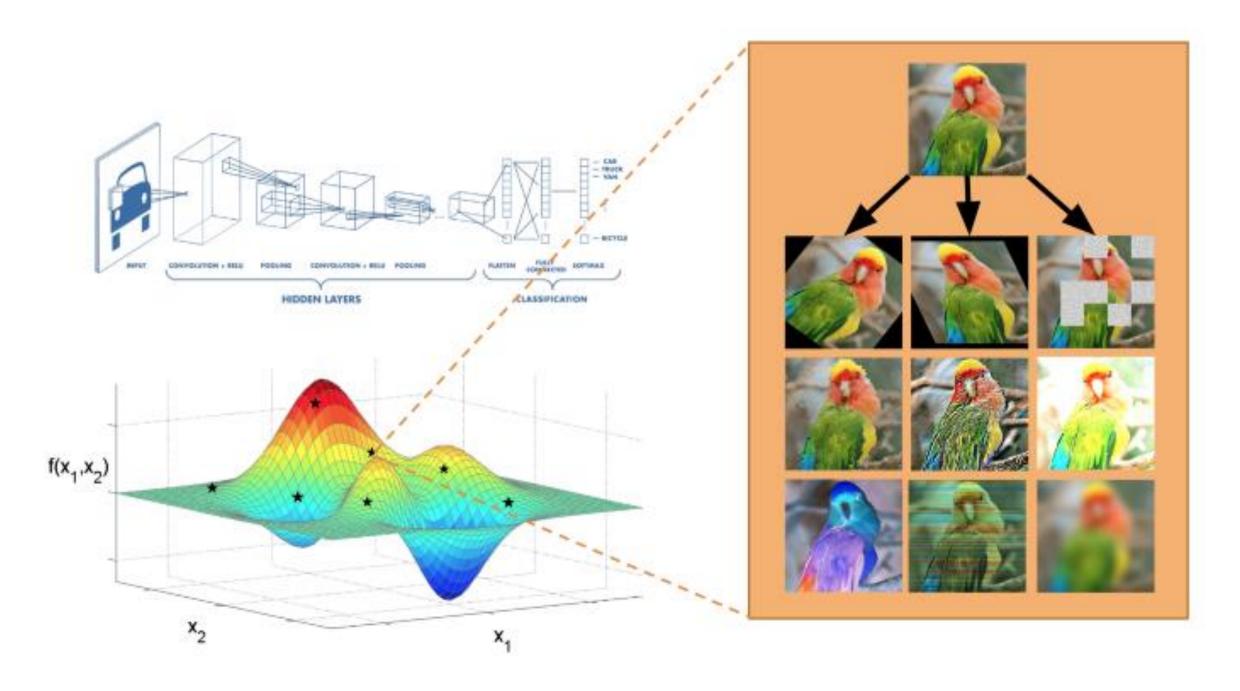
Augmentacja danych

Weronika Hryniewska



https://blog.insightdatascience.com/automl-for-data-augmentation-e87cf692c366

Three ways to improve data

1 - Collect more



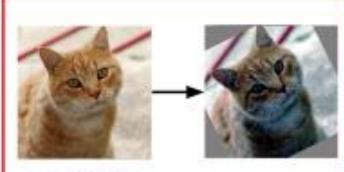
- expensive
- requires manual labor

2 - Synthesize



- complicated
- might not truly represent the real data

3 - Augment



- simple
- but finding a good augmentation strategy takes lots of trial & error (=time of AI engineers)

6.2. Data augmentation

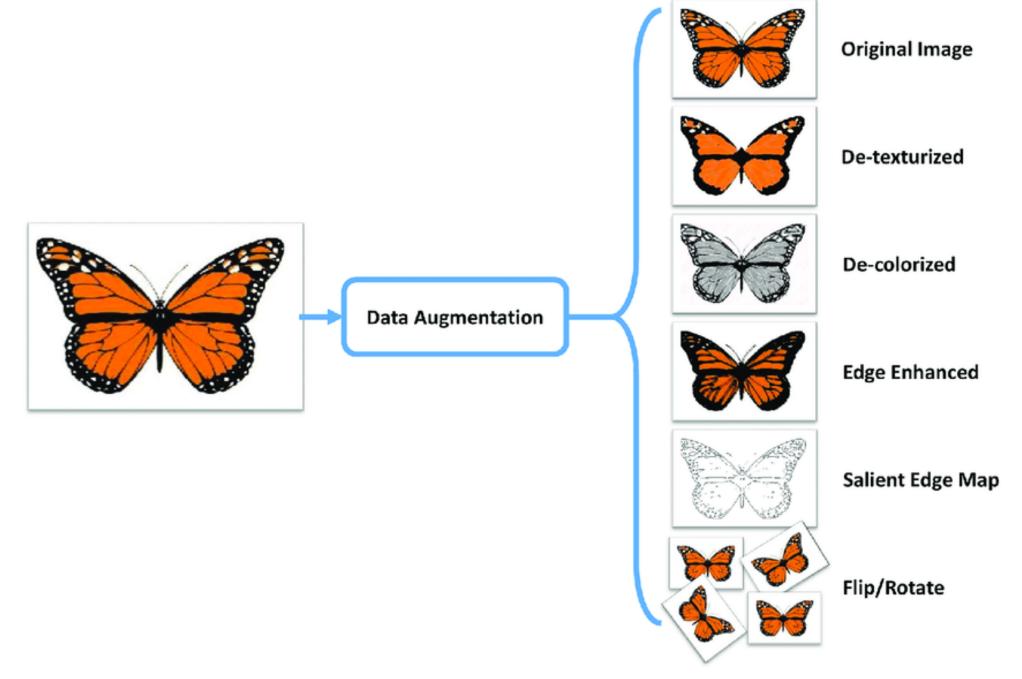
rotacje, odbicia lustrzane, skalowanie tj. RandomRotate90, Flip, Compose, Normalize, RandomResizedCrop

```
# data augmentation on both tile level and big image level
augmentation pipeline before splitting = A.Compose([
    A.HorizontalFlip(p=0.6),
    A. VerticalFlip(p=0.6),
    A. OneOf([
        A.RandomContrast(),
        A.RandomGamma(),
        A.RandomBrightness(),
        A.RGBShift()
         1, p=0.9),
   A.ElasticTransform(alpha=120, sigma=120 * 0.05, alpha affine=120 * 0.03, p=0.5),
    A.GridDistortion(p=0.5).
    A.OpticalDistortion(distort limit=2, shift limit=0.5, p=0.5),
], p=1)
augmentation pipeline after splitting = A.Compose([
   A. Flip (p=0.7),
   A.RandomRotate90(p=1.0),
], p=1)
```

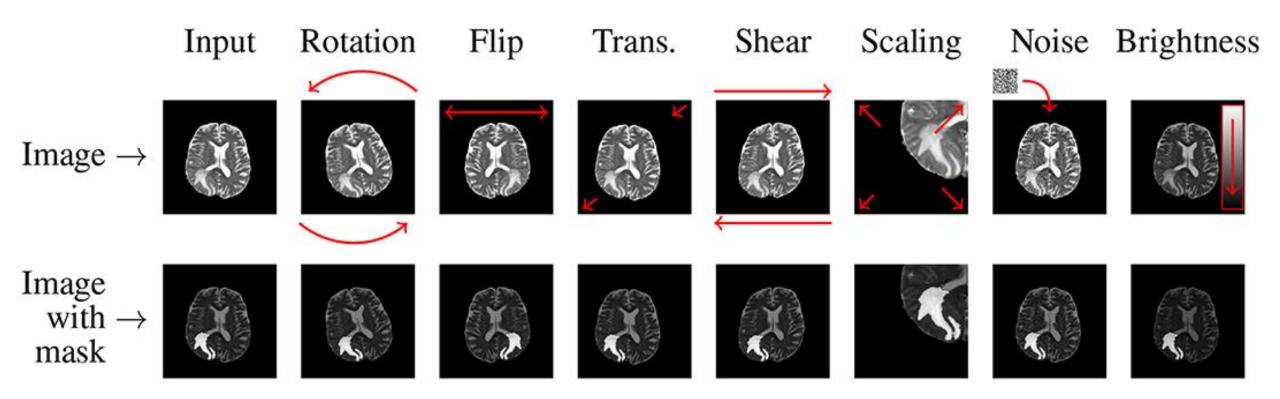
Base Augmentations

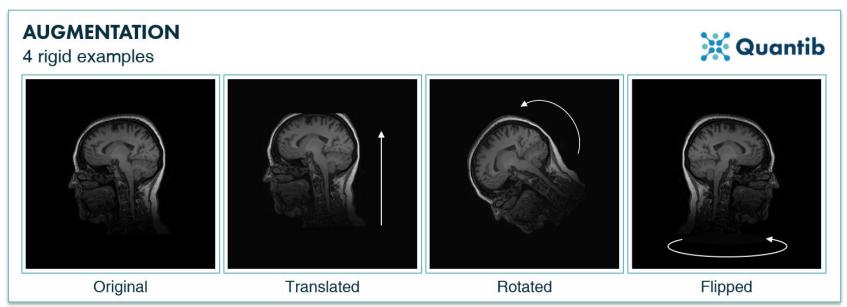


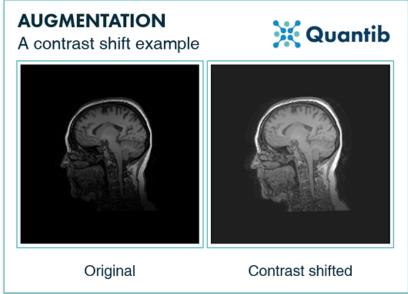
https://blog.insightdatascience.com/automl-for-data-augmentation-e87cf692c366

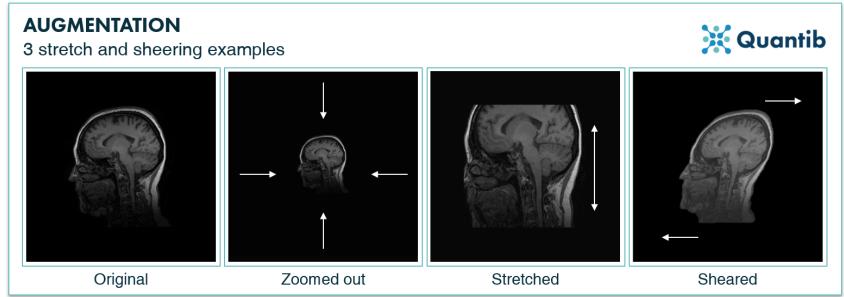


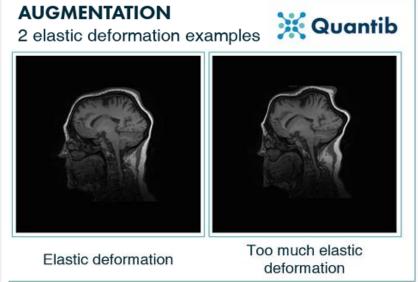
www.researchgate.net/figure/Data-augmentation-using-semantic-preserving-transformation-for-SBIR_fig2_319413978

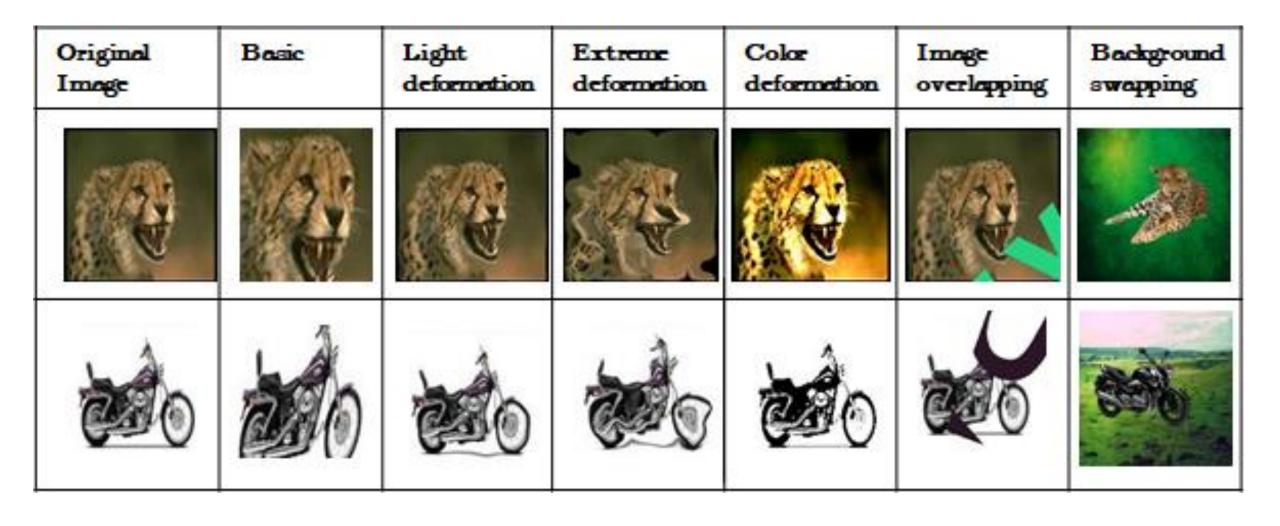








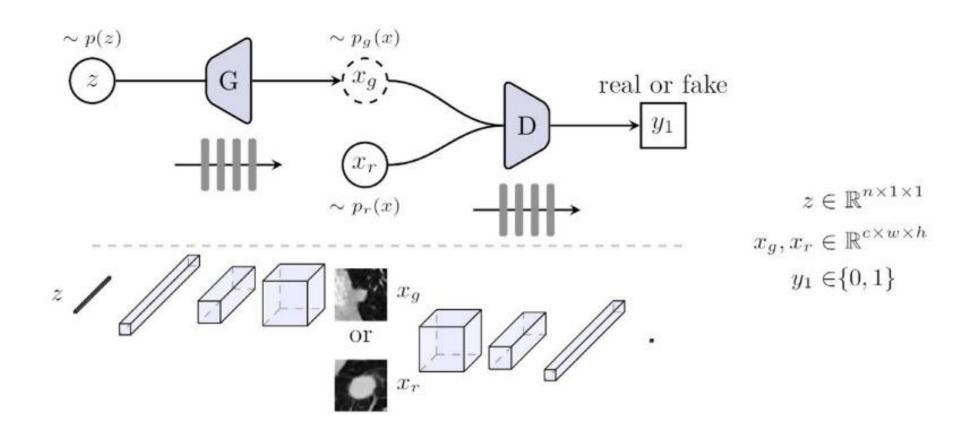




Vanilla GAN

$$\mathcal{L}_D^{GAN} = \max_D \mathbb{E}_{x_r \sim p_r(x)} [\log D(x_r)] + \mathbb{E}_{x_g \sim p_g(x)} [\log (1 - D(x_g))],$$

$$\mathcal{L}_G^{GAN} = \min_G \mathbb{E}_{x_g \sim p_g(x)} [\log (1 - D(x_g))].$$



Problemy

- Brak gwarancji równowagi między treningiem G i D
 - W większości przypadków D jest mocniejsza.
 - Gradienty z D zbliżają się do zera, nie dając żadnych wskazówek dla dalszego treningu G
- Generowanie obrazów o wysokiej rozdzielczości
- Mode collapse

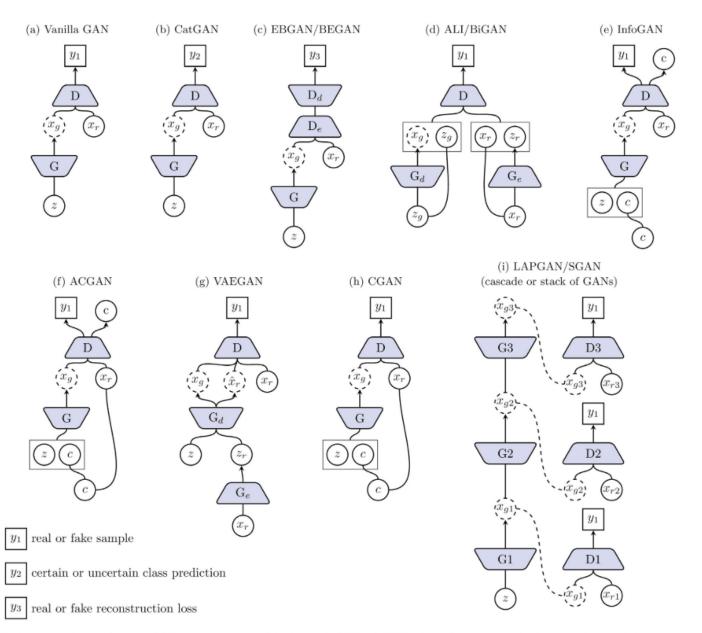


Fig. 3. A schematic view of variants of GAN. *c* represents the conditional vector. In CGAN and ACGAN, *c* is the discrete categorical code (e.g. one hot vector) that encodes class labels and in InfoGAN it can also be continuous code that encodes attributes. *x*_g generally refers to the generated image but can also be internal representations as in SGAN.