

*PickPosition*

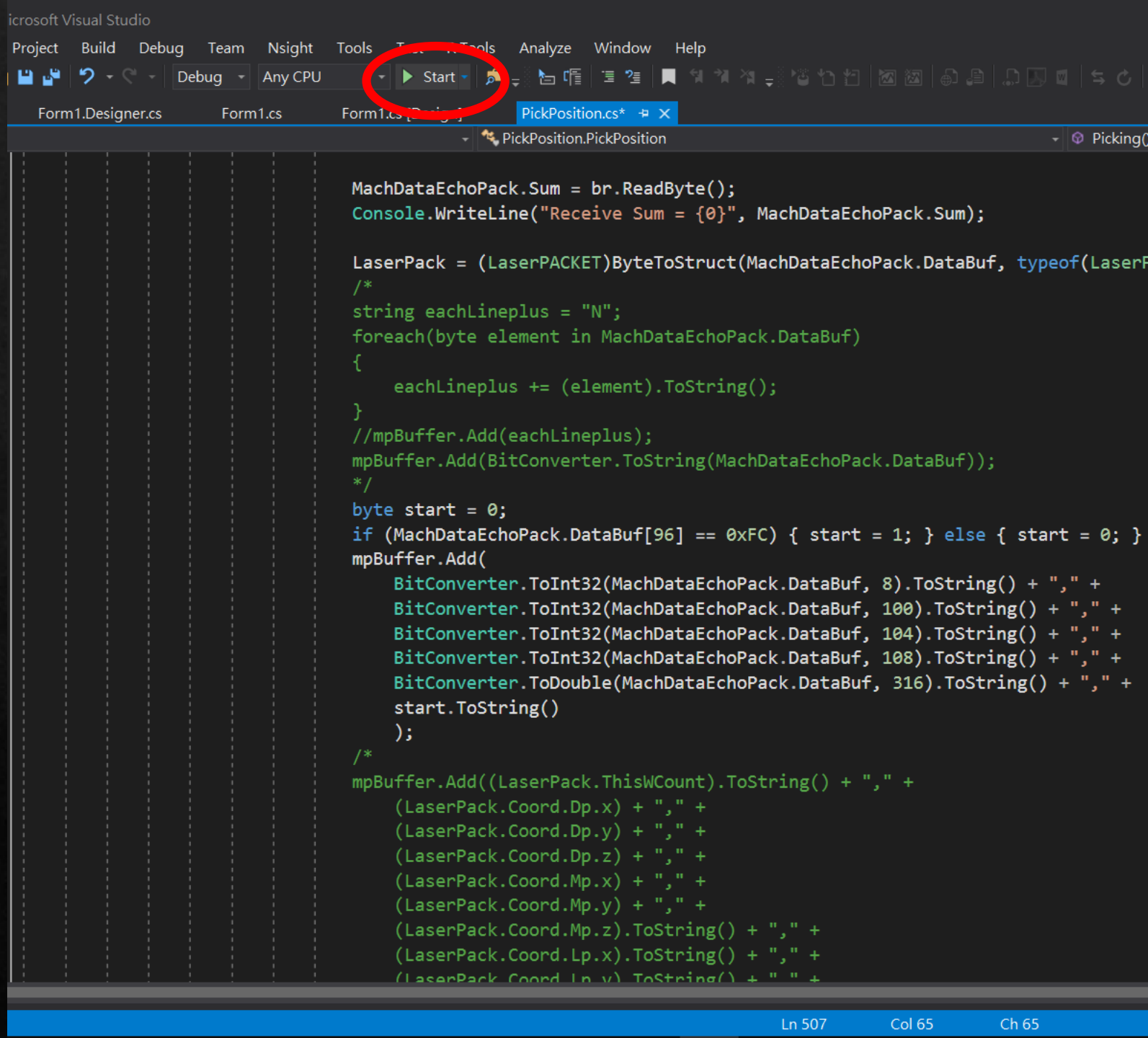
About Laser

# *Picking Data*

<i>Data</i>	<i>For Instance</i>
<i>Time</i>	<i>21:11:7.021</i>
<i>X-coordinate</i>	<i>40235</i>
<i>Y-coordinate</i>	<i>-582369</i>
<i>Z-coordinate</i>	<i>470200</i>
<i>Speed</i>	<i>19.980</i>
<i>Cycle Start Flag</i>	<i>1(or 0)</i>

# Instructions1

*Using visual studio, open solution of PickPosition Project, and build it and debug it.*



# Instructions2

*Fill out form, including location where you save your csv file, local ip address and laser ip address.*

*When finish filling, push the “Start Pick” button to run it.*

The image shows a Visual Studio IDE with a C# project named 'PickPosition'. The code in 'PickPosition.cs' includes comments in Chinese and C# code for setting up a UDP client and a loop to pick positions. The application is running in debug mode, and the output window shows multiple log messages. To the right, a separate window titled 'PickPos' displays a user interface with three input fields: 'Location', 'Local IP', and 'Laser IP'. The 'Local IP' field has a hint text '(Go to control panel to set the same IP)'. Below these fields is a large text area. At the bottom of the window are two buttons: 'Start Pick' and 'Finish Picking'. Red circles highlight the input fields and the 'Start Pick' button.

```
//預設byte陣列數量
int bufferSize = 512;

//初始化物件
UdpClient udpSocket = null;
byte[] sendBuffer = new byte[bufferSize], receiveBuffer = new byte[bufferSize];
int byteSize;
ushort cmdState = 0;

int count = 0;
List<string> mpBuffer = new List<string>();
long records = 0;

try
{
    while (true)
    {
        if(flagflag == 0)
        {
            break;
        }
    }
}
```

Output:

```
'PickPosition.exe' (CLR v4.0.30319: DefaultDomain): I
'PickPosition.exe' (CLR v4.0.30319: DefaultDomain): I
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
'PickPosition.exe' (CLR v4.0.30319: PickPosition.exe)
```

PickPos

Location

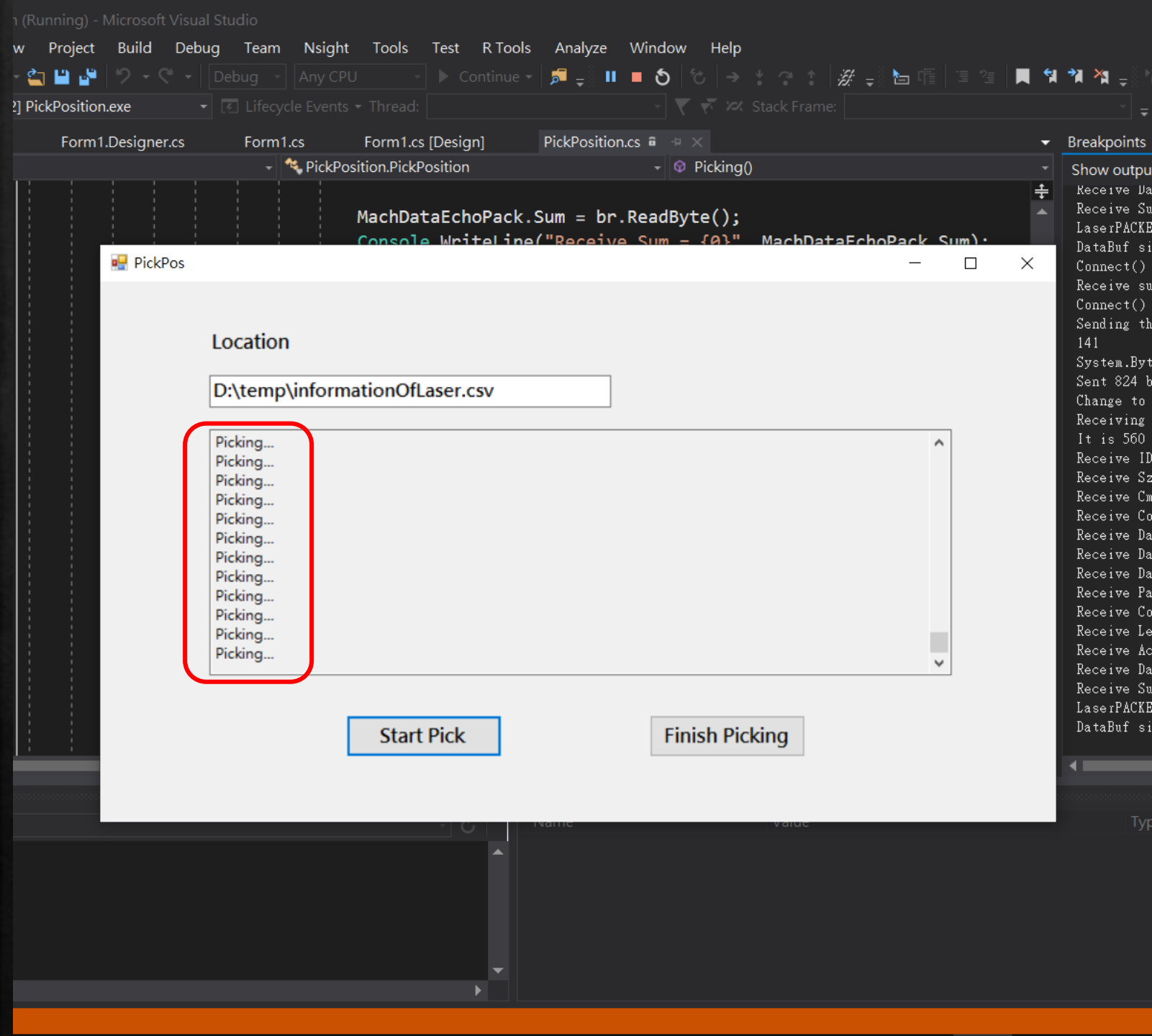
Local IP  (Go to control panel to set the same IP)

Laser IP

Start Pick Finish Picking

# Instructions3

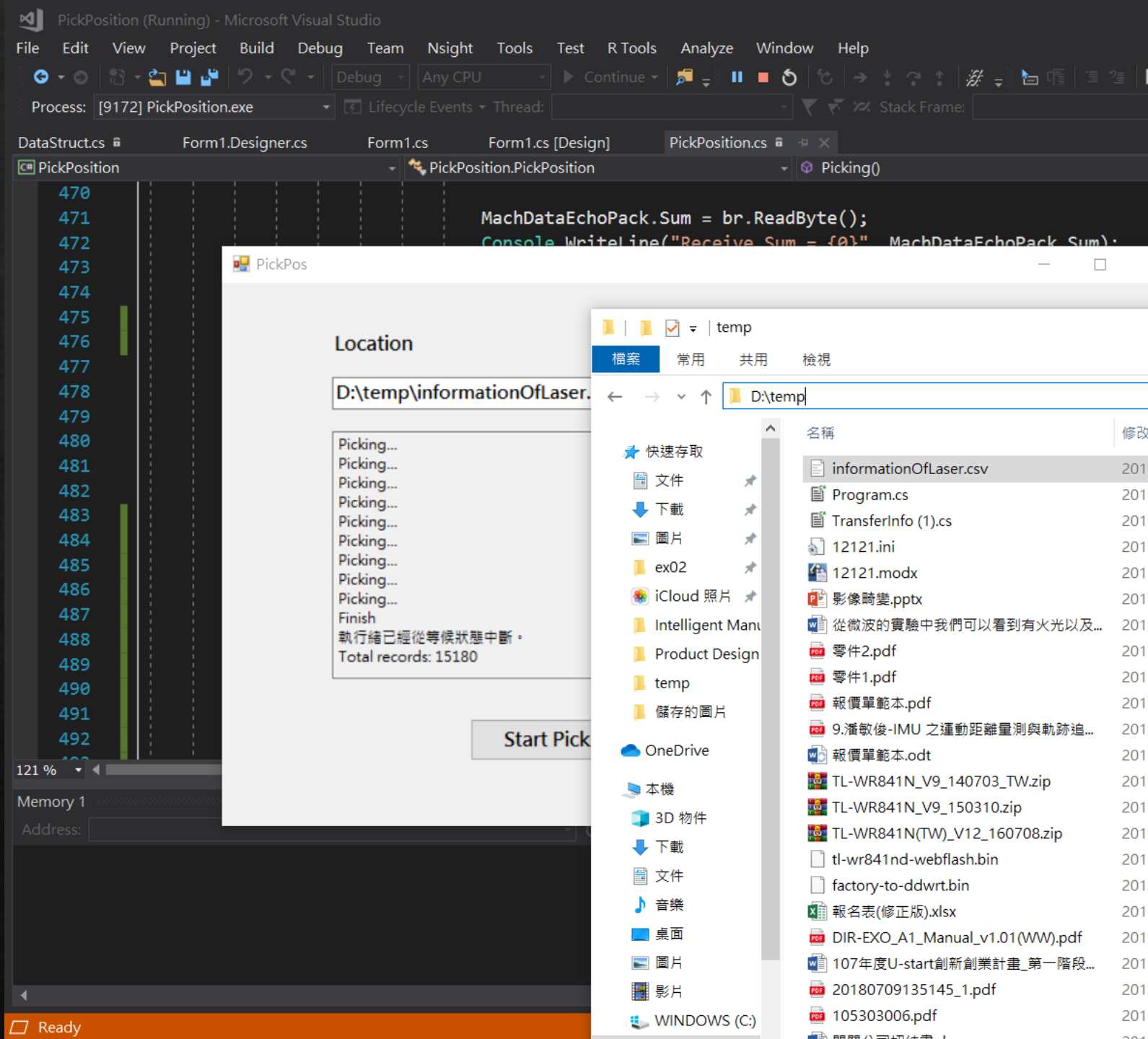
*When information field displays “Picking...”, then you can start the laser machine (run G code).*



## Instructions4

*While laser machine completely executes, push “Finish Picking” button and information field will show total records.*

*Finally, go to file location to check information be correct.*





Preview 'informationOfLaser.csv' X

*Execution  
complete*

## Test Result

*P.S.*

- *Last four digits of  $x$ ,  $y$ , and  $z$  coordinates are decimal places*