

Given (Ω, \mathcal{F}, P) and $A \in \mathcal{F}$ with $P(A) > 0$,
we have the conditioned probability measure

$$P_A(B) = P[B|A] = \frac{P(A \cap B)}{P(A)}.$$

We can then take integrals of random variables $X \in L^1(\Omega, \mathcal{F}, P_A)$

$$\mathbb{E}_A[X] = \mathbb{E}[X|A] = \int X dP_A$$

Lemma: $L^1(P) = L^1(P_A)$, and $\mathbb{E}_A[X] = \frac{\mathbb{E}[X|A]}{P(A)} \leftarrow \mathbb{E}[X|A]$

Pf. If X is simple, $X = \sum_j \alpha_j \mathbb{1}_{B_j}$, then

$$\int X dP_A = \sum_j \alpha_j P_A(B_j) = \sum_j \alpha_j \frac{P(A \cap B_j)}{P(A)} = \frac{1}{P(A)} \int \underbrace{\sum_j \alpha_j \mathbb{1}_{B_j \cap A}}_{\left(\sum_j \alpha_j \mathbb{1}_{B_j} \right) \mathbb{1}_A} dP$$

For general $X = X^+ - X^-$ $X_n^+ + X_n^- \leq X^+ + X^- = |X| \in L^1$

$$\mathbb{E}[X|A]/P(A)$$

$$0 \leq X_n^\pm \leq X^\pm$$

$$|X_n^+ - X_n^-|$$

$$= \mathbb{E}[X|A] \frac{\mathbb{1}_A}{P(A)}$$

$$\underbrace{\int X_n^+ \mathbb{1}_A dP - \int X_n^- \mathbb{1}_A dP}_{P(A)} = \int (X_n^+ - X_n^-) dP_A \rightarrow \int X dP_A$$

If $\{A_n\}_{n=1}^\infty$ is a partition of Ω by events with $P(A_n) > 0$, we can string the different E_{A_n} functionals together into a single function:

$$E_{\{A_n\}_{n=1}^\infty}[X] = \sum_{n=1}^{\infty} E_{A_n}[X] \mathbb{I}_{A_n}$$

I.e., $\omega \mapsto \left\{ \begin{array}{l} : \\ : \\ E_{A_n}[x] = \frac{E[X|A_n]}{P(A_n)} \text{ for } \omega \in A_n. \end{array} \right.$

Labeling: instead of indexing this by the partition $\{A_n\}_{n=1}^\infty$, it is more convenient (and suggestive) to label it by $\mathcal{G} = \sigma(\{A_n\}_{n=1}^\infty)$.

This makes sense because:

Exercise: If $A_n \in \mathcal{F}$ with $\Omega = \bigsqcup_{n=1}^\infty A_n$, then

$$\sigma(\{A_n\}_{n=1}^\infty) = \left\{ \bigsqcup_{n \in \Lambda} A_n : \Lambda \subseteq \mathbb{N} \right\}$$

Thus, we can "recover" the partition from \mathcal{G} (minimal generating set)

Cor: If $\mathcal{G} = \sigma(\{A_n\}_{n=1}^{\infty})$ for some partition $\{A_n\}_{n=1}^{\infty}$,

then $E_{\mathcal{G}}[X]$ is \mathcal{G} -measurable.

Pf. $E_{\mathcal{G}}[X] = \sum_{n=1}^{\infty} E_{A_n}[X] 1_{A_n}$ is a linear combination

of the indicator functions $1_{A_n} \in \mathcal{G}$. ///

$$\sigma(E_{\mathcal{G}}[X]) = \mathcal{G}.$$

Note: even in this special case where \mathcal{G} is generated by a countable partition, it is not practically possible to recover the partition from \mathcal{G} (unless \mathcal{G} , and \therefore the partition, is finite)

(Motivating) Eg. Suppose $Y: \Omega \rightarrow S$ is a random variable whose state space S is countable, and $P(Y=s) > 0$ for each $s \in S$. Then $\{Y^{-1}(s) : s \in S\}$ forms a partition of Ω .

$$\begin{aligned} &\sigma \{Y^{-1}(s) : s \in S\} \\ &\sigma(Y) \end{aligned}$$

For $X \in L^1(\Omega, \mathcal{F}, P)$,

$$E[X|Y] = E[X|\sigma(Y)] = \sum_{s \in S} E_{\{Y=s\}}[X] \mathbb{1}_{\{Y=s\}} = \sum_{s \in S} \frac{E[X : Y=s]}{P(Y=s)} \mathbb{1}_{\{Y=s\}}$$

$$E[X|Y](\omega) = \frac{E[X \mathbb{1}_{Y=Y(\omega)}]}{P(Y=Y(\omega))}$$

$E[X|Y]$ is $\sigma(Y)$ -measurable $\xrightarrow{\text{only depends on } \omega \text{ through } Y(\omega)}$

\therefore by Doob-Dynkin, $E[X|Y] = g(Y)$ for some $g: S \rightarrow \mathbb{R}$

$$\begin{aligned} g(s) &= "E[X|Y=s]" \\ &= E_{P_{\{Y=s\}}}[X] \end{aligned}$$

There is a more "invariant" way to define
conditioned expectation, owing to the following.

Prop: Let $\{A_n\}_{n=1}^{\infty}$ be a partition of Ω by positive probability events, and set $\mathcal{G} = \sigma(\{A_n\}_{n=1}^{\infty})$. If $X \in L^2(\Omega, \mathcal{F}, P)$ and $Y \in L^2(\Omega, \mathcal{G}, P)$, then

$$\mathbb{E}[XY] = \mathbb{E}[\mathbb{E}_Y[X]Y].$$

Pf. Step 1: the case that Y is simple. So $Y = \sum_j \beta_j \mathbb{1}_{B_j} \leftarrow B_j \in \mathcal{G}$

$$\therefore \mathbb{E}[XY] = \sum_{k=1}^{\infty} \beta'_k \mathbb{E}[X \mathbb{1}_{A_k}]$$

$$\mathbb{E}_Y[X] = \sum_{j=1}^{\infty} \mathbb{E}_{A_j}[X] \mathbb{1}_{A_j} \quad \leftarrow \quad Y = \sum_{k=1}^{\infty} \beta'_k \mathbb{1}_{A_k}$$

$$\begin{aligned} \text{So } \mathbb{E}[\mathbb{E}_Y[X]Y] &= \sum_{j,k=1}^{\infty} \mathbb{E}_{A_j}[X] \beta'_k \mathbb{E}[\mathbb{1}_{A_j} \mathbb{1}_{A_k}] \\ &= \sum_{k=1}^{\infty} \mathbb{E}_{A_k}[X] \beta'_k P(A_k) \\ &\quad \leftarrow \quad S_{jk} \mathbb{E}[\mathbb{1}_{A_k}] = S_{jk} P(A_k) \\ &= \beta'_k \mathbb{E}[X \mathbb{1}_{A_k}] \end{aligned}$$

Step 2: If $Y \in L^2(\Omega, \mathcal{G}, P) \subseteq L^1(\Omega, \mathcal{G}, P)$,

\exists sequence of simple Y_n (\mathcal{G} -measurable) s.t.

$$Y_n \rightarrow Y \text{ a.s. and } |Y_n| \leq |Y| \in L^2$$

$\therefore XY_n \rightarrow XY \text{ a.s. and } |XY_n| \leq |XY| \in L^1 \text{ b/c } XY \in L^2 \text{ by CS}$

\therefore By DCT, $E[XY_n] \rightarrow E[XY]$ $|E_Y[X]Y_n| \leq |E_Y[X]Y| \in L^1$

$$\text{DCT} \quad E\left[\sum_{j=1}^n E_{A_j}[X] Y_n\right] \xrightarrow{\text{DCT}} E\left[\sum_{j=1}^n E_{A_j}[X] Y\right]$$

$$\text{Note: } \|E_Y[X]\|_{L^2}^2 = E\left[\left(\sum_{j=1}^n E_{A_j}[X] \mathbb{1}_{A_j}\right)^2\right] = \sum_{j=1}^n \underbrace{E_{A_j}[X]^2}_{P(A_j)} \leq \sum_{j=1}^n E[X^2 \mathbb{1}_{A_j}] \xrightarrow{\text{DCT}} E[X^2] = \|X\|_{L^2}^2$$

$$\begin{aligned} & (\mathbb{E}[X \mathbb{1}_{A_j}])^2 \\ & \leq \mathbb{E}[(X \mathbb{1}_{A_j})^2] \mathbb{E}[\mathbb{1}_{A_j}^2] \\ & = \mathbb{E}[X^2 \mathbb{1}_{A_j}] P(A_j) \end{aligned}$$