## simple\_CNN\_GRAD\_CAM-256x

## May 20, 2024

```
[1]: import os
     import pandas as pd
     import numpy as np
     import seaborn as sns
     import tensorflow as tf
     from tensorflow.keras import layers, models
     from tensorflow.keras.callbacks import ModelCheckpoint
     from tensorflow.keras.preprocessing.image import ImageDataGenerator
     from tensorflow.keras.preprocessing.image import img_to_array, load_img
     from sklearn.metrics import confusion_matrix, classification_report
     from sklearn.model_selection import train_test_split
     import matplotlib.pyplot as plt
     import matplotlib.cm as cm
     import cv2
     # Update image size to 128x128
     w, h = 256, 256
     batch_size = 5
     train_data_gen = ImageDataGenerator(rescale = 1.0/255)
     test_data_gen = ImageDataGenerator(rescale = 1.0/255)
     train_Dataset = train_data_gen.flow_from_directory(
         "../images/car/preprocessed_256x/train",
         target_size = (w, h),
         batch_size = batch_size,
         class_mode = 'binary',
         shuffle = True
     )
     test_Dataset = test_data_gen.flow_from_directory(
         "../images/car/preprocessed_256x/test",
         target_size = (w, h),
```

```
batch_size = batch_size,
    class_mode = 'binary',
    shuffle = False
# Update model architecture
model = models.Sequential()
model.add(layers.Conv2D(16, (3, 3), activation='relu', input_shape=(w, h, 3),

¬name='conv2d 1'))
model.add(layers.MaxPooling2D((2, 2), name='max_pooling2d_1'))
model.add(layers.Conv2D(32, (3, 3), activation='relu', name='conv2d_2'))
model.add(layers.MaxPooling2D((2, 2), name='max_pooling2d_2'))
model.add(layers.Conv2D(64, (3, 3), activation='relu', name='conv2d 3'))
model.add(layers.MaxPooling2D((2, 2), name='max_pooling2d_3'))
model.add(layers.Flatten(name='flatten'))
model.add(layers.Dense(128, activation='relu', name='dense_1'))
model.add(layers.Dropout(0.5, name='dropout 1'))
model.add(layers.Dense(1, activation='sigmoid', name='output'))
model.compile(optimizer='adam', loss='binary_crossentropy',_
 →metrics=['accuracy'])
model.summary()
weight_path = './weights/'
model_checkpoint = ModelCheckpoint(
   filepath = weight_path,
   save best only = True,
   save_weights_only = True,
   mode = 'max',
   monitor = 'val_accuracy'
history = model.fit(train_Dataset,
                    epochs=2,
                    validation data=test Dataset,
                    callbacks=[model_checkpoint]
                   )
# Load best weights and make predictions
model.load_weights(weight_path)
predictions = model.predict(test_Dataset)
binary_predictions = (predictions > 0.5).astype(int)
# Generate confusion matrix and classification report
true_labels = test_Dataset.classes
sns.heatmap(confusion_matrix(true_labels, binary_predictions), annot=True)
print(classification_report(true_labels, binary_predictions))
```

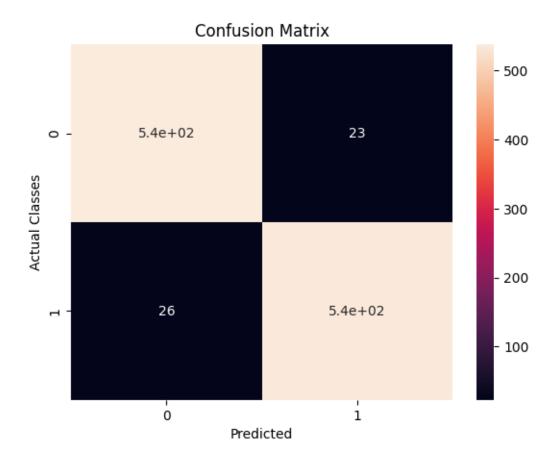
```
plt.title('Confusion Matrix')
plt.xlabel('Predicted')
plt.ylabel('Actual Classes')
plt.show()
```

Found 4486 images belonging to 2 classes. Found 1122 images belonging to 2 classes.

Model: "sequential"

<u> </u>					
Layer (type)	Output	Shape	Param #		
conv2d_1 (Conv2D)					
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None,	127, 127, 16)	0		
conv2d_2 (Conv2D)	(None,	125, 125, 32)	4640		
max_pooling2d_2 (MaxPoolin g2D)	(None,	62, 62, 32)	0		
conv2d_3 (Conv2D)	(None,	60, 60, 64)	18496		
max_pooling2d_3 (MaxPooling2D)	(None,	30, 30, 64)	0		
flatten (Flatten)	(None,	57600)	0		
dense_1 (Dense)	(None,	128)	7372928		
dropout_1 (Dropout)	(None,	128)	0		
output (Dense)	(None,	1)	129		
cotal params: 7396641 (28.22 rainable params: 7396641 (28.22 ron-trainable params: 0 (0.00 poch 1/2 ps/898 [===================================	MB) 8.22 MB 0 Byte) 0.2799	)  ====] - 127s 141ms/ - val_accuracy: 0.	 step - loss: 8939		
398/898 [===================================	0.1161	- val_accuracy: 0.	9563		
precision recall f1-score support					

0	0.95	0.96	0.96	561
1	0.96	0.95	0.96	561
accuracy			0.96	1122
macro avg	0.96	0.96	0.96	1122
weighted avg	0.96	0.96	0.96	1122



```
# Berechnung des Gradienten der am höchsten vorhergesagten Klasse für dasu
      \hookrightarrow Eingabebild
         # in Bezug auf die Aktivierungen der letzten Conv-Schicht
         with tf.GradientTape() as tape:
             last_conv_layer_output, preds = grad_model(img_array)
             if pred_index is None:
                 pred_index = tf.argmax(preds[0])
             class_channel = preds[:, pred_index]
         # Dies ist der Gradient des Ausgabeneurons
         # in Bezug auf die Ausgabefeaturemap der Conv-Schicht
         grads = tape.gradient(class_channel, last_conv_layer_output)
         # Dies ist ein Vektor, wobei jeder Eintrag die mittlere Intensität des⊔
      \hookrightarrow Gradienten
         # über einem spezifischen Featuremap-Kanal darstellt
         pooled_grads = tf.reduce_mean(grads, axis=(0, 1, 2))
         # Multiplikation jedes Kanals in der Featuremap
         # mit dem Durchschnittswert des Gradienten für diesen Kanal, um zu erfahren,
         # wie wichtig dieser Kanal für die am höchsten vorhergesagte Klasse ist.
         # Dann summieren wir alle Kanäle, um die Klassenaktivierung für die Heatmap⊔
      \rightarrow zu erhalten.
         last_conv_layer_output = last_conv_layer_output[0]
         heatmap = last_conv_layer_output @ pooled_grads[..., tf.newaxis]
         heatmap = tf.squeeze(heatmap)
         # Die Heatmap normalisieren
         heatmap = tf.maximum(heatmap, 0) / tf.math.reduce_max(heatmap)
         # Eine Kanal-Dimension hinzufügen und die Größe anpassen
         heatmap = tf.expand_dims(heatmap, -1) # Eine Kanal-Dimension hinzufügen
         heatmap = tf.image.resize(heatmap, (w, h)) # Heatmap in der Größe an das_
      \hookrightarrow Eingabebild anpassen
         heatmap = tf.squeeze(heatmap) # Die letzte Dimension entfernen, um sie_
      ⇒wieder 2D zu machen
         return heatmap.numpy(), preds.numpy()
[6]: counter = 0
     for images, labels in test_Dataset:
         for i in range(len(images)):
```

if binary\_predictions[i] == 0 and labels[i] == 0:

```
counter = counter + 1
           image_processed = np.expand_dims(images[i], axis=0)
           plt.figure(figsize=(12, 6)) # Größere Figure, um alle Heatmaps⊔
⇔sichtbar zu machen
           # Ursprüngliches Bild anzeigen
          plt.subplot(1, 4, 1)
          plt.imshow((images[i] * 255).astype("uint8"))
          plt.title(f'Original\nPredicted: {binary_predictions[i]}, Actual:__

√{labels[i]}')
          plt.axis('off')
           # Heatmaps für jede Layer generieren und anzeigen
           layer_names = ['conv2d_1', 'conv2d_2', 'conv2d_3']
           for j, layer_name in enumerate(layer_names, start=2): # Startet_
⇔bei 2, da das Originalbild auf 1 ist
              heatmap, _ = make_gradcam_heatmap(image_processed, model,__
→layer_name)
              plt.subplot(1, 4, j)
              plt.imshow((images[i] * 255).astype("uint8"), alpha=0.6)
              plt.imshow(heatmap, cmap='magma', alpha=0.5) # Ensure heatmap_
⇒is 2D
              plt.title(f'Grad-CAM\nLayer: {layer_name}')
              plt.axis('off')
          plt.show()
      if i >= 10:
          break
  if counter >= 10:
      break
```

Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d 1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



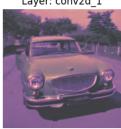
Grad-CAM Layer: conv2d\_3



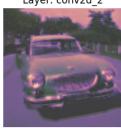
Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d 1



Grad-CAM Layer: conv2d 2



Grad-CAM Layer: conv2d 3



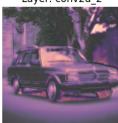
Original Predicted: [0], Actual: 0.0



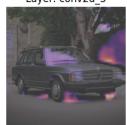
Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



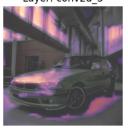
Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3



Original Predicted: [0], Actual: 0.0



Grad-CAM Layer: conv2d\_1



Grad-CAM Layer: conv2d\_2



Grad-CAM Layer: conv2d\_3

