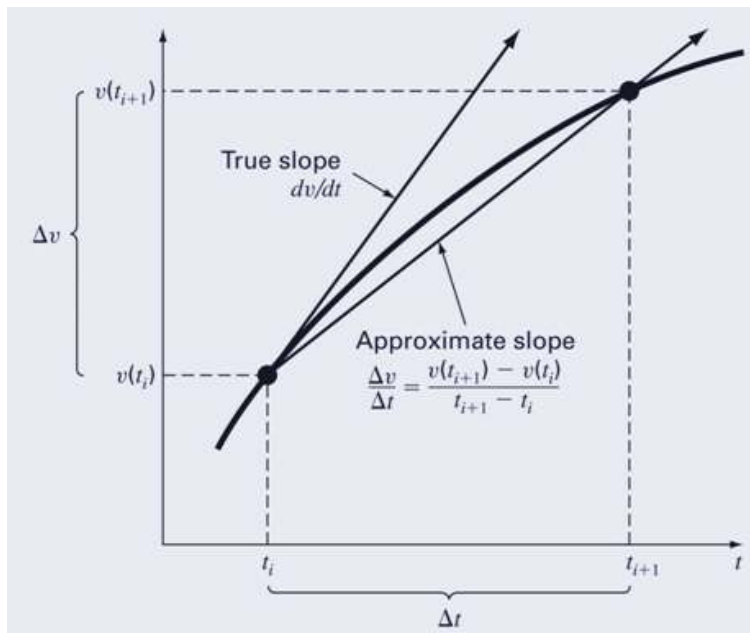
$$F_U = -cv$$

$$\frac{dv}{dt} = \frac{mg - cv}{m}$$

# Numerical vs. Analytical solutions

$$v(t) = \frac{gm}{c} \left( 1 - e^{-(c/m)t} \right)$$

$$\frac{dv}{dt} \approx \frac{\Delta v}{\Delta t} = \frac{v(t_{i+1}) - v(t_i)}{t_{i+1} - t_i}$$



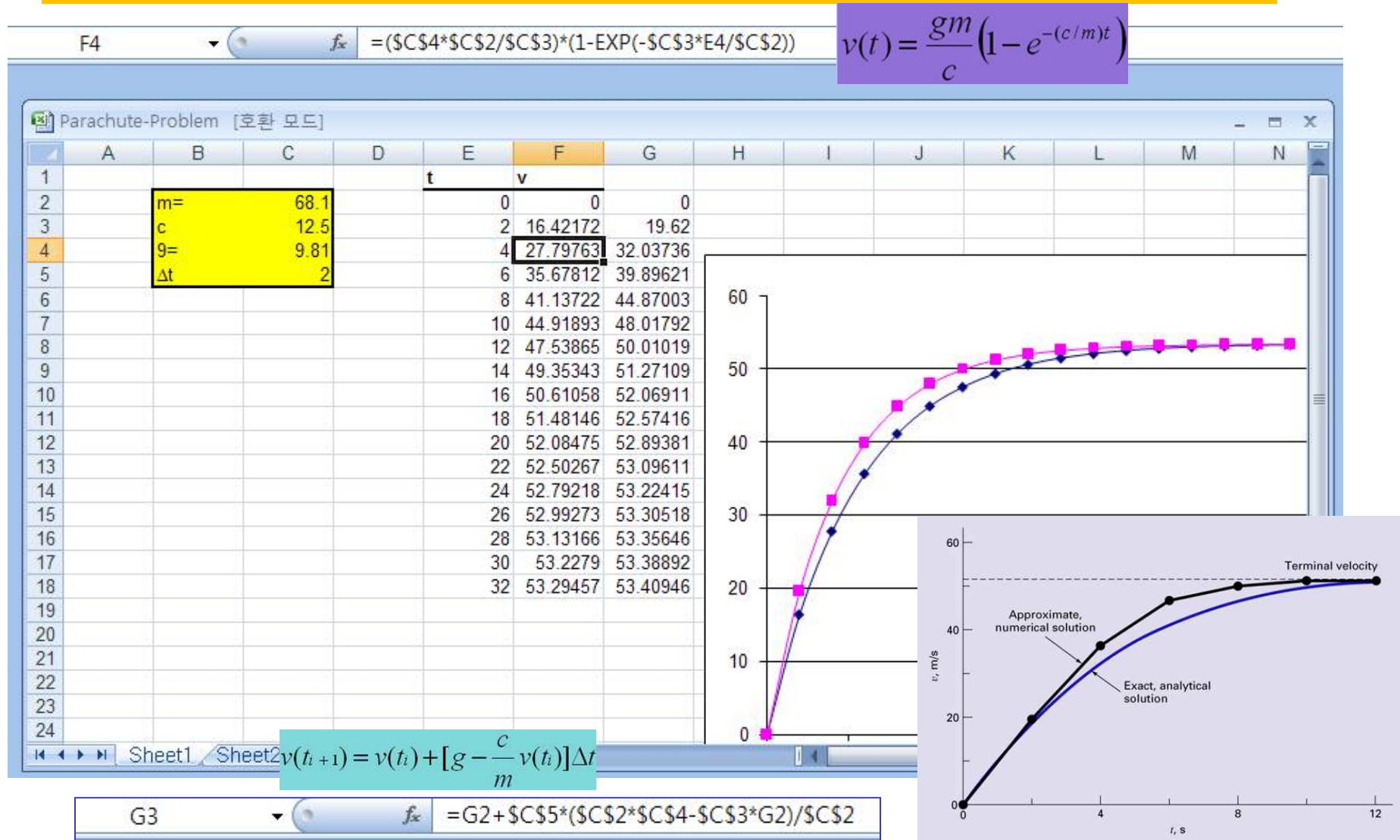
## Euler's Method

$$v(t_{i+1}) = v(t_i) + \left[ g - \frac{c_d}{m} v(t_i)^2 \right] (t_{i+1} - t_i)$$

$$\text{new} = \text{old} + \text{slope} \times \text{step}$$



# Numerical vs. Analytical solutions





## Analytical

vs.

## Numerical solution

$m=68.1 \text{ kg}$   $c=12.5 \text{ kg/s}$   
 $g=9.8 \text{ m/s}$

$\Delta t = 2 \text{ sec}$

t (sec.)	V (m/s)
0	0
2	16.40
4	27.77
8	41.10
10	44.87
12	47.49
$\infty$	53.39

$\Delta t = 0.5 \text{ sec}$

t (sec.)	V (m/s)
0	0
2	19.60
4	32.00
8	44.82
10	47.97
12	49.96
$\infty$	53.39

$\Delta t = 0.01 \text{ sec}$

t (sec.)	V (m/s)
0	0
2	17.06
4	28.67
8	41.94
10	45.60
12	48.09
$\infty$	53.39

t (sec.)	V (m/s)
0	0
2	16.41
4	27.83
8	41.13
10	44.90
12	47.51
$\infty$	53.39

$$v(t) = \frac{gm}{c} \left( 1 - e^{-(c/m)t} \right)$$

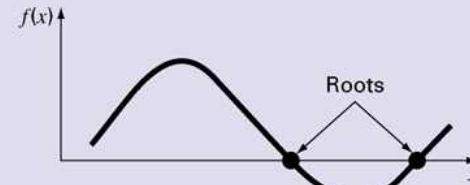
$$v(t_{i+1}) = v(t_i) + \left[ g - \frac{c}{m} v(t_i) \right] \Delta t$$

**CONCLUSION:** If you want to minimize the error, use a smaller step size,  $\Delta t$

# Numerical Methods

## (a) Part 2: Roots

Solve  $f(x) = 0$  for  $x$

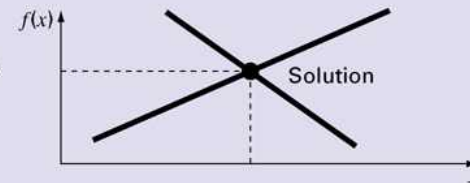


## (b) Part 3: Linear algebraic equations

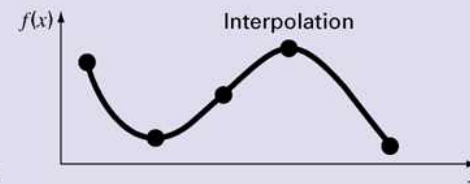
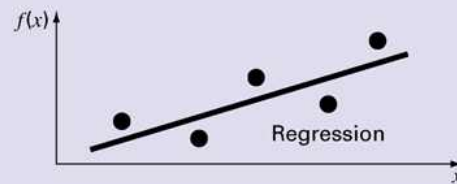
Given the  $a$ 's and the  $b$ 's, solve for the  $x$ 's

$$a_{11}x_1 + a_{12}x_2 = b_1$$

$$a_{21}x_1 + a_{22}x_2 = b_2$$



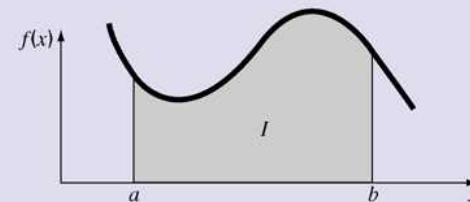
## (c) Part 4: Curve fitting



## (d) Part 5: Integration

$$I = \int_a^b f(x) dx$$

Find the area under the curve.



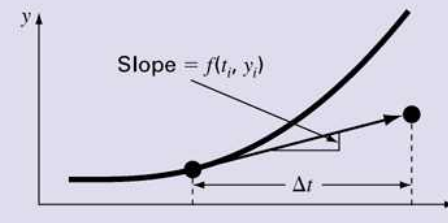
## (e) Part 6: Differential equations

Given

$$\frac{dy}{dt} \approx \frac{\Delta y}{\Delta t} = f(t, y)$$

solve for  $y$  as a function of  $t$

$$y_{i+1} = y_i + f(t_i, y_i)\Delta t$$



THE END

# Homework/Report

