

Integer and Combinatorial Optimization – Solution Methods

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Agenda

- Cutting Plane
- Brand and Bound
- Bender Decomposition
- Lagrangian Relaxation

Branch and Bound Method

- Traditional approach to solving integer programming problems.
- Based on principle that total set of feasible solutions can be partitioned into smaller subsets of solutions.
- Smaller subsets evaluated until best solution is found.
- Method is a tedious and complex mathematical process.

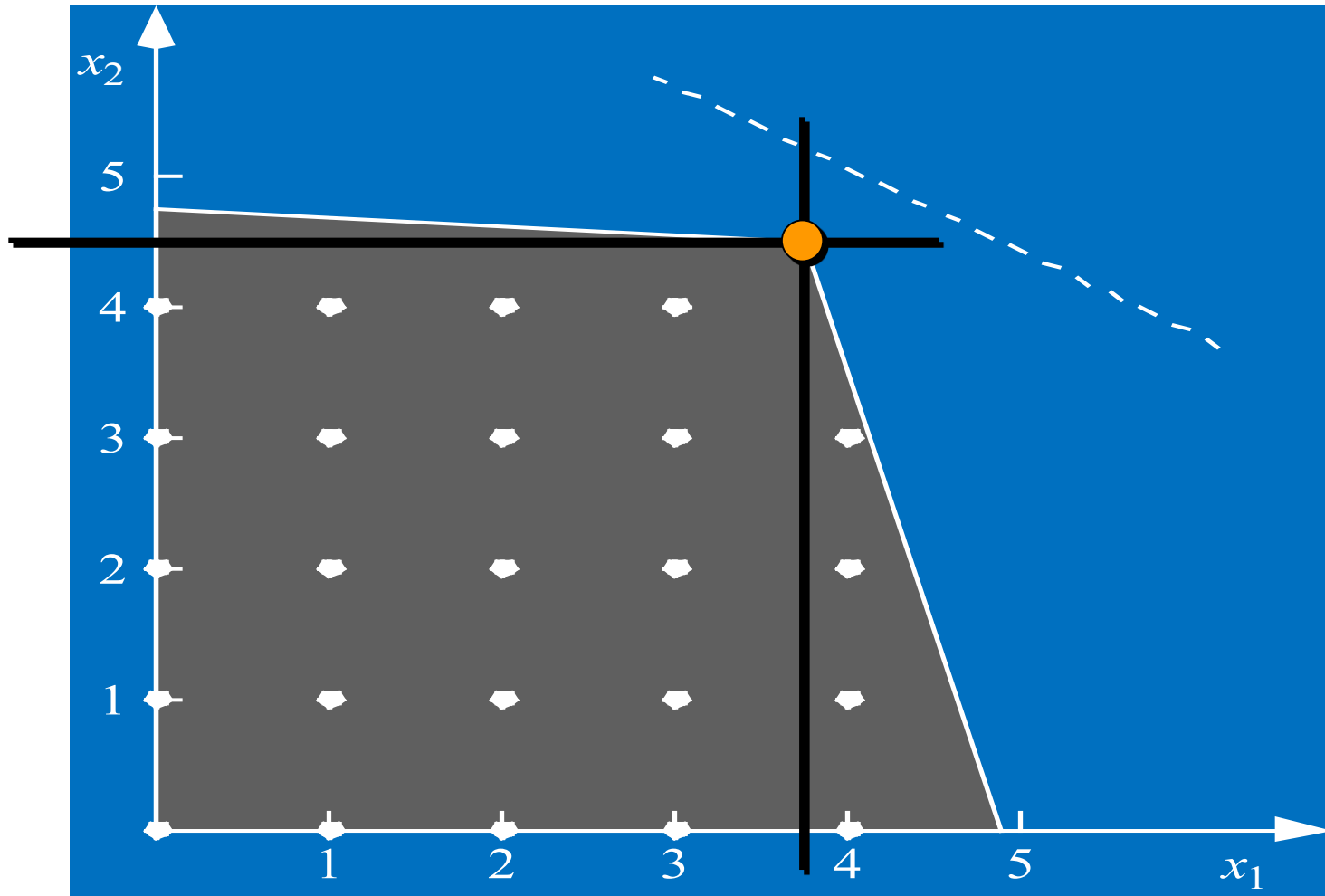
Branch and Bound

Problems are solved as LP. If not integers, one of them is chosen and 2 new constraints are added.

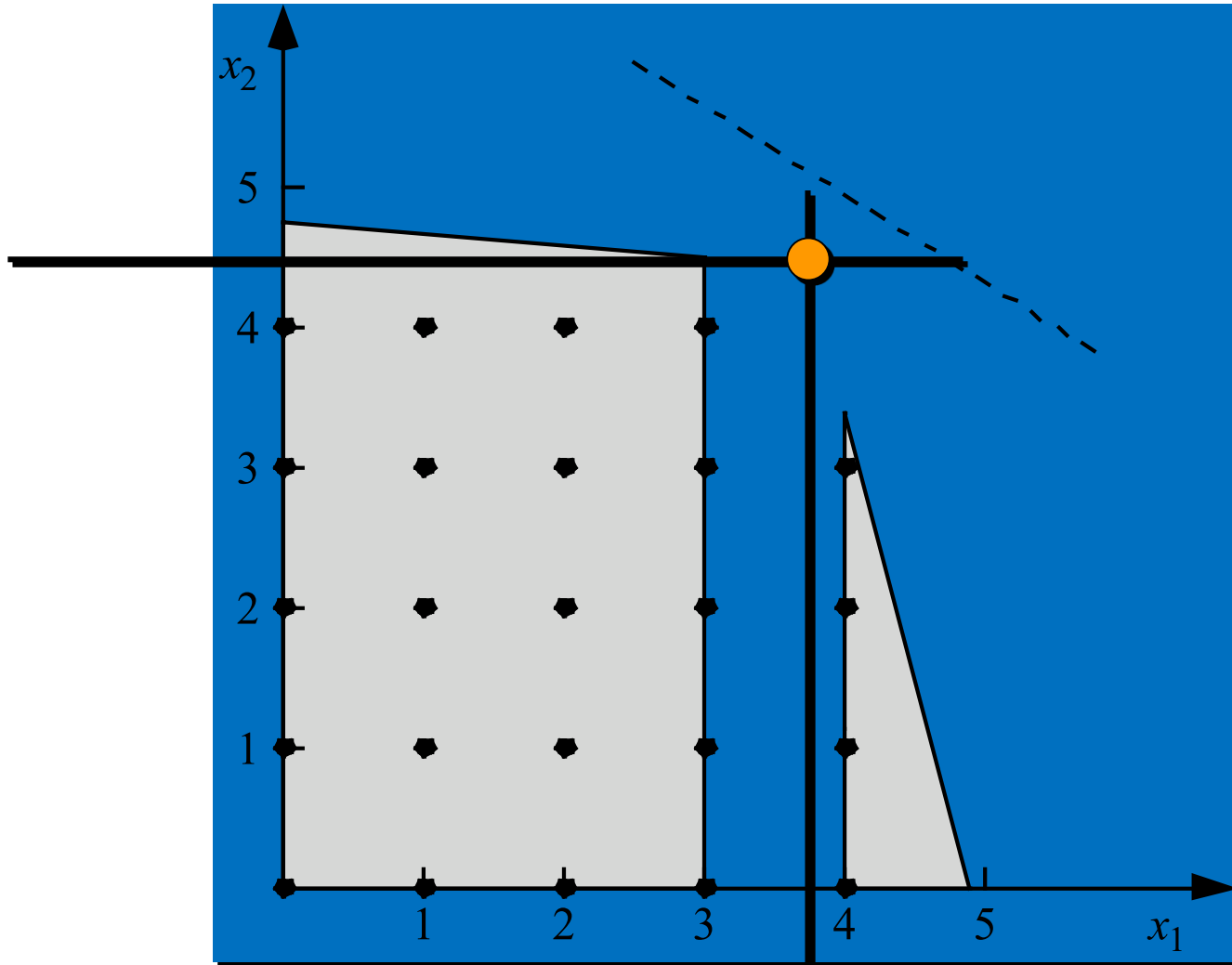
$$x_i \leq \lfloor v \rfloor \text{ and } x_i \geq \lfloor v \rfloor + 1$$

Proceeds until optimal.

How Integer Programs are Solved: Original Graph



After Branch and Bound on x_1



Branch & Bound 1/3

Step 1: Solve problem using LP. If solution is integer—finished. Otherwise, next.

Step 2: Branch on non-integer variable from step 1. Split problem into two pieces: integer above, and integer below.

Branch & Bound 2/3

Step 3: Create nodes of these branches and solve the new LP problems.

Step 4:

- a) Infeasible, terminate branch;
- b) Feasible, not integer, back to Step 2;
- c) Feasible and integer, go to Step 5.

Branch & Bound 3/3

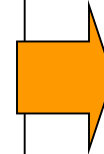
Step 5: Check branches.

- 1) The feasible solution is a _____ bound of the optimum (Max problem).
- 2) If the feasible solution is better than the LP solution of a node, the branch of that node is _____ .
- 3) If there are no remaining branches, the feasible solution is the solution to the problem.

First Branch

Original Problem

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30\end{array}$$



$$\begin{array}{l}x_1 = 3.75 \\ x_2 = 1.50 \\ Z = 35.25\end{array}$$

Sub-problem A

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30\end{array}$$

$$x_1 \geq 4$$

Sub-problem B

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30\end{array}$$

$$x_1 \leq 3$$

Second Branch

Sub-problem A

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4\end{array}$$



$$\begin{array}{l}x_1 = 4 \\ x_2 = 1.20 \\ Z = 35.2\end{array}$$

Sub-problem C

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4 \\ & x_2 \geq 2\end{array}$$

Sub-problem D

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4 \\ & x_2 \leq 1\end{array}$$

Third Branch

Sub-problem B

$$\text{Max } 7x_1 + 6x_2$$

$$\text{st. } 2x_1 + 3x_2 \leq 12$$

$$6x_1 + 5x_2 \leq 30$$

$$x_1 \leq 3$$



$$x_1 = 3$$

$$x_2 = 2$$

$$Z = 33$$

Integer solution \Rightarrow

No more branch is needed
along this sub-problem.

Fourth Branch

Sub-problem C

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4 \\ & x_2 \geq 2\end{array}$$



**No
feasible
solution**

**No feasible solution \Rightarrow
No more branch is needed
along this sub-problem.**

Fifth Branch

Sub-problem D

$$\begin{aligned} \text{Max } & 7x_1 + 6x_2 \\ \text{st. } & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4 \\ & x_2 \leq 1 \end{aligned}$$



$$\begin{aligned} x_1 &= 4.16 \\ x_2 &= 1 \\ Z &= 35.12 \end{aligned}$$

Sub-problem E

$$\begin{aligned} \text{Max } & 7x_1 + 6x_2 \\ \text{st. } & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4, x_1 \leq 4 \\ & x_2 \leq 1 \end{aligned}$$


Sub-problem F

$$\begin{aligned} \text{Max } & 7x_1 + 6x_2 \\ \text{st. } & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4, x_1 \geq 5 \\ & x_2 \leq 1 \end{aligned}$$

Sixth Branch


Sub-problem E

$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4, x_1 \leq 4 \\ & x_2 \leq 1\end{array}$$


$$\begin{array}{l}x_1 = 4 \\ x_2 = 1 \\ Z = 34\end{array}$$

Sub-problem F

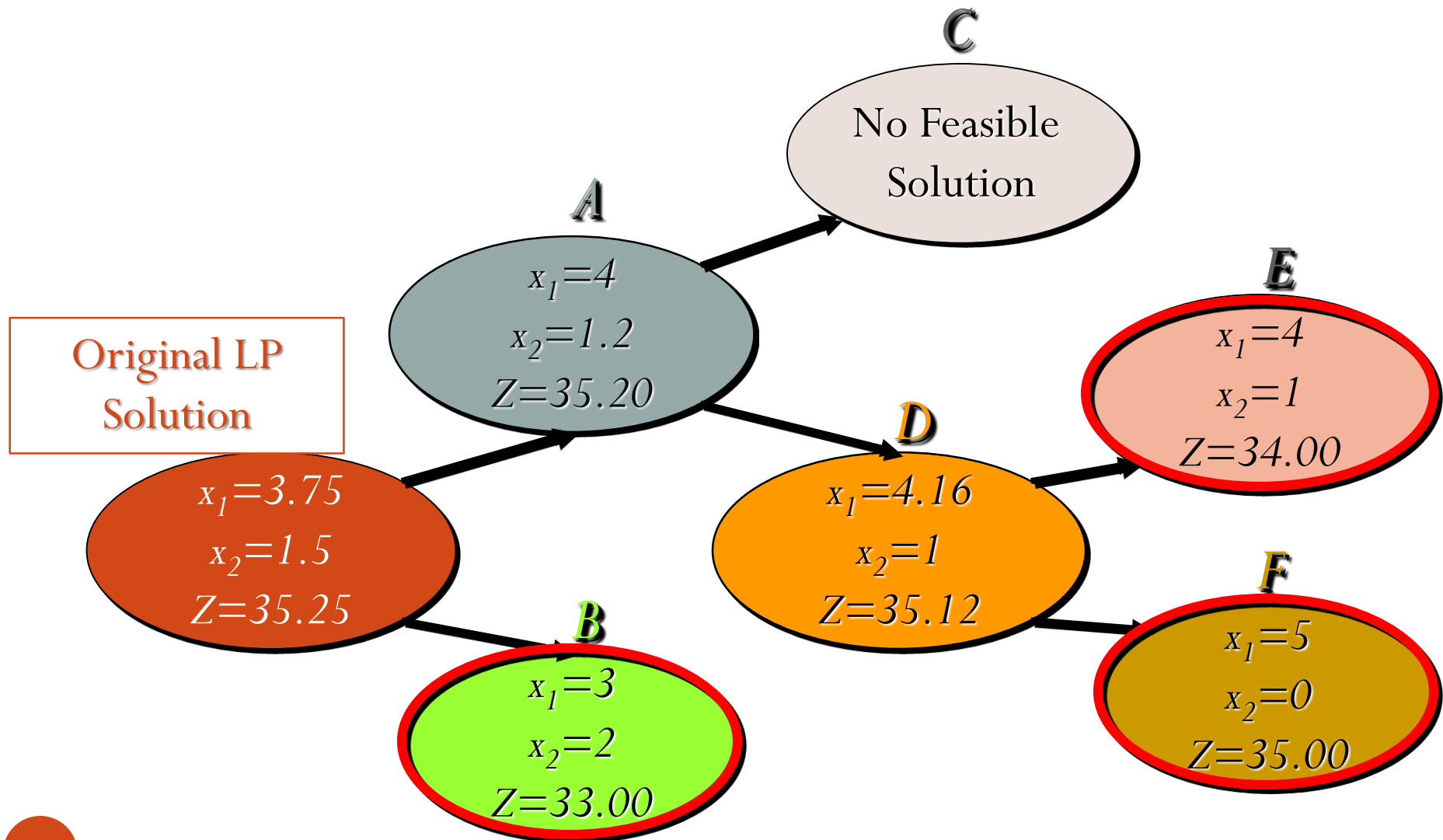
$$\begin{array}{ll}\text{Max} & 7x_1 + 6x_2 \\ \text{st.} & 2x_1 + 3x_2 \leq 12 \\ & 6x_1 + 5x_2 \leq 30 \\ & x_1 \geq 4, x_1 \geq 5 \\ & x_2 \leq 1\end{array}$$


$$\begin{array}{l}x_1 = 5 \\ x_2 = 0 \\ Z = 35\end{array}$$

Integer solutions \Rightarrow

No more branch is needed
along this sub-problem.

Branch & Bound - Overall



Special Case: 1-0 Problem (BIP)

- Now consider an IP problem where all integer variable are either 0 or 1.
- For any integer variable x_i ,

$$x_i \leq 0 \Rightarrow x_i = 0,$$

$$x_i \geq 1 \Rightarrow x_i = 1.$$

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Introduction

- For large MILP problems, if there are complicating constraints, we can use **Lagrangian relaxation** or **Lagrangian decomposition** to find near optimal solutions. If there are complicating variables, we can use **Bender's decomposition** to find an optimal solution
- Consider the following MILP problem:

$$\begin{array}{ll} \text{(MILP)} & \textit{maximize} \quad z = c^T x + h^T y, \\ & \textit{subject to} \quad Ax + Gy \leq b, \\ & \quad \quad \quad x \geq 0, \text{integer}, \\ & \quad \quad \quad y \geq 0. \end{array}$$

Bender's Decomposition (1/4)

- In Bender's decomposition, the MILP problem is reformulated in terms of the integer(x) variables and **only one continuous variable**.
- However, the reformulation contains a huge number of constraints. Usually, only a small number of constraints is active in an optimal solution and a natural relaxation is obtained by dropping most of the constraints.
- Constraint Generation Algorithm can be used to solve the problem.

Bender's Decomposition (2/4)

- If we fix the x variables (**integer**), we obtain the following LP:

$$\begin{aligned} (\text{LP}(x)) \quad z_{LP}(x) = & \text{maximize } h^T y, \\ & \text{subject to } Gy \leq b - Ax, \quad : u \\ & y \geq 0, \end{aligned}$$

and its dual is

$$\begin{aligned} & \text{minimize } u^T (b - Ax), \\ & \text{subject to } u^T G \geq h^T, \\ & u \geq 0. \end{aligned}$$

Bender's Decomposition (3/4)

- The dual polyhedron, $Q = \{u : u^T G \geq h^T, u \geq 0\}$, can be represented in terms of its extreme points and extreme directions
- Set of extreme points of $Q = \{u^T : k \in K\}$
- Set of extreme directions of $Q = \{v^j : j \in J\}$
- Characterization of $z_{LP}(x)$:
 1. If $Q = \emptyset$, then $z_{LP}(x) = \infty$, if $\langle v^j \rangle^T (b - Ax) \geq 0$, for all $j \in J$,
 $z_{LP}(x) = -\infty$, otherwise.
 2. If $Q \neq \emptyset$, then $z_{LP}(x) = \min \left\{ (u^k)^T (b - Ax), k \in K \right\}$, if $(v^j)^T (b - Ax) \geq 0$, for all $j \in J$,
 $z_{LP}(x) = -\infty$, otherwise.

Bender's Decomposition (4/4)

- Then, if $Q \neq \emptyset$, MILP is equivalent to

$$z^* = \max \left\{ c^T x + \min \left\{ \left(u^k \right)^T (b - Ax), k \in K \right\} \right\},$$

$$\text{subject to } \left(v^j \right)^T (b - Ax) \geq 0, \text{ for all } j \in J,$$

$$x \geq 0, \text{ integer},$$

and for any Q , MILP is equivalent to (Bender's Reformulation)

$$\text{(MILP')} \quad z^* = \text{maximize } \eta,$$

$$\text{subject to } \eta \leq c^T x + \left(u^k \right)^T (b - Ax), \text{ for all } k \in K,$$

$$\left(v^j \right)^T (b - Ax) \geq 0, \quad \text{for all } j \in J,$$

$$x \geq 0, \text{ integer}.$$

Example (1/4)

$$\begin{aligned} \text{maximize } z &= 5x_1 - 2x_2 + 9x_3 + 2y_1 - 3y_2 + 4y_3, \\ \text{subject to } & 5x_1 - 3x_2 + 7x_3 + 2y_1 + 3y_2 + 6y_3 \leq -2, \\ & 4x_1 + 2x_2 + 4x_3 + 3y_1 - y_2 + 3y_3 \leq 10, \\ & 0 \leq x_j \leq 5, \text{ integer, } \quad j = 1, 2, 3, \\ & y_j \geq 0 \quad \quad \quad j = 1, 2, 3. \end{aligned}$$

Example (2/4)

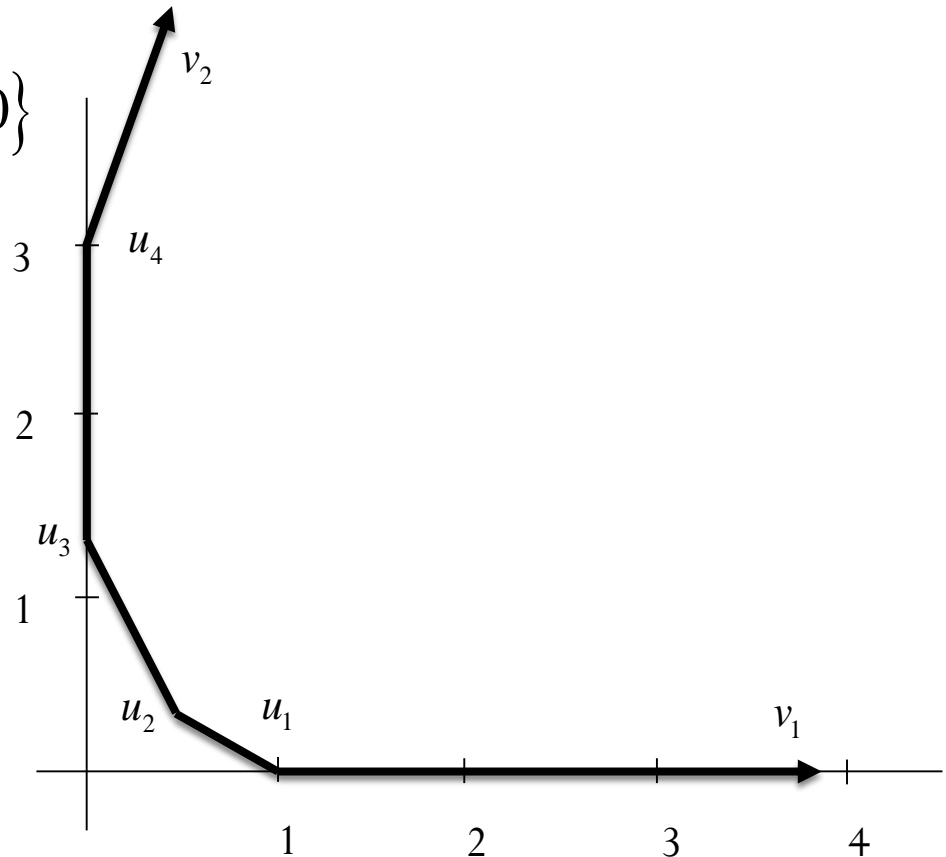
The polygon $Q = \{u : u^T G \geq h, u \geq 0\}$
is defined by

$$2u_1 + 3u_2 \geq 2,$$

$$3u_1 - u_2 \geq -3,$$

$$6u_1 + 3u_2 \geq 4,$$

$$u_1, u_2 \geq 0.$$



Set of extreme points of $Q = \left\{ u^1 = (1, 0)^T, u^2 = (\frac{1}{2}, \frac{1}{3})^T, u^3 = (0, \frac{4}{3})^T, u^4 = (0, 3)^T \right\},$

Set of extreme directions of $Q = \{v^1 = (1, 0)^T, v^2 = (1, 3)^T\}.$

Example (3/4)

- For extreme point $(1, 0)$:

According to $\eta \leq c^T x + (u^k)^T (b - Ax)$, for all $k \in K$,
we have

- For extreme direction $(1, 0)$:

Based on $(v^j)^T (b - Ax) \geq 0$, for all $j \in J$,
we have

Example (4/4)

The resulting Bender's reformulation is

$z = \text{maximize } \eta,$

subject to $\eta \leq 5x_1 - 2x_2 + 9x_3 + (-2 - 5x_1 + 3x_2 - 7x_3),$

$$\eta \leq 5x_1 - 2x_2 + 9x_3 + \frac{1}{2}(-2 - 5x_1 + 3x_2 - 7x_3) + \frac{1}{3}(10 - 4x_1 - 2x_2 - 4x_3),$$

$$\eta \leq 5x_1 - 2x_2 + 9x_3 + \frac{4}{3}(10 - 4x_1 - 2x_2 - 4x_3),$$

$$\eta \leq 5x_1 - 2x_2 + 9x_3 + 3(10 - 4x_1 - 2x_2 - 4x_3),$$

$$(-2 - 5x_1 + 3x_2 - 7x_3) \geq 0,$$

$$(-2 - 5x_1 + 3x_2 - 7x_3) + 3(10 - 4x_1 - 2x_2 - 4x_3) \geq 0,$$

$$0 \leq x_j \leq 5, \text{ integer, } j=1,2,3.$$

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Integer Programming Problem

- Consider the following ILP problem:

$$z_{\text{IP}} = \text{maximize } c^T x$$

$$\left. \begin{array}{l} A^1 x \leq b^1 \text{ (complicating constraints) : } \lambda \geq 0 \\ \text{subject to } A^2 x \leq b^2 \text{ (nice(easy) constraints)} \\ x \geq 0, \text{ integer} \end{array} \right\} = S$$

$$\text{where } A = \begin{pmatrix} A^1 \\ A^2 \end{pmatrix}_{m \times n}, \quad A^1_{m_1 \times n}, \quad A^2_{m_2 \times n}, \quad b = \begin{pmatrix} b^1 \\ b^2 \end{pmatrix}.$$

Relax Hard Constraint

- The problem is easy to solve when the complicating constraints are dropped.
- For any m_1 -vector $\lambda \geq 0$, the **Lagrangian relaxation** of ILP with respect to any $A^1x \leq b^1$ is

$$LR(\lambda): z_{LR}(\lambda) = \\ \text{maximize } z(\lambda, x) = c^T x + \lambda^T (b^1 - A^1 x)$$

Subject to

$$A^2 x \leq b^2, \\ x \geq 0, \text{ integer}$$

- Define $Q = \{x: A^2 x \leq b^2, x \geq 0, \text{ integer}\}$.
- $LR(\lambda)$ does not contain the complicating constraints.

$LR(\lambda)$

- **Theorem:** $LR(\lambda)$ is a relaxation of ILP for all $\lambda \geq 0$.
- **Proof:** For any x feasible in ILP, x is in $LR(\lambda)$ and

$$z(\lambda, x) = c^T x + \lambda^T \left(\underbrace{b^1 - A^1 x}_{\geq 0} \right) \quad c^T x.$$

Lagrangian Dual

- The **Lagrangian dual** of ILP with respect to $A^1x \leq b^1$ is

$$(LD) \quad z_{LD} = \text{minimize} \quad z_{LR}(\lambda),$$

$$\text{subject to} \quad \lambda \geq 0$$

Example(1/3)

Maximize $x_1 + 2x_2,$

Subject to

$$\left. \begin{array}{rcl} x_1 + 2x_2 & \leq & 4 \quad : \lambda \\ 5x_1 + x_2 & \leq & 20 \\ -2x_1 - 2x_2 & \leq & -7 \\ -x_1 & \leq & -2 \\ x_2 & \leq & 4 \\ x_1, x_2 & \geq & 0, \text{ integer} \end{array} \right\} = Q$$

Example(2/3)

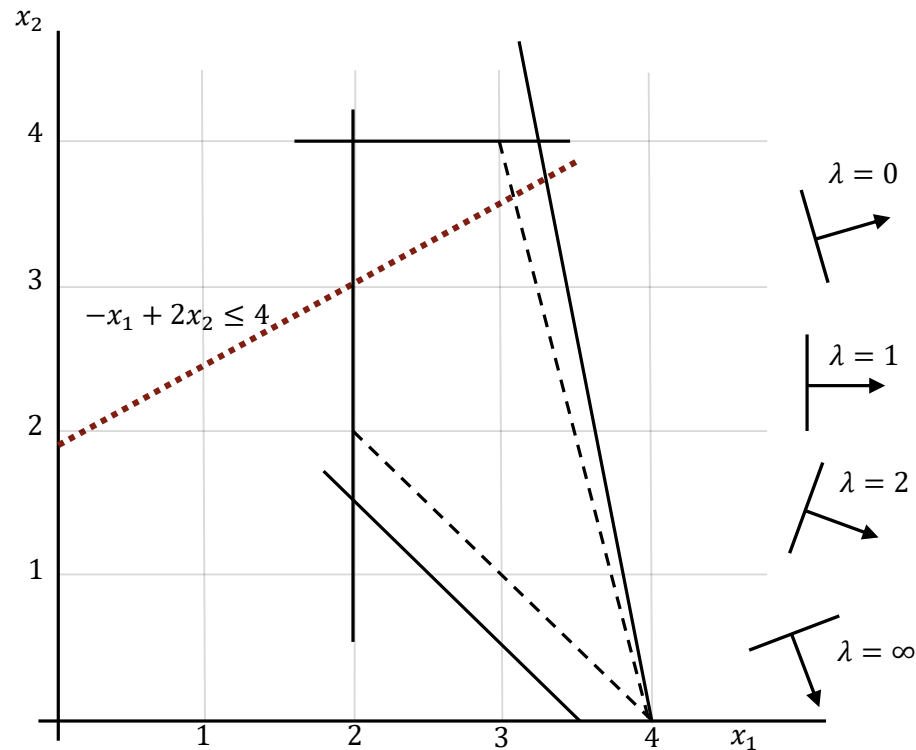
- The Lagrangian relaxation with respect to $-x_1 + 2x_2 \leq 4$ is

$$\begin{aligned} z_{LR}(\lambda) &= \text{maximize } 7x_1 + 2x_2 + \lambda(4 + x_1 - 2x_2) \\ &= (7 + \lambda)x_1 + (2 - 2\lambda)x_2 + 4\lambda, \end{aligned}$$

subject to

$$\begin{aligned} 5x_1 + x_2 &\leq 20, \\ -2x_1 - 2x_2 &\leq -7, \\ -x_1 &\leq -2, \\ x_2 &\leq 4, \\ x_1, x_2 &\geq 0, \text{ integer.} \end{aligned}$$

Example(3/3)



$$Q = \left\{ x^1 = \begin{pmatrix} 2 \\ 2 \end{pmatrix}, x^2 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, x^3 = \begin{pmatrix} 2 \\ 4 \end{pmatrix}, x^4 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}, x^5 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}, x^6 = \begin{pmatrix} 3 \\ 3 \end{pmatrix}, x^7 = \begin{pmatrix} 3 \\ 4 \end{pmatrix}, x^8 = \begin{pmatrix} 4 \\ 0 \end{pmatrix} \right\}.$$

Convex Hull

- Note that $z(\lambda, x)$ is an affine function for a fixed λ , and $z_{LR}(\lambda)$ is determined by solving LP.

$$\begin{aligned} z_{LR}(\lambda) = & \textit{maximize} \quad z(\lambda, x) \\ & \text{subject to} \quad x \in \text{conv}(Q), \end{aligned}$$

where $\text{conv}(Q)$ is the convex hull of Q (which is the set of all points that are convex combinations of points in S .)

Example for Points 7 & 8

- For example,

$$\text{conv}(Q) = \{x \in R_+^2 : -x_1 \leq -2, x_2 \leq 4, -x_1 - x_2 \leq -4, 4x_1 + x_2 \leq 16\}.$$

Thus,

$$z_{LR}(0) = \max\{7x_1 + 2x_2 : x \in \text{conv}(Q)\} = z(0, x^7) = 29,$$

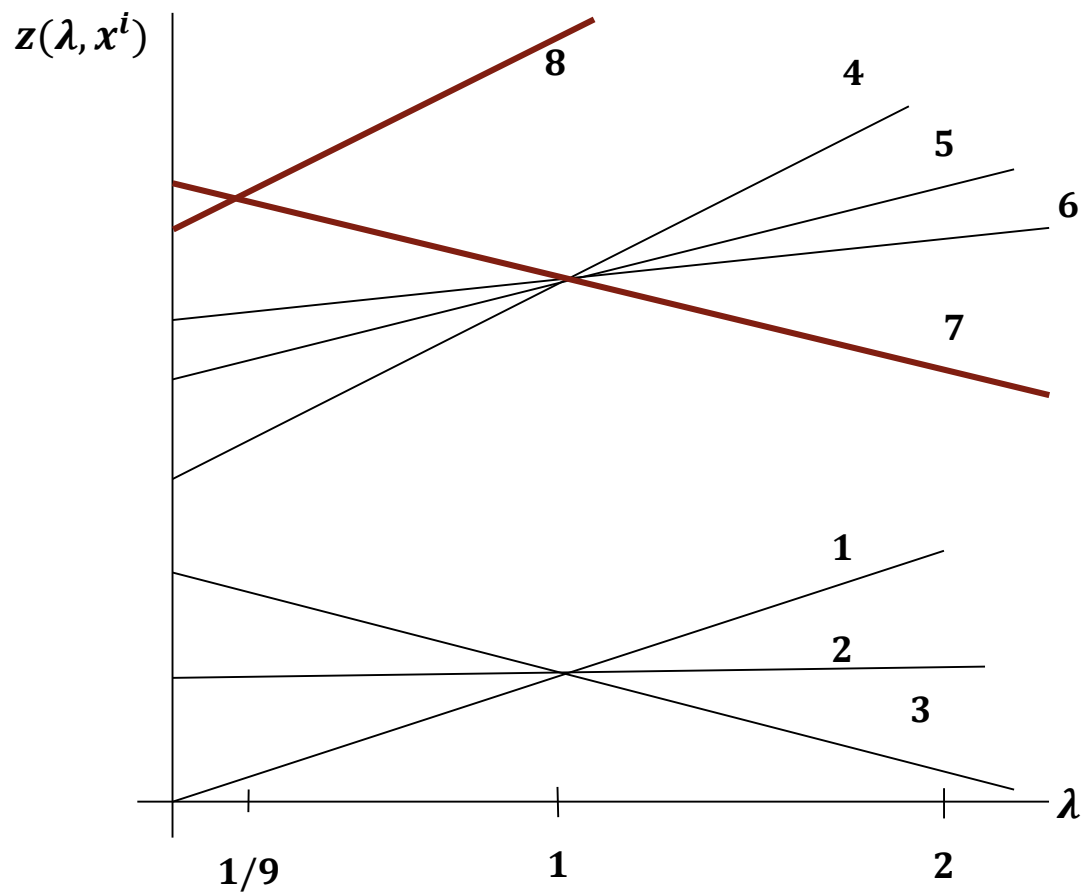
$$z_{LR}(1) = \max\{8x_1 + 0x_2 + 4 : x \in \text{conv}(Q)\} = z(1, x^8) = 36.$$

In general, we obtain

$$z_{LR}(\lambda) = \begin{cases} z(\lambda, x^7) = (7 + \lambda) \times 3 + (2 - 2\lambda) \times 4 + 4\lambda, & 0 \leq \lambda \leq \frac{1}{9} \\ z(\lambda, x^8) = (7 + \lambda) \times 3 + (2 - 2\lambda) \times 0 + 4\lambda, & \lambda \geq \frac{1}{9} \end{cases}$$

$$\text{Hence, } z_{LD} = z_{LR}\left(\frac{1}{9}\right) = z\left(\frac{1}{9}, x^7\right) = z\left(\frac{1}{9}, x^8\right) = 28\frac{8}{9} \text{ and } \lambda^* = \frac{1}{9}.$$

Affine functions for Set Q



Linear and Convex

- Equivalently,

$$\begin{aligned} z_{LR}(\lambda) = \text{maximize } z(\lambda, x^i), \quad &\equiv \quad \text{minimize } w, \\ \text{subject to } x^i \in Q, \quad &\text{subject to } w \geq z(\lambda, x^i), \quad i=1, \dots, 8, \end{aligned}$$

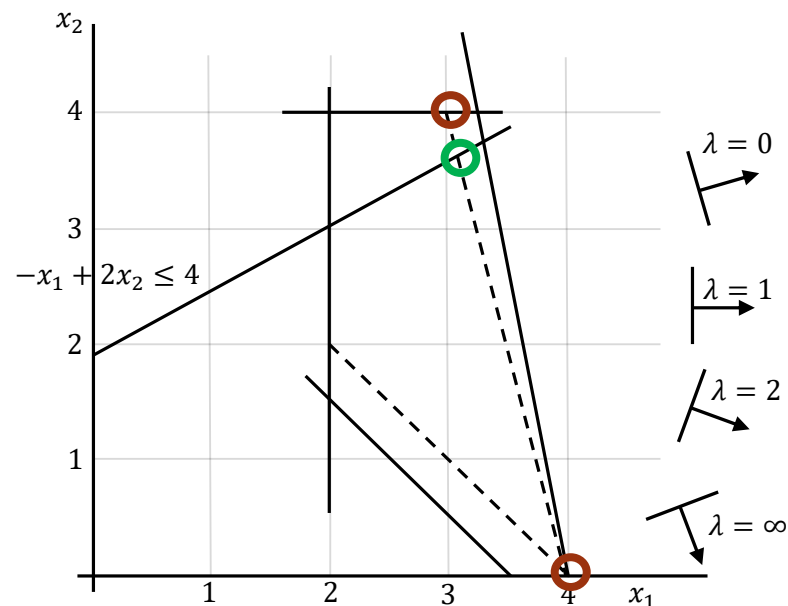
- Which shows that $z_{LR}(\lambda)$ is the maximum of a finite number of affine (linear) functions and is therefore piecewise linear and convex.
- We want to know the relationship between the solution of the Lagrangian dual (LD) and the original ILP.

Example

- In the example,

$$\begin{aligned}
 Z_{LD} &= 28\frac{8}{9} = z\left(\frac{1}{9}, x^7\right) = z\left(\frac{1}{9}, x^8\right), \\
 &= z\left(\frac{1}{9}, \frac{8}{9}x^7 + \frac{1}{9}x^8\right), \\
 &= z\left(\frac{1}{9}, \frac{8}{9}\begin{pmatrix} 3 \\ 4 \end{pmatrix} + \frac{1}{9}\begin{pmatrix} 4 \\ 0 \end{pmatrix}\right), \\
 &= z\left(\frac{1}{9}, \begin{pmatrix} 28/9 \\ 32/9 \end{pmatrix}\right) = z\left(\frac{1}{9}, x^*\right), \\
 &= c^T x^* + \frac{1}{9}(4 + x_1^* - 2x_2^*), \\
 &= c^T x^*, \quad \text{since } -x_1^* + 2x_2^* = 4.
 \end{aligned}$$

since $z(\lambda, x)$ is affine in x .



Theorems

- It can be shown that, in general, we can find a convex combination of points in Q that can generate a point x^* satisfying the complicating constraint $A^1 x \leq b^1$ such that $c^T x^* = z_{LD}$
- **Theorem:** $z_{LD} = \text{maximize } c^T x,$
subject to $A^1 x \leq b^1,$
 $x \in \text{conv}(Q)$
- **Theorem:** $z_{IP} \leq z_{LD}.$

Questions?

- Next week (1 / 3), the classroom is still room 101.
- 20% of the final exam will cover the lecture of IP.