

include/PoseTransformer.hpp

```
graph TD; A[include/PoseTransformer.hpp] --> B[eigen3/Eigen/Dense]; A --> C[vector];
```

The diagram illustrates the dependencies of the file `include/PoseTransformer.hpp`. It is shown in a grey box at the top. Two blue arrows point downwards from this box to two white boxes below it. The left box contains the text `eigen3/Eigen/Dense` and the right box contains the text `vector`.

eigen3/Eigen/Dense

vector