## OpenCV - Histogram 활용

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### 학습 내용

- Histogram Scaling 구현
- Histogram Equalization 구현
- Histogram Backprojection
- Histogram Comparison

#### Histogram scaling 구현

$$I'(x, y) = \left[\frac{S_{MAX} - S_{MIN}}{I_{MAX} - I_{MIN}}\right] [I(x, y) - I_{MIN}] + S_{MIN}$$

 $I_{\text{MAX}}$ : largest gray-level value in the image I(x,y)

 $I_{MIN}$ : smallest gray-level value in I(x,y)

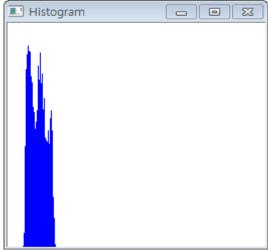
 $S_{\text{MAX}}$  : maximum gray-level values possible

(for an 8-bit image this is 255)

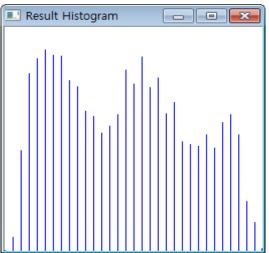
 $S_{MTN}$ : minimum gray-level values possible

(for an 8-bit image this is 0)









```
MatND getHistogram( const Mat & image, int bins=256 );
Mat createHistImage( const MatND &hist, int bins=256 );
void histScaling( const Mat &image, Mat &result,
                   float minValue=0.0001f, float minScale=0,
                   float maxScale=255 );
int main(void)
  Mat image = imread( "input.jpg", 0 );
  if( image.data == NULL ) return -1;
  // histogram scaling
  Mat result;
  histScaling( image, result );
  // create histogram image & display
  MatND orgHist = getHistogram( image );
  MatND resultHist = getHistogram( result );
  Mat orghistImg = createHistImage( orgHist );
  Mat resulthistImg = createHistImage( resultHist );
```

```
// Display the images
namedWindow( "Image" );
namedWindow( "Result" );
namedWindow( "Histogram" );
namedWindow( "Result Histogram" );
imshow( "Image", image );
imshow( "Result", result );
imshow( "Histogram", orghistImg );
imshow( "Result Histogram", resulthistImg );
waitKey();
return 0;
```

```
void histScaling( const Mat &image, Mat &result,
        float minValue, float minScale, float maxScale )
  // Compute histogram
  int bins = 256;
  orgHist = getHistogram( image, bins );
  minValue *= (image.rows*image.cols);
  // find left extremity of the histogram
  int lbin;
  for( lbin=0; lbin<bins; lbin++ )</pre>
     if( orgHist.at<float>(lbin) > minValue ) break;
  // find right extremity of the histogram
  int ubin;
  for( ubin=bins-1; ubin>=0; ubin-- )
     if( orgHist.at<float>(ubin) > minValue ) break;
```

-

```
result.create( image.rows, image.cols, image.type() );
int numOfLines = image.rows;
int numOfPixels = image.cols;
// do scaling
for( int r=0; r<numOfLines; r++ ) {</pre>
   const uchar *data_in = image.ptr<uchar>( r );
   uchar *data_out = result.ptr<uchar>( r );
   for( int c=0; c<numOfPixels; c++ ) {</pre>
      data out[ c ] = saturate_cast<uchar>(
                             ((maxScale-minScale)/(ubin-lbin))*
                             (data in[c]-lbin)+minScale+0.5 );
                                  I'(x, y) = \frac{S_{MAX} - S_{MIN}}{I_{MAX} - I_{MIN}} [I(x, y) - I_{MIN}] + S_{MIN}
```

#### Method 2

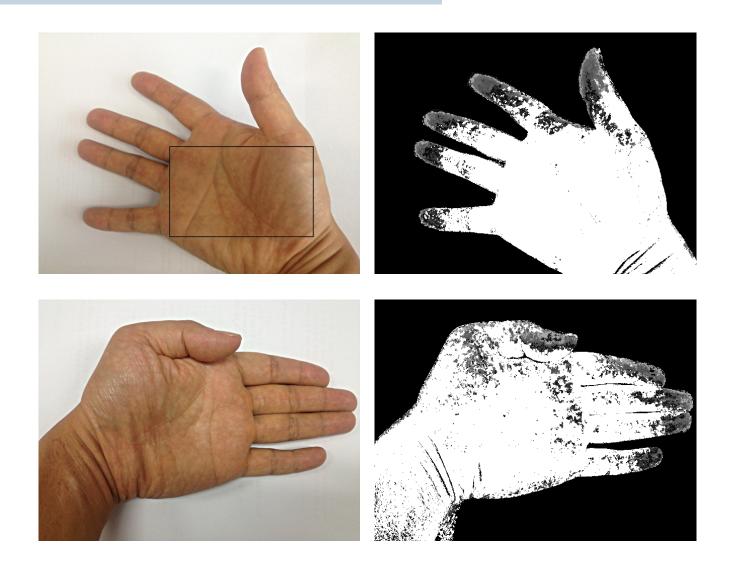
$$I'(x, y) = \left[\frac{S_{MAX} - S_{MIN}}{I_{MAX} - I_{MIN}}\right] [I(x, y) - I_{MIN}] + S_{MIN}$$

## $dst(I) = \text{saturate\_cast} < \text{uchar} > \left( |src(I) * \alpha + \beta| \right)$ Method 3 void convertScaleAbs( InputArray **src**, // source OutputArray **dst**, // destination double alpha=1, // scale factor double **beta**=0 // added to the scaled values convertScaleAbs( image-lbin, result, (maxScale-minScale)/(ubin-lbin), minScale $I'(x, y) = \frac{S_{MAX} - S_{MIN}}{I_{MIN} - I_{MIN}} [I(x, y) - I_{MIN}] + S_{MIN}$

```
dst(I) = \text{saturate\_cast} < \text{rtype} > (|src(I) * \alpha + \beta|)
Method 4
 Mat::convertTo(
         OutputArray m, // destination
         int rtype, // desired dest. type
         double alpha=1, // scale factor
         double beta=0 // added value
 Mat image2 = image - lbin;
 image2.convertTo( result, result.type(),
                       (maxScale-minScale)/(ubin-lbin),
                      minScale
 );
                                    I'(x, y) = \frac{S_{MAX} - S_{MIN}}{I_{MAX} - I_{MIN}} [I(x, y) - I_{MIN}] + S_{MIN}
```

#### Histogram Equalization 구현

## Histogram Backprojection



```
void calcBackProject(
    const Mat* images,
    int nimages,
    const int* channels,
    InputArray hist,
    OutputArray backProject,
    const float** ranges,
    double scale=1,
    bool uniform=true
)
```

```
void normalize(
            InputArray src,
            OutputArray dst,
            double alpha=1,
            double beta=0,
            int norm type=NORM L2,
            int dtype=-1,
            InputArray mask=noArray()
                                                                   #define CV 8U 0
\left| \| src \|_{L} = \max | src(I) | = \alpha \quad if \quad normType = NORM \ \_INF \right|
                                                                   #define CV_8S 1
\left| \left| |src| \right|_{L_1} = \sum \left| src(I) \right| = \alpha \quad \text{if } normType = NORM\_L1
                                                                   #define CV_16U 2
                                                                   #define CV 16S 3
\left\| |src| \right\|_{L_{\alpha}} = \sqrt{\sum src(I)^{2}} = \alpha \text{ if } normType = NORM \_L2
                                                                   #define CV 32S 4
                                                                   #define CV 32F 5
\left| \| src \|_{MM} = [alpha, beta] \right|  if normType = NORM \_MINMAX
                                                                    #define CV 64F 6
                                                                              dtype
                      norm type
```





thresholding with 30

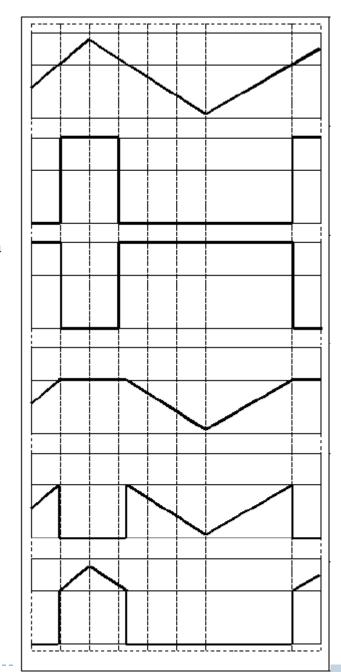
$$dst(x,y) = \begin{cases} maxval & if src(x,y) > thresh \\ 0 & otherwise \end{cases}$$

$$dst(x,y) = \begin{cases} 0 & \text{if } src(x,y) > thresh \\ maxval & \text{otherwise} \end{cases}$$

$$dst(x,y) = \begin{cases} threshold & if src(x,y) > thresh\\ src(x,y) & otherwise \end{cases}$$

$$\mathtt{dst}(x,y) = \left\{ \begin{array}{ll} \mathtt{src}(x,y) & \mathrm{if} \ \mathtt{src}(x,y) > \mathtt{thresh} \\ \mathtt{0} & \mathrm{otherwise} \end{array} \right.$$

$$\text{-THRESH\_TOZERO\_INV} \qquad \text{dst}\,(x,y) = \left\{ \begin{array}{ll} 0 & \text{if } \text{src}(x,y) > \text{thresh} \\ \text{src}(x,y) & \text{otherwise} \end{array} \right.$$



```
MatND getHistogram( const Mat & image, int hbins=30, int sbins=32);
void backprojectHist( const Mat &image, Mat &result, MatND hist );
int main(void)
  Mat image1 = imread( "hand.jpg", -1 );
   if( image1.data == NULL ) return -1;
  Mat image2 = imread( "hand2.jpg", -1 );
   if( image2.data == NULL ) return -1;
  Mat hsv1, hsv2;
   cvtColor( image1, hsv1, CV BGR2HSV );
   cvtColor( image2, hsv2, CV BGR2HSV );
   // get histogram from ROI
  Mat hand = hsv1(Rect(270, 230, 280, 180));
  MatND hist = getHistogram( hand );
  Mat result1, result2;
  backprojectHist( hsv1, result1, hist );
   backprojectHist( hsv2, result2, hist );
```

```
// Display the images
namedWindow( "Image1" );
namedWindow( "Result1" );
namedWindow( "Image2" );
namedWindow( "Result2" );
imshow( "Image1", image1 );
imshow( "Result1", result1 );
imshow( "Image2", image2 );
imshow( "Result2", result2 );
waitKey();
return 0;
```

```
MatND getHistogram( const Mat & image, int hbins, int sbins )
   int histSize[] = { hbins, sbins };
   // hue: 0 ~ 179, saturation: 0 ~ 255
   float hranges[] = { 0, 179 };
   float sranges[] = { 0, 255 };
   const float* ranges[] = { hranges, sranges };
  MatND hist;
   // we compute the histogram from the 0-th and 1-st channels
   int channels[] = { 0, 1 };
   calcHist( &image, 1, channels, Mat(), // do not use mask
        hist, 2, histSize, ranges,
        true, // the histogram is uniform
        false );
  return hist;
```

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```
void backprojectHist( const Mat &image, Mat &result, MatND hist )
  // hue: 0 ~ 179, saturation: 0 ~ 255
  float hranges[] = { 0, 179 };
  float sranges[] = { 0, 255 };
  const float* ranges[] = { hranges, sranges };
  // we compute the histogram from the 0-th and 1-st channels
  int channels[] = { 0, 1 };
  normalize( hist, hist, 0, 255, NORM MINMAX, -1, Mat() );
  calcBackProject( &image,
           // use one image at a time
     1,
     channels, // specifying image channels
     hist, // the histogram we are using
     result, // the resulting back projection image
     ranges, // the range of values, for each dimension
     255.0 // the scaling factor
   );
```

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# Histogram Comparison







#### Reference

- R. Laganière, OpenCV2 Computer Vision: Application
   Programming Cookbook, PACKT Publishing, 2011
- G. Bradski and A. Kaebler, Learning OpenCV: Computer
   Vision with the OpenCV Library, O'REILLY, 2008
- http://docs.opencv.org