- Complete Binary Tree
- Max-Heap

n = 6  
h = 2  
$$2^{h}$$
 = 4  
 $2^{h+1}$  - 1 = 7

### Heap

- What is a complete binary tree?
- What is a heap?
  - What is a max heap?
  - What is a min heap?
- Two ways to build a heap
  - Top down (Time complexity O(nlog n) ) is iterative and in place.
  - Bottom up (Time complexity O(n) ) is iterative and in place.
- Heap Sort
  - Phase I: Build the heap bottom up (Reason: it is O(n) and we have all the data)
  - Phase II: Sort (Time complexity O(nlog n)) is iterative and in place.
- Priority Queue
  - Insert (Time complexity : O(log n) )
  - Delete ((Time complexity : O(log n). You must restore the heap)
  - Build the heap top down (Reason: we do not have all the data)

Note: An **in-place algorithm** is an algorithm which transforms input using no auxiliary **data structure**. (Can use O(1) temporary variables).

#### **Build Max-Heap in-place Iteratively**

- There two ways you can build the heap
- Both are iterative and in-place

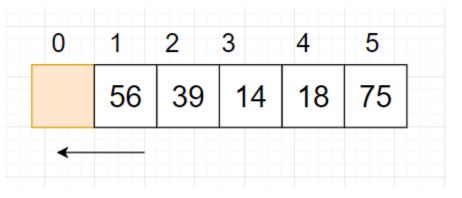
An **in-place algorithm** is an algorithm which transforms input using no auxiliary **data structure**. (Can use O(1) temporary variables).

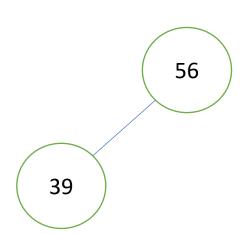
Top-down: O(nlog n).

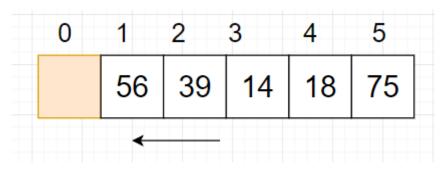
Bottom-up: O(n)

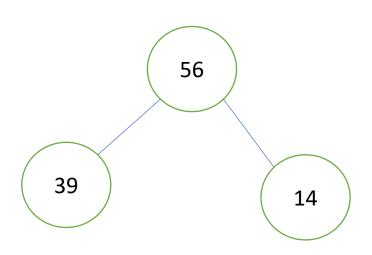
```
build MaxHeap TopDown(A, n)
  for (i <- 1 to n)
       upHeap(A, i)
                                       upHeap(A, i)
                                       j <- i
                                       while (j > 1 \& A[j/2] < A[j])
                                           swap(A[i], A[i/2])
                                            i < -i/2
```

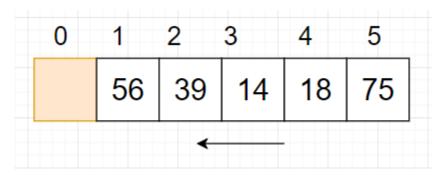


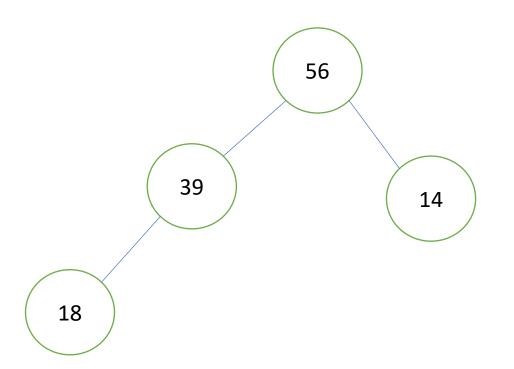


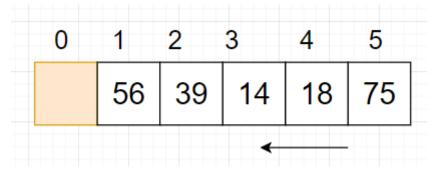


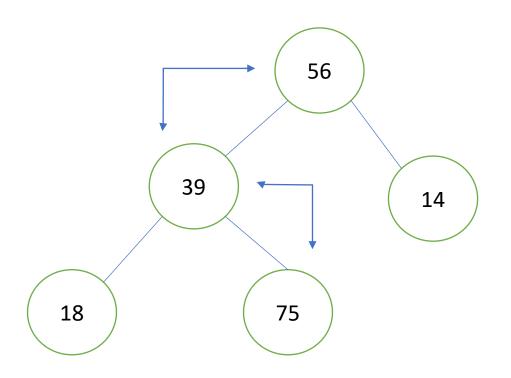


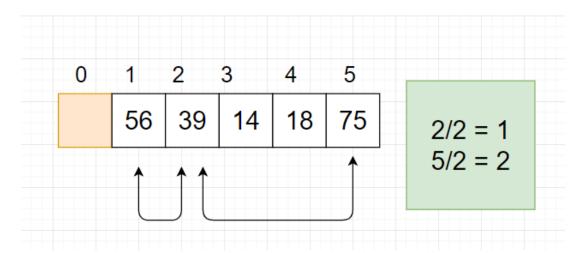


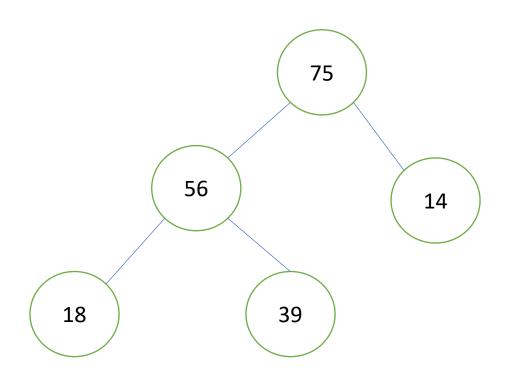










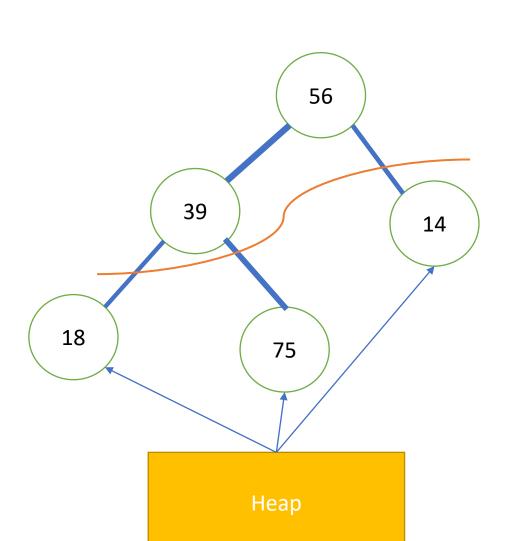


#### **Heap Sort**

There are two phases.

Phase I: Build the heap. In-place, bottom-up, iteratively

Phase II: Sort. In-place, iteratively



- $\lfloor n/2 \rfloor$  = 3 leaves are already heaps.
- There are  $\lfloor n/2 \rfloor = 2$  internal nodes.
- A[1..n] is the heap.

```
build_MaxHeap_BottomUp(A, n)
    for (i <- [n/2] to 1) downHeap(A, i, n)

downHeap(A, i, n)
    j <- i
    k <- maxChildIndex(A, j, n)
    while (k !=0)
        swap(A[j], A[k])
        j <- k
        k <- maxChildIndex(A, j, n)</pre>
```

Note: maxChildIndex returns the index of a child of A[j] with maximum value among A[j], A[2j], A[2j+1]. If there is no such child it returns 0.

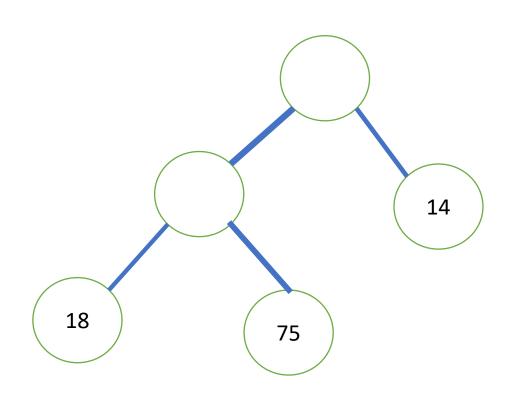
#### maxChildIndex(A, j, n)

```
k = j

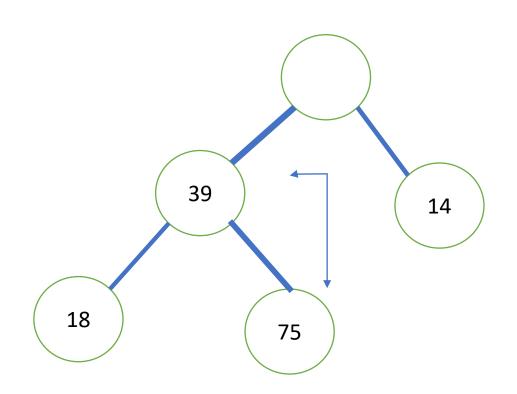
if (2j \le n \&\& A[2j] > A[k]) k \le 2j

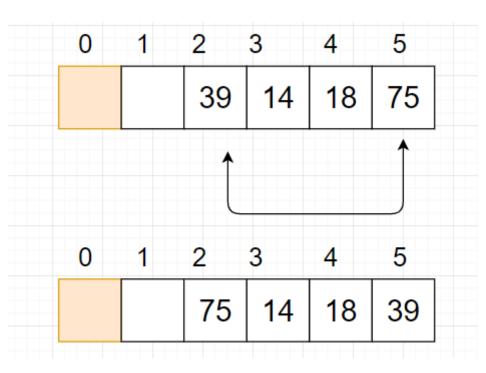
if (2j + 1 \le n \&\& A[2j + 1] > A[k]) k \le 2j + 1

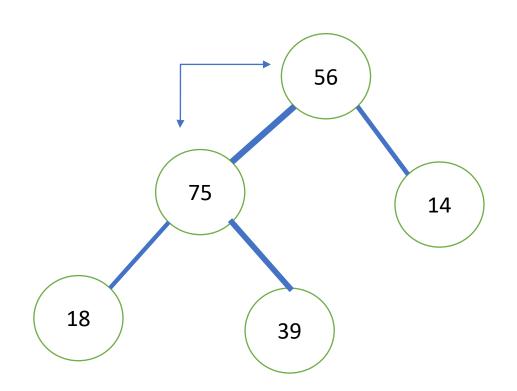
if (k = j) return 0 else return k
```

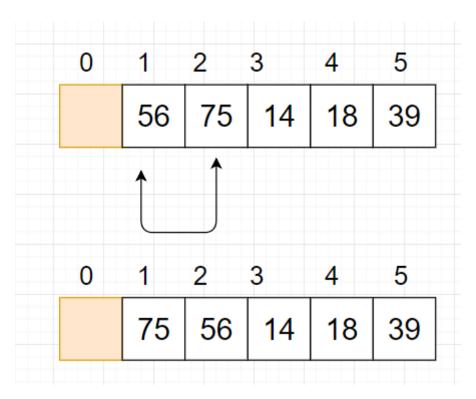


0	1	2	3	4	5
			14	18	75







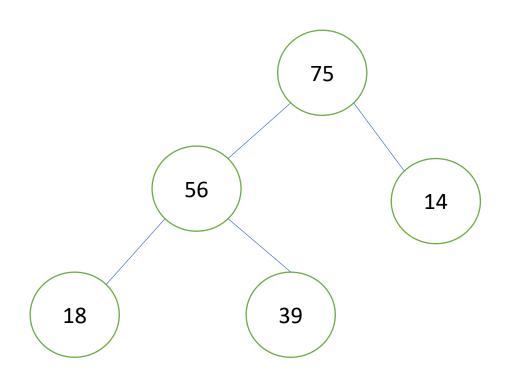


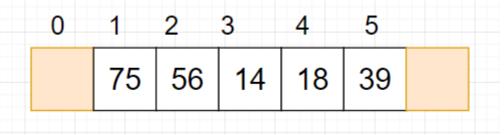
```
heapSortPhaseTwo(A, n)

for (i <- n to 2)

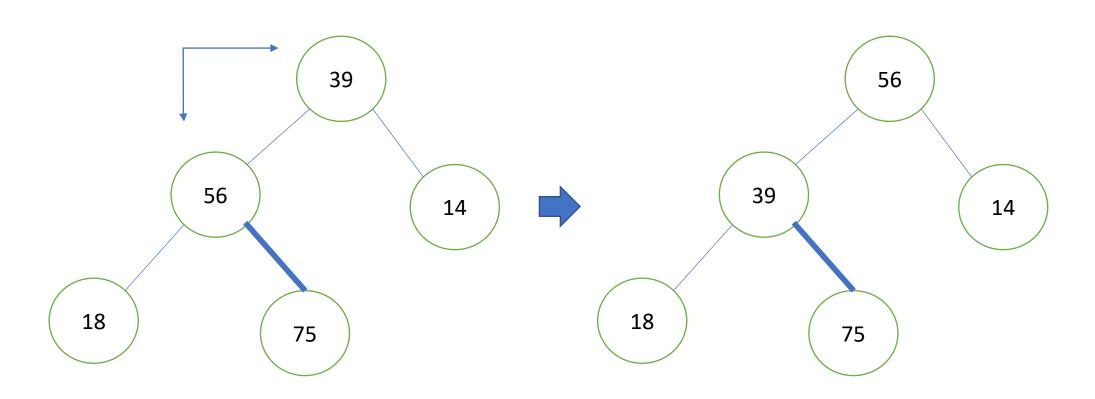
swap(A[1], A[i])

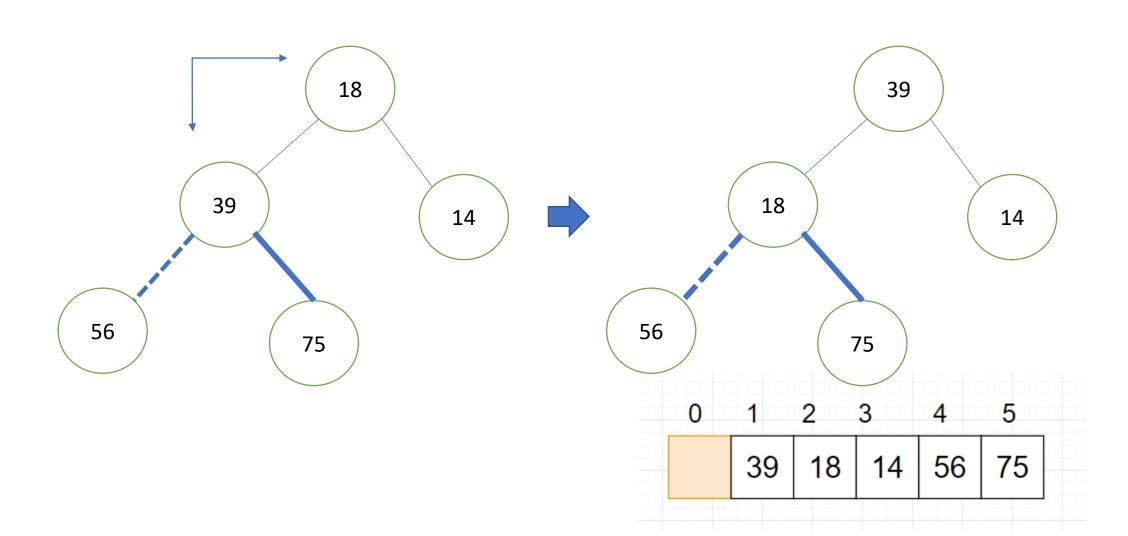
downHeap(A, 1, i -1)
```

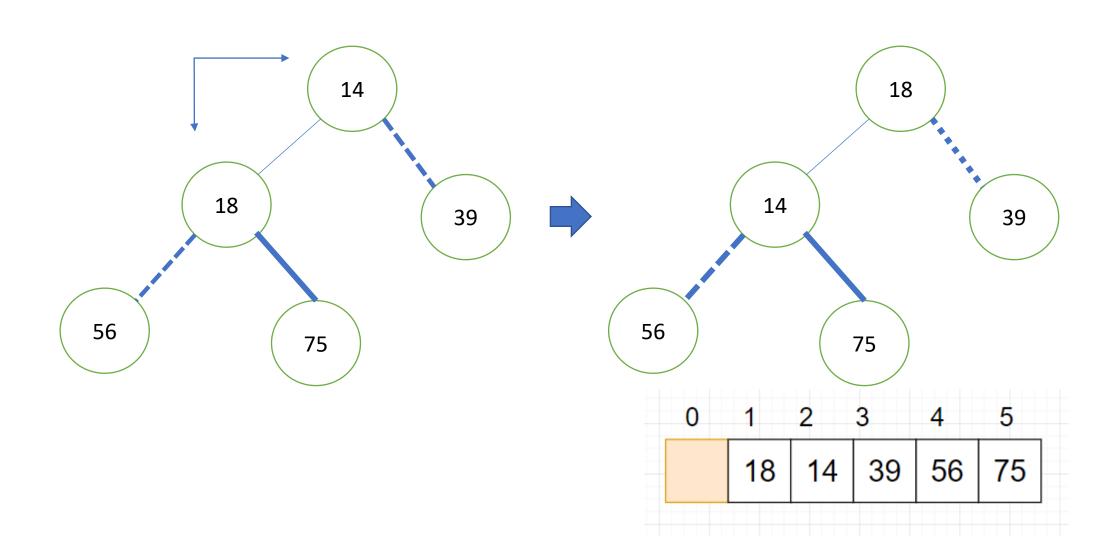


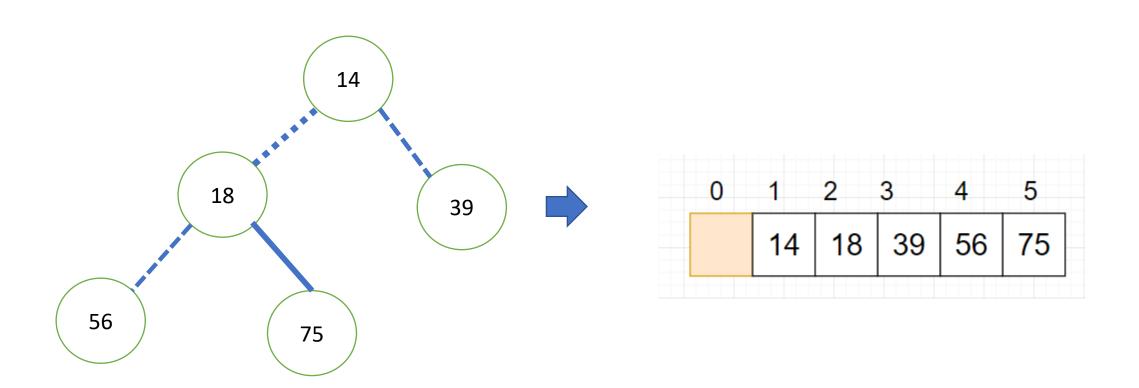


Put the root to sorted list, place the last element in the heap to the root and rebuild the heap









# **Assume small number stands for high** priority

Just as the queue you are very familiar with, Priority queue also has two major operations. If q is a priority queue, then q.enqueue(x) "inserts" an item into the queue and

x <- q.dequeue() "removes" an item from the queue.

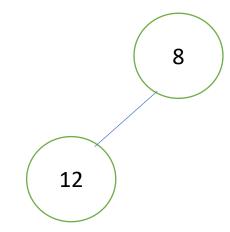
When you are dequeuing, you are removing the item with the "highest" priority from the queue. In the case of heap implementation, we keep that item at the root. Thus, both operations have O(log n) time complexity.

#### enqueue examples

• enqueue(8)

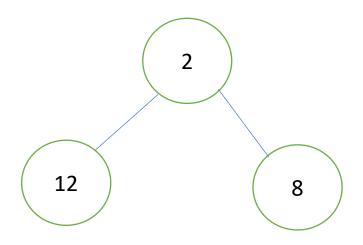
8

enqueue(12)

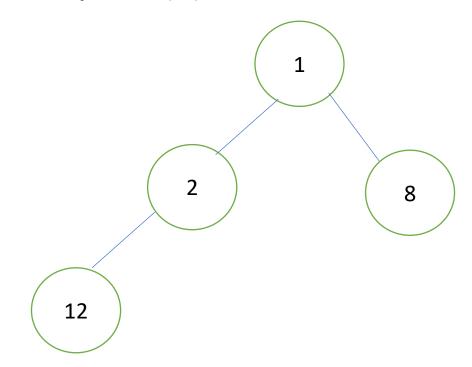


### Note that upheap is invoked just as in Top-Down construction

enqueue(2)



enqueue(1)



# Note that downheap is invoked just as in Bottom-Up construction

dequeue()

12 8

dequeue()

