

Numerical Analysis

Mathematics of Scientific Computing

主讲人 邱欣欣
幻灯片制作 邱欣欣

中国海洋大学 信息科学与工程学院

2013 年 10 月 18 日

Solving Systems of Linear Equations

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- Operation Counts
- Diagonally Dominant Matrices
- Tridiagonal System

Contents

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- Operation Counts
- Diagonally Dominant Matrices
- Tridiagonal System

Basic Gaussian Elimination



$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$

$$Ax = b$$

Basic Gaussian Elimination

- For the process, there are $n-1$ principal steps. In the first step, we refer to the first equation as the first **pivot equation** and to a_{11} as the first **pivot element**. For the remaining equations ($2 \leq i \leq n$),

$$\left\{ \begin{array}{l} a_{ij} \leftarrow a_{ij} - \left(\frac{a_{i1}}{a_{11}} \right) a_{1j} \\ b_i \leftarrow b_i - \left(\frac{a_{i1}}{a_{11}} \right) b_1 \end{array} \right. \quad (1 \leq j \leq n)$$

Note that the quantities (a_{i1}/a_{11}) are the multipliers.

- Just prior to the k th step in the forward elimination, the system will appear as follows:

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & \dots & \dots & a_{1n} \\ 0 & a_{22} & a_{23} & \dots & \dots & \dots & a_{2n} \\ 0 & 0 & a_{33} & \dots & \dots & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & & & \vdots \\ 0 & 0 & 0 & \dots & a_{kk} & \dots & a_{kj} & \dots & a_{kn} \\ \vdots & \vdots & \vdots & \vdots & \vdots & & \vdots & & \vdots \\ 0 & 0 & 0 & \dots & a_{ik} & \dots & a_{ij} & \dots & a_{in} \\ \vdots & \vdots & \vdots & \vdots & \vdots & & \vdots & & \vdots \\ 0 & 0 & 0 & \dots & a_{nk} & \dots & a_{nj} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_k \\ \vdots \\ x_i \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_k \\ \vdots \\ b_i \\ \vdots \\ b_n \end{bmatrix}$$

- $$\left\{ \begin{array}{l} a_{ij} \leftarrow a_{ij} - \left(\frac{a_{ik}}{a_{kk}} \right) a_{kj} \\ b_i \leftarrow b_i - \left(\frac{a_{ik}}{a_{kk}} \right) b_k \end{array} \right. \quad (k \leq j \leq n)$$

- Obviously, we must assume that all the divisors in this algorithm are nonzero.

Pseudocode

```

input  $n, (a_{ij}), (b_i)$ 
for  $k = 1$  to  $n-1$  do
  for  $i = k + 1$  to  $n$  do
     $z \leftarrow a_{ik} / a_{kk}$ 
     $a_{ik} \leftarrow 0$ 
    for  $j = k + 1$  to  $n$  do
       $a_{ij} \leftarrow a_{ij} - z a_{kj}$ 
    end do
     $b_i \leftarrow b_i - z b_k$ 
  end do
end do
output  $(a_{ij}), (b_i)$ 

```

Basic Gaussian Elimination

```

1 function a=Gaussian(a)
2 n=length(a);
3 for k=1:n-1
4     for i=k+1:n
5         z=a(i,k)/a(k,k);
6         a(i,k)=0;
7         for j=k+1:n
8             a(i,j)=a(i,j)-z*a(k,j);
9         end
10    end
11 end

```

```

1 function x=GaussianBacksub(a,b)
2 n=length(a);
3 for k=1:n-1
4     for i=k+1:n
5         z=a(i,k)/a(k,k);a(i,k)=0;
6         for j=k+1:n
7             a(i,j)=a(i,j)-z*a(k,j);
8         end
9         b(i)=b(i)-z*b(k);
10    end
11 end
12 for i=n:-1:1
13     s=b(i);
14     for j=i+1:1:n
15         s=s-a(i,j)*x(j);
16     end
17     x(i)=s/a(i,i);
18 end

```

Basic Gaussian Elimination

$$\bullet A = A^{(1)} \rightarrow A^{(2)} \rightarrow \dots \rightarrow A^{(n)}$$

$$\begin{bmatrix} a_{11}^{(k)} & \dots & a_{1,k-1}^{(k)} & a_{1k}^{(k)} & \dots & a_{1j}^{(k)} & \dots & a_{1n}^{(k)} \\ \vdots & \ddots & & \vdots & & \vdots & & \vdots \\ 0 & \dots & a_{k-1,k-1}^{(k)} & a_{k-1,k}^{(k)} & \dots & a_{k-1,j}^{(k)} & \dots & a_{k-1,n}^{(k)} \\ 0 & \dots & 0 & a_{kk}^{(k)} & \dots & a_{kj}^{(k)} & \dots & a_{kn}^{(k)} \\ 0 & \dots & 0 & a_{k+1,k}^{(k)} & \dots & a_{k+1,j}^{(k)} & \dots & a_{k+1,n}^{(k)} \\ \vdots & & \vdots & \vdots & & \vdots & & \vdots \\ 0 & \dots & 0 & a_{ik}^{(k)} & \dots & a_{ij}^{(k)} & \dots & a_{in}^{(k)} \\ \vdots & & \vdots & \vdots & & \vdots & & \vdots \\ 0 & \dots & 0 & a_{nk}^{(k)} & \dots & a_{nj}^{(k)} & \dots & a_{nn}^{(k)} \end{bmatrix}$$

Basic Gaussian Elimination

- Our task is to describe how $A^{(k+1)}$ is obtained from $A^{(k)}$. The formula is

$$a_{ij}^{(k+1)} = \begin{cases} a_{ij}^{(k)} & \text{if } i \leq k \\ a_{ij}^{(k)} - (a_{ik}^{(k)} / a_{kk}^{(k)}) a_{kj}^{(k)} & \text{if } i \geq k+1 \text{ and } j \geq k+1 \\ 0 & \text{if } i \geq k+1 \text{ and } j \leq k \end{cases}$$

Then we set $U = A^{(n)}$ and define L by

$$l_{ik} = \begin{cases} a_{ik}^{(k)} / a_{kk}^{(k)} & \text{if } i \geq k + 1 \\ 1 & \text{if } i = k \\ 0 & \text{if } i \leq k - 1 \end{cases}$$

Basic Gaussian Elimination

THEOREM 1 (Theorem on Nonzero Privots)

If all the pivot elements $a_{kk}^{(k)}$ are nonzero in the process just described, then $A = LU$.

Proof.

Observe that $a_{ij}^{(k+1)} = a_{ij}^{(k)}$ if $i \leq k$ or $j \leq k-1$. Note $u_{kj} = a_{kj}^{(n)} = a_{kj}^{(k)}$, $l_{ik} = 0$ if $k > i$, and $u_{kj} = 0$ if $k > j$. Now let $i \leq j$. We have

$$\begin{aligned}(LU)_{ij} &= \sum_{k=1}^n l_{ik} u_{kj} = \sum_{k=1}^i l_{ik} u_{kj}^{(k)} = \sum_{k=1}^i l_{ik} a_{kj}^{(k)} \\ &= \sum_{k=1}^{i-1} l_{ik} a_{kj}^{(k)} + l_{ii} a_{ij}^{(i)}\end{aligned}$$

Proof.

$$\begin{aligned} &= \sum_{k=1}^{i-1} (a_{ik}^{(k)} / a_{kk}^{(k)}) a_{kj}^{(k)} + a_{ij}^{(i)} \\ &= \sum_{k=1}^{i-1} (a_{ij}^{(k)} - a_{ij}^{(k+1)}) + a_{ij}^{(i)} \\ &= a_{ij}^{(1)} = a_{ij} \end{aligned}$$



Basic Gaussian Elimination

Proof.

If $i > j$, then

$$\begin{aligned}
 (LU)_{ij} &= \sum_{k=1}^n l_{ik} u_{kj} = \sum_{k=1}^j l_{ik} a_{kj}^{(k)} \\
 &= \sum_{k=1}^j (a_{ij}^{(k)} - a_{ij}^{(k+1)}) \\
 &= a_{ij}^{(1)} - a_{ij}^{j+1} \\
 &= a_{ij}^{(1)} = a_{ij}
 \end{aligned}$$

Since $a_{ij}^{(k)} = 0$ if $i \geq j+1$ and $k \geq j+1$.



- Basic Gaussian Elimination
- **Pivoting**
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- Operation Counts
- Diagonally Dominant Matrices
- Tridiagonal System

Pivoting

- The first example

$$\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

The algorithm fails because $a_{11} = 0$.

Pivoting

- Another example, which ε is a small number different from 0.

$$\begin{bmatrix} \varepsilon & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

The solution is

$$\begin{cases} x_2 = (2 - \varepsilon^{-1})/(1 - \varepsilon^{-1}) \approx 1 \\ x_1 = (1 - x_2)\varepsilon^{-1} \approx 0 \end{cases}$$

But the correct solution is

$$\begin{cases} x_1 = 1/(1 - \varepsilon) \approx 1 \\ x_2 = (1 - 2\varepsilon)/(1 - \varepsilon) \approx 1 \end{cases}$$

- $$\begin{bmatrix} 1 & 1 \\ \varepsilon & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{cases} x_2 = (1 - 2\varepsilon)/(1 - \varepsilon) \approx 1 \\ x_1 = (2 - x_1) \approx 1 \end{cases}$$

Contents

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- **Gaussian Elimination with Scaled Row Pivoting**
- Factorizations $PA = LU$
- Operation Counts
- Diagonally Dominant Matrices
- Tridiagonal System

Gaussian Elimination with Scaled Row Pivoting

$$Ax = b$$

The algorithm has two parts: a factorization phase and a solution phase.

- The factorization phase is designed to produce the LU -decomposition of PA , the permuted linear system is $PAx = Pb$. P is a permutation matrix.
 - The factorization is obtained from a modified Gaussian elimination algorithm to be explained below.
- In the solution phase, we consider two equations $Lz = Pb$ and $Ux = z$.
 - b is rearranged according to P and $b \leftarrow Pb$.
 - $Lz = b$ is solved for z and $b \leftarrow L^{-1}b$.
 - Then back substitution is used to solve $Ux = b$ for x_n, x_{n-1}, \dots, x_1 .

Gaussian Elimination with Scaled Row Pivoting

- Computing the scale of each row. We put

$$s_i = \max_{1 \leq j \leq n} |a_{ij}| = \max\{|a_{i1}|, |a_{i2}|, \dots, |a_{in}|\} \quad (1 \leq i \leq n)$$

These n numbers are recorded in the scale vector $s = [s_1, s_2, \dots, s_n]$.

- Firstly, define the index vector p to be $[p_1, p_2, \dots, p_n] = [1, 2, \dots, n]$. Selecting an index j for which $|a_{i1}|/s_i$ is largest. Interchanging p_j with p_1 in the index vector. Next, use multipliers (a_{p_i1}/a_{p_11}) times row 1, and subtract from equations p_i for $2 \leq i \leq n$.
- At step k , select j to be the first index corresponding to the largest of the ratios, $\{|a_{p_ik}|/s_{p_i} \mid k \leq i \leq n\}$, interchanging p_j with p_k in p .

```

• input  $n, (a_{ij})$ 
  for  $i = 1$  to  $n$  do
     $p_i \leftarrow i$ 
     $smax \leftarrow 0$ 
    for  $j = 1$  to  $n$  do
       $smax \leftarrow \max(smax, |a_{ij}|)$ 
    end do
     $s_i \leftarrow smax$ 
  end do

```



```

• for  $k = 1$  to  $n-1$  do
  for  $i = k+1$  to  $n$  do
     $b_{p_i} \leftarrow b_{p_i} - a_{p_i k} b_{p_k}$ 
  end do
end do
for  $i = n$  to  $1$  step  $-1$  do
   $x_i \leftarrow (b_{p_i} - \sum_{j=i+1}^n a_{p_i j} x_j) / a_{p_i i}$ 
end do
output  $(x_i)$ 

```

Gaussian Elimination with Scaled Row Pivoting

```
1 function x=ScaleGaussian(a,b)
2 n=length(a);
3 for i=1:n
4     p(i)=i;
5     smax=0;
6     for j=1:n
7         smax=max(smax, abs(a(i,j)));
8     end
9     s(i)=smax;
10 end
11 for k=1:n-1
12     format rat rmax=0;
13     for i=k:n
14         r=abs(a(p(i),k))/s(p(i))
15         if r>rmax
16             rmax=r;j=i;
17         end
18     end
```

```
1      c=p(k);p(k)=p(j);p(j)=c;
2  for i=k+1:n
3      z=a(p(i),k)/a(p(k),k);a(p(i),k)=z;
4      for j=k+1:n
5          a(p(i),j)=a(p(i),j)-z*a(p(k),j);
6      end
7  end
8  for i=k+1:n
9      b(p(i))=b(p(i))-a(p(i),k)*b(p(k));
10 end
11 end
12 for i=n:-1:1
13     q=b(p(i));
14     for j=i+1:1:n
15         q=q-a(p(i),j)*x(j);
16     end
17     x(i)=q/a(p(i),i);
18 end
```

Contents

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- Operation Counts
- Diagonally Dominant Matrices
- Tridiagonal System

Factorizations $PA = LU$

- Let p_1, p_2, \dots, p_n be the indices of the rows in the order in which they become pivoting rows. Let $A^{(1)} = A$, and define $A^{(2)}, A^{(3)}, \dots, A^{(n)}$ recursively by the formula

$$a_{p_i j}^{(k+1)} = \begin{cases} a_{p_i j}^{(k)} & \text{if } i \leq k \text{ or } i > k > j \\ a_{p_i j}^{(k)} - (a_{p_i k}^{(k)} / a_{p_k k}^{(k)}) a_{p_k j}^{(k)} & \text{if } i > k \text{ and } j > k \\ a_{p_i k}^{(k)} / a_{p_k k}^{(k)} & \text{if } i > k \text{ and } j = k \end{cases}$$

THEOREM 2 (Theorem on LU Factorization of PA)

Define a permutation matrix P whose elements are $P_{ij} = \delta_{p_i j}$. Define an upper triangular matrix U whose elements are $u_{ij} = a_{p_i j}^{(n)}$ if $j \geq i$. Define a unit lower triangular matrix L whose elements are $l_{ij} = a_{p_i j}^{(n)}$ if $j < i$. Then $PA = LU$.

Factorizations $PA = LU$

Proof.

From the recursive formula, we have

$$\begin{aligned} u_{kj} &= a_{p_k j}^{(n)} = a_{p_k j}^{(k)} & (j \geq k) \\ l_{ik} &= a_{p_i k}^{(n)} = a_{p_i k}^{(k+1)} = a_{p_i k}^{(k)} / a_{p_k k}^{(k)} & (i \geq k) \end{aligned}$$

Because the row p_k in $A^{(n)}$ became fixed in step k , and column k in $A^{(n)}$ became fixed in step $k+1$. Thus

$$a_{p_k j}^{(n)} = a_{p_k j}^{(k)} \quad a_{p_i k}^{(n)} = a_{p_i k}^{(k+1)}$$



Factorizations $PA = LU$

Proof.

Suppose that $i \leq j$.

$$\begin{aligned}
(LU)_{ij} &= \sum_{k=1}^i l_{ik} u_{kj} \\
&= \sum_{k=1}^{i-1} (a_{p_i k}^{(k)} / a_{p_k k}^{(k)}) a_{p_k j}^{(k)} + l_{ii} a_{p_i j}^{(i)} \\
&= \sum_{k=1}^{i-1} (a_{p_i j}^{(k)} - a_{p_i j}^{(k+1)}) + a_{p_i j}^{(i)} \\
&= a_{p_i j}^{(1)} = a_{p_i j}
\end{aligned}$$



Factorizations $PA = LU$

Proof.

If $i > j$, then

$$\begin{aligned}
 (LU)_{ij} &= \sum_{k=1}^j l_{ik} u_{kj} \\
 &= \sum_{k=1}^{j-1} (a_{p_i k}^{(k)} / a_{p_k k}^{(k)}) a_{p_k j}^{(k)} + (a_{p_i j}^{(j)} / a_{p_j j}^{(j)}) \\
 &= \sum_{k=1}^{j-1} (a_{p_i j}^{(k)} - a_{p_i j}^{(k+1)}) + a_{p_i j}^{(j)} \\
 &= a_{p_i j}^{(1)} = a_{p_i j}
 \end{aligned}$$



Proof.

And,

$$(PA)_{ij} = \sum_{k=1}^n P_{ik} a_{kj} = \sum_{k=1}^n \delta_{p_i k} a_{kj} = a_{p_i j}$$

So for all pairs (i, j) , that

$$(PA)_{ij} = (LU)_{ij}$$



Factorizations $PA = LU$

THEOREM 3 (Theorem on Solving $PA = LU$)

If the factorization $PA = LU$ is produced from the Gaussian algorithm with scaled row pivoting, then the solution of $Ax = b$ is obtained by first solving $Lz = Pb$ and then solving $Ux = z$. Similarly, the solution of $y^T A = c^T$ is obtained by solving $U^T z = c$ and then $L^T P y = z$.

Pseudocode in terms of L and U

- input $n, (l_{ij}), (u_{ij}), (b_i), (p_i)$
 - for $i = 1$ to n do
 - $z_i \leftarrow b_{p_i} - \sum_{j=1}^{i-1} l_{ij} z_j$
 - end do
 - for $i = n$ to 1 step -1 do
 - $x_i \leftarrow (z_i - \sum_{j=i+1}^n u_{ij} x_j) / u_{ii}$
 - end do
 - output (x_i)

- input $n, (a_{ij}), (b_i), (p_i)$
for $i = 1$ to n do
 $z_i \leftarrow b_{p_i} - \sum_{j=1}^{i-1} a_{p_i j} z_j$
end do
for $i = n$ to 1 step -1 do
 $x_i \leftarrow (z_i - \sum_{j=i+1}^n a_{p_i j} x_j) / a_{p_i i}$
end do
output (x_i)

- input $n, (a_{ij}), (c_i), (p_i)$
for $j = 1$ to n do
 $z_j \leftarrow (c_i - \sum_{i=1}^{j-1} a_{p_{ij}} z_i) / a_{p_{jj}}$
end do
for $j = n$ to 1 step -1 do
 $y_{p_j} \leftarrow z_j - \sum_{i=j+1}^n a_{p_{ij}} y_{p_i}$
end do
output (x_i)

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- **Operation Counts**
- Diagonally Dominant Matrices
- Tridiagonal System

THEOREM 4 (Theorem on Long Operations)

If Gaussian elimination is used with scaled row pivoting, then the solution of the system $Ax = b$, with fixed A , and m different vectors b , involves approximately

$$\frac{1}{3}n^3 + (\frac{1}{2} + m)n^2$$

long operations (multiplications or divisions).

Factorizations $PA = LU$

Proof.

Consider the first major step.

- Define p_1 involves n divisions (n ops).
- For each of the $n - 1$ rows, a multiplier is computed (1 op), then a multiple of row p_1 is subtracted from p_i for $2 \leq i \leq n$. So the multiplier and the elimination process consume n ops per row.
- Since $n - 1$ rows are processed, we have $n(n - 1)$ ops. So the total is n^2 ops.

For the entire calculation, the factorization requires

$$n^2 + (n - 1)^2 + \dots + 2^2 = \frac{1}{3}n^3 + \frac{1}{2}n^2 + \frac{1}{6}n - 1 \approx \frac{1}{3}n^3 + \frac{1}{2}n^2$$

long operations.



Proof.

- In updating the b , there are $n - 1$ steps. In the first, there are $n - 1$ long operations. In the second, there are $n - 2$, and so on. The total is

$$(n-1) + (n-2) + \dots + 1 = \frac{1}{2}n^2 - \frac{1}{2}n$$

- In the back substitution, there is one long operation in the first step (computing x_n). Then there are successively 2, 3,..., n long operations. The total is

$$1 + 2 + \dots + n = \frac{1}{2}n^2 + \frac{1}{2}n$$

The grand total is n^2 .

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- Operation Counts
- **Diagonally Dominant Matrices**
- Tridiagonal System

The property of **diagonally dominant matrices** is expressed by the inequality $|a_{ii}| > \sum_{\substack{j=2 \\ j \neq i}}^n |a_{ij}| \quad (1 \leq i \leq n).$

It has the property that Gaussian elimination without pivoting can be safely used.

Gaussian elimination without pivoting preserves the diagonal dominance of a matrix.

Proof.

It suffices to consider the first step in Gaussian elimination, so we have to prove that for $i = 2, 3, \dots, n$,

$$|a_{ii}^{(2)}| > \sum_{\substack{j=2 \\ j \neq i}}^n |a_{ij}^{(2)}|$$

In terms of A , this means $|a_{ii} - (a_{i1}/a_{11})a_{1i}| > \sum_{\substack{j=2 \\ j \neq i}}^n |a_{ij} - (a_{i1}/a_{11})a_{1j}|$

It suffices to prove the stronger inequality

$$|a_{ii}| - |(a_{i1}/a_{11})a_{1i}| > \sum_{\substack{j=2 \\ j \neq i}}^n \{|a_{ij}| + |(a_{i1}/a_{11})a_{1j}|\}$$

An equivalent inequality is $|a_{ii}| - \sum_{\substack{j=2 \\ j \neq i}}^n |a_{ij}| > \sum_{j=2}^n |(a_{i1}/a_{11})a_{1j}|$

Form the diagonal dominance in the i th row, we know that

$$|a_{ii}| - \sum_{\substack{j=2 \\ j \neq i}}^n |a_{ij}| > |a_{i1}|$$

Hence, it suffices to prove that $|a_{i1}| \geq \sum_{j=2}^n |(a_{i1}/a_{11})a_{1j}|$

This is true because of the diagonal dominance in row 1:

$$|a_{11}| > \sum_{j=2}^n |a_{1j}| \implies 1 > \sum_{j=2}^n |a_{1j}/a_{11}|$$



Diagonally Dominant Matrices

COROLLARY 1 (First Corollary on Diagonally Dominant Matrix)

Every diagonally dominant matrix is nonsingular and has an LU -factorization.

COROLLARY 2 (Second Corollary on Diagonally Dominant Matrix)

If the scaled row pivoting version of Gaussian elimination recomputes the scale array after each major step and is applied to a diagonally dominant matrix, then the pivots will be the natural ones: $1, 2, \dots, n$. Hence, the work of choosing the pivots can be omitted in this case.

Diagonally Dominant Matrices

Proof.

By Theorem 5, we only need to prove that the first pivot chosen in the algorithm is 1. So we should prove $|a_{11}|/s_1 > |a_{i1}|/s_i$ ($2 \leq i \leq n$).

By the diagonal dominance, $|a_{ii}| = \max_j |a_{ij}| = s_i$ for all i .

Hence, $|a_{11}|/s_1 = 1$.

For $i \geq 2$, We have $|a_{i1}| \leq \sum_{\substack{j=2 \\ j \neq i}}^n |a_{ij}| < |a_{ii}| = s_i$

Thus, $|a_{i1}|/s_i < 1$. □

1 Pivoting and Constructing an algorithm

- Basic Gaussian Elimination
- Pivoting
- Gaussian Elimination with Scaled Row Pivoting
- Factorizations $PA = LU$
- Operation Counts
- Diagonally Dominant Matrices
- Tridiagonal System

Tridiagonal System

- A square matrix $A = (a_{ij})$ is said to be tridiagonal if $a_{ij} = 0$ for all pairs (i, j) that satisfy $|i - j| > 1$.

$$\begin{bmatrix} d_1 & c_1 & & & & & \\ a_1 & d_2 & c_2 & & & & \\ & a_2 & d_3 & c_3 & & & \\ & & a_3 & d_4 & c_4 & & \\ & & & \ddots & \ddots & \ddots & \\ & & & & a_{n-2} & d_{n-1} & c_{n-1} \\ & & & & & a_{n-1} & d_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ \vdots \\ x_{n-1} \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \\ \vdots \\ b_{n-1} \\ b_n \end{bmatrix}$$

Tridiagonal System

- Step 1 consists of these replacements:

$$d_2 \leftarrow d_2 - (a_1/d_1)c_1$$

$$b_2 \leftarrow b_2 - (a_1/d_1)b_1$$

In the back substitution phase, the first step is

$$x_n \leftarrow b_n/d_n$$

The next step is

$$x_{n-1} \leftarrow (b_{n-1} - c_{n-1}x_n)/d_{n-1}$$

Tridiagonal System

```
input  $n, (a_i), (b_i), (c_i), (d_i)$ 
for  $i = 2$  to  $n$  do
     $d_i \leftarrow d_i - (a_{i-1}/d_{i-1})c_{i-1}$ 
     $b_i \leftarrow b_i - (a_{i-1}/d_{i-1})b_{i-1}$ 
end do
 $x_n \leftarrow b_n/d_n$ 
for  $i = n - 1$  to  $1$  step  $-1$  do
     $x_i \leftarrow (b_i - c_i x_{i+1})/d_i$ 
end do
output( $x_i$ )
```

Tridiagonal System

```
1 function x=tri(a,b,c,d)
2 n=length(d);
3 for i=2:n
4     d(i)=d(i)-(a(i-1)/d(i-1))*c(i-1);
5     b(i)=b(i)-(a(i-1)/d(i-1))*b(i-1);
6 end
7 x(n)=b(n)/d(n);
8 for i=n-1:-1:1
9     x(i)=(b(i)-c(i)*x(i+1))/d(i);
10 end
```