



ES203

Cordic Processor



Overview

CORDIC (**C**oordinate **R**otation **D**igital **C**omputer) Algorithm uses straightforward and simple operations like shifting and addition along with look up tables to facilitate and speed up the process of computation. Not only it can be used to compute logarithmic, trigonometric and hyperbolic functions but also eigenvalue estimation, QR factorization, etc. In this project, we plan to implement a few of its diverse applications.

Why did we choose CORDIC?

The motivation behind choosing CORDIC as a subject of study comes from the idea of CORDIC itself. It is fascinating to think how arithmetic subtraction, addition and shift registers can form the basis of large number of functions which are usually calculated by computational intensive Taylor's expansion. CORDIC algorithm has a lot of scope in terms of image processing and waveform generation as it is a fast iterative algorithm which does not require multipliers or dividers for function generation.

Since our course deals with hardware design and coding, we believe it will be interesting to implement this algorithm that can be extended to wide applications like QR factorization, eigen estimation, 3D graphing and much more.

How Does Cordic Work?

$$x_R = x_{in} \cos(\theta) - y_{in} \sin(\theta)$$

$$y_R = x_{in} \sin(\theta) + y_{in} \cos(\theta)$$

$$\begin{bmatrix} x_R \\ y_R \end{bmatrix} = \cos(\theta) \begin{bmatrix} 1 & -\tan(\theta) \\ \tan(\theta) & 1 \end{bmatrix} \begin{bmatrix} x_{in} \\ y_{in} \end{bmatrix}$$

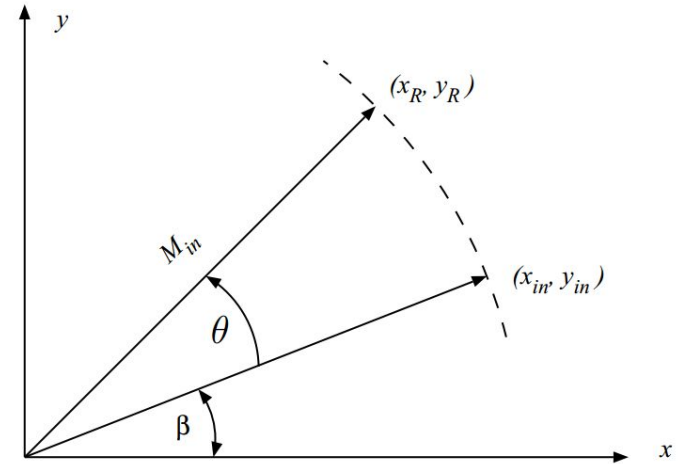
$$x[i+1] = x[i] - \sigma_i 2^{-i} y[i]$$

$$y[i+1] = y[i] + \sigma_i 2^{-i} x[i]$$

$$\tan(\theta_i) = 2^{-i}.$$

Main concept of CORDIC

NOT the complete algorithm



Functions that use Taylor's expansion (hyperbolic, inverse functions, sine, cosine, exponential, logarithmic) can be evaluated using CORDIC in two modes:

1. Rotation Mode: In this mode, the angle is iteratively pushed to *approaching* zero. It is used for sine, cosine, hyperbolic functions, rotating 2D coordinates.

For sine and cosine and hyperbolic, the y coordinate is set to zero.

2. Vectoring Mode: In this mode, then 'y' coordinate is iteratively pushed to *approaching* zero and the initial angle is set to 0. Any function which involves inverse functions (like arctan, arctanh) can be computed using this mode.

Advantages:

1. Cost of CORDIC is way less as only adders, subtractors and LUTs are required.
2. Either in absence of multiplier or if there is a need to optimise the overall design, CORDIC is the best algorithm.
3. Number of gates required in hardware implementation, such as on an FPGA, is minimum as hardware complexity is greatly reduced compared to other processors such as DSP multipliers.

Disadvantages:

1. The accuracy depends on the size of LUT and hence the number of iterations.
2. In Microprocessors which can handle multipliers well, taylor series computation is more effective.

Goals

1. **Finding angle:** To find the angle between a vector and a chosen axis using its coordinates.
2. **Trigonometric functions:** Computing the sine and cosine of the given angle using simple shift-add operations.
3. **Logarithm:** Finding the approximated natural log of a given number.
4. **Coordinate Rotation:** Finding the new coordinates after vector rotation by a given angle.
5. **Evaluation of DFT (using FFT Algorithm):** Using the built modules for DFT which relies on sine and cosine modules.

Week wise plan

1. **Week 1:** implement basic functions in python (sine, cosine, logarithmic functions). This requires use of division and addition functions to make the algorithm clear and easy to implement in verilog.
2. **Week 2:** implement them in verilog. Also, learn about how to use them in various applications.
3. **Week 3:** implement the applications in python (coordinate rotation, determining angle for input coordinates), along with implementation of DFT (based on FFT)
4. **Week 4:** present the final project after implementation of the applications in verilog and burning the code on FPGA or BASYS 3

Week 1

Python Codes

Status:
Implemented Successfully



GitHub Repository and Repl.it Codes

Computing angle of given coordinates:

Github link ○ <https://repl.it/@hrushti/ES203-Cordic-Finding-Angle>

Computing new coordinates:

Github link ○ <https://repl.it/@hrushti/ES203-Cordic-Rotation>

Computing Sine, Cosine:

Github link ○ <https://repl.it/@hrushti/ES203-Cordic-Sine-Cosine>

Computing Logarithm using atan hyperbolic:

Github link ○ <https://repl.it/@hrushti/ES203-Cordic-Logarithm>

Snippets of some results:

```
= RESTART: /Users/nipunmahajan/Desktop/Academ
```

```
given coordinates.py
```

```
enter the x coordinate: 3.2567
```

```
enter the y coordinate: 648.4
```

```
Angle in radians: 1.565774234723597
```

```
Expected angle is: 1.5657736978396546
```

```
= RESTART: /Users/nipunmahajan/Desktop/Academics/ES 203/Project/Project Submissio
```

```
enter the x coordinate: 2
```

```
enter the y coordinate: 10
```

```
Enter the angle in degrees: 30
```

```
The expected values of X and Y are: -3.2679491924311215 9.660254037844387
```

```
The CORDIC rotated values of X, Y are: (-3.2679491919164128, 9.66025403801851)
```

```
>>>
```

Enter the angle in degrees: 78.45

The CORDIC values of sine and cosine are: (0.9797503501923033, 0.20022300391828043)

The expected value of sine and cosine is: 0.9797503501713428 0.2002230040208446

>>>

===== RESTART: /Users/nipunmahajan/Desktop/Academics/ES 203/Project/sin_cos.py

Enter the angle in degrees: 0.8783475

The CORDIC values of sine and cosine are: (0.01532945545429695, 0.9998824969942597)

The expected value of sine and cosine is: 0.015329455404414168 0.999882496995024

>>> |

Enter value whose log has to be calculated 764.238237

The CORDIC value is 6.6388809054

The actual value of logarithm is: 6.638879569092139

>>>

===== RESTART: /Users/nipunmahajan/Desktop/Ac

Enter value whose log has to be calculated -128

The actual value of logarithm is: INVALID

>>>

===== RESTART: /Users/nipunmahajan/Desktop/Ac

Enter value whose log has to be calculated 0.08672

The CORDIC value is -2.4450703706

The actual value of logarithm is: -2.445070741290801

|

Week 2

Verilog Codes

Status:
Implemented Successfully



Eda Playground

Computing angle of given coordinates:

https://edaplayground.com/x/WX_m

Computing new coordinates:

<https://edaplayground.com/x/tU6w>

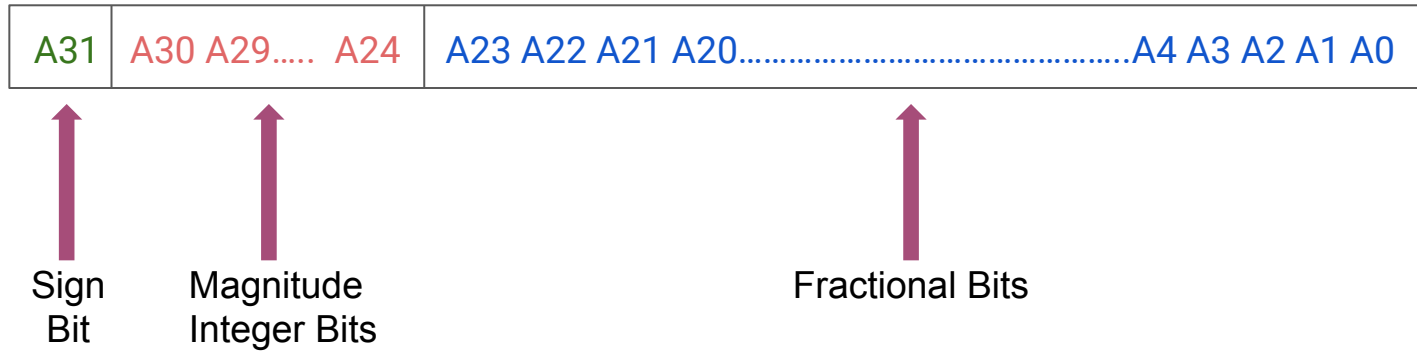
Computing Sine, Cosine:

<https://www.edaplayground.com/x/tTvQ>

Computing Logarithm using atan hyperbolic:

<https://www.edaplayground.com/x/G87Y>

Fixed Point Representation: [32 24]



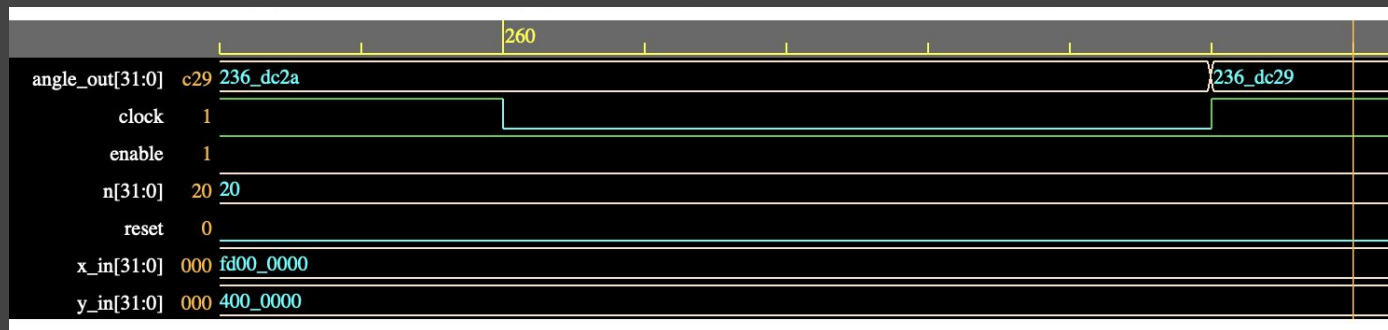
Range of I/O Values: **-128** to **127.99999994**

Snippets of some results: (Angular Outputs in Radians)

#	Name	Value	328,996 ps	328,997 ps	328,998 ps	328,999 ps
1	🔌 reset	0				
2	🔌 enable	1				
3	🔌 clock	1				
4	> 🐼 x_in[31:0]	00110111011011001000101101	00110111011011001000101101000011			
5	> 🐼 y_in[31:0]	00100000000000000000000000	001000000000000000000000000000			
6	> 🐼 angle...1:0]	00100001100000101101100110	001000011000001011011001110000			
7	> 🐼 n[31:0]	0000000000000000000000000000	000000000000000000000000100000			

Finding the angle of a given vector

Coordinates: $(\sqrt{3}/2, 1/2)$
Output angle: 30°



Coordinates:
 $(-3, 4)$

Output angle:
127°
(0236_dc29)

								335,000 p
#	Name	Value	334,995 ps	334,996 ps	334,997 ps	334,998 ps	334,999 ps	335,000 p
1	> x_old[31:0]	001000000000000000	00100000000000000000000000000000					
2	> y_old[31:0]	000000000000000000	00000000000000000000000000000000					
3	> angle_in[31:0]	00110010010000111	00110010010000111111011010101001					
4	reset	0						
5	enable	1						
6	clock	1						
7	> x_new[31:0]	01001010100001100	01001010100001100001101111010101					
8	> y_new[31:0]	01001010100001100	01001010100001100001101111010011					
9	> n[31:0]	000000000000000000	00000000000000000000000000100000					











Rotating given coordinates by a given angle

Coordinates: (1, 0)

Angle: $\pi/4$

X_out: 0.707

Y_out: 0.707

Name	Value	294,997 ps	294,998 ps	294,999 ps	295,000 ps
 reset	0				
 enable	1				
 clock	1				
>  angle_in[31:0]	146408896	146408896			
>  x_in[31:0]	10188016	10188016			
>  y_in[31:0]	-40752064	-40752064			
>  xo[31:0]	1	1			
>  yo[31:0]	-4	-4			
>  x_out[31:0]	30284372	30284372			
>  y_out[31:0]	62192711	62192711			
>  n[31:0]	32	32			

Coordinates: (1, -4)

Angle: 500°

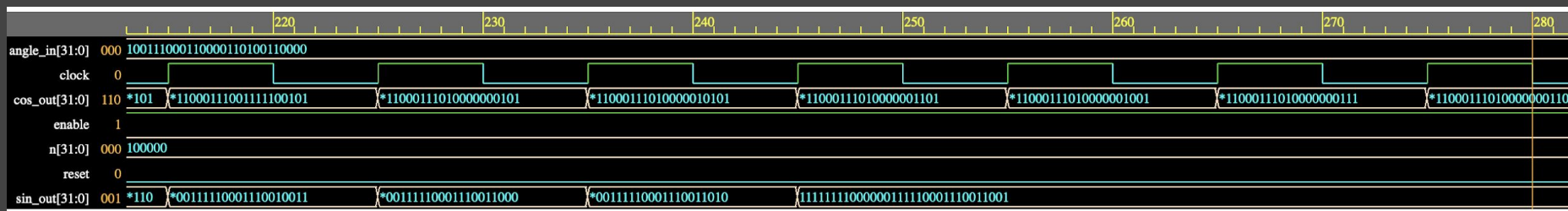
X_out: 1.805105

Y_out: 3.706965

#	Name	Value	334,996 ps	334,997 ps	334,998 ps	334,999 ps	335,000 ps
1	reset	0					
2	enable	1					
3	clock	1					
4	> angle_in[31:0]	00110010010000111	00110010010000111111111001011100				
5	> cos_out[31:0]	00101101010000010	00101101010000010011011101011001				
6	> sin_out[31:0]	00101101010000010	00101101010000010100001001000000				
7	> n[31:0]	00000000000000000	00000000000000000000000001000000				

Finding sin and cos of a given angle

Angle: $\pi/4$



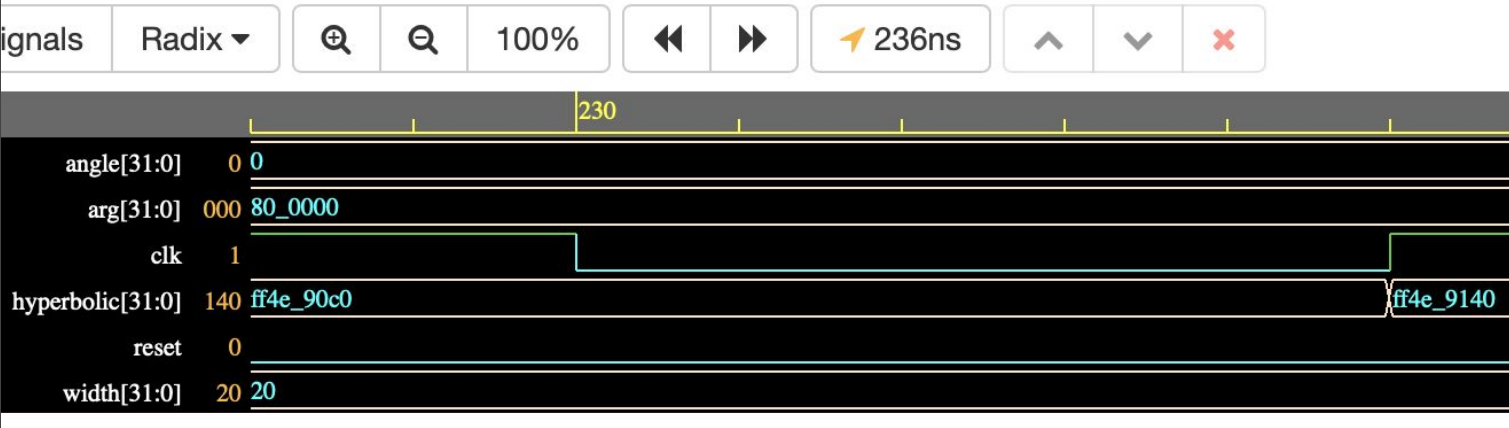
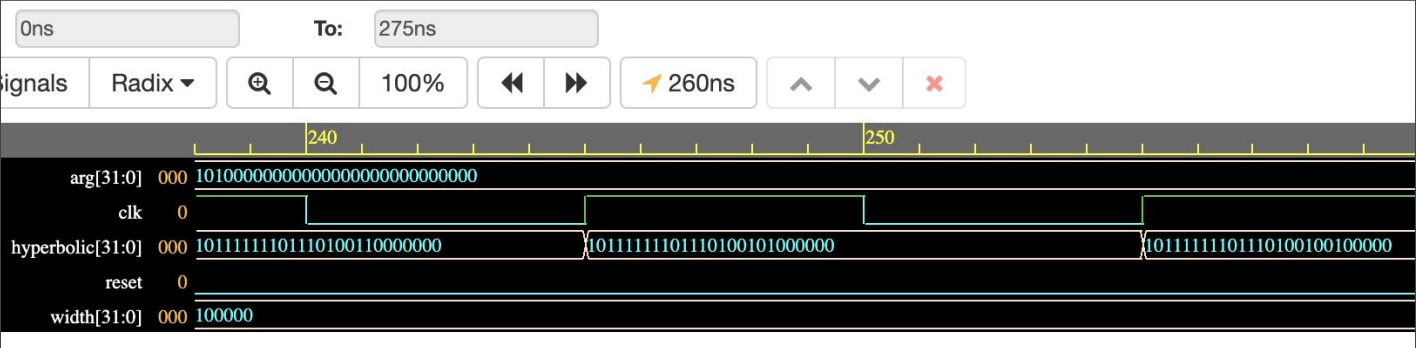
Input angle: 280°

Sin: -0.98480

Cos: 0.17364

Finding the logarithm of
given number

Input: 20
Output: 2.995743



Input: 0.5
Output: -0.6931498

Week 3

DFT & FFT in python

Status:
Implemented Successfully

DFT

Repl link - <https://repl.it/@hrushti/ES203-DFT>

Snippets of results:

```
Enter the degree of the polynomial: 3
the polynomial has 4 terms
enter the term: -10
enter the term: 23
enter the term: 2
enter the term: 3
CORDIC real values      : 18.000000 -11.999956 -34.000000 -12.000050
expected real components : 18.000000 -12.000000 -34.000000 -12.000000
CORDIC imag values      : 0.000004 -20.000003 -0.000008 19.999997
expected imag components : 0.000000 -20.000000 0.000000 20.000000
> 
```

Enter the degree of the polynomial: 2

the polynomial has 3 terms

enter the term: -8

enter the term: 4

enter the term: 6

CORDIC real values : 2.000000 -13.999991 -6.000000 -14.000010

expected real components : 2.000000 -14.000000 -6.000000 -14.000000

CORDIC imag values : 0.00000 -4.00003 -0.00001 3.99997

expected imag components : 0.00000 -4.00000 0.00000 4.00000



Enter the degree of the polynomial: 4

the polynomial has 5 terms

enter the term: 3

enter the term: 12

enter the term: 4

enter the term: 8

enter the term: 0

CORDIC real values : 27.000000 5.828425 -0.999993 0.171552 -13.000000 0.171593 -1.000012 5.828429

expected real components : 27.000000 5.828427 -1.000000 0.171573 -13.000000 0.171573 -1.000000 5.828427

CORDIC imag values : 0.000006 -18.14213 -4.00000 -10.14213 -0.00003 10.14214 4.00000 18.14214

expected imag components : 0.00000 -18.14214 -4.00000 -10.14214 0.00000 10.14214 4.00000 18.14214

FFT

Repl link - <https://repl.it/@hrushti/ES203-FFT>

Snippets of results:

```
Enter the degree of the polynomial: 3
the polynomial has 4 terms
enter the term: -10
enter the term: 23
enter the term: 2
enter the term: 3
CORDIC real values    :  18.000000 -11.999962 -34.000000 -12.000038
expected real components :  18.000000 -12.000000 -34.000000 -12.000000
CORDIC imag values    :  0.000007 -20.000000 -0.000006 20.000000
expected imag components :  0.000000 -20.000000 0.000000 20.000000
```


Enter the degree of the polynomial: 5

the polynomial has 6 terms

enter the term: 39

enter the term: 0

enter the term: 0

enter the term: 0

enter the term: 1

enter the term: 1

CORDIC real values : 41.000000 37.292892 40.000004 38.707106 39.000000 38.707108 39.999996 37.292894

expected real components : 41.000000 37.292893 40.000000 38.707107 39.000000 38.707107 40.000000 37.292893

CORDIC imag values : 0.00001 0.70710 -1.00000 0.70711 -0.00000 -0.70711 1.00000 -0.70711

expected imag components : 0.00000 0.70711 -1.00000 0.70711 0.00000 -0.70711 1.00000 -0.70711

>>> |

===== RESTART: /Users/nipunmahajan/Desktop/fft.py =====

Enter the degree of the polynomial: 7

the polynomial has 8 terms

enter the term: 2

enter the term: 4

enter the term: 5

enter the term: 0

enter the term: 7

enter the term: 34

enter the term: 2

enter the term: 3

CORDIC real values : 57.000000 -24.091925 2.000140 14.091837 -25.000000 14.091929 1.999860 -24.091841

expected real components : 57.000000 -24.091883 2.000000 14.091883 -25.000000 14.091883 2.000000 -24.091883

CORDIC imag values : 0.00022 20.33448 -35.00000 26.33454 -0.00014 -26.33451 35.00000 -20.33457

expected imag components : 0.00000 20.33452 -35.00000 26.33452 0.00000 -26.33452 35.00000 -20.33452

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Week 4

Verilog Codes

Status:
Implemented Successfully



Eda Playground

Master Cordic:

<https://www.edaplayground.com/x/D6KR>

DFT:

<https://www.edaplayground.com/x/kjSW>

FFT:

<https://www.edaplayground.com/x/84TY>

Snippets of DFT results:

Name	Value	264,997 ps	264,998 ps	264,999 ps
reset	0			
enable	1			
clock	1			
> coeff_0[31:0]	0000000100110110111010011110000	000000001001101101110100111100000		
> coeff_1[31:0]	0000001001101101110100111100000	000000010011011011101001111000000		
> coeff_2[31:0]	0000000000000000000000000000000	0000000000000000000000000000000		
> coeff_3[31:0]	0000000000000000000000000000000	0000000000000000000000000000000		
> coeff_4[31:0]	0000000000000000000000000000000	0000000000000000000000000000000		
> coeff_5[31:0]	0000000000000000000000000000000	0000000000000000000000000000000		
> coeff_6[31:0]	0000000000000000000000000000000	0000000000000000000000000000000		
> coeff_7[31:0]	0000000000000000000000000000000	0000000000000000000000000000000		
> c_0[31:0]	00000000000000000000000000000001	000000000000000000000000000000010		
> c_1[31:0]	000000000000000000000000000000010	0000000000000000000000000000000100		
> c_2[31:0]	00000000000000000000000000000000	00000000000000000000000000000000		
> c_3[31:0]	00000000000000000000000000000000	00000000000000000000000000000000		
> c_4[31:0]	00000000000000000000000000000000	00000000000000000000000000000000		
> c_5[31:0]	00000000000000000000000000000000	00000000000000000000000000000000		
> c_6[31:0]	00000000000000000000000000000000	00000000000000000000000000000000		
> c_7[31:0]	00000000000000000000000000000000	00000000000000000000000000000000		
> yk_cos_out_0[31:0]	000001100000000000000000000010110	0000001100000000000000000000101100		

Name	Value
c_6[31:0]	00000000000000000000000000000000
c_7[31:0]	00000000000000000000000000000000
yk_cos_out_0[31:0]	000001100000000000000000000010110
yk_cos_out_1[31:0]	0000010011010100000100111000010
yk_cos_out_2[31:0]	0000000111111111111111111111011
yk_cos_out_3[31:0]	1111111100101011111011000000000
yk_cos_out_4[31:0]	1111111000000000000000000000001
yk_cos_out_5[31:0]	1111111100101011111011000010001
yk_cos_out_6[31:0]	00000010000000000000000000010100
yk_cos_out_7[31:0]	000001001101010000010100000101
yk_sin_out_0[31:0]	111111111111111111111111111010110
yk_sin_out_1[31:0]	1111110100101011111010111001010
yk_sin_out_2[31:0]	111110111111111111111111100000
yk_sin_out_3[31:0]	1111110100101011111011000010110
yk_sin_out_4[31:0]	1111111111111111111111111110000
yk_sin_out_5[31:0]	0000001011010100000100111001000
yk_sin_out_6[31:0]	0000001111111111111111111110001
yk_sin_out_7[31:0]	0000001011010100000100110111000
n[31:0]	00000000000000000000000000000000

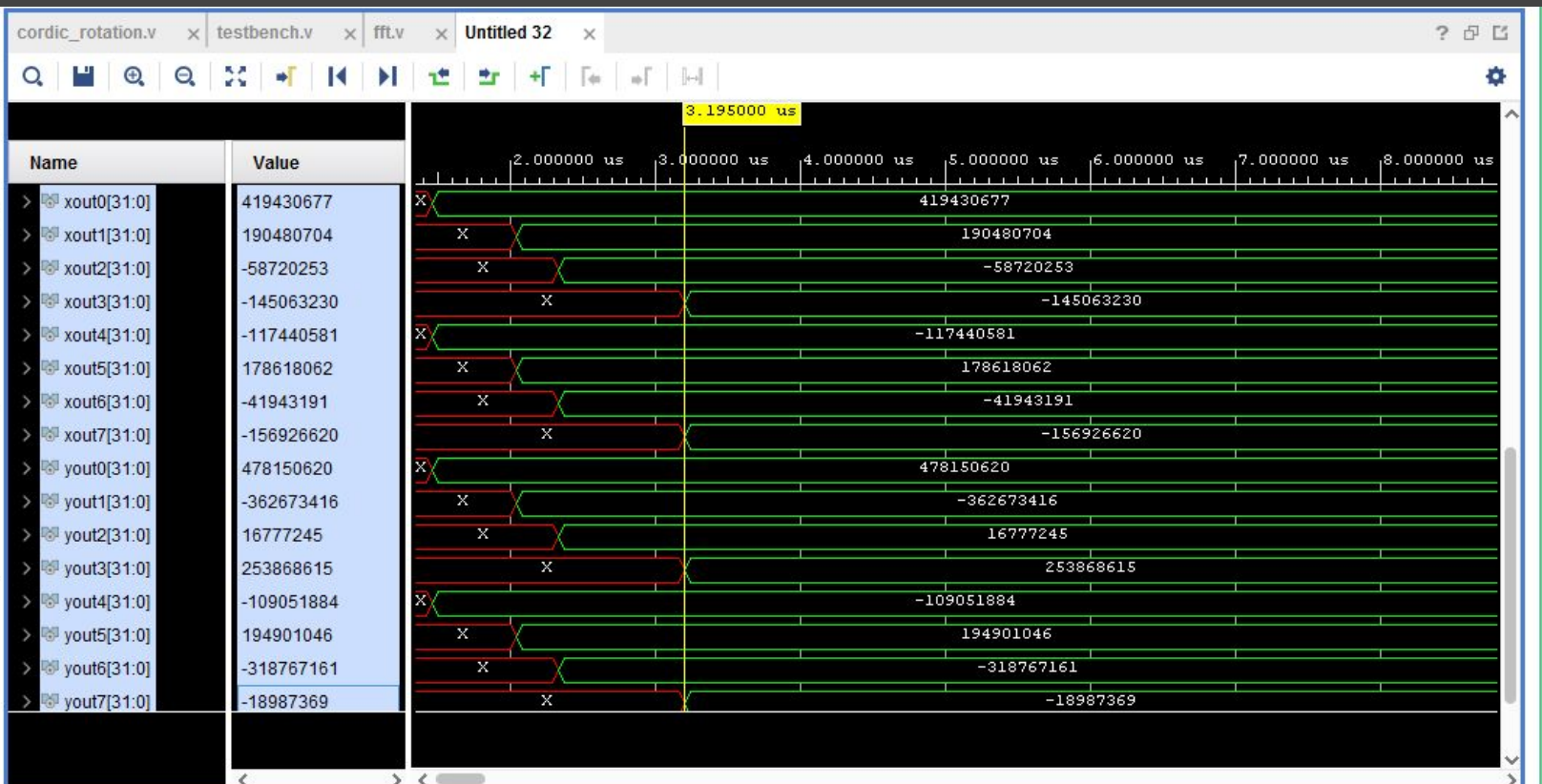
Snippet of FFT results:

Average Error : 1.107126984050883e-06

Name	Value	2,900.000000 us	3,000.000000 us	3,100.000000 us
> xout0[31:0]	251658297	251658297		
> xout1[31:0]	73215146	73215146		
> xout2[31:0]	100663332	100663332		
> xout3[31:0]	-140324088	-140324088		
> xout4[31:0]	-50331657	-50331657		
> xout5[31:0]	-140324034	-140324034		
> xout6[31:0]	100663308	100663308		
> xout7[31:0]	73215192	73215192		
> yout0[31:0]	-91	-91		
> yout1[31:0]	11863174	11863174		
> yout2[31:0]	16777184	16777184		
> yout3[31:0]	11863337	11863337		
> yout4[31:0]	17	17		
> yout5[31:0]	-11863146	-11863146		
> yout6[31:0]	-16777258	-16777258		
> yout7[31:0]	-11863301	-11863301		

Inputs:

$x = \{2, 4, 0, 0, 4, 0, 0, 5\}$ $y = \{0, 0, 0, 0, 0, 0, 0, 0\}$



$A0 = 2+j$

$A1 = 3$

$A2 = 6+j10$

$A3 = 8+j9$

$A4 = 1$

$A5 = 8.5j$

$A6 = 0$

$A7 = 5$

Cordic FFT Real values:

25.00001651	11.353534698	-3.49999982	-8.646244229	-7.000000411	10.6464661359
-2.500009000	-9.3535554409				

Cordic FFT Imaginary values:

28.499997854	-21.617020130	1.0000017285	15.13174861669	-6.49999888	11.617007613
-19.000003397	-1.131735384464				

Python FFT Result (truncated to 5 decimal places):

```
===== RESTART: /Users/nipunmahajan/Desktop/trial.py =====  
expected real components : 25.00000 11.35355 -3.50000 -8.64645 -7.00000 10.64645 -2.50000 -9.35355  
expected imag components : 28.50000 -21.61701 1.00000 15.13173 -6.50000 11.61701 -19.00000 -1.13173  
>>>
```









Buffer Time String Matching

Status:
Implemented Successfully

String Matching

EDA Playground : <https://edaplayground.com/x/Ltj>

Snippet of the result:

Name	Value	264,997 ps	264,998 ps	264,999 ps
 reset	0			
 enable	1			
 clock	1			
>  text[0:15]	1011100001110100	1011100001110100		
>  pattern[0:3]	0111	0111		
>  flag[0:15]	0100000010000000	0100000010000000		
>  m[31:0]	00000000000000000000000000000000100	00000000000000000000000000000000100		
>  n[31:0]	000000000000000000000000000000001000	000000000000000000000000000000001000		

References:

Logarithm using CORDIC:

1. Llamocca, Daniel & Agurto, Carla. (2006). *A fixed-point implementation of the natural logarithm based on a expanded hyperbolic CORDIC algorithm.*
2. Llamocca, Daniel & Agurto, Carla. (2007). *A fixed-point implementation of the expanded hyperbolic CORDIC algorithm. Latin American Applied Research.* 37. 83-91.
3. *Coordinate rotation digital computer algorithm (CORDIC) to compute trigonometric and hyperbolic functions By Andrea Vitali / DT0085 Rev 1*

Sine, cosine using CORDIC:

1. (IJITR) *INTERNATIONAL JOURNAL OF INNOVATIVE TECHNOLOGY AND RESEARCH* Volume No.2, Issue No. 2, February – March 2014, 891 – 895 / *Calculation of Sine and Cosine of an Angle using the CORDIC Algorithm*
2. Bhattarai, Bibek. (2013). *FPGA Implementation of CORDIC Processor.* 10.13140/RG.2.1.4432.1364.

Computing tan inverse in CORDIC:

1. *Coordinate rotation digital computer algorithm (CORDIC) to compute trigonometric and hyperbolic functions By Andrea Vitali / DT0085 Rev 1*

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