

a b
c d

FIGURE 1.22
(a) and (b) Fractal images. (c) and (d) Images generated from 3-D computer models of the objects shown. (Figures (a) and (b) courtesy of Ms. Melissa D. Binde, Swarthmore College; (c) and (d) courtesy of NASA.)

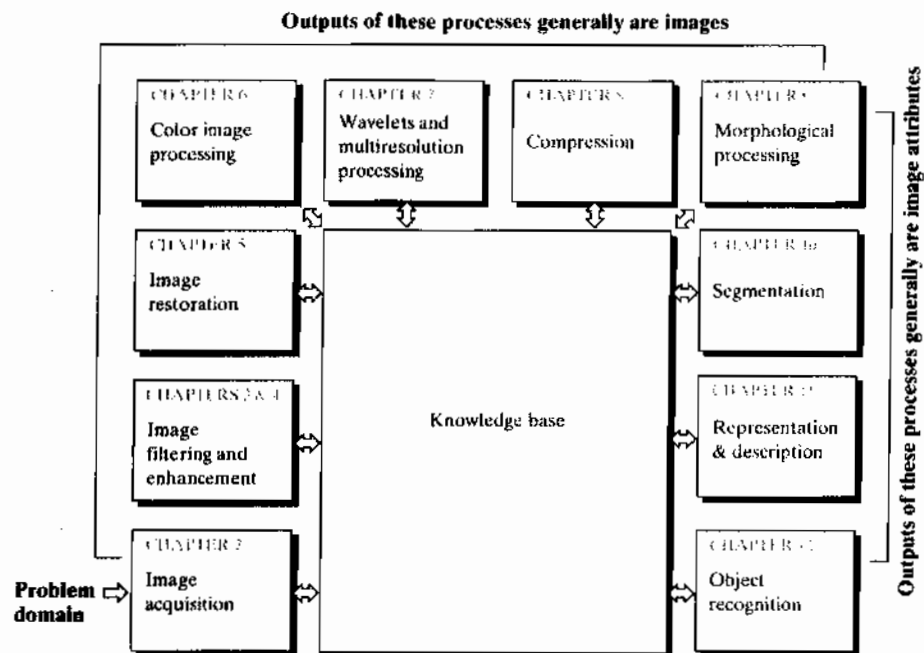
1.4 Fundamental Steps in Digital Image Processing

It is helpful to divide the material covered in the following chapters into the two broad categories defined in Section 1.1: methods whose input and output are images, and methods whose inputs may be images but whose outputs are attributes extracted from those images. This organization is summarized in Fig. 1.23. The diagram does not imply that every process is applied to an image. Rather, the intention is to convey an idea of all the methodologies that can be applied to images for different purposes and possibly with different objectives. The discussion in this section may be viewed as a brief overview of the material in the remainder of the book.

Image acquisition is the first process in Fig. 1.23. The discussion in Section 1.3 gave some hints regarding the origin of digital images. This topic is considered in much more detail in Chapter 2, where we also introduce a number of basic digital image concepts that are used throughout the book. Note that acquisition could be as simple as being given an image that is already in digital form. Generally, the image acquisition stage involves preprocessing, such as scaling.

Image enhancement is the process of manipulating an image so that the result is more suitable than the original for a specific application. The word *specific* is important here, because it establishes at the outset that enhancement techniques are problem oriented. Thus, for example, a method that is quite useful for enhancing X-ray images may not be the best approach for enhancing satellite images taken in the infrared band of the electromagnetic spectrum.

FIGURE 1.23
Fundamental steps in digital image processing. The chapter(s) indicated in the boxes is where the material described in the box is discussed.



There is no general “theory” of image enhancement. When an image is processed for visual interpretation, the viewer is the ultimate judge of how well a particular method works. Enhancement techniques are so varied, and use so many different image processing approaches, that it is difficult to assemble a meaningful body of techniques suitable for enhancement in one chapter without extensive background development. For this reason, and also because beginners in the field of image processing generally find enhancement applications visually appealing, interesting, and relatively simple to understand, we use image enhancement as examples when introducing new concepts in parts of Chapter 2 and in Chapters 3 and 4. The material in the latter two chapters span many of the methods used traditionally for image enhancement. Therefore, using examples from image enhancement to introduce new image processing methods developed in these early chapters not only saves having an extra chapter in the book dealing with image enhancement but, more importantly, is an effective approach for introducing newcomers to the details of processing techniques early in the book. However, as you will see in progressing through the rest of the book, the material developed in these chapters is applicable to a much broader class of problems than just image enhancement.

Image restoration is an area that also deals with improving the appearance of an image. However, unlike enhancement, which is subjective, image restoration is objective, in the sense that restoration techniques tend to be based on mathematical or probabilistic models of image degradation. Enhancement, on the other hand, is based on human subjective preferences regarding what constitutes a “good” enhancement result.

Color image processing is an area that has been gaining in importance because of the significant increase in the use of digital images over the Internet. Chapter 6 covers a number of fundamental concepts in color models and basic color processing in a digital domain. Color is used also in later chapters as the basis for extracting features of interest in an image.

Wavelets are the foundation for representing images in various degrees of resolution. In particular, this material is used in this book for image data compression and for pyramidal representation, in which images are subdivided successively into smaller regions.

Compression, as the name implies, deals with techniques for reducing the storage required to save an image, or the bandwidth required to transmit it. Although storage technology has improved significantly over the past decade, the same cannot be said for transmission capacity. This is true particularly in uses of the Internet, which are characterized by significant pictorial content. Image compression is familiar (perhaps inadvertently) to most users of computers in the form of image file extensions, such as the jpg file extension used in the JPEG (Joint Photographic Experts Group) image compression standard.

Morphological processing deals with tools for extracting image components that are useful in the representation and description of shape. The material in this chapter begins a transition from processes that output images to processes that output image attributes, as indicated in Section 1.1.

Segmentation procedures partition an image into its constituent parts or objects. In general, autonomous segmentation is one of the most difficult tasks in digital image processing. A rugged segmentation procedure brings the process a long way toward successful solution of imaging problems that require objects to be identified individually. On the other hand, weak or erratic segmentation algorithms almost always guarantee eventual failure. In general, the more accurate the segmentation, the more likely recognition is to succeed.

Representation and description almost always follow the output of a segmentation stage, which usually is raw pixel data, constituting either the boundary of a region (i.e., the set of pixels separating one image region from another) or all the points in the region itself. In either case, converting the data to a form suitable for computer processing is necessary. The first decision that must be made is whether the data should be represented as a boundary or as a complete region. Boundary representation is appropriate when the focus is on external shape characteristics, such as corners and inflections. Regional representation is appropriate when the focus is on internal properties, such as texture or skeletal shape. In some applications, these representations complement each other. Choosing a representation is only part of the solution for transforming raw data into a form suitable for subsequent computer processing. A method must also be specified for describing the data so that features of interest are highlighted. *Description*, also called *feature selection*, deals with extracting attributes that result in some quantitative information of interest or are basic for differentiating one class of objects from another.

Recognition is the process that assigns a label (e.g., "vehicle") to an object based on its descriptors. As detailed in Section 1.1, we conclude our coverage of

digital image processing with the development of methods for recognition of individual objects.

So far we have said nothing about the need for prior knowledge or about the interaction between the *knowledge base* and the processing modules in Fig. 1.23. Knowledge about a problem domain is coded into an image processing system in the form of a knowledge database. This knowledge may be as simple as detailing regions of an image where the information of interest is known to be located, thus limiting the search that has to be conducted in seeking that information. The knowledge base also can be quite complex, such as an interrelated list of all major possible defects in a materials inspection problem or an image database containing high-resolution satellite images of a region in connection with change-detection applications. In addition to guiding the operation of each processing module, the knowledge base also controls the interaction between modules. This distinction is made in Fig. 1.23 by the use of double-headed arrows between the processing modules and the knowledge base, as opposed to single-headed arrows linking the processing modules.

Although we do not discuss image display explicitly at this point, it is important to keep in mind that viewing the results of image processing can take place at the output of any stage in Fig. 1.23. We also note that not all image processing applications require the complexity of interactions implied by Fig. 1.23. In fact, not even all those modules are needed in many cases. For example, image enhancement for human visual interpretation seldom requires use of any of the other stages in Fig. 1.23. In general, however, as the complexity of an image processing task increases, so does the number of processes required to solve the problem.

Components of an Image Processing System

As recently as the mid-1980s, numerous models of image processing systems being sold throughout the world were rather substantial peripheral devices that attached to equally substantial host computers. Late in the 1980s and early in the 1990s, the market shifted to image processing hardware in the form of single boards designed to be compatible with industry standard buses and to fit into engineering workstation cabinets and personal computers. In addition to lowering costs, this market shift also served as a catalyst for a significant number of new companies specializing in the development of software written specifically for image processing.

Although large-scale image processing systems still are being sold for massive imaging applications, such as processing of satellite images, the trend continues toward miniaturizing and blending of general-purpose small computers with specialized image processing hardware. Figure 1.24 shows the basic components comprising a typical *general-purpose* system used for digital image processing. The function of each component is discussed in the following paragraphs, starting with image sensing.

With reference to *sensing*, two elements are required to acquire digital images. The first is a physical device that is sensitive to the energy radiated by the object we wish to image. The second, called a *digitizer*, is a device for converting

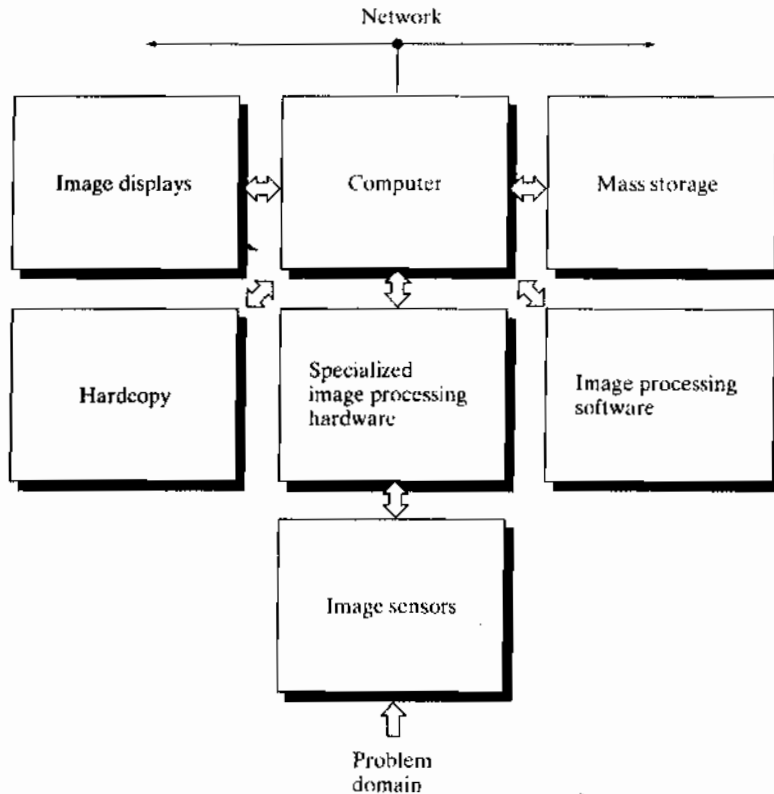


FIGURE 1.24
Components of a
general-purpose
image processing
system.

the output of the physical sensing device into digital form. For instance, in a digital video camera, the sensors produce an electrical output proportional to light intensity. The digitizer converts these outputs to digital data. These topics are covered in Chapter 2.

Specialized image processing hardware usually consists of the digitizer just mentioned, plus hardware that performs other primitive operations, such as an arithmetic logic unit (ALU), that performs arithmetic and logical operations in parallel on entire images. One example of how an ALU is used is in averaging images as quickly as they are digitized, for the purpose of noise reduction. This type of hardware sometimes is called a *front-end subsystem*, and its most distinguishing characteristic is speed. In other words, this unit performs functions that require fast data throughputs (e.g., digitizing and averaging video images at 30 frames/s) that the typical main computer cannot handle.

The *computer* in an image processing system is a general-purpose computer and can range from a PC to a supercomputer. In dedicated applications, sometimes custom computers are used to achieve a required level of performance, but our interest here is on general-purpose image processing systems. In these systems, almost any well-equipped PC-type machine is suitable for off-line image processing tasks.

Software for image processing consists of specialized modules that perform specific tasks. A well-designed package also includes the capability for the user

to write code that, as a minimum, utilizes the specialized modules. More sophisticated software packages allow the integration of those modules and general-purpose software commands from at least one computer language.

Mass storage capability is a must in image processing applications. An image of size 1024×1024 pixels, in which the intensity of each pixel is an 8-bit quantity, requires one megabyte of storage space if the image is not compressed. When dealing with thousands, or even millions, of images, providing adequate storage in an image processing system can be a challenge. Digital storage for image processing applications falls into three principal categories: (1) short-term storage for use during processing, (2) on-line storage for relatively fast recall, and (3) archival storage, characterized by infrequent access. Storage is measured in bytes (eight bits), Kbytes (one thousand bytes), Mbytes (one million bytes), Gbytes (meaning giga, or one billion, bytes), and Tbytes (meaning tera, or one trillion, bytes).

One method of providing short-term storage is computer memory. Another is by specialized boards, called *frame buffers*, that store one or more images and can be accessed rapidly, usually at video rates (e.g., at 30 complete images per second). The latter method allows virtually instantaneous image *zoom*, as well as *scroll* (vertical shifts) and *pan* (horizontal shifts). Frame buffers usually are housed in the specialized image processing hardware unit in Fig. 1.24. On-line storage generally takes the form of magnetic disks or optical-media storage. The key factor characterizing on-line storage is frequent access to the stored data. Finally, archival storage is characterized by massive storage requirements but infrequent need for access. Magnetic tapes and optical disks housed in “jukeboxes” are the usual media for archival applications.

Image displays in use today are mainly color (preferably flat screen) TV monitors. Monitors are driven by the outputs of image and graphics display cards that are an integral part of the computer system. Seldom are there requirements for image display applications that cannot be met by display cards available commercially as part of the computer system. In some cases, it is necessary to have stereo displays, and these are implemented in the form of headgear containing two small displays embedded in goggles worn by the user.

Hardcopy devices for recording images include laser printers, film cameras, heat-sensitive devices, inkjet units, and digital units, such as optical and CD-ROM disks. Film provides the highest possible resolution, but paper is the obvious medium of choice for written material. For presentations, images are displayed on film transparencies or in a digital medium if image projection equipment is used. The latter approach is gaining acceptance as the standard for image presentations.

Networking is almost a default function in any computer system in use today. Because of the large amount of data inherent in image processing applications, the key consideration in image transmission is bandwidth. In dedicated networks, this typically is not a problem, but communications with remote sites via the Internet are not always as efficient. Fortunately, this situation is improving quickly as a result of optical fiber and other broadband technologies.

Summary

The main purpose of the material presented in this chapter is to provide a sense of perspective about the origins of digital image processing and, more important, about current and future areas of application of this technology. Although the coverage of these topics in this chapter was necessarily incomplete due to space limitations, it should have left you with a clear impression of the breadth and practical scope of digital image processing. As we proceed in the following chapters with the development of image processing theory and applications, numerous examples are provided to keep a clear focus on the utility and promise of these techniques. Upon concluding the study of the final chapter, a reader of this book will have arrived at a level of understanding that is the foundation for most of the work currently underway in this field.

References and Further Reading

References at the end of later chapters address specific topics discussed in those chapters, and are keyed to the Bibliography at the end of the book. However, in this chapter we follow a different format in order to summarize in one place a body of journals that publish material on image processing and related topics. We also provide a list of books from which the reader can readily develop a historical and current perspective of activities in this field. Thus, the reference material cited in this chapter is intended as a general-purpose, easily accessible guide to the published literature on image processing.

Major refereed journals that publish articles on image processing and related topics include: *IEEE Transactions on Image Processing*; *IEEE Transactions on Pattern Analysis and Machine Intelligence*; *Computer Vision, Graphics, and Image Processing* (prior to 1991); *Computer Vision and Image Understanding*; *IEEE Transactions on Systems, Man and Cybernetics*; *Artificial Intelligence*; *Pattern Recognition*; *Pattern Recognition Letters*; *Journal of the Optical Society of America* (prior to 1984); *Journal of the Optical Society of America—A: Optics, Image Science and Vision*; *Optical Engineering*; *Applied Optics—Information Processing*; *IEEE Transactions on Medical Imaging*; *Journal of Electronic Imaging*; *IEEE Transactions on Information Theory*; *IEEE Transactions on Communications*; *IEEE Transactions on Acoustics, Speech and Signal Processing*; *Proceedings of the IEEE*; and issues of the *IEEE Transactions on Computers* prior to 1980. Publications of the International Society for Optical Engineering (SPIE) also are of interest.

The following books, listed in reverse chronological order (with the number of books being biased toward more recent publications), contain material that complements our treatment of digital image processing. These books represent an easily accessible overview of the area for the past 30-plus years and were selected to provide a variety of treatments. They range from textbooks, which cover foundation material; to handbooks, which give an overview of techniques; and finally to edited books, which contain material representative of current research in the field.

- Prince, J. L. and Links, J. M. [2006]. *Medical Imaging, Signals, and Systems*, Prentice Hall, Upper Saddle River, NJ.
- Bezdek, J. C. et al. [2005]. *Fuzzy Models and Algorithms for Pattern Recognition and Image Processing*, Springer, New York.
- Davies, E. R. [2005]. *Machine Vision: Theory, Algorithms, Practicalities*, Morgan Kaufmann, San Francisco, CA.
- Rangayyan, R. M. [2005]. *Biomedical Image Analysis*, CRC Press, Boca Raton, FL.

- Umbaugh, S. E. [2005]. *Computer Imaging: Digital Image Analysis and Processing*, CRC Press, Boca Raton, FL.
- Gonzalez, R. C., Woods, R. E., and Eddins, S. L. [2004]. *Digital Image Processing Using MATLAB*, Prentice Hall, Upper Saddle River, NJ.
- Snyder, W. E. and Qi, Hairong [2004]. *Machine Vision*, Cambridge University Press, New York.
- Klette, R. and Rosenfeld, A. [2004]. *Digital Geometry—Geometric Methods for Digital Picture Analysis*, Morgan Kaufmann, San Francisco, CA.
- Won, C. S. and Gray, R. M. [2004]. *Stochastic Image Processing*, Kluwer Academic/Plenum Publishers, New York.
- Soille, P. [2003]. *Morphological Image Analysis: Principles and Applications*, 2nd ed., Springer-Verlag, New York.
- Dougherty, E. R. and Lotufo, R. A. [2003]. *Hands-on Morphological Image Processing*, SPIE—The International Society for Optical Engineering, Bellingham, WA.
- Gonzalez, R. C. and Woods, R. E. [2002]. *Digital Image Processing*, 2nd ed., Prentice Hall, Upper Saddle River, NJ.
- Forsyth, D. F. and Ponce, J. [2002]. *Computer Vision—A Modern Approach*, Prentice Hall, Upper Saddle River, NJ.
- Duda, R. O., Hart, P. E., and Stork, D. G. [2001]. *Pattern Classification*, 2nd ed., John Wiley & Sons, New York.
- Pratt, W. K. [2001]. *Digital Image Processing*, 3rd ed., John Wiley & Sons, New York.
- Ritter, G. X. and Wilson, J. N. [2001]. *Handbook of Computer Vision Algorithms in Image Algebra*, CRC Press, Boca Raton, FL.
- Shapiro, L. G. and Stockman, G. C. [2001]. *Computer Vision*, Prentice Hall, Upper Saddle River, NJ.
- Dougherty, E. R. (ed.) [2000]. *Random Processes for Image and Signal Processing*, IEEE Press, New York.
- Etienne, E. K. and Nachtgael, M. (eds.) [2000]. *Fuzzy Techniques in Image Processing*, Springer-Verlag, New York.
- Goutsias, J., Vincent, L., and Bloomberg, D. S. (eds.) [2000]. *Mathematical Morphology and Its Applications to Image and Signal Processing*, Kluwer Academic Publishers, Boston, MA.
- Mallot, A. H. [2000]. *Computational Vision*, The MIT Press, Cambridge, MA.
- Marchand-Maillet, S. and Sharaiha, Y. M. [2000]. *Binary Digital Image Processing: A Discrete Approach*, Academic Press, New York.
- Mitra, S. K. and Sicuranza, G. L. (eds.) [2000]. *Nonlinear Image Processing*, Academic Press, New York.
- Edelman, S. [1999]. *Representation and Recognition in Vision*, The MIT Press, Cambridge, MA.
- Lillesand, T. M. and Kiefer, R. W. [1999]. *Remote Sensing and Image Interpretation*, John Wiley & Sons, New York.
- Mather, P. M. [1999]. *Computer Processing of Remotely Sensed Images: An Introduction*, John Wiley & Sons, New York.
- Petrou, M. and Bosdogianni, P. [1999]. *Image Processing: The Fundamentals*, John Wiley & Sons, UK.
- Russ, J. C. [1999]. *The Image Processing Handbook*, 3rd ed., CRC Press, Boca Raton, FL.