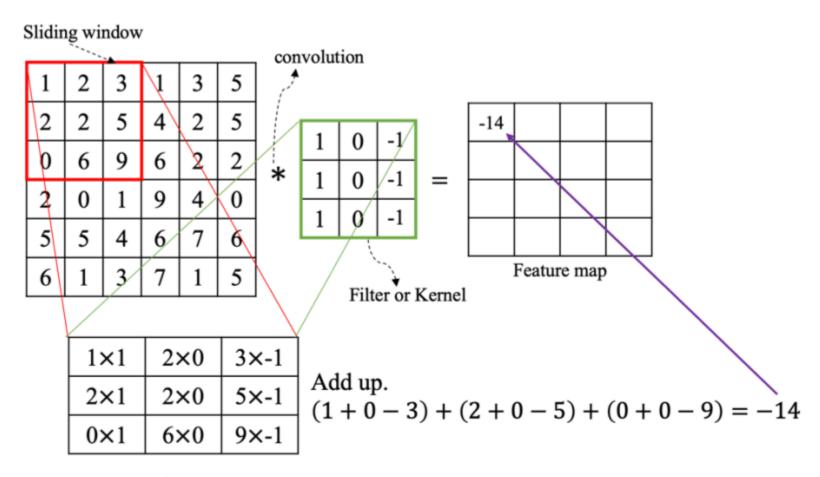
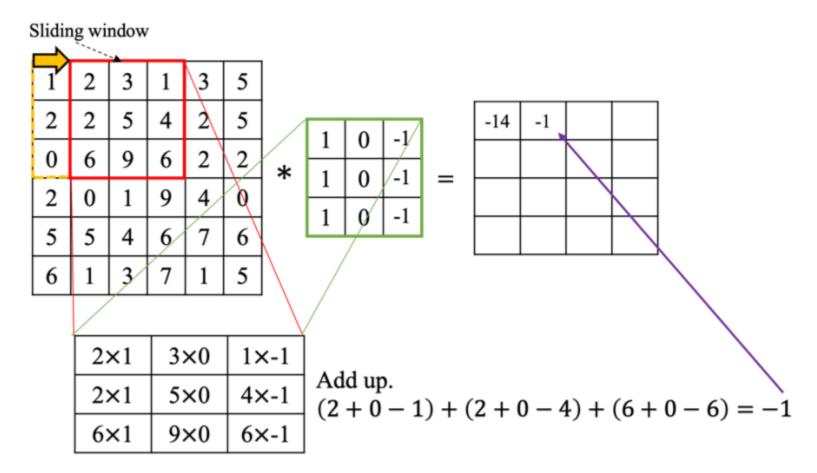


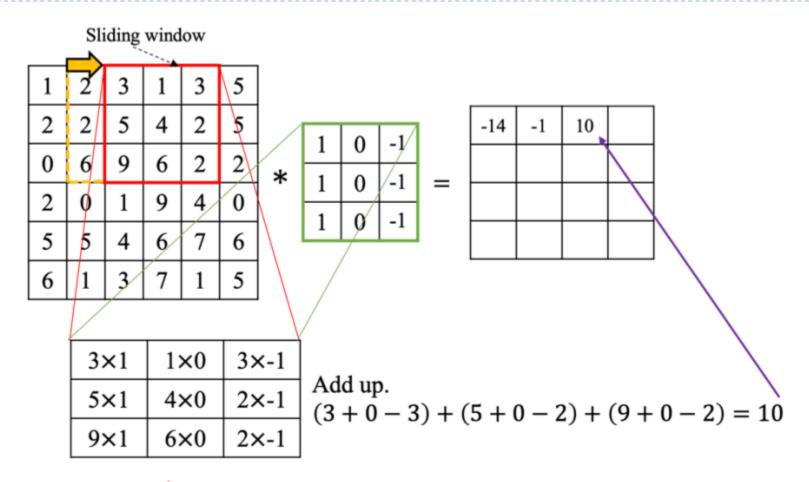
Digital Image Processing

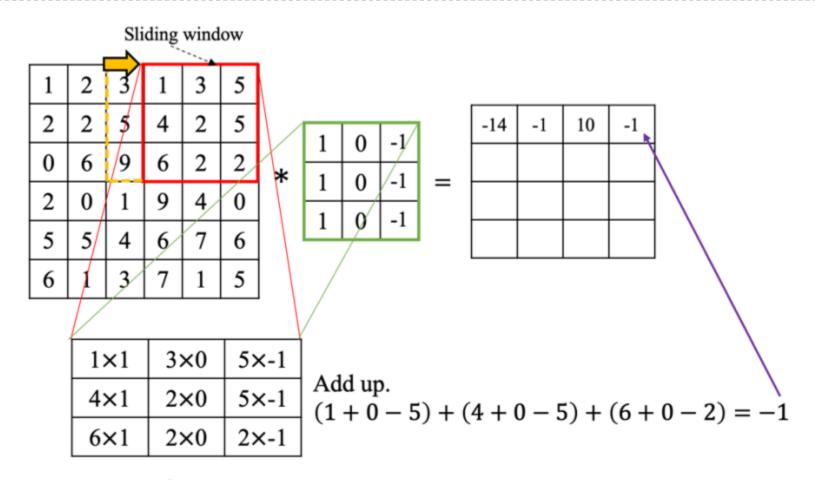
Sobel Edge Detection, Image Sharpening and Gaussian Blur

22-Jun-22

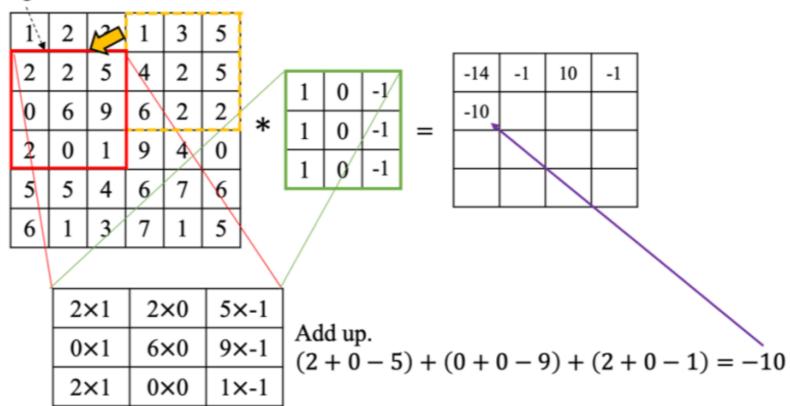


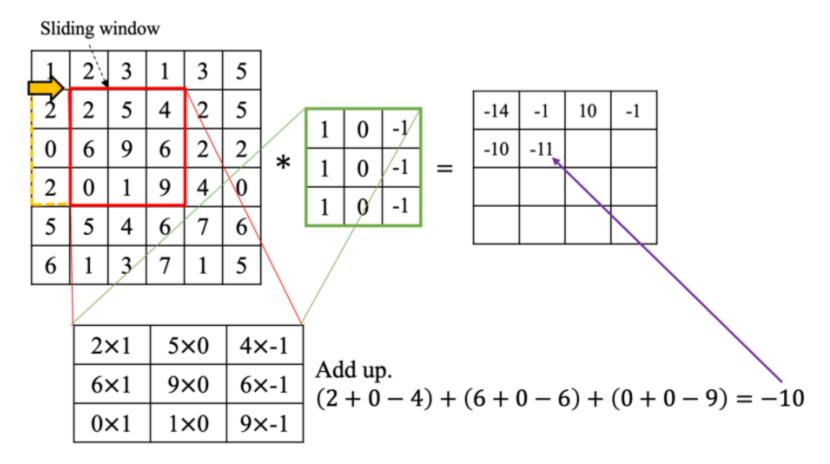


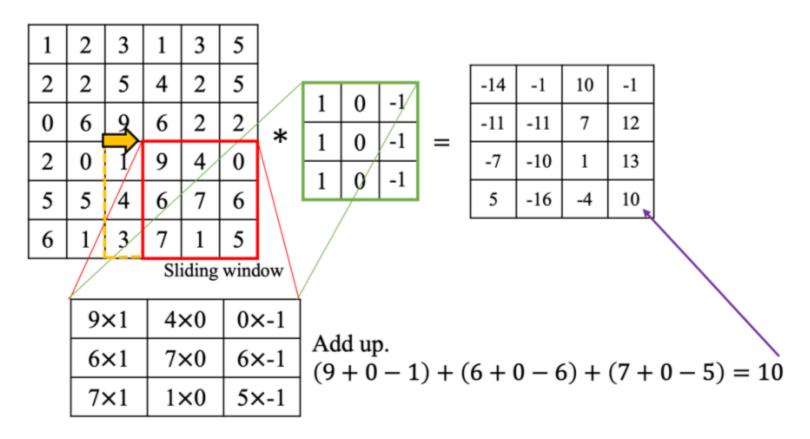


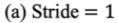


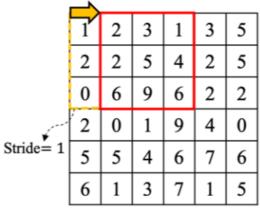
Sliding window











	1	0	-1	
*	1	0	-1	
	1	0	-1	

-14	-1	10	-1
-11	-11	7	12
-7	-10	1	13
5	-16	-4	10

(b) Stride
$$= 2$$

	$\overline{}$				
1	2	3	1	3	5
2	2	5	4	2	5
0	6	9	6	2	2
2	0	1	9	4	0
5	5	4	6	7	6
6	1	3	7	1	5
	0 2 5	2 2 0 6 2 0 5 5	2 2 5 0 6 9 2 0 1 5 5 4	2 2 5 4 0 6 9 6 2 0 1 9 5 5 4 6	2 2 5 4 2 0 6 9 6 2 2 0 1 9 4 5 5 4 6 7

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Zero Padding

0	0	0	0	0	0	0	0
0	1	2	3	1	3	5	0
0	2	2	5	4	2	5	0
0	0	6	9	6	2	2	0
0	2	0	1	9	4	0	0
0	5	5	4	6	7	6	0
0	6	1	3	7	1	5	0
0	0	0	0	0	0	0	0

-4	-5	-1	3	-5	5
-10	-14	-1	10	-1	7
-8	-11	-11	7	12	8
11	-7	-10	1	13	13
-6	5	-16	-4	10	12
-6	4	-7	-1	2	8

Parameters for convolution layer: Input feature size $(n \times n) = (6 \times 6)$ Padding (p) = 1 (Zero-padding) Stride (s) = 1Kernel $(f \times f) = (3 \times 3)$

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Calculate the size of output feature map:

floor
$$\left(\frac{(n+2p-f)}{s} + 1\right)$$

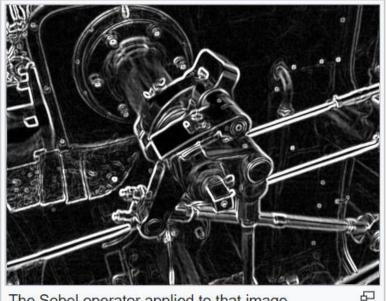
= $\frac{(6+2\times 1-3)}{1} + 1 = 6$

Output feature map = (6×6)

Sobel Operator

▶ The Sobel operator, sometimes called the Sobel–Feldman operator or Sobel filter, is used in image processing and computer vision, particularly within edge detection algorithms where it creates an image emphasizing edges.





The Sobel operator applied to that image

Sobel Operator

Sobel Horizontal Mask

1	2	1
0	0	0
-1	-2	-1

3X3

5X5

7X7

 2
 3
 4
 3
 2

 1
 2
 3
 2
 1

 0
 0
 0
 0
 0

 -1
 -2
 -3
 -2
 -1

 -2
 -3
 -4
 -3
 -2

	3	4	5	6	5	4	3
ľ	2	3	4	5	4	3	2
	1	2	3	4	3	2	1
ľ	0	0	0	0	0	0	0
ľ	-1	-2	-3	-4	-3	-2	-1
ľ	-2	-3	-4	-5	-4	-3	-2
	-3	-4	-5	-6	-5	-4	-3

Sobel Vertical Mask

1	0	-1
2	0	-2
1	0	-1

2	1	0	-1	- 2
3	2	0	-2	-3
4	3	0	ئ	-4
3	2	0	-2	-3
2	1	0	-1	-2

3	2	1	0	-1	-2	-3
4	3	2	0	-2	-3	-4
5	4	3	0	-3	-4	-5
6	5	4	0	-4	-5	-6
5	4	3	0	-3	-4	-5
4	3	2	0	-2	-3	-4
3	2	1	0	-1	-2	-3

Other Operators

Prewitt operator

$$egin{bmatrix} +1 & 0 & -1 \ +1 & 0 & -1 \ +1 & 0 & -1 \end{bmatrix} egin{bmatrix} +1 & +1 & +1 \ 0 & 0 & 0 \ -1 & -1 & -1 \end{bmatrix}$$

► Laplacian operator

0	-	0
-1	4	1
0	۲-	0

-1	٦	7
-1	8	-1
-1	-	-1

1	-2	1	
-2	4	-2	
1	-2	1	

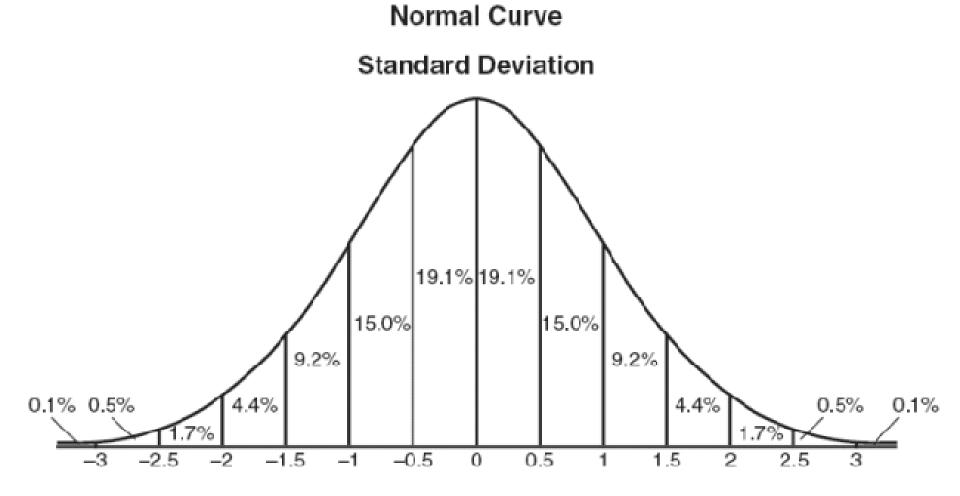
Image Sharpening

► The Image Sharpening Mask

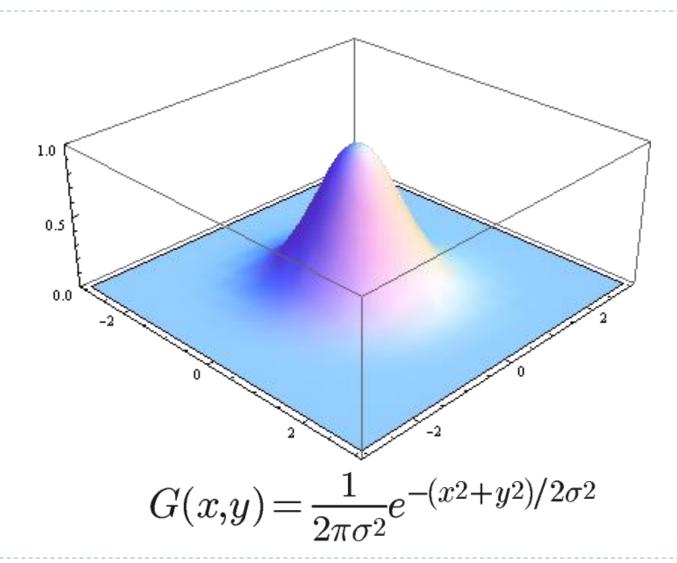


$$\begin{bmatrix} 0 & -a & 0 \\ -a & 4a+1 & -a \\ 0 & -a & 0 \end{bmatrix}$$

Gaussian Function



Gaussian function



Gaussian Mask

Assume that the center is (0,0), $\sigma=1.5$

(-1,1)	(0,1)	(1,1)	0.0453542	0.0566406	0.0453542
(-1,0)	(0,0)	(1,0)	0.0566406	0.0707355	0.0566406
(-1,-1)	(0,-1)	(1,-1)	0.0453542	0.0566406	0.0453542

References

- https://en.wikipedia.org/wiki/Sobel_operator
- https://blog.csdn.net/farmwang/article/details/74452750
- https://www.brilliantcode.net/1584/convolutional-neural-networks-1-convolution-layer-stride-padding-kernel/