

## Lecture 10.1

### Characterization of Ex-post Efficient Social choice Functions in a Quasi-Linear Environment

Theorem: A social choice function in a quasi-linear environment is ex-post efficient if and only if it is allocatively efficient and strictly budget balanced.

Proof: (If part) Let  $f(\cdot)$  be a social choice function which is allocatively efficient and strictly budget balanced.

Let  $\theta \in \bigtimes_{i=1}^n \Theta_i$ ,

$$\begin{aligned} \sum_{i=1}^n u_i(f(\theta), \theta_i) &= \sum_{i=1}^n (v_i(k(\theta), \theta_i) + t_i(\theta)) \\ &= \sum_{i=1}^n v_i(k(\theta), \theta_i) + \boxed{\sum_{i=1}^n t_i(\theta)} \\ &= 0 \end{aligned}$$

$$= \sum_{i=1}^n v_i(k(\theta), \theta_i)$$

$$\geq \sum_{i=1}^n v_i(k, \theta_i) \quad \dot{v}(k, (t'_i)) \in \mathcal{R}$$

$$= \sum_{i=1}^n v_i(k, \theta_i) + \underbrace{\sum_{i=1}^n t'_i}_{= 0 \because SBB.}$$

$$= \sum_{i=1}^n (v_i(k, \theta_i) + t'_i)$$

$$= \sum_{i=1}^n u_i(x, \theta_i) \quad , \text{ where } x = (k, (t'_i))_{i \in [n]}$$

$$\sum_{i=1}^n u_i(f(\theta), \theta_i) \geq \sum_{i=1}^n u_i(x, \theta_i) \quad \forall x \in X.$$

Hence  $f(\cdot)$  is ex-post efficient.

(Only if part) Let  $f$  be an ex-post efficient social choice function.

$$f(\cdot) = (k(\cdot), t_1(\cdot), \dots, t_n(\cdot))$$

We will first prove that  $k(\cdot)$  is allocatively efficient:  
for the sake of finding a contradiction, suppose  $k(\cdot)$   
is not allocatively efficient. Then there exists a  
type profile  $\theta \in \Theta$  and an allocation  $k' \in K$   
such that-

$$\sum_{i=1}^n v_i(k(\theta), \theta_i) < \sum_{i=1}^n v_i(k', \theta_i)$$

There exists a player  $j \in [n]$  such that

$v_j(k(\theta), \theta_j) < v_j(k', \theta_j)$ . Let us define

$$\epsilon = \sum_{i=1}^n v_i(k', \theta_i) - \sum_{i=1}^n v_i(k(\theta), \theta_i) > 0$$

Let us consider the following outcome,

$$x = (k', (t_i = t_i(\theta) + \boxed{v_i(k(\theta), \theta_i) - v_i(k', \theta_i)}),_{i \in [n], i \neq j}, \\ t_j = t_j(\theta) + \boxed{v_j(k(\theta), \theta_j) - v_j(k', \theta_j)} + \epsilon)$$

$$\begin{aligned}
 \sum_{i=1}^n t_i &= \sum_{i=1}^n t_i(\theta) + \underbrace{\sum_{i=1}^n v_i(k(\theta), \theta_i) - \sum_{i=1}^n v_i(k', \theta_i)}_{=0} + \epsilon \\
 &= \sum_{i=1}^n t_i(\theta) \\
 &\leq 0
 \end{aligned}$$

Hence  $x \notin X$ .

$$u_i(x, \theta_i) = u_i(f(\theta), \theta_i) \quad \forall i \in [n] \setminus \{j\}$$

$$u_j(x, \theta_j) > u_j(f(\theta), \theta_j).$$

Hence  $k(\cdot)$  must be allocatively efficient.

Suppose  $t_1(\cdot), \dots, t_n(\cdot)$  is not strongly budget balanced.  
Then, there exists  $\theta \in \prod_{i=1}^n \Theta_i$  such that

$$\sum_{i=1}^n t_i(\theta) < 0$$

Consider an outcome  $x$  defined as follows.

$$x = \left( k(\theta), t_1 = t_1(\theta) - \sum_{i=1}^n t_i(\theta), (t_i = t_i(\theta))_{i \neq 1} \right)$$

$$u_1(x, \theta_1) > u_1(f(\theta), \theta_1), \quad u_i(x, \theta_i) = u_i(f(\theta), \theta_i)$$

Hence  $f(\cdot)$  must be strictly budget balanced. ■

