Convolutional neural network:-((NN)

the main objective of CNN is to do the image purcessing, image classification.

The process of conventing to as a grayscale (Black Stubile) or the RGB image into simpler image with minimum scale is cared the convolution.

again and again inorder to purcess the image as step by step.

* The convolutional layers will d'here
detect dépenent parts of image such as e
Vertical edge, horizontal edge, using
différent filters.

Lets consider a 6x6 image (Black & White image)

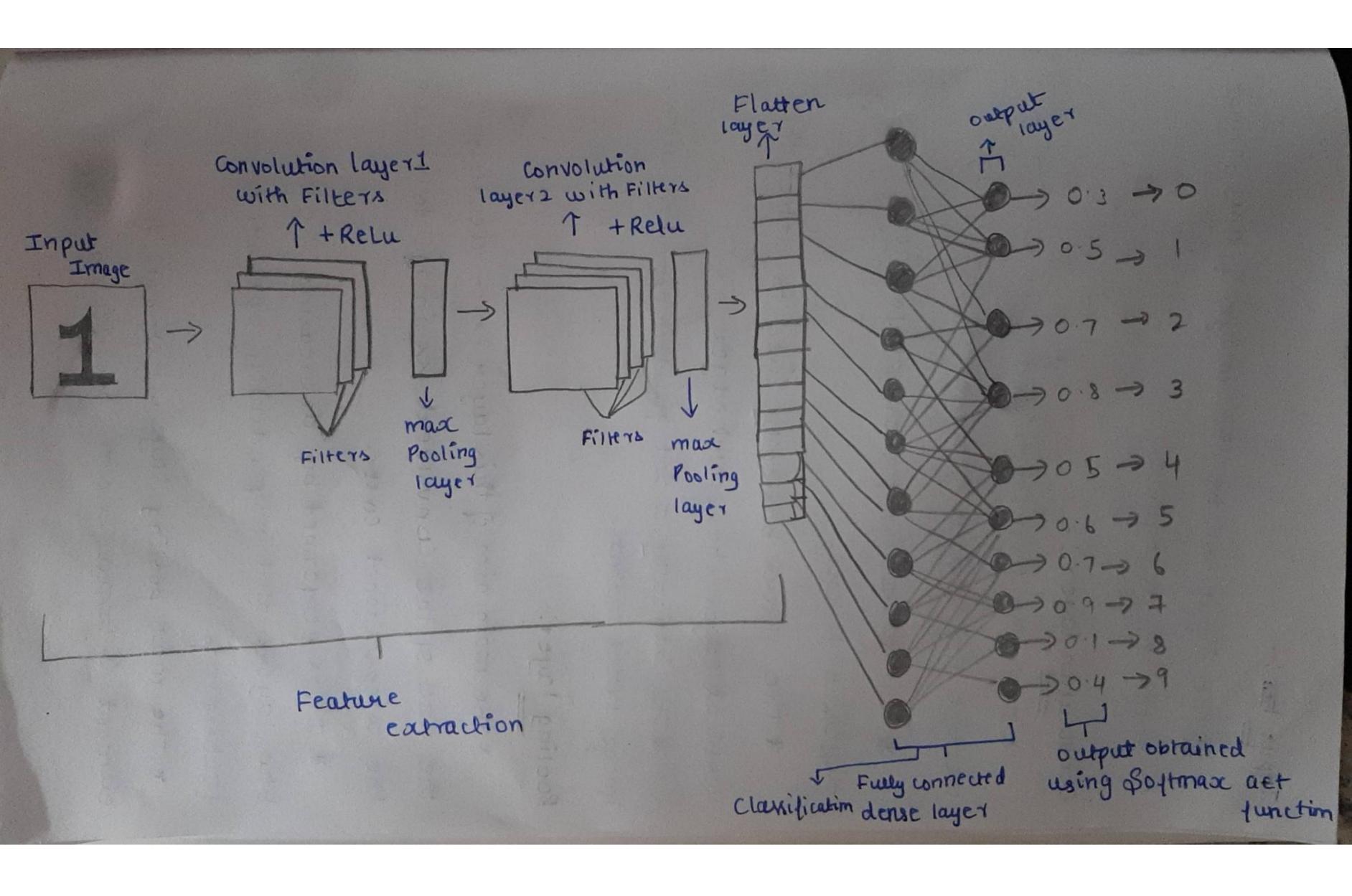
Grayscale: 0-255 0=)dork 255=)light

The same of the sa			_		
0	0	0	256	255	255
0	0	0	255	255	255
0	0	0	255	255	255
0	0	0	255	255	255
0	0	0	255	255	255
0	0	0	255	255	255

6×6

* Now the task is to puwcers this 6×6 image.

I For this we have to do convolution puwcers
using filter.



*The input will be the image of any format
in order to recognize.

convolution layer:-

* It is the first layer and it is used to extract the various yeatures of the image.

* The extraction process payormed using different filters.

* The filters basically used to detect the Vertical edges, horizontal edges

#Its basically a dot puroduct operation with image Pixel matrix.

Pooling layer:

* The main aim of this layer is to decrease the size of the convolved yes image to reduce the computational costs.

btw layers and independently operates on each leature map.

* The max pooling layer earracts the largest element is tooken from the yeather map

it literally means, it extracts the maximum information of feature map.

in a puedefined sized image section.

Fully connected layer:-

& It is the dense layer

It The output person the convolution layer will be glavened in the player layer.

It then values in platter layer given to the dense layer.

& Then actual ANN purocess takes place.

If then output will be puroduced as classified what the image is, Like, if the input is image of number, then output will be number.