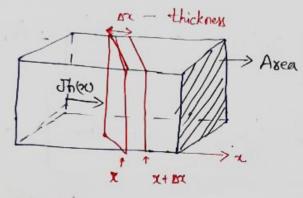
(33)

## The Continuity Equation

> All semiconductor devices operates under non equilibrium conditions in which covered of holes and electrions flow through the semicondudor > The equaction that stades a condition of elyramic couriers in elementary valume of the serviconductor is known as continuity equation.



lised form

In(x) = coverent dentity at a point

In (x+ Dx) = Correct density concentration gradiant Charge in e- concentration: -

$$\frac{\partial n}{\partial t} A \cdot \Delta x = \frac{J_n(\alpha)}{-q} - \frac{J_n(\alpha + \Delta \alpha)}{-q} + (G_n - R_n) A \cdot \Delta \alpha$$
(here)

Charge in e consendancion = no of e flowing - no of e flowing with time and in Box out of Box

no of e increased to no of e generaled to no of e

Box hole stecom

Think in Box hime in Box

Think in Box

Here, => -9 for e charge corrier.

$$\frac{\partial n}{\partial t} \not R \not \Delta = \frac{J_n(x) \cdot \partial t}{-q} \cdot \frac{\partial t}{\partial x} - \frac{J_n(x + \Delta x)}{q} \cdot \mathcal{R} \underbrace{\frac{\partial n}{\partial x}}_{+(n - R_n)} = \frac{1}{q} \underbrace{\begin{bmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{bmatrix}}_{+(n - R_n)} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x \end{pmatrix}}_{-q \cdot \Delta x} + \underbrace{\begin{pmatrix} J_p(x + \Delta x) \\ -q \cdot \Delta x$$

(GP-RP) A DA

Semicordudor.

$$\frac{A}{\Delta x} = \frac{1}{2} \left[ \frac{J_p(x+\Delta x) - J_p(x)}{\Delta x} \right] + (G_p - R_p) \frac{A - \Delta x}{\Delta x}$$

eg? (2) & B/as continuity equation of Servicorductor.