Naïve Bayes and SVM

Bayes Classifier

- A probabilistic framework for solving classification problems
 P(C | A) = $\frac{P(A,C)}{P(A)}$ Conditional Probability:

$$P(A \mid C) = \frac{P(A,C)}{P(C)}$$

 $P(C \mid A) = \frac{P(A \mid C)P(C)}{P(A)}$ Bayes theorem:

Example of Bayes Theorem

• Given:

- A doctor knows that meningitis causes stiff neck 50% of the time
- Prior probability of any patient having meningitis is 1/50,000
- Prior probability of any patient having stiff neck is 1/20
- If a patient has stiff neck, what's the probability he/she has meningitis?

$$P(M \mid S) = \frac{P(S \mid M)P(M)}{P(S)} = \frac{0.5 \times 1/50000}{1/20} = 0.0002$$

Bayesian Classifiers

Consider each attribute and class label as random variables

- Given a record with attributes (A₁, A₂,...,A_n)
 - Goal is to predict class C
 - Specifically, we want to find the value of C that maximizes $P(C \mid A_1, A_2,...,A_n)$
- Can we estimate P(C| A₁, A₂,...,A_n) directly from data?

Bayesian Classifiers

- Approach:
 - compute the posterior probability $P(C \mid A_1, A_2, ..., A_n)$ for all values of C using the Bayes theorem

$$P(C \mid A_{1}A_{2}...A_{n}) = \frac{P(A_{1}A_{2}...A_{n} \mid C)P(C)}{P(A_{1}A_{2}...A_{n})}$$

- Choose value of C that maximizes $P(C \mid A_1, A_2, ..., A_n)$
- Equivalent to choosing value of C that maximizes $P(A_1, A_2, ..., A_n | C) P(C)$
- How to estimate P(A₁, A₂, ..., A_n | C)?

Naïve Bayes Classifier

- Assume independence among attributes A_i when class is given:
 - $P(A_1, A_2, ..., A_n | C) = P(A_1 | C_i) P(A_2 | C_i)... P(A_n | C_i)$
 - Can estimate $P(A_i | C_j)$ for all A_i and C_j .
 - New point is classified to C_i if $P(C_i)$ Π $P(A_i | C_i)$ is maximal.

How to Estimate Probabilities from Data?

Tid	Refund	Marital Status	Taxable Income	Evade
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes

• Class: $P(C) = N_c/N$

$$-$$
 e.g., $P(No) = 7/10$, $P(Yes) = 3/10$

For discrete attributes:

$$P(A_i \mid C_k) = |A_{ik}| / N_c$$

- where |A_{ik}| is number of instances having attribute A_i and belongs to class C_k
- Examples:

How to Estimate Probabilities from Data?

- For continuous attributes:
 - Discretize the range into bins
 - one ordinal attribute per bin
 - violates independence assumption
 - Two-way split: (A < v) or (A > v)
 - choose only one of the two splits as new attribute

k

- Probability density estimation:
 - Assume attribute follows a normal distribution
 - Use data to estimate parameters of distribution (e.g., mean and standard deviation)
 - Once probability distribution is known, can use it to estimate the conditional probability P(A_i|c)

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Normal distribution:

$$P(A_{i} | c_{j}) = \frac{1}{\sqrt{2\pi\sigma_{ij}^{2}}} e^{-\frac{(A_{i} - \mu_{ij})^{2}}{2\sigma_{ij}^{2}}}$$

- One for each (A_i,c_i) pair
- For (Income, Class=No):
 - If Class=No
 - sample mean = 110
 - sample variance = 2975

$$P(Income = 120 \mid No) = \frac{1}{\sqrt{2\pi}(54.54)}e^{\frac{-(120-110)^2}{2(2975)}} = 0.0072$$

Example of Naïve Bayes Classifier

Given a Test Record:

X = (Refund = No, Married, Income = 120K)

naive Bayes Classifier:

```
P(Refund=Yes|No) = 3/7
P(Refund=No|No) = 4/7
P(Refund=Yes|Yes) = 0
P(Refund=No|Yes) = 1
P(Marital Status=Single|No) = 2/7
P(Marital Status=Divorced|No)=1/7
P(Marital Status=Married|No) = 4/7
P(Marital Status=Single|Yes) = 2/7
P(Marital Status=Divorced|Yes)=1/7
P(Marital Status=Married|Yes) = 0
```

For taxable income:

If class=No: sample mean=110

sample variance=2975

If class=Yes: sample mean=90

sample variance=25

```
    P(X|Class=No) = P(Refund=No|Class=No)
    × P(Married| Class=No)
    × P(Income=120K| Class=No)
    = 4/7 × 4/7 × 0.0072 = 0.0024
```

P(X|Class=Yes) = P(Refund=No| Class=Yes)
 × P(Married| Class=Yes)
 × P(Income=120K| Class=Yes)
 = 1 × 0 × 1.2 × 10⁻⁹ = 0

Since P(X|No)P(No) > P(X|Yes)P(Yes)

Therefore P(No|X) > P(Yes|X)

=> Class = No

Naïve Bayes Classifier

- If one of the conditional probability is zero, then the entire expression becomes zero
- Probability estimation:

Original:
$$P(A_i \mid C) = \frac{N_{ic}}{N_c}$$

Laplace :
$$P(A_i \mid C) = \frac{N_{ic} + 1}{N_c + c}$$

m - estimate :
$$P(A_i \mid C) = \frac{N_{ic} + mp}{N_c + m}$$

c: number of classes

p: prior probability

m: parameter

Example of Naïve Bayes Classifier

Name	Give Birth	Can Fly	Live in Water	Have Legs	Class
human	yes	no	no	yes	mammals
python	no	no	no	no	non-mammals
salmon	no	no	yes	no	non-mammals
whale	yes	no	yes	no	mammals
frog	no	no	sometimes	yes	non-mammals
komodo	no	no	no	yes	non-mammals
bat	yes	yes	no	yes	mammals
pigeon	no	yes	no	yes	non-mammals
cat	yes	no	no	yes	mammals
leopard shark	yes	no	yes	no	non-mammals
turtle	no	no	sometimes	yes	non-mammals
penguin	no	no	sometimes	yes	non-mammals
porcupine	yes	no	no	yes	mammals
eel	no	no	yes	no	non-mammals
salamander	no	no	sometimes	yes	non-mammals
gila monster	no	no	no	yes	non-mammals
platypus	no	no	no	yes	mammals
owl	no	yes	no	yes	non-mammals
dolphin	yes	no	yes	no	mammals
eagle	no	yes	no	yes	non-mammals

A: attributes

M: mammals

N: non-mammals
$$P(A|M) = \frac{6}{7} \times \frac{6}{7} \times \frac{2}{7} \times \frac{2}{7} = 0.06$$

$$P(A|N) = \frac{1}{13} \times \frac{10}{13} \times \frac{3}{13} \times \frac{4}{13} = 0.0042$$

$$P(A|M)P(M) = 0.06 \times \frac{7}{20} = 0.021$$

$$P(A \mid N)P(N) = 0.004 \times \frac{13}{20} = 0.0027$$

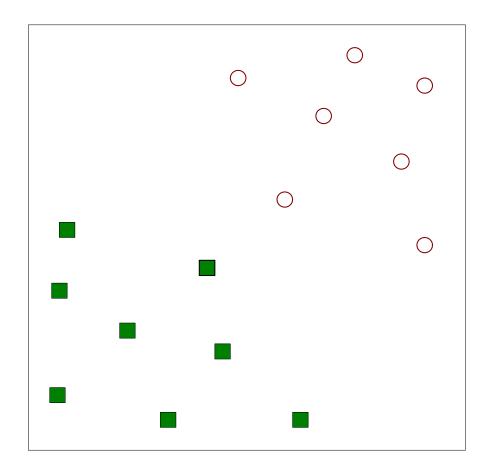
Give Birth	Can Fly	Live in Water	Have Legs	Class
yes	no	yes	no	?

P(A|M)P(M) > P(A|N)P(N)

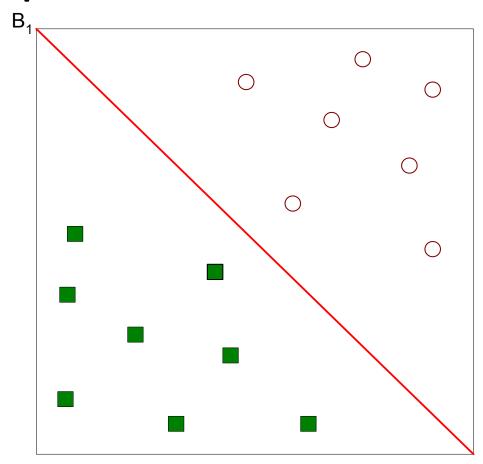
=> Mammals

Naïve Bayes (Summary)

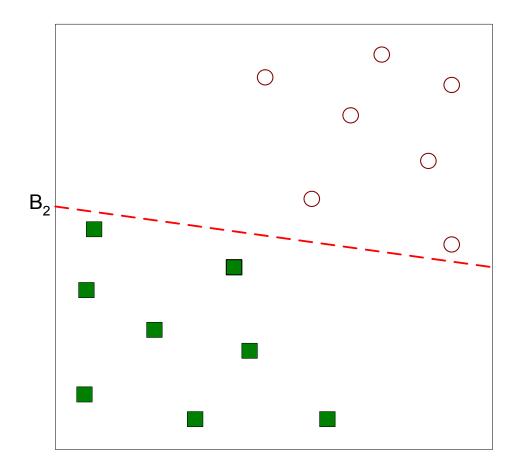
- Robust to isolated noise points
- Handle missing values by ignoring the instance during probability estimate calculations
- Robust to irrelevant attributes
- Independence assumption may not hold for some attributes
 - Use other techniques such as Bayesian Belief Networks (BBN)



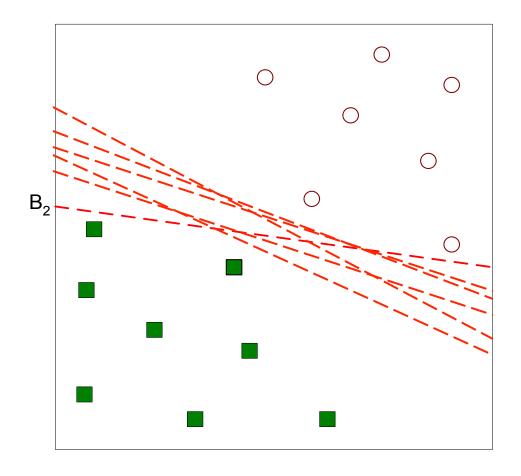
Find a linear hyperplane (decision boundary) that will separate the data



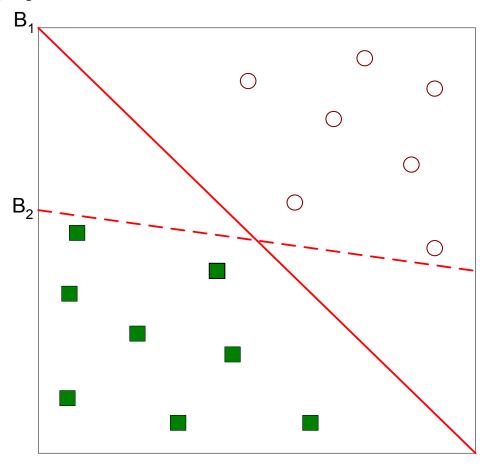
One Possible Solution



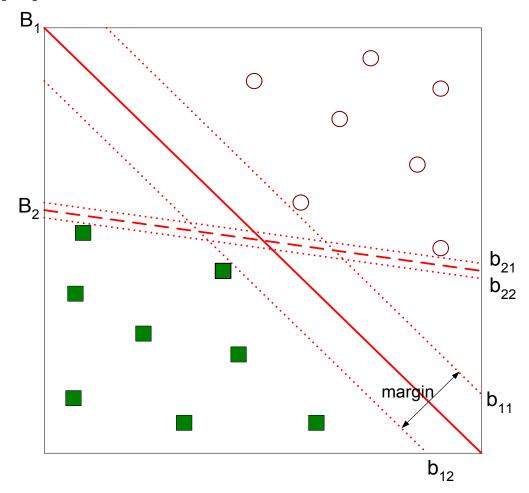
Another possible solution



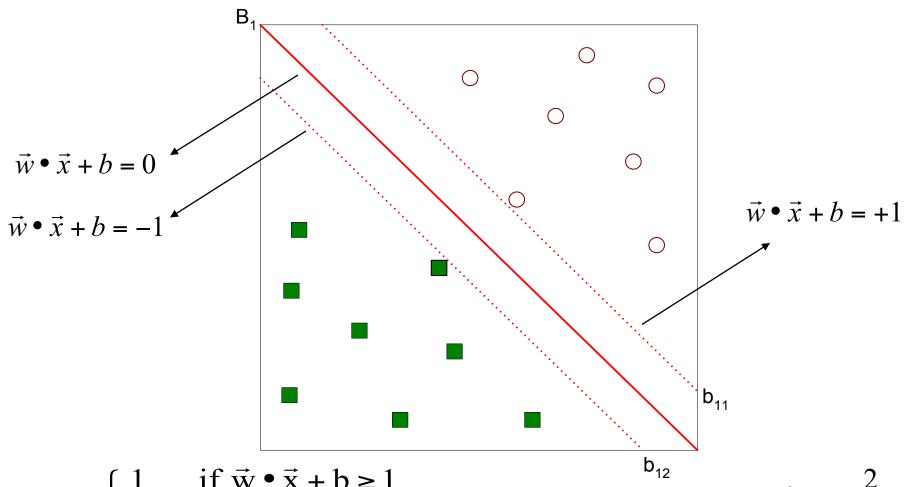
Other possible solutions



- Which one is better? B1 or B2?
- How do you define better?



Find hyperplane maximizes the margin => B1 is better than B2



$$f(\vec{x}) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x} + b \ge 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x} + b \le -1 \end{cases}$$

$$Margin = \frac{2}{\|\vec{w}\|^2}$$

$$Margin = \frac{2}{\|\vec{w}\|^2}$$

• We want to maximize:

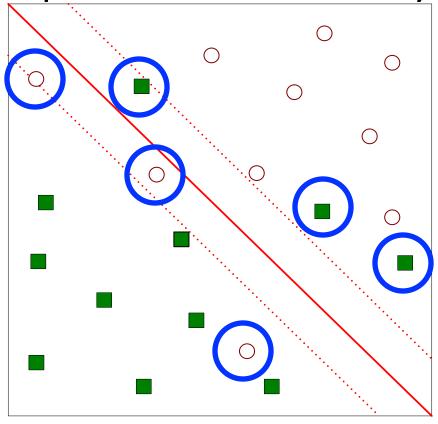
$$L(w) = \frac{\|\vec{w}\|^2}{2}$$

- Which is equivalent to minimizing:
- But subjected to the following constraints:

$$f(\vec{x}_i) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x}_i + b \ge 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x}_i + b \le -1 \end{cases}$$

- This is a constrained optimization problem
 - Numerical approaches to solve it (e.g., quadratic programming)

What if the problem is not linearly separable?



- What if the problem is not linearly separable?
 - Introduce slack variables

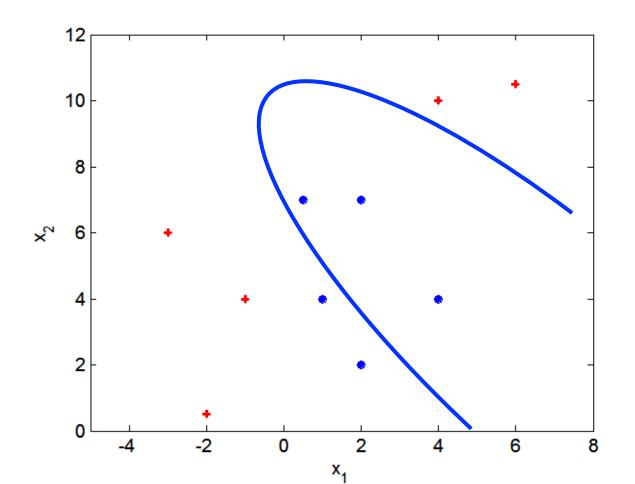
• Need to minimize:
$$L(w) = \frac{\|\vec{w}\|^2}{2} + C\left(\sum_{i=1}^N \xi_i^k\right)$$

• Subject to:

$$f(\vec{x}_i) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x}_i + b \ge 1 - \xi_i \\ -1 & \text{if } \vec{w} \cdot \vec{x}_i + b \le -1 + \xi_i \end{cases}$$

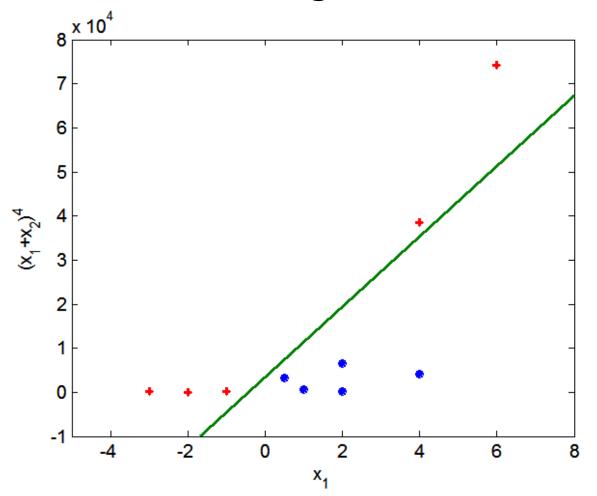
Nonlinear Support Vector Machines

What if decision boundary is not linear?



Nonlinear Support Vector Machines

Transform data into higher dimensional space



Kernel Trick!

- We do not need to actually map explicitly each point to a high dimensional space!!
- We just need to have a function that computes the similarity (distance) in the mapped space given the points in the input space (without the need to do the mapping!!!)
- Kernel function!!! (unfortunate term☺)

Kernel function

- Given x and y two vectors in R^d assume that we want to map them in a higher dimensional space R^n using a function φ
- We can define a function K(x,y): $R^d \times R^d \rightarrow R$ that computes directly the distance of $\phi(x)$ and $\phi(y)$! No need to compute the actual ϕ !!
- Actually, the Kernel function K should give the same results as the inner (dot) product between of $\phi(x)$ and $\phi(y)$ (simulates a dot product in the "mapped" space)

$$K(x,y) = \langle \phi(x), \phi(y) \rangle_n$$

SVM with Kernels

 Using the kernel trick, we can compute the linear separator in the mapped space without the need to do the actual mapping!! just use the Kernel function when you need to compute the inner product between two "mapped" vectors.

Kernel options

- Many different ways to define kernels
- Most popular kernels:
 - Linear: $K(x,y) = (x \cdot y)$
 - Polynomial: $K(x,y) = (x \cdot y)^d$ or $K(x,y) = (x \cdot y+1)^d$
 - RBF: $K(x,y) = \exp(-\gamma ||x-y||^2)$

In practice, RBF works well in most cases (adds small bumps around the "mapped" points)