

include/PoseTransformer.hpp

```
graph TD; A[include/PoseTransformer.hpp] --> B[eigen3/Eigen/Dense]; A --> C[vector];
```

The diagram illustrates the dependencies of the file `include/PoseTransformer.hpp`. It is shown as a gray box at the top. Two blue arrows point downwards from this box to two white boxes below it. The left arrow points to a box containing `eigen3/Eigen/Dense`, and the right arrow points to a box containing `vector`.

eigen3/Eigen/Dense

vector