

HW07

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1. Eigenface and fisherface

eigenface:

Because $X @ X.T$ will be a very large matrix, we find the eigenvalues & eigenvectors of $X.T @ X$ matrix, these corresponding eigenvectors (without eigenvalue smaller than 0) then multiply X again representing a partial eigenvectors of $X @ X.T$.

Doing PCA to reduce dimension from $231 * 195 \rightarrow 134$.

```
def pca(X, num_dim=None):
    X_mean = np.mean(X, axis=1).reshape(-1, 1)
    X_center = X - X_mean

    # PCA
    eigenvalues, eigenvectors = np.linalg.eig(X_center.T @ X_center)
    sort_index = np.argsort(-eigenvalues)

    if num_dim is None:
        for eigenvalue, i in zip(eigenvalues[sort_index], np.arange(len(eigenvalues))):
            if eigenvalue <= 0:
                sort_index = sort_index[:i]
                break
    else:
        sort_index = sort_index[:num_dim]

    eigenvalues = eigenvalues[sort_index]
    # from X.T @ X eigenvector to X @ X.T eigenvector
    eigenvectors = X_center @ eigenvectors[:, sort_index]
    eigenvectors_norm = np.linalg.norm(eigenvectors, axis=0)
    eigenvectors = eigenvectors / eigenvectors_norm

    return eigenvalues, eigenvectors, X_mean
```

```
H, W = 231, 195
X, y = imread(filepath, H, W)

eigenvalues, eigenvectors, X_mean = pca(X)
# Transform matrix
U = eigenvectors.copy()
print('U shape: {}'.format(U.shape))

# show top 25 eigenface
show_eigenface(U[:25], H, W)

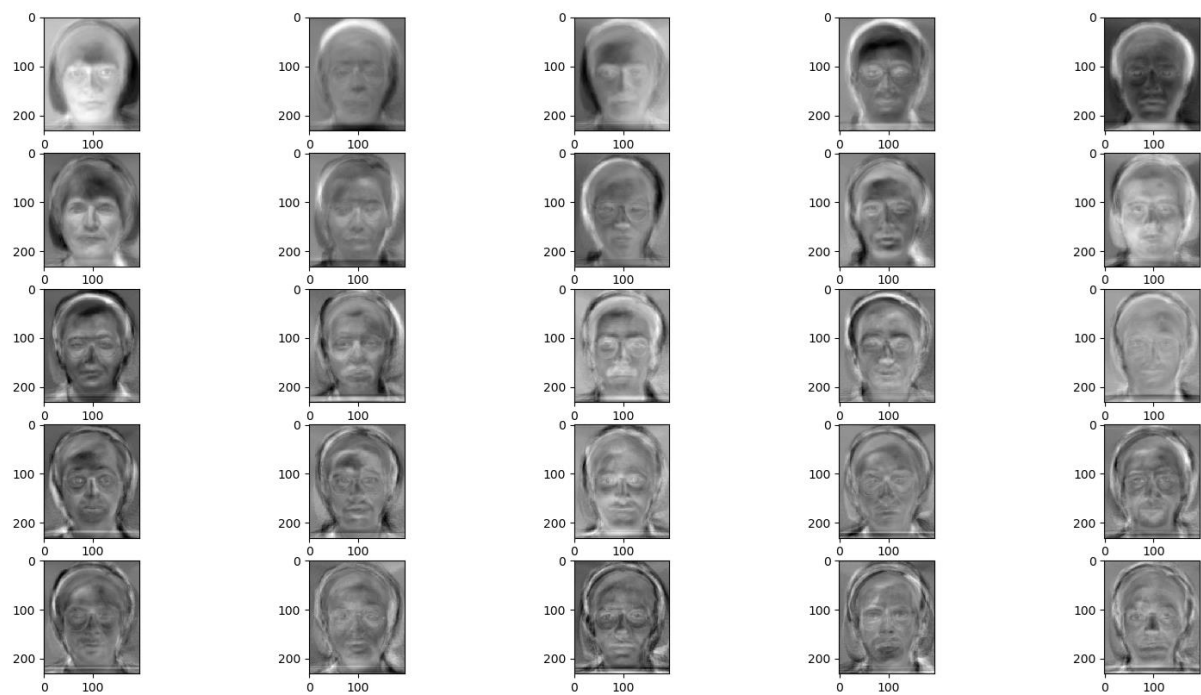
# reduce dim (projection)
Z = U.T @ (X - X_mean)

# recover
X_recover = U @ Z + X_mean
show_reconstruction(X, X_recover, 10, H, W)
```

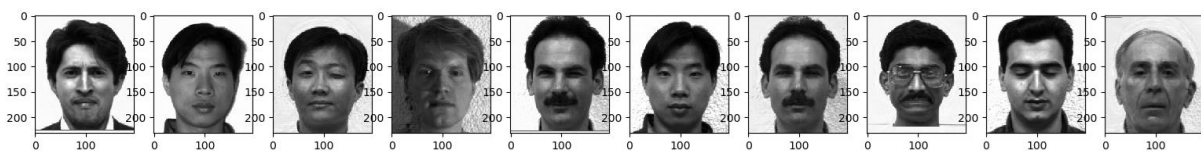
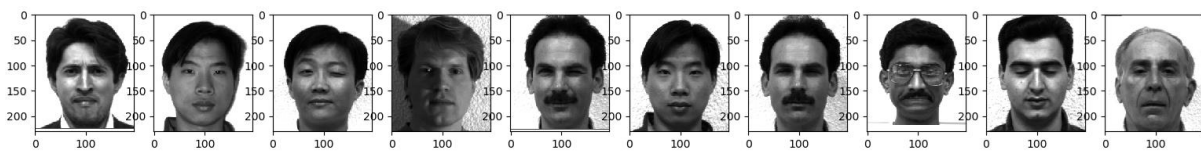
U is the transformation matrix.

We can get eigenface from the columns of U .

When doing recovering, just project X into a lower dimension using U then project back to the original dimension using $U.T$.



Showing the eigenface from the columns of matrix U.



Showing the reconstructed result.

The first row is the original faces , the second row is the reconstructed faces.

When doing recovering , just project X into a lower dimension using U then project back to the original dimension using $U.T$, after that remember to add the mean of the X due to the preprocessing step(we center the X in beginning).

```

# reduce dim (projection)
Z_test=U.T@(X_test-X_mean)

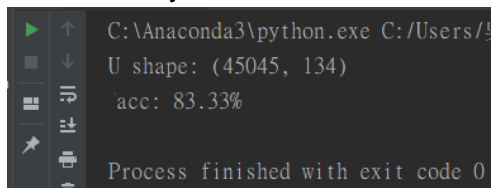
# k-nn
predicted_y=np.zeros(Z_test.shape[1])
for i in range(Z_test.shape[1]):
    distance=np.zeros(Z_train.shape[1])
    for j in range(Z_train.shape[1]):
        distance[j]=np.sum(np.square(Z_test[:,i]-Z_train[:,j]))
    sort_index=np.argsort(distance)
    nearest_neighbors=y_train[sort_index[:k]]
    unique, counts = np.unique(nearest_neighbors, return_counts=True)
    nearest_neighbors=[k for k,v in sorted(dict(zip(unique, counts)).items(), key=lambda item: -item[1])]
    predicted_y[i]=nearest_neighbors[0]

acc=np.count_nonzero((y_test-predicted_y)==0)/len(y_test)

```

Using the k-nn to predict the testing image label , in my case , I set k to be 3.

The accuracy is 83.33%.



```

C:\Anaconda3\python.exe C:/Users/!
U shape: (45045, 134)
acc: 83.33%
Process finished with exit code 0

```

fisherface:

Because of the singularity of the within-class scatter matrix , I first do the PCA to reduce the dimension from 231*195 to a lower dimension , then do the LDA to get my result.

```
def lda(X,y,num_dim=None):
    N=X.shape[0]
    X_mean = np.mean(X, axis=1).reshape(-1, 1)

    classes_mean = np.zeros((N, 15)) # 15 classes
    for i in range(X.shape[1]):
        classes_mean[:, y[i]] += X[:, y[i]]
    classes_mean = classes_mean / 9

    # within-class scatter
    S_within = np.zeros((N, N))
    for i in range(X.shape[1]):
        d = X[:, y[i]].reshape(-1,1) - classes_mean[:, y[i]].reshape(-1,1)
        S_within += d @ d.T

    # between-class scatter
    S_between = np.zeros((N, N))
    for i in range(15):
        d = classes_mean[:, i].reshape(-1,1) - X_mean
        S_between += 9 * d @ d.T

    eigenvalues,eigenvectors=np.linalg.eig(np.linalg.inv(S_within)@S_between)
    sort_index=np.argsort(-eigenvalues)
    if num_dim is None:
        sort_index=sort_index[:1] # reduce 1 dim
    else:
        sort_index=sort_index[:num_dim]

    eigenvalues=np.asarray(eigenvalues[sort_index].real,dtype='float')
    eigenvectors=np.asarray(eigenvectors[:,sort_index].real,dtype='float')

    return eigenvalues,eigenvectors
```

In my case , I first reduce the dimension to 31-dim by PCA , then reduce the dimension to 30-dim by LDA. The reason why I choose 31 as my objected dimension is by the final testing images' accuracy , I test this value from 30~130.

The transformation matrix U is composed of eigenvector of PCA & eigenvector of LDA.

```
X,y=imread(filepath,H,W)

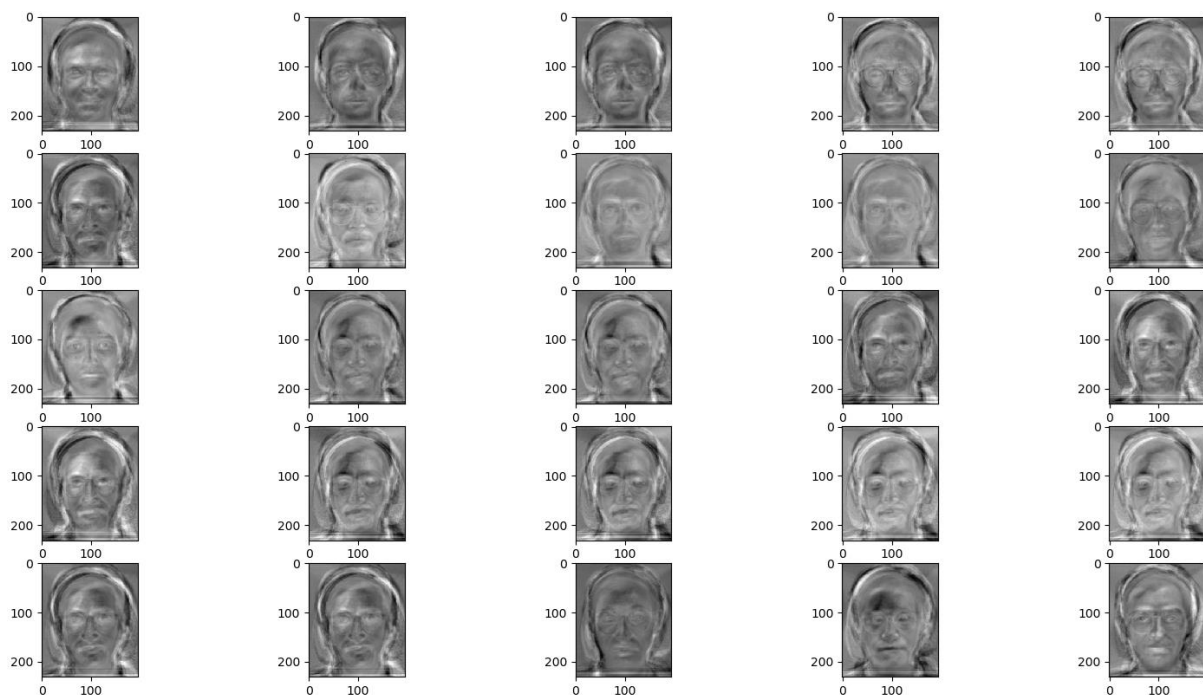
eigenvalues_pca,eigenvectors_pca,X_mean=pca(X,num_dim=31)
X_pca=eigenvectors_pca.T@(X-X_mean)
eigenvalues_lda,eigenvectors_lda=lda(X_pca,y)

# Transform matrix
U=eigenvectors_pca@eigenvectors_lda
print('U shape: {}'.format(U.shape))

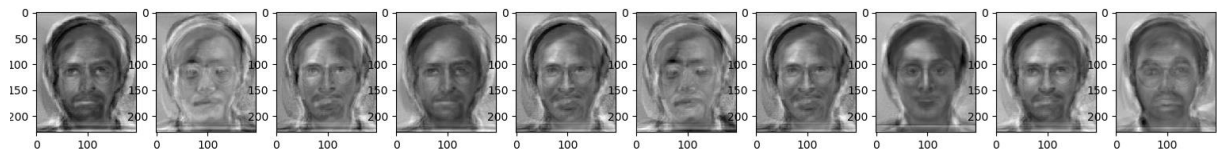
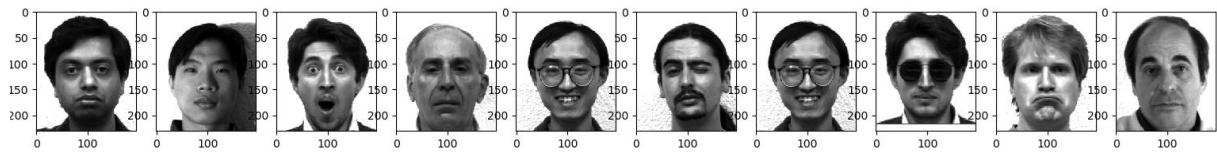
# show top 25 eigenface
show_eigenface(U,25,H,W)

# reduce dim (projection)
Z=U.T@X

# recover
X_recover=U@Z+X_mean
show_reconstruction(X,X_recover,10,H,W)
```



Showing the fisherface from the columns of matrix U .



Showing the reconstructed result.

The first row is the original faces , the second row is the reconstructed faces.

When doing recovering , just project X into a lower dimension using U then project back to the original dimension using $U.T$, after that remember to add the mean of the X due to the preprocessing step(we center the X in beginning).

In my case , I set the k of k -nn to be 5.

The final testing image accuracy is 70%.

```

C:\Anaconda3\python.exe C:/Users/!
U shape: (45045, 30)
acc: 70.00%

Process finished with exit code 0
  
```

2.t-SNE

To change to symmetric SNE , just have to modify two lines of code.

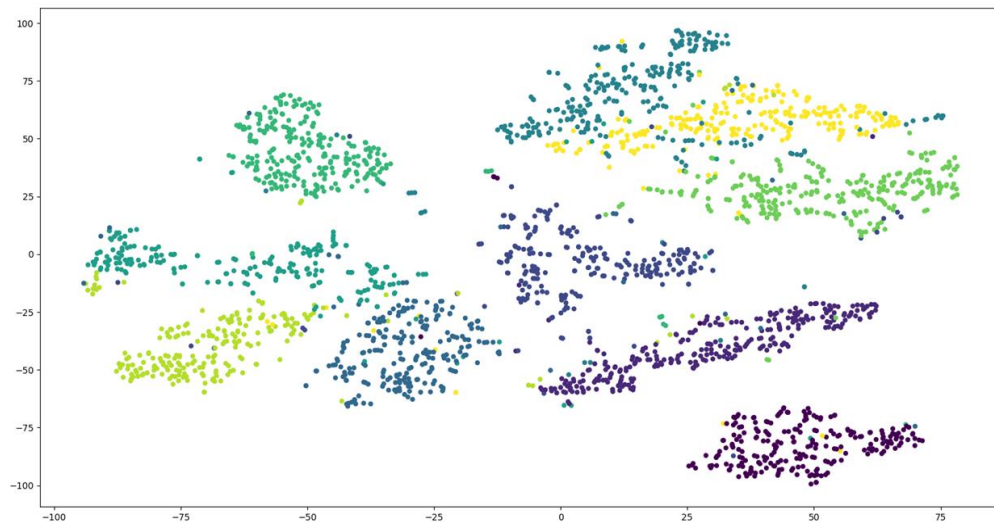
The first one is “num=np.exp(-(num+.....))” from student-t distribution to pairwise similarity estimate by exponential of 2-norm , the second one is “dY[i,:]=np.dot(PQ.....)” a different gradient descent from t-SNE.

```
for iter in range(max_iter):

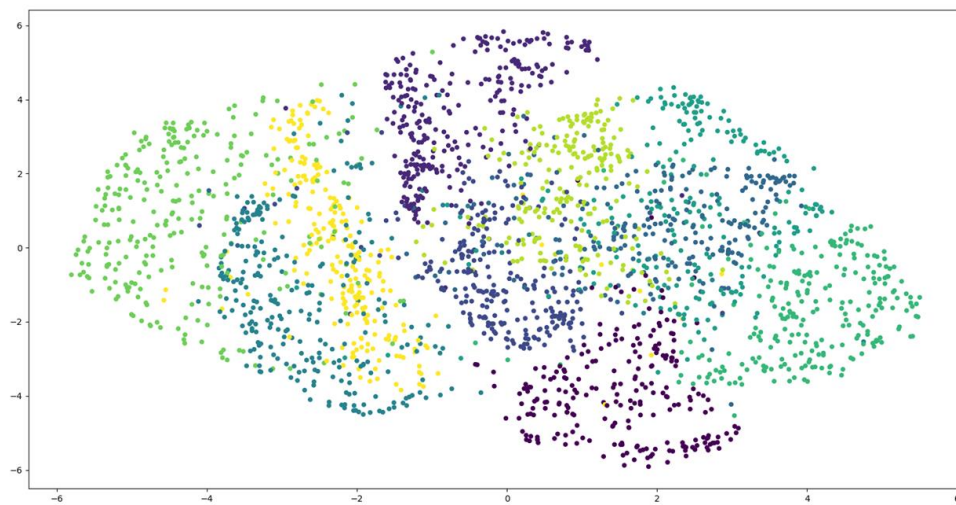
    # Compute pairwise affinities
    sum_Y = np.sum(np.square(Y), 1)
    num = -2. * np.dot(Y, Y.T)
    num=np.exp(-(num+sum_Y+sum_Y.reshape(-1,1)))
    num[range(n), range(n)] = 0.
    Q = num / np.sum(num)
    Q = np.maximum(Q, 1e-12)

    # Compute gradient
    PQ = P - Q
    for i in range(n):
        dY[i, :] = np.dot(PQ[i,:], Y[i,:]-Y)

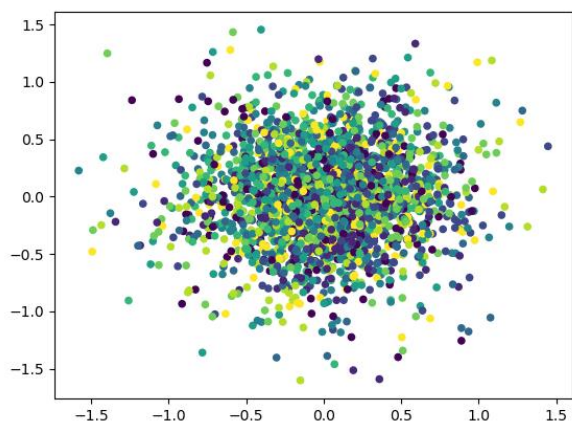
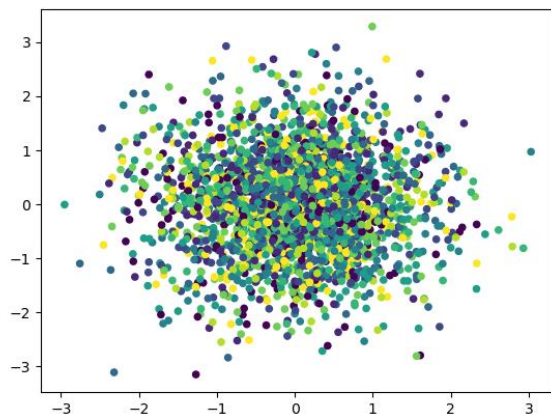
    # Perform the update
```



The t-SNE scatter plot after 500 iterations.



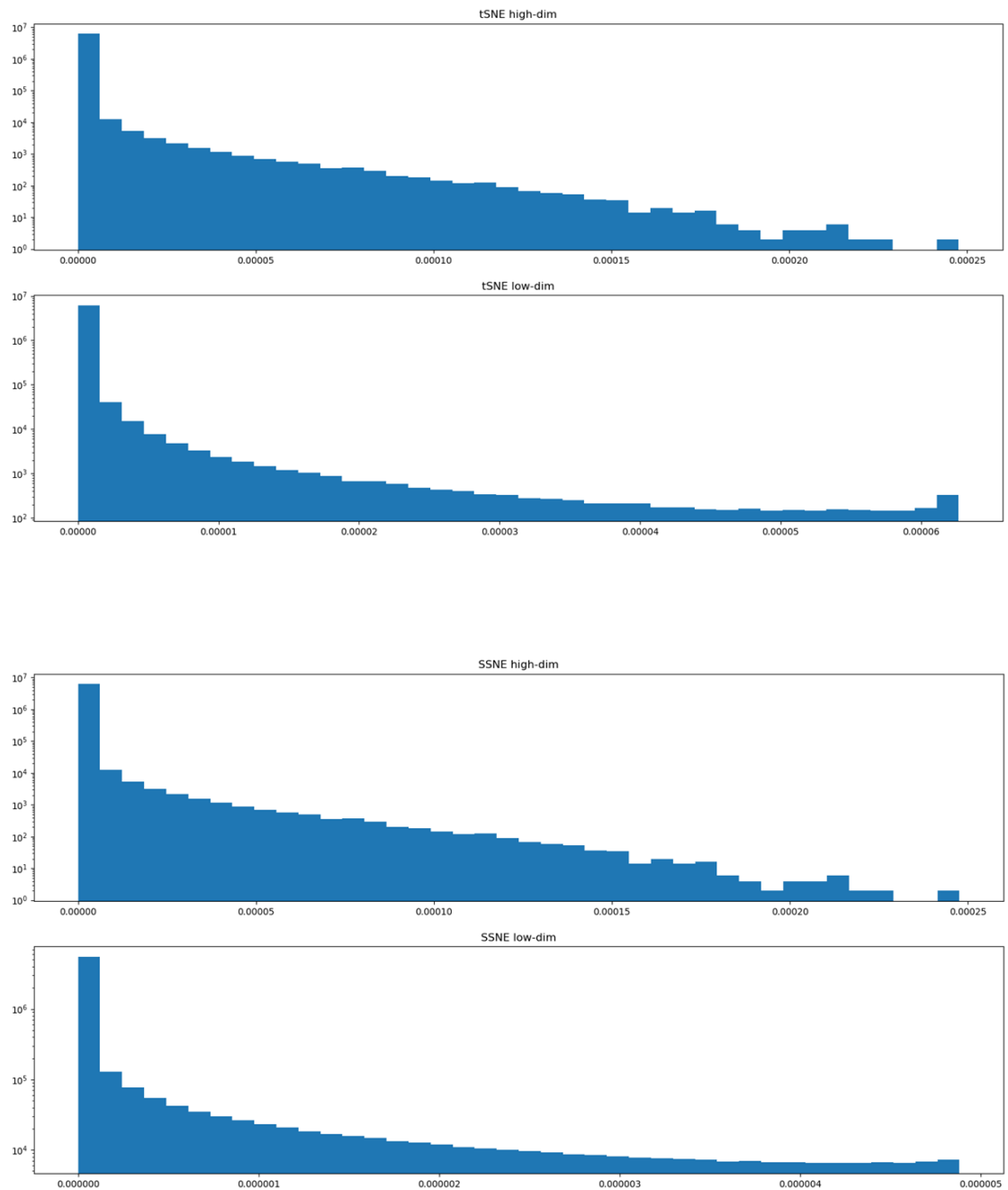
The symmetric SNE scatter plot after 500 iterations.



Upper gif: t-SNE scatter plot when doing iterate.

Lower gif: SSNE scatter plot when doing iterate.

Visualize the distribution of pairwise similarities in both high dimensional space and low-dimensional space.

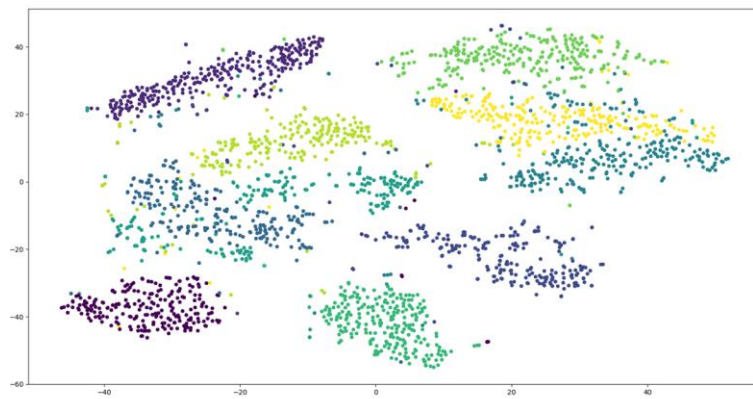
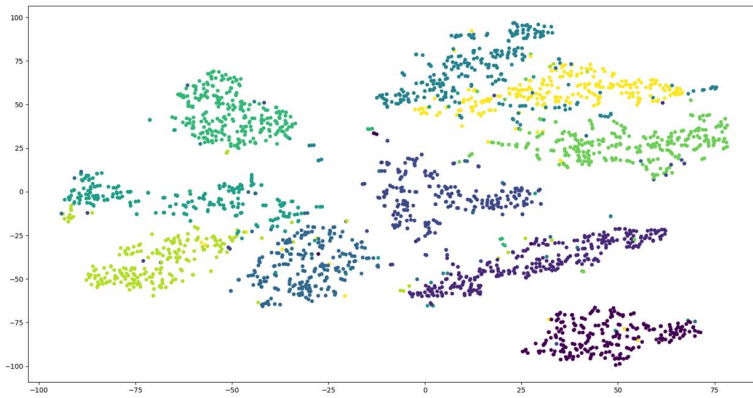
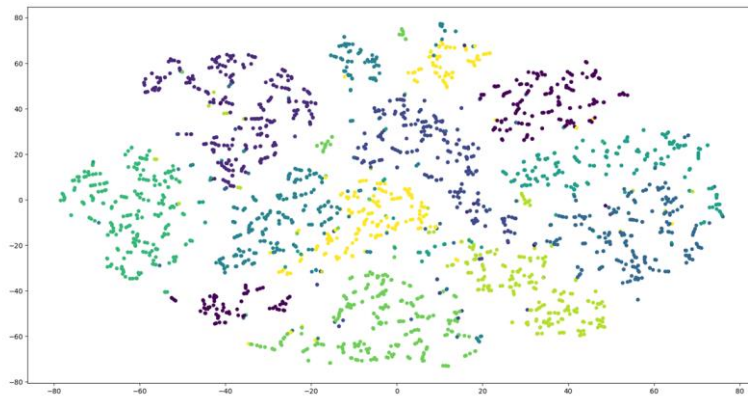


Both tSNE & SSNE case are converge after 500 iterations.

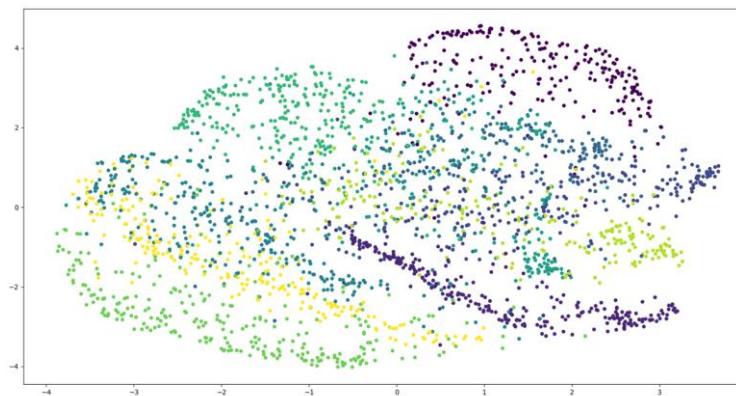
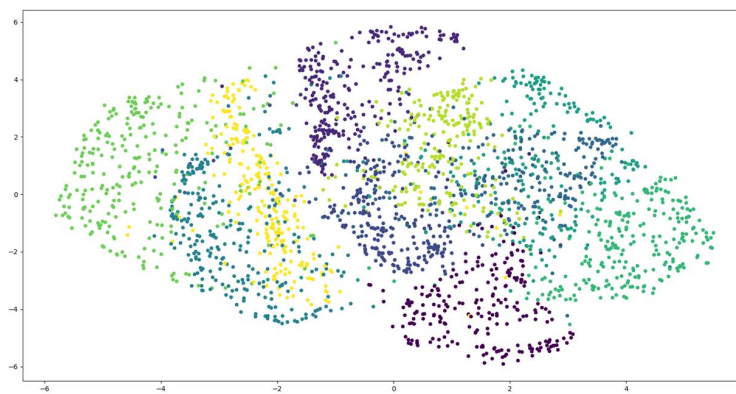
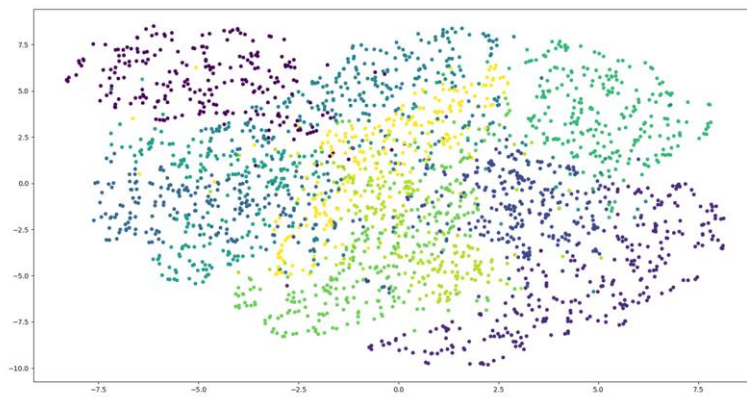
We can found that in t-SNE , the pairwise similarity in the low-dim is in a range from 0 to 0.00006 , but in SSNE , the pairwise similarity in the low-dim is only in a range from 0 to 0.000005 , which is a much smaller range comparing with t-SNE.

Therefore may cause the crowded problem.

Changing the perplexity of t-SNE and SSNE.



From top to down: t-SNE with perplexity 5, perplexity 20, perplexity 50



From top to down: SSNE with perplexity 5, perplexity 20, perplexity 50

We can found that with higher perplexity , the global structure is more obvious , but it may be impossible to distinguish between groups. In lower perplexity , only a few neighbors are influential and may split the same group into multiple groups.