## 高等數位訊號處理(Advanced Digital Signal Processing)

Homework 04 – 2017/06/08

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1. Write the Matlab program to compute the FFT of two N-point real signals x and y using only one N-point FFT.

$$[Fx, Fy] = \text{fftreal}(x, y)$$

The Matlab file should be mailed to displab531@gmail.com.

Code 已寄至信箱。

2. How do we use three real multiplications to implement a complex multiplication?

$$(a+bj)(c+dj) = (ac-bd) + (ad+bc)j$$

$$= e+fj$$

$$\begin{bmatrix} e \\ f \end{bmatrix} = \begin{bmatrix} c & -d \\ d & c \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} c & c \\ c & c \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} + \begin{bmatrix} 0 & -c-d \\ d-c & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$e_1 = c(a+b)$$

$$f_1 = e_2$$

$$e_2 = b(-c-d)$$

$$f_2 = b(d-c)$$

$$\implies e = e_1 + e_2, \ f = f_1 + f_2$$

3. How do we implement the following matrix operations with the lest number of multiplications?

 $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} b & a & b \\ a & b & a \\ b & a & b \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$   $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} a & b & c & d \\ b & -d & -a & -c \\ c & -a & d & b \\ d & -c & b & -a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$ 

(a)

整理可得

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} b & a & b \\ a & b & a \\ b & a & b \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$= \frac{1}{2} \left( \begin{bmatrix} (a+b) & (a+b) & (a+b) \\ (a+b) & (a+b) & (a+b) \\ (a+b) & (a+b) & (a+b) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \\ -(a-b) & (a-b) & -(a-b) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right)$$

考慮

$$\begin{bmatrix} y_4 \\ y_5 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} (a+b) & (a+b) & (a+b) \\ (a+b) & (a+b) & (a+b) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & -(a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & (a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & (a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & (a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & (a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b) & (a-b) \\ (a-b) & -(a-b) & (a-b) \end{bmatrix}} \not = \underbrace{\frac{1}{2} \begin{bmatrix} -(a-b) & (a-b)$$

其中

$$y_4 = y_5 = \frac{(a+b)(x_1 + x_2 + x_3)}{2}, \ y_6 = -y_7 = \frac{(b-a)(x_1 - x_2 + x_3)}{2}$$

則有

$$y_1 = y_4 + y_6, \ y_2 = y_3 = y_5 + y_7$$

(b)

整理可得

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} a & b & c & d \\ b & -d & -a & -c \\ c & -a & d & b \\ d & -c & b & -a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$= \frac{1}{3} \left( \begin{bmatrix} (a+b+c+d) & (a+b+c+d) & (a+b+c+d) & (a+b+c+d) \\ (a+b+c+d) & (a+b+c+d) & (a+b+c+d) & (a+b+c+d) \\ (a+b+c+d) & (a+b+c+d) & (a+b+c+d) & (a+b+c+d) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right)$$

- 4. Determining the numbers of real multiplications for the
  - (a) 100 point DFT
  - (b) 176 point DFT
  - (c) 338 point DFT
  - # 假設 N-point DFT,其中  $N=P_1 \times P_2 \times \cdots \times P_k$  且  $P_1,P_2,\cdots,P_k$  彼此互質,則其總乘法量為

$$\frac{N}{P_1}B_1 + \frac{N}{P_2}B_2 + \dots + \frac{N}{P_k}B_k$$

 $oldsymbol{x}$  假設 N- point DFT, 其中  $N=P^c$  且 P 為質數,則其總乘法量為

$$N_2B_1 + N_1B_2 + 3D_1 + 2D_2$$

- (a)  $N = 100 = 10 \times 10$ 
  - $\implies$  The numbers of real multiplications:  $10 \times 10 + 10 \times 20 + 3 \times 80 = 640$
- (b)  $N = 176 = 11 \times 16$ 
  - $\implies$  The numbers of real multiplications:  $11 \times 20 + 16 \times 46 = 956$
- (c)  $N = 338 = 2 \times 13^2$ 
  - $\implies$  The numbers of real multiplications:  $2(13 \times 52 + 13 \times 52 + 3 \times 144) = 3568$

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5. Suppose that a 1 - D ridge detection filter is:

$$x_s[n] = x[n] * h[n]$$
  $h[1] = h[-1] = -0.3$   $h[2] = h[-2] = -0.125$   $h[3] = h[-3] = -0.075$   $h[0] = 1$   $h[n] = 0$  otherwise

Design an efficient way to implement the above filter operation.

上述一維濾波器由於具備偶函數對稱,採用 Directly Computing Method 最有效率。

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- 6. Suppose that length(x[n]) = 1200. What is the best way to implement the convolution of x[n] and y[n] if
  - (a) length(y[n]) = 600
- (b) length(y[n]) = 50
- (c) length(y[n]) = 9
- (d)  $\operatorname{length}(y[n]) = 3$
- (a)  $\underline{\operatorname{length}(y[n]) = 600}$  採用  $1799 \operatorname{point}$  DFT/IDFT 實現折積計算。
- (c)  $\frac{\operatorname{length}(y[n]) = 9}{$ 直接計算。
- (d)  $\frac{\operatorname{length}(y[n]) = 3}{$ 直接計算。