Numerical Analysis Mathematics of Scientific Computing

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- Basic Concepts and Taylor's Theorem
 - Limit, Continuity, and Derivative
 - Taylor's Theorem
 - Other Forms of Taylor's Formula

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If f is a real-valued function of a real variable, then the limit of the function f at c (if it exists) is defined as the following:

$$\lim_{x \to c} f(x) = L$$

means that to each positive ε there corresponds a positive δ such that the distance between f(x) and L is less than ε whenever the distance between x and c is less than δ ; that is $|f(x)-L|<\varepsilon$ whenever $0<|x-c|<\delta$.

If there is no number L with this property, the limit of f at c does not exist.

If f is defined only on a specified subset X of the real line, the definition of limit is modified so that $|f(x)-L|<\varepsilon$ whenever $x\in X$ and $0<|x-c|<\delta$.

The function f is said to be continuous at c if

$$\lim_{x \to c} f(x) = f(c)$$

THEOREM 1 Intermediate-Value Theorem for Continuous Functions

On an interval [a,b], a continuous function assumes all values between f(a) and f(b).

The derivative of f at c (if it exists) is defined by the equation

$$f'(c) = \lim_{x \to c} \frac{f(x) - f(c)}{x - c}$$

If f is a function for which f(c) exists, we say that f is differentiable at c, then f must be continuous at c, f(x) exists and $\lim_{x\to c} f(x) = f(c)$.

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THEOREM 2 Taylor's Theorem with Lagrange Remainder

If $f \in C^n[a, b]$ and if $f^{(n+1)}$ exists on the open interval (a,b), then for any points c and x in the closed interval [a,b],

$$f(x) = \sum_{k=0}^{n} \frac{1}{k!} f^{(k)}(c) (x-c)^k + E_n(x)$$

where , for some point ξ between c and x , the error term is

$$E_n(x) = \frac{1}{(n+1)!} f^{(n+1)}(\xi)(x-c)^{(n+1)}$$

Here " ξ between c and x" means that either $c < \xi < x$ or $x < \xi < c$ depending on the particular values of x and c involved.

An important special case arises when c = 0. The equation becomes the **Maclaurin series** for f(x):

$$f(x) = \sum_{k=0}^{n} \frac{1}{k!} f^{(k)}(0) x^{k} + E_{n}(x)$$

where

$$E_n(x) = \frac{1}{(n+1)!} f^{(n+1)}(\xi) x^{(n+1)}$$

THEOREM 3 Mean-Value Theorem

If f is in C[a,b] and if f' exists on the open interval (a,b), then for x and c in the closed interval[a,b],

$$f(x) = f(c) + f'(\xi)(b - a)$$

where ξ is between c and x. Taking x = b and c = a and rearranging, we have the important equation

$$f(b) - f(a) = f(\xi)(b-a)$$
 where $a < \xi < b$

THEOREM 4 Rolle's Theorem

If f is continuous on [a,b], if f exists on (a,b), and if f(a) = f(b), then $f'(\xi) = 0$ for some ξ in the open interval(a,b).

This is an immediate consequence of an equation above. (Actually, in a formal development, Rolle's Theorem is proved first, and from it, Talor's Theorem is derived.) In both Rolle's Theorem and the Mean-value Theorem, there may be more than one point ξ in the interval[a,b] that satisfies the given equations.

THEOREM 5 Taylor's Theorem with Integral Remainder

If $f \in C^{(n+1)}[a,b]$, then for any points x and c in the closed interval [a,b],

$$f(x) = \sum_{k=0}^{n} \frac{1}{k!} f^{(k)}(c) (x-c)^k + R_n(x)$$

where

$$R_n(x) = \frac{1}{n!} \int_{c}^{x} f^{(n+1)}(t) (x-t)^n dt$$

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THEOREM 6 Alternative Form of Taylor's Theorem

If $f \in C^{(n+1)}[a,b]$, then for any points x and x + h in the closed interval [a,b],

$$f(x+h) = \sum_{k=0}^{n} \frac{h^{k}}{k!} f^{(k)}(x) + E_{n}(h)$$

where

$$E_n(h) = \frac{h^{n+1}}{(n+1)!} f^{(n+1)}(\xi)$$

In which the point ξ lies between x and x + h. In detail,

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \frac{h^3}{3!}f'''(x) + \dots + \frac{h^n}{n!}f^{(n)}(x) + E_n(h)$$

It is an important form for many applications.

THEOREM 7 Taylor's Theorem in Two Variables

Let $f \in C^{(n+1)}([\mathbf{a},\mathbf{b}] \times [\mathbf{c},\mathbf{d}])$. If (x,y) and (x+h,y+k) are points in the rectangle $[\mathbf{a},\mathbf{b}] \times [\mathbf{c},\mathbf{d}] \subseteq R^2$, then

$$f(x+h, y+k) = \sum_{i=0}^{n} \frac{1}{i!} \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^{i} f(x+y) + E_n(h, k)$$

where

$$E_n(h,k) = \frac{1}{(n+1)!} \left(h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^{(n+1)} f(x + \theta h, y + \theta k)$$

in which θ lies between 0 and 1.

$$\left(h\frac{\partial}{\partial x} + k\frac{\partial}{\partial y}\right)^{0} f(x,y) = f(x,y)$$

$$\left(h\frac{\partial}{\partial x} + k\frac{\partial}{\partial y}\right)^{1} f(x,y) = \left(h\frac{\partial}{\partial x} + k\frac{\partial}{\partial y}\right)(x,y)$$

$$\left(h\frac{\partial}{\partial x} + k\frac{\partial}{\partial y}\right)^{2} f(x,y) = \left(h^{2}\frac{\partial^{2} f}{\partial x^{2}} + 2hk\frac{\partial^{2} f}{\partial x \partial y} + k^{2}\frac{\partial^{2} f}{\partial y^{2}}\right)(x,y)$$

and so on.Letting $f_x = \frac{\partial f}{\partial x}$, $f_y = \frac{\partial f}{\partial y}$, $f_{xx} = \frac{\partial^2 f}{\partial x^2}$, $f_{xy} = \frac{\partial^2 f}{\partial x \partial y}$, $f_{yy} = \frac{\partial^2 f}{\partial y^2}$, we can write the first few terms of (5) as

$$f(x+h, y+k) = f + (hf_x + kf_y) + \frac{1}{2}(h^2f_{xx} + 2hkf_{xy} + k^2f_{yy}) + \dots$$

where on the right-hand side the function f and each of the following partial derivatives are evaluated at (x,y).