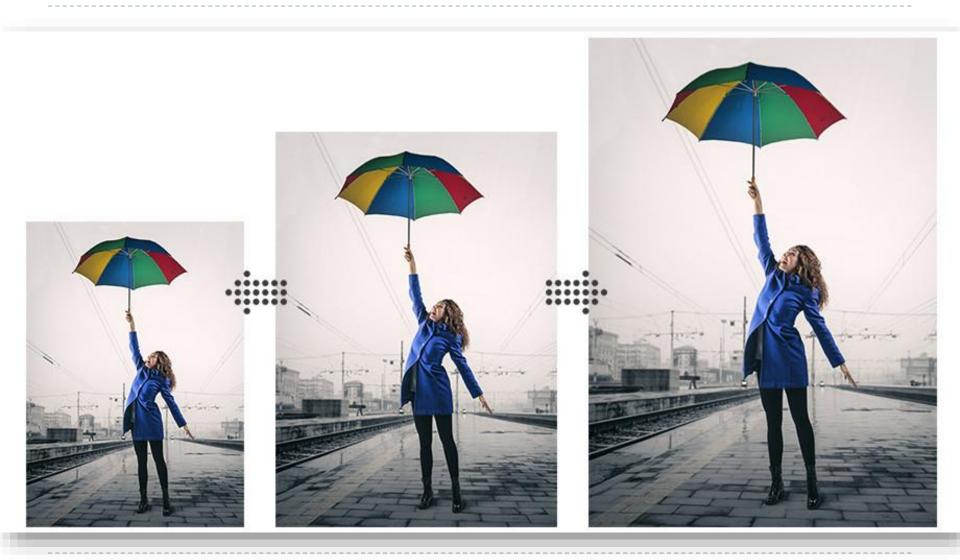


# Digital Image Processing

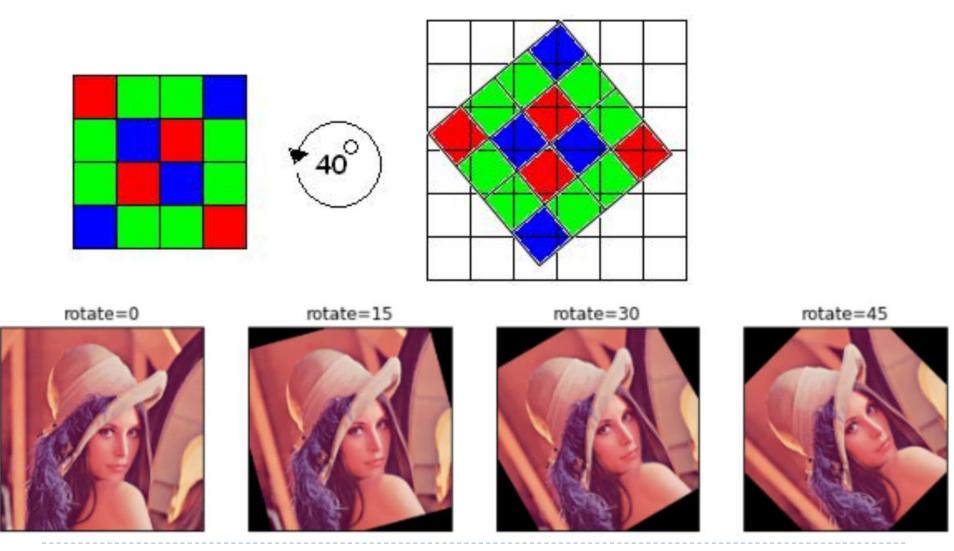
Image Rotation and Resizing

22-Jun-22

## Image Resizing



## **Image Rotation**



#### **Rotation matrix**

In two dimensions, the standard rotation matrix has the following form:

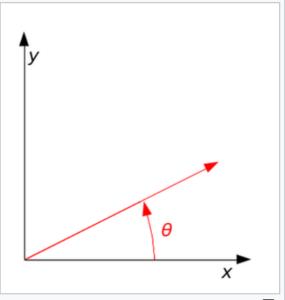
$$R = egin{bmatrix} \cos heta & -\sin heta \ \sin heta & \cos heta \end{bmatrix}$$

▶ This rotates column vectors by means of the following matrix multiplication,

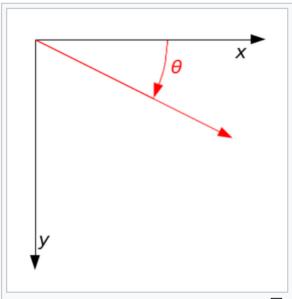
$$egin{bmatrix} x' \ y' \end{bmatrix} = egin{bmatrix} \cos heta & -\sin heta \ \sin heta & \cos heta \end{bmatrix} egin{bmatrix} x \ y \end{bmatrix}$$

► Thus, the new coordinates (x', y') of a point (x, y) after rotation are

$$x' = x \cos \theta - y \sin \theta$$
  
 $y' = x \sin \theta + y \cos \theta$ 



A counterclockwise rotation of a vector through angle  $\theta$ . The vector is initially aligned with the x-axis.



A rotation through angle  $\theta$  with nonstandard axes.

### References

- https://en.wikipedia.org/wiki/Rotation\_matrix
- https://ansta.co.uk/blog/how-to-resize-images-using-image-editing-software-605/