

Lecture 9.5

Quasi-Linear Setting / Environment

The outcomes are not arbitrary. In particular, an outcome is a tuple (k, t_1, \dots, t_n) . The first component k is an allocation which belongs to a set \mathcal{K} of set of allocations. t_i is the money received by player i .

The set of outcomes:

$$\chi = \{(k, t_1, \dots, t_n) \mid k \in \mathbb{R}, \sum_{i=1}^n t_i \leq 0\}$$

since no external supply of money.

The utility function has the following structure.

$$\begin{aligned} u_i(x, \theta_1, \dots, \theta_n) &= u_i(k, t_1, \dots, t_n, \theta_1, \dots, \theta_n) \\ &= u_i(k, t_1, \dots, t_n, \theta_i) \\ &= v_i(k, \theta_i) + t_i \end{aligned}$$

$v_i(k, \theta_i)$ is the valuation of allocation k to player i when its type is θ_i .

$$\text{utility} = \text{valuation} + \text{payment}.$$

A social choice function $f(\theta_1, \dots, \theta_n)$ has the following structure:-

$$f(\theta_1, \dots, \theta_n) = (k(\theta_1, \dots, \theta_n), (t_i(\theta_1, \dots, \theta_n))_{i \in [n]})$$

The social choice function consists of two functions.

(i) Allocation function: $k: \prod_{i=1}^n \Theta_i \rightarrow \mathbb{R}$

(ii) payment functions: $t_j: \prod_{i=1}^n \Theta_i \rightarrow \mathbb{R}$

Q: How does any efficient social choice function look like in a quasi-linear environment?

Allocative Efficiency (AE): An allocation function is called allocatively efficient if

$\forall (\theta_1, \dots, \theta_n) \in \bigtimes_{i=1}^n \mathbb{H}$, we have

$$k(\theta_1, \dots, \theta_n) \in \operatorname{argmax}_{k \in \mathcal{R}} \sum v_i(k, \theta_i)$$

equivalently,

$$\sum_{i=1}^n v_i(k(\theta_1, \dots, \theta_n), \theta_i) = \max_{k \in \mathcal{R}} \sum_{i=1}^n v_i(k, \theta_i)$$

Budget Balanced (BB): The payment functions $(t_i(\cdot))_{i \in [n]}$

are called strongly budget balanced (sBB) if

$$\forall (\theta_1, \dots, \theta_n) \in \bigtimes_{i=1}^n \Theta_i,$$

$$\sum_{i=1}^n t_i(\theta_1, \dots, \theta_n) = 0$$

The payment functions $(t_i(\cdot))_{i \in [n]}$ are called weakly budget-balanced if

$$\forall (\theta_1, \dots, \theta_n) \in \bigtimes_{i=1}^n \Theta_i,$$

$$\sum_{i=1}^n t_i(\theta_1, \dots, \theta_n) \leq 0$$

Observation: If we have at least two players, then no social choice function is dictatorial in a quasi-linear environment.

Proof: Let $n (\geq 2)$ be the number of players. If possible, let us assume that there exists a social choice function $f(\cdot)$ where a player, say player d , is a dictator.

Let $\epsilon > 0$ be any positive real number, & any type profile. Suppose $f(\theta) = (k(\theta), (t_d(\theta), t_{-d}(\theta)))$

Consider the outcome,

$$x = \left(k(\theta), \left(t_j(\theta) - \epsilon \right)_{j \in [n], j \neq d}, t_d(\theta) + (n-1)\epsilon \right)$$

$$\begin{aligned} u_d(x, \theta_d) &= \underbrace{v_d(k(\theta))}_{\text{constant}} + \underbrace{t_d}_{\text{constant}} + (n-1)\epsilon \\ &= u_d(f(\theta), \theta_d) + (n-1)\epsilon \\ &> u_d(f(\theta), \theta_d) \end{aligned}$$

This contradicts our assumption that d is the dictator
of the social choice function f . □