

Single Parameter Domain

Lecture 11.4

The allocation rules implementable in DSE in the single parameter domain are monotone allocation rule.

Recall: The allocation rules implementable in DSE in quasi-linear environment (Groves Theorem and Roberts Theorem) are the affine maximizers.

Example of affine maximizer:

$$k(\theta_1, \dots, \theta_n) = \arg \max_{k \in \mathcal{R}} \sum_{i=1}^n a_i v_i(k, \theta) + c$$

$$a_i \geq 0, c \in \mathbb{R}$$

Monotone

Affine maximizer

Examples of monotone allocation rules which are not

affine maximizer:-

$$k(\theta_1, \dots, \theta_n) = \arg \max_{k \in \mathcal{R}} \sum_{i=1}^n a_i v_i(k, \theta_i)^{\lambda_i} + c$$

$$a_i, \lambda_i \in \mathbb{R}_{\geq 0}, c \in \mathbb{R}.$$

Recall, we have worked with a restricted version of single parameter domain.

Myerson's Lemma: We have the following in any single-parameter domain.

- (i) An allocation rule $k: \Theta \rightarrow \mathcal{K}$ is DSIC if and only if $k(\cdot)$ is monotone in each θ_i .
- (ii) If $k(\cdot)$ is monotone, there exist unique payment rules $t_1(\cdot), \dots, t_n(\cdot)$ where players reporting 0

as their type do not pay anything such that the mechanism $f(\cdot) = (k(\cdot), t_1(\cdot), \dots, t_n(\cdot))$ is DSIC.

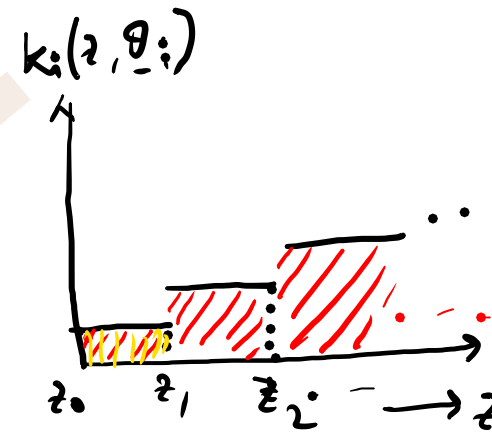
(ii) The payment rule of part (ii) is given by the following explicit formula.

$$t_i(\theta_i, \underline{\theta}_i) = - \int_{\underline{\theta}_i}^{\theta_i} z \cdot \frac{d}{dz} k_i(z, \theta_i) dz.$$

where $k(\cdot) = (k_1(\cdot), \dots, k_n(\cdot))$, $k_i(\cdot)$ is differentiable in its domain.

If $k_i(\cdot)$ is a step function having jumps at z_0, z_1, z_2, \dots

$$t_i(\theta_i, \theta_i) = k_i(z_0, \theta_i) \cdot (z_1 - z_0) + k_i(z_1, \theta_i) \cdot (z_2 - z_1) + \dots$$



Uniqueness of VCG Payment Rule: Assume Θ_i is connected.

in some Euclidean space for every $i \in [n]$. Let

$f(\cdot) = (k(\cdot), t_1(\cdot), \dots, t_n(\cdot))$ be DSIC. If $f'(\cdot) = (k(\cdot), t'_1(\cdot), \dots,$

$t'_n(\cdot))$ is also DSIC, then

$$\forall \theta \in \Theta, \quad t'_i(\theta) = t_i(\theta) + h_i(\underline{\theta}_i)$$

for some function $h_i: \Theta_i \rightarrow \mathbb{R}$.

