

Economic Games in Combinatorial Structures,
Artificial Intelligence, Stochastic Partial
Differential Equations and Portfolio Theory
Theory, Data, Agents, Strategies, Balance, Fun, Value, Code and
More

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Abstract

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1 Conventions and Notations

we denote the set of natural numbers $\mathbb{N} = \{1, 2, 3, \dots\}$, the set of integers $\mathbb{Z} = \{\dots, -2, -1, 0, 1, 2, \dots\}$.

Definition 1.1. Let P be a partially ordered set, which will also henceforth be called posets. If $a \leq b \in P$, we denote

1. $[a, b]_P := \{x \in P; a \leq x \leq b\}$,
2. $]a, b]_P := \{x \in P; a < x \leq b\}$,
3. $[a, b[_P := \{x \in P; a \leq x < b\}$,
4. $]a, b[_P := \{x \in P; a < x < b\}$.

As a special case, we have, for $n \leq m \in \mathbb{Z}$ ($n \leq m \in \mathbb{N}$),

$$\mathbb{Z}_n^m = \{x \in \mathbb{Z}; n \leq x \leq m\} \quad (\mathbb{N}_n^m = \{x \in \mathbb{N}; n \leq x \leq m\})$$

Definition 1.2. Given a set X , its cardinality is denoted by $|X|$. If Y is another set, denote the set of all maps from X to Y by X^Y . Symbolically:

$$Y^X := \{f; f : X \rightarrow Y\}.$$

Definition 1.3. Let X be a set. We denote the set of all subsets of X by 2^X .

Definition 1.4. Let $f_1 : X_1 \rightarrow Y_1$, $f_2 : X_2 \rightarrow Y_2$ be maps. We denote $f_1 \times f_2 : X_1 \times X_2 \rightarrow Y_1 \times Y_2$ the product of f_1 and f_2 , to be map defined by

$$f_1 \times f_2(x_1, x_2) = (f_1(x_1), f_2(x_2)).$$

Definition 1.5. Let $X \subset Y$. The inclusion map is defined by $\iota : X \rightarrow Y$, $\iota(x) = x$. We use the same notation for the identity function, since it can be seen as the inclusion of a set into itself.

2 Elements of Combinatorics

Proposição 2.1. *Let X, Y be finite sets. The number of maps from X to Y is $|Y|^{|X|}$. In other words:*

$$|Y^X| = |Y|^{|X|}$$

Proof. We proceed by induction on $|X|$. Let $Y = \{y_1, \dots, y_m\}$. If $|X| = 1$, say $X = \{x\}$. Given $1 \leq i \leq m$, denote $f_i : X \rightarrow Y$, the map given by $f_i(x) = y_i$. There are m of these maps, and any map $f : X \rightarrow Y$ has to be one of these, and therefore there are $|Y|^{|X|} = m^1$ maps in Y^X .

Assuming the assertion true for all sets X such that $|X| = n$, let us prove it in the case where $|X| = n + 1$.

(finish) □

Proposição 2.2. *Let X be a set with cardinality $|X|$. For every $n \leq |X|$ there are exactly $\binom{|X|}{n}$ different subsets of X with cardinality n .*

Proposição 2.3. *Let X, Y be two finite sets with the same cardinality, say n . Then there are $n!$ bijections between them. Symbolically:*

$$|\text{Bij}(X, Y)| = n!$$

Proof. We shall prove the assertion in the case where $Y = X$, since the general case follows from this using the fact that $|\text{Bij}(X, Y)| \simeq |\text{Bij}(X, X)|$ for all sets X, Y .

We prove it via induction on n . The case where $n = 1$ is trivial. Assume then, that for all sets S_1, S_2 with cardinality $|S| \leq n$, we have $|\text{Bij}(S_1, S_2)| = n!$, and let X be a set with $|X| = n + 1$.

Choose any element $x_1 \in X$. Then we have $|X \setminus \{x_1\}| = n$, and there

(finish) □

Proposição 2.4. *If X is a finite set, then $|2^X| = 2^{|X|}$.*

Proof. (finish) □

Proposição 2.5. *Given a finite set X , there exists a unique $n \in \mathbb{N}$ for which there is a bijection $f : X \rightarrow [1, n]_{\mathbb{N}}$.*

Definition 2.1. Given a finite set X , by proposition (ref), there exists a unique n and bijection between X and $[1, n]_{\mathbb{N}}$. This unique n depending exclusively on the set X is called the cardinality of X and is denoted by $|X|$.

Proposição 2.6. *If X, Y are finite sets such that $|X| \leq |Y|$*

Proposição 2.7. *Let X, Y, Z be sets, and let $f : Y \rightarrow Z$ be a bijection. Then the map $\phi : Y^X \rightarrow Z^X$ given by $\phi(g) = g \circ f$ is a bijection between Y^X and Z^X .*

As a result we have:

Corolário 2.1. *If X, Y, Z are finite sets, then $|Y^X| = |Z^X|$.*

2.1 Multisets

Definition 2.2. A multiset is a pair $X = (X^0, \mu)$ where X^0 is a set and $\mu : X^0 \rightarrow \mathbb{N}$ is a multiplicity map. If $x \in X^0$, the value $\mu(x)$ is called the multiplicity of x in X .

If no confusion is likely, we shall abuse notation slightly and denote both the pair and the underlying set by the same symbol. Additionally, for clarity we may denote the multiplicity map by μ_X .

Example 2.1. Consider the following elementary examples and notations for multisets.

1. $(\{x\}, \mu)$, where $\mu(x) = a$ for some $a \in \mathbb{N}$, will also be denoted $\{x^{\times a}\}$.
2. $(\{x, y, z\}, \mu)$, where $\mu(x) = a, \mu(y) = b, \mu(z) = c$ for some $a, b, c \in \mathbb{N}$, will also be denoted $\{x^{\times a}, y^{\times b}, z^{\times c}\}$.

Definition 2.3. Let $X = (X^0, \mu)$ be a multiset. There is an important associate set, which is given by $M(X) := \{(x, i); x \in X, 1 \leq i \leq \mu(x)\}$.

Multisets generalize sets in the sense that every set X can be seen as a multiset with multiplicity map given $\mu(x) = 1$ for all $x \in X$.

Definition 2.4. Let X, Y be multisets. A map between multisets is a map $f : M(X) \rightarrow M(Y)$. We extend the notation of the set of all maps between two sets to multisets, *i.e.*, we denote $Y^X = \{f : M(X) \rightarrow M(Y)\}$. Two maps $f, g : X \rightarrow Y$ are called equivalent whenever they satisfy the following property:

(finish)

It is readily seen that this reduces to the usual notion of a map between sets if X and Y are normal sets. A particular case of interest for combinatorics is when X is a multiset and Y is a set, and we consider equivalence classes of maps between them. This case is a good model for the situation where you indistinguishable balls being placed on cells randomly.

Proposição 2.8. Let $X = (\{x\}, \mu)$, where $\mu(x) = n$, and consider $Y = [1, m]_{\mathbb{N}} = \{1, \dots, m\}$. There are $\binom{n-1}{m-1}$ multiset maps $f : X \rightarrow Y$. Symbolically:

$$|Y^X| = \binom{n-1}{m-1}$$

Proof. Let $f \in Y^X$, we denote, for each $1 \leq i \leq m$, $n_i^f = |f^{-1}(i)|$, *i.e.*, the amount of elements of $M(X)$ whose image is i . We have that $\sum_i n_i^f = n$. We claim that there is a bijection (finish) \square

Definition 2.5. Let $X = (X^0, \mu_X)$ be a multiset. A multisubset is a pair $Y = (Y^0, \mu_Y)$ such that $Y^0 \subset X^0$, and $\mu_Y(y) \leq \mu_X(y)$ for all $y \in Y^0$.

Proposição 2.9. Let $X = (X^0, \mu)$ be a multiset and Y a set. Then there are

2.2 Equivalent Definitions of Multiset

Definition 2.6. A multiset is a pair (X, \sim) , where X is a set and \sim is an equivalence relation on X .

2.3 Words

Let X be a set. A word on X is a sequence $x = (x_1, x_2, \dots)$ of elements x_j of X . It can also be denoted $x = x_1 x_2 \dots$. If the sequence is finite, the size of the word, denoted $|x|$ is the number of elements in the sequence, and if the sequence is infinite, we say the word has infinite size, and write $|x| = \omega$.

2.4 Permutations

In this subsection we fix $X = \mathbb{Z}_n$, for some n , and shall study permutations on X .

Definition 2.7. A permutation on any set is a bijection of the set into itself.

In order to facilitate our presentation of permutations, we introduce the following notation:

Definition 2.8. Let $x_1, y_1, x_2, y_2, \dots, x_n, y_n \in X$, and $\phi : X \rightarrow X$ be a selfmap. We write $\phi(x_1, x_2, \dots, x_n) = y_1, y_2, \dots, y_n$ to mean $\phi(x_j) = y_j, j = 1, \dots, n$.

Example 2.2. Let us look at low values of n .

1. Let $n = 1$, so that $X = \{1\}$. It is clear that there is a single bijection $\phi : X \rightarrow X$ given by $\phi(1) = 1$. It is even true that this is the only selfmap on X . We denote this bijection by the symbol (1) .
2. Let $n = 2$, so that $X = \{1, 2\}$. We then have two possibilities, either $\phi(1, 2) = 1, 2$ or $\phi(1, 2) = 2, 1$. We denote the first bijection by (12) and the second one by $(1)(2)$.
3. Let $n = 3$, so that $X = \{1, 2, 3\}$. We have 6 possibilities:

$$\begin{aligned} \phi(1, 2, 3) = 1, 2, 3 & \quad \phi(1, 2, 3) = 2, 1, 3 & \quad \phi(1, 2, 3) = 3, 1, 2 \\ \phi(1, 2, 3) = 1, 3, 2 & \quad \phi(1, 2, 3) = 2, 3, 1 & \quad \phi(1, 2, 3) = 3, 2, 1 \end{aligned}$$

Generalizing the notation in the previous items, we introduce:

Definition 2.9. Let $r \leq n$, and let i_1, \dots, i_r be pairwise distinct numbers such that $1 \leq i_j \leq n, j = 1, \dots, r$. We define the bijection $(i_1 \ i_2 \ \dots \ i_{j-1} \ i_j) : X \rightarrow X$ given by

$$\begin{aligned} (i_1 \ i_2 \ \dots \ i_{j-1} \ i_j)(i_r) &= i_1 \\ (i_1 \ i_2 \ \dots \ i_{j-1} \ i_j)(i_j) &= i_{j+1}, j \neq r \\ (i_1 \ i_2 \ \dots \ i_{j-1} \ i_j)(x) &= x, x \neq i_j \end{aligned}$$

These bijections are called cycles, or r -cycles to emphasize the size of the cycle. A 2-cycle is also called a transposition.

Notice the space between the numbers i_j . There are problems with this notation, for example, if we are dealing with \mathbb{Z}_{15} , it might lead to mistakes if we consider $(1\ 2\ 3)$ and $(12\ 3)$.

Example 2.3. We provide some basic examples

1. The permutations in example (ref)(3) are all cycles and can be written respectively as:

$$\begin{array}{lll} \phi = \iota & \phi = (1\ 2) & \phi = (1\ 2\ 3) \\ \phi = (2\ 3) & \phi = (1\ 3\ 2) & \phi = (1\ 3) \end{array}$$

2. the r -cycle $(1\ 2\ 3\ \dots\ (r-1)\ r)$ is such that $(1\ 2\ 3\ \dots\ (r-1)\ r)j = j + 1$, if $1 \leq j < r$, and $(1\ 2\ 3\ \dots\ (r-1)\ r)r = 1$.
3. Just as any map, permutations can be composed, sometimes compositions of cycles are again cycles. For example, we have $(1\ 2)(1\ 3) = (1\ 3\ 2)$.

Definition 2.10. The support of a permutation $\phi \in \text{perm}(X)$ is the set of x not kept constant by ϕ . More precisely:

$$\text{supp}(\phi) := \{x \in X; \phi(x) \neq x\}.$$

Lema 2.1. A simple greedy algorithm is able to find the support of a permutation in linear time.

Proposição 2.10. Given a permutation $\phi \in \text{perm}(X)$, where X is a finite set, then there are transpositions $t_j, j = 1, \dots, r$ such that $\phi = \prod t_j$.

Algoritmo 2.1. The following is an algorithm to find a decomposition of any permutation $\phi : \mathbb{Z}_n \rightarrow \mathbb{Z}_n$ into transpositions.

This decomposition is unique, up to rearrangements:

Teorema 2.1. Suppose $\prod_1^m \alpha_i = \prod_1^n \beta_j$, where all the α_i, β_j are transpositions on some set X . Then $n = m$ and there is a permutation $\psi : \mathbb{Z}_n \rightarrow \mathbb{Z}_n$ such that $\alpha_i = \beta_{\psi(j)}$.

Proof.

□

Proposição 2.11. The following are equivalent about a decomposition $\phi = \prod_1^n \alpha_i$ into transpositions.

1. n is even

Problema 2.1. Let $m, n \in \mathbb{N}$.

1. How many transpositions of size m act on \mathbb{Z}_n ?

2. What are the decompositions of the permutations of \mathbb{Z}_n into transpositions?
3. Create algorithm to generate all the different products of transpositions on \mathbb{Z}_n . Preferably, each product should be generated only once.
- 4.

3 Graph Theory

Definition 3.1. A graph is a triple $X = (X^0, X^1, \phi)$ where X^0, X^1 are sets whose elements are called *nodes* and *edges* respectively, while $\phi : X^1 \rightarrow 2^{X^0}$ is a map.

Definition 3.2. Let $X = (X^0, X^1, \phi_X)$ be a graph. A subgraph is a graph $Y = (Y^0, Y^1, \phi_Y)$ such that $Y^0 \subset X^0$, $Y^1 \subset X^1$ and $\phi_X|_{Y^1} = \phi_Y$.

Definition 3.3. Let $X = (X^0, X^1, \phi_X)$ be a graph. Given a subset $S^0 \subset X^0$, there is a natural associated subgraph S associated to S^0 given by $S = (S^0, S^1, \phi_S)$ where $S^1 = \{e \in X^1; \phi(e) \subset S^0\}$ and $\phi_S := \phi_X|_{S^1}$. This graph is called the graph generated by S^0 .

Similarly, if $S^1 \subset X^1$, the associated generated graph is given by (S^0, S^1, ϕ_S) , $S^0 = \{x \in X^0; \exists e \in S^1, x \in \phi_X(e)\}$, and again $\phi_S := \phi_X|_{S^1}$.

In each case, the subgraph generated is denoted by $\langle S^0 \rangle_X$ or $\langle S^1 \rangle_X$ accordingly.

Example 3.1. There are some elementary graphs which are very fundamental to all of graph theory, we describe some of them here. Let $n \in \mathbb{N}$, we define:

1. the path graphs

$$P_n^0 = \mathbb{N}_1^n$$

$$P_n^1 := \{\{x, x+1\}; x = 1, \dots, n-1\},$$

2. the cycle graphs

$$C_n^0 = \mathbb{N}_1^n$$

$$C_n^1 := \{\{x, x+1\}; x = 1, \dots, n-1\} \cup \{1, n\},$$

3. the complete graphs

$$K_n^0 = \mathbb{N}_1^n$$

$$K_n^1 = \{xy; 1 \leq x, y \leq n\},$$

4. the empty graphs

$$0_n^0 = \mathbb{N}_1^n$$

$$0_n^1 = \emptyset,$$

5. the cube graphs

$$Q_n^0 = \prod_1^n \mathbb{F}_2$$

$$Q_n^1 = \{\mathbf{ij}; \exists 1 \leq r \leq n, \mathbf{j} = \text{tog}_r(\mathbf{i})\}$$

where

$$\begin{aligned} \text{tog} : \mathbb{F}_2 &\rightarrow \mathbb{F}_2, \text{tog}(x) = 1 - x \\ \text{and } \text{tog}_r &= (\prod_1^{r-1} \iota) \times \text{tog} \times (\prod_{r+1}^n \iota) \end{aligned}$$

Intuitively, the cube graphs are the graphs whose nodes are binary sequences of size n , and two such sequences are neighbors when one differs from the other by a single toggle from 0 to 1 or from 1 to 0 on some element of the sequence. For example,

Definition 3.4. Let $x \in X^0$. The neighborhood of x in X is defined by

$$N_X(x) := \{y \in X^0; xy \in X^1\}.$$

Example 3.2. $Q_3^0 = \{000, 001, 010, 011, 100, 101, 110, 111\}$
 $N_{Q_3}(000) = \{001, 010, 100\}$, $N_{Q_3}(010) = \{000, 110, 011\}$.

Definition 3.5. A graph homomorphism of graphs X, Y is a map $\phi : X^0 \rightarrow Y^0$ such that for every $x, y \in X^0$ such that $xy \in X^1$, we have $\phi(x)\phi(y) \in Y^1$. In other words, it carries neighbors into neighbors.

A graph isomorphism is a bijective graph homomorphism

Lema 3.1. *The inverse of a graph isomorphism is a graph isomorphism.*

Proof.

□

Definition 3.6. A path P in a graph X is a subgraph of X isomorphic to a path graph.

Example 3.3. Let $X = C_n$ the cycle graph of order n . Then the subgraph $P^0 = C_n^0$, $P^1 = C_n^1 \setminus \{n, 1\}$ is isomorphic to a path graph.

3.1 Coloring

One of the important properties of graphs is that we can "traverse" a graph by starting at any node, "going through" one edge at a time reaching node after node, provided, naturally, that you can only go through an edge if it is incident on the node you currently occupy, and after going through the edge you will then occupy the other incident node. There are some definitions based on this idea:

Definition 3.7. Let X be a graph.

1. A walk on X is a finite sequence $w = (x_1, e_1, \dots, x_n, e_n, x_{n+1})$, where the $x_j \in X^0$, $j = 1, \dots, n+1$ and $e_j \in X^1$, $j = 1, \dots, n$, and such that for all $j = 1, \dots, n$, x_j, x_{j+1} are the incident nodes on e_j . We will also denote $w = x_1 e_1 \dots e_n x_{n+1}$. The length of such a walk is n , and will be denoted by $\text{len}(w)$.
2. A trail is a walk $w = x_1 e_1 \dots e_n x_{n+1}$ such that if $1 \leq j \neq k \leq n$, then $e_j \neq e_k$.
3. A path is a walk $w = x_1 e_1 \dots e_n x_{n+1}$ such that $1 \leq j \neq k \leq n+1$, then $x_j \neq x_k$.

Lema 3.2. *Let X be a graph and w be a path on X . Then w is also a trail on X .*

Proof.

□

Definition 3.8. The set of all walks of length $n \leq 0$ on a graph X is denoted X^n . The set of all walks on X is denoted X^* .

Notice that there seems to be two meanings to each of the symbols X^0, X^1 , but the two meanings coincide by equating walks of length 0 with nodes and walks of length 1 with edges of the graph, which is a natural procedure.

Definition 3.9. Let X, Y be graphs. A cover of X by Y is a partition

$$X^0 = \bigcup_{j=1}^r Y_j^0$$

where for each $1 \leq j \leq r$ the subgraph $\langle Y_j^0 \rangle_X$ generated by Y_j^0 is isomorphic to Y .

Definition 3.10. A very import specific case of cover is the of perfect matching. A perfect matching in X is a cover of X by K_2 .

Definition 3.11. A r -dimensional grid graph is a graph obtained by the direct product of r path graphs. Symbolically, the grid with parameters n_1, \dots, n_r is given by:

$$\text{Grid}(n_1, \dots, n_r) = P_{n_1} \square P_{n_2} \square \dots \square P_{n_r}$$

Problema 3.1. Given two grids $X = \text{Grid}(n_1, \dots, n_r)$, $Y = \text{Grid}(m_1, \dots, m_s)$, with $r \geq s$, we ask two questions:

1. Is there a cover of X by Y ?
2. If so, how many different covers are there?

3.2 Operations on Graphs

In the section, we describe operations on sets of graphs that yield other graphs. Many important results have proofs using operations such as these. Furthermore they also lead to interesting combinatorial questions. Whenever we apply some operation to some collection of graphs obtaining a graph in the end, we say that this final graph was obtained from the initial collection via the operation.

Let X, Y be graphs.

Definition 3.12. Let $x_0 \in X^0$. We denote by $X \setminus x_0$ the graph obtained by removing x_0 from X^0 , i.e., $(X \setminus x_0)^0 = X^0 \setminus \{x_0\}$, $(X \setminus x_0)^1 = \{e \in X^1; x_0 \text{ is not incident on } e\}$.

Similarly, if $e_0 \in X^1$ we denote $X \setminus e_0$ the graph obtained by removing e_0 from X^1 , i.e., $(X \setminus e_0)^0 = X^0$, $(X \setminus e_0)^1 = X^1 \setminus e_0$.

If $Y \leq X$, there is always a way of obtaining Y from X by sequentially deleting nodes and edges, and it is usually the case that there are many ways of doing this sequential procedure.

Definition 3.13. The cartesian (or box) product of X and Y is denoted by $X \square Y$, and is defined by:

1. $(X \square Y)^0 := X^0 \times Y^0$,
2. $(X \square Y)^1 := \{(x, y)(x, b); yb \in Y^1\} \cup \{(x, y)(a, y); xa \in X^1\}$.

Example 3.4. The grid graphs are defined as

$$\text{grid}(n_1, \dots, n_r) := P_{n_1} \square \dots \square P_{n_r}.$$

3.3 Directed Graphs

3.4 Hypergraphs

Definition 3.14. A Hypergraph is a pair $H = (H^0, H^1, \phi)$ where H^0, H^1 are sets and $\phi : H^1 \rightarrow \mathcal{P}(H^0)$ is a map. The elements of H^0 are called nodes of H and the elements of H^1 are called hyperedges of H , whereas the map ϕ is called the incidence map.

The hypergraph is called simple when ϕ is an injection, so that we may consider $H^1 \subset \mathcal{P}(H^0)$.

Example 3.5. The Tic-Tac-Toe hypergraphs are denoted by $TTT = TTT(n_1, \dots, n_d)$, where $n_1, \dots, n_d \in \mathbb{N}$ and given by

$$\begin{aligned} TTT^0 &= [1, n_1]_{\mathbb{N}} \times \dots \times [1, n_d]_{\mathbb{N}}, \\ TTT^1 &= \{i_j(x); j = 1, \dots, d, x = 1, \dots, n_j\}, \text{ where} \\ i_j(x) &= (i_1, \dots, i_{j-1}, x, i_{j+1}, \dots, i_d), i_r \text{ fixed for all } r \neq j. \end{aligned}$$

3.5 Algorithms

Definition 3.15. content...

4 Enumerative Combinatorics

5 Algebraic Combinatorics

5.1 Algebra

Definition 5.1. A group is a pair $(G, *)$ where G is a set and $*$ is a map

$$*: G \times G \rightarrow G, (x, y) \mapsto x * y =: xy$$

satisfying for all x, y, z :

1. $x * (y * z) = (x * y) * z$, i.e., $x(yz) = (xy)z$.
2. There exists an element $1 \in G$ such that $x * 1 = 1 * x = x$, i.e., $x1 = 1x = x$.
3. There exists $x^{-1} \in G$ such that $x * x^{-1} = x^{-1} * x = 1$, i.e., $xx^{-1} = x^{-1}x = 1$.

Definition 5.2. Let G_1, G_2 be groups. A homomorphism between G_1, G_2 is a map $f : G_1 \rightarrow G_2$ such that $f(xy) = f(x)f(y)$ for all $x, y \in G$. A bijective homomorphism is called a group isomorphism.

A homomorphism from a group into itself is called an endomorphism and a bijective endomorphism is called an automorphism.

The set of all homomorphism between G_1, G_2 is denote by $\text{Hom}(G_1, G_2)$. We also denote $\text{End}(G)$, $\text{Aut}(G)$ the set of endomorphism and automorphisms of G respectively.

Lema 5.1. For every set X , the set $\text{Aut}(X)$ is a group under map composition.

Proof. □

The previous lemma provides us with plenty of examples of groups. But in fact, this situation is always the case. In fact we have the following:

Lema 5.2. Let G be a group, $g \in G$. Consider the map $L_g : G \rightarrow G$ given by $L_g(h) = gh$. Then L_g is an automorphism of G , i.e., $L_g \in \text{Aut}(G)$.

Proof. □

Corolário 5.1. For any group G , the map $L : G \rightarrow \text{Aut}(G)$, given by $L(g) = L_g$ is an injective homomorphism.

Example 5.1. The following are the most canonical examples of groups.

1. Let $n \in \mathbb{N}$. We denote $S_n = \text{Aut}(\mathbb{N}_1^n)$, the group of permutations of the numbers 1 through n .
2. Let V be a vector space. Then

$$\text{GL}(V) := \{T \in \text{Hom}_{\text{vect}}(V); T \text{ is invertible}\}.$$

is a group under composition of maps, known as the General Linear Group of V .

Isomorphic groups share many important properties.

Definition 5.3. A representation of G is a pair (ρ, V) where V is a vector space and $\rho : G \rightarrow \text{GL}(V)$ is a group homomorphism.

Definition 5.4. An (a left) action of a group G is a pair (ρ, X) where X is a set, $\rho : G \times X \rightarrow X$ satisfying, for all $g, h \in G, x \in X$:

1. $\rho(g, \rho(h, x)) = \rho(gh, x)$,
2. $\rho(1, x) = x$.

We will often abuse notation slightly and suppress ρ and say V is a representation of G , and conversely we may also declare a representation ρ of G , suppressing V .

Lema 5.3. *Let G be a group.*

Let (ρ, V) be a representation of G . Then, if you consider the underlying set of V , you obtain a group action $\rho_X : G \times V \rightarrow V$, given by $gv = \rho(g)v$.

Conversely, if (ρ, X) is a group action of G , then the map $\rho_V : G \rightarrow \text{GL}(\text{Vect}(X))$, given by $\rho(g)v = gv$ for all $v = \sum_{x \in X} \lambda_x x$ is a representation of G .

Combinatorial structures sometimes have interesting symmetries

Definition 5.5. Let V be a representation of G , and $W \subset V$ be a subspace. We say that W is G -invariant if for all $g \in G, w \in W$ $gw \in W$.

An extremely important and very profound problem of group theory is to find all irreducible finite-dimensional representations of a given group G .

We have had partial success with some classes of groups, especially finite groups and finite representations which will be the main focus of our attention here.

6 Finite Geometry

6.1 Polyominoes

Definition 6.1. We consider the natural graph structure on \mathbb{Z}^r given by the edges

$$\{e = xy; \|x - y\| = 1\}.$$

Definition 6.2. A r -dimensional shape S is a subgraph of \mathbb{N}^r . A shape S is connected if it is connected as a graph, *i.e.*, if for any two nodes x, y , there is a path $P(x, y)$ subgraph of S connecting x and y .

Definition 6.3. A polyomino is a connected finite shape.

There are many ways to study polynomials, for instance with respect to symmetries or without them.

Proposição 6.1. For $n \leq 6$, the following table holds data on polyominoes with cardinality less or equal to 6.

Proof. □

7 Design Theory

8 Cellular Automata

9 Order Theory

Definition 9.1. A partial order on a set X is a binary relation \leq satisfying:

- (Reflexivity) for all $x \in X$, $x \leq x$,
- (Associativity) if $x, y, z \in X$ are such that $x \leq y$ and $y \leq z$ then $x \leq z$,
- (Antisymmetry) if $x, y \in X$ are such that $x \leq y$ and $y \leq x$, then $x = y$.

A partially ordered set, or poset for convenience, is a pair (X, \leq) , where X is a set and \leq is a partial order on X .

Definition 9.2. Let X, Y be posets. An order preserving map from X to Y is a map $\phi : X^0 \rightarrow Y^0$ such that if $x_1 \leq x_2$ in X , then $f(x_1) \leq f(x_2)$ in Y .

Example 9.1. The canonical example of poset is the set of subsets of some set, or a subset of the power set. More precisely, if $\mathcal{F} \subset 2^X$ is a family of subsets of some set X , then (\mathcal{F}, \subset) is a poset.

Proposição 9.1. The number of partial orders on a set with x is

Lema 9.1. Let P be a finite poset and $P_0 \subset P$. For every $s \in P_0$ there exists an element \tilde{s} such that for every $t \in P$ we have:

1. $s \leq \tilde{s}$,
2. either $t \leq \tilde{s}$ or t and s are incomparable.

In other words, in a poset P , every element of P is less or equal to a maximal element.

Proof. □

Corolário 9.1. If X is a set and $\mathcal{F} \subset 2^X$ is a set of subsets of X , then there is a $Y \in \mathcal{F}$ such that $X \subset Y$ and if $Z \in \mathcal{F}$ then either $Z \subset Y$ or Z and Y are incomparable. In other words, every subset is contained in a maximal subset with respect to \mathcal{F} .

10 Matroid Theory

11 Probability Theory

Proposição 11.1. *Let $n \in \mathbb{N}$, $\{X_1, \dots, X_n\}$ be i.i.d. random variables in Ω , $T \subset \mathbb{R}$. Then*

$$P(X_{n_1}, \dots, X_{n_m} \in T) = \binom{n}{m} P(X_{n_1} \in T)^m$$

12 Statistics

13 Combinatorial Species

14 Combinatorial Games

14.1 Combinatorial Games on Hypergraphs

Let us consider tic-tac-toe. It is played on a 3×3 grid by two players X and O that take alternating turns in which they chooses one cell to capture (by drawing their symbol on the cell). The player who captures either 3 cells in a horizontal line or 3 in a vertical line or 3 in one of the two diagonals (descending or ascending) wins. Player X goes first.

We can generalize this game in many ways. In (ref) the authors study the n^d version of the game defined loosely as follows. Consider the grid graph $\text{Grid}(n^d)$ with dimension d and width n . The game is completely similar to the original tic-tac-toe except that players have to capture n in a line (horizontal, vertical or diagonal). A precise definition will be given momentarily.

Notice that by saying n in a line implies that you have to capture a whole line, since there are exactly n cells in each line.

But we can generalize this further in many directions. We can make more than two players play each match, or require fewer than n in a row, for example having three players whose marks are 1, 2, 3 and they take turns according to their marks' order and they only have to capture 3 in a row in a n^d game where $n > 3$. This means you do not have to capture a whole line to win. Additionally you can allow more general grids such as $\text{Grid}(n_1, \dots, n_d)$, as well as remove some of the cells from the game so that they are not capturable and finally changing the "pattern" of victory set, instead of always using a segment of a line.

We are interested in developing AI systems that come up with interesting strategies for high victory proportions rather than completely solving the game.

Definition 14.1. Let $n \in \mathbb{N}$ and consider, for $i \leq n$, the functions

$$\begin{aligned} \text{succ}_i : \mathbb{Z}^n &\rightarrow \mathbb{Z}^n, \\ \text{succ}_i(j_1, \dots, j_i, \dots, j_n) &= (j_1, \dots, j_i + 1, \dots, j_n), \end{aligned}$$

and $S \subset \mathbb{N}^n$,

$$succ_S : \mathbb{Z}^n \rightarrow \mathbb{Z}^n, succ_S = \prod_{i \in S} succ_i.$$

Definition 14.2. Let $d, N, v \in \mathbb{N}, d > 0, N > 1, \mathbf{n} \in \mathbb{N}^d$, consider the graph $\mathbf{Grid}(\mathbf{n})$ defined in (ref) and $E \subset \mathbf{Grid}(\mathbf{n})^0$ and finally $\mathcal{V} \subset \mathcal{P}(\mathbf{Grid}(\mathbf{n})^0)$.

We define the generalized tic-tac-toe in the graph $\mathbf{Grid}(\mathbf{n}) \setminus E$ to be the game played by N players in this graph where the players take turns in a cycle according to their order. The victory sets are \mathcal{V} .

In player i 's turn they choose an element $p \in \mathbf{Grid}(\mathbf{n}) \setminus E$ to capture, which means labeling this p with label i . Player i wins if they complete a victory set $V \in \mathcal{V}$ first.

Such a game will be denoted $\mathbf{TTT}(N, \mathbf{n}, E, \mathcal{V})$.

Definition 14.3. A random strategy with probability distribution p in the game $\mathbf{TTT}(\mathbf{n}, E, \mathcal{V})$ is a strategy where each turn a lottery with a natural rescaling of the probability distribution p is taken on all available cells of the game and whichever cell wins this lottery is chosen as the captured. (finish)

14.2 Combinatorial Card Games

14.3 Combinatorial Economic Games

15 Cryptography

16 Game Theory

17 Analysis

Let M be a metric space and $T : M \rightarrow M$ be a map. We say that T is

Let $T \in \text{End}(B)$ where B is a Banach space and suppose T is k -contractive for some $k < 1$. Then there exists a neighborhood N of T in $\text{End}(B)$ such that all S in N is l_S -contractive for some $l_S < 1$.

18 Turing Machines

19 Algorithms

20 Game of Life

21 Dynamic Games

22 Board Games

23 Card Games

We shall now turn to the study of games in which the players played with cards. A precise definition will be given later, but examples of such games are poker, the Blizzard videogame hearthstone, set, freecell, solitaire, uno, Magic the Gathering, etc...

We wish to develop a general language for such games as well as a rigorous theory about them in terms of combinatorial structures previously studied, in order to develop AI agents to solve or excel at them.

The oldest examples of card games were games played on the standard deck of cards with 52 cards of four different suits. These are not only classic examples, but many of them are still played by large communities, and some are even studied academically. We therefore make a separation by classifying them as "deck games".

24 Deck Games

We first define the deck of cards.

Definition 24.1. Let $S = \{\diamondsuit, \heartsuit, \clubsuit, \spadesuit\}$ and $D = \mathbb{N}_1^{13} \times S = \{c = (n_c, s_c) \mid 1 \leq n_c \leq 13, s_c \in S\}$. We call this set the deck of cards, or deck for short.

We shall denote \mathbf{n} the first projection $p_1 : D \rightarrow \mathbb{N}_1^{13}$ and $\mathbf{s} = p_2 : D \rightarrow S$ the second one.

It is clear that D has cardinality 52.

In this description, the 4 of hearts corresponds to the element $c = (4, \heartsuit) \in D$ (in this case $\mathbf{n}(c) = 4$), the jack of clubs to the element $c = (11, \clubsuit)$ (in this case $\mathbf{s}(c) = \clubsuit$) and so on.

24.1 Poker

Poker is a family of deck games

We calculate some essential probabilities on D related to the game of poker.

Definition 24.2. A hand is subset $H \subset D$ with cardinality 5. If we say n hands, we mean a collection H_1, \dots, H_n disjoint hands.

Definition 24.3. 1. Let Ω_n be the sample space of the experiment of drawing n cards where $n \leq 52$. More precisely:

$$\Omega_n := \{\omega \subset \Omega; |\omega| = n\}.$$

2. We define the probability spaces (Ω_n, P_n) by putting:

$$P_n(\omega) = 1/C_n^{52} = \frac{1}{C_n^{52}},$$

i.e., we use the counting measure on Ω_n .

3. We define the number counting function on Ω_n by

$$\#_n : \Omega_n \rightarrow \mathbb{N}, \#_n(m, \omega) = |\{c \in \omega; \mathbf{n}(c) = m\}|$$

For convenience we shall denote $\omega \in \Omega_n$ as $\omega =$
Let $\omega \in \Omega_n$.

Proposição 24.1. *The probability of drawing 2 cards with the same number on one hand is given by:*

$$P(\omega)\{\}$$

Proof. .

First, notice that

□

25	Mixed Structure Games
26	Mod Theory
27	Economic Games
28	Agent Theory
29	Strategies
30	Balance Theory
31	Portfolio Theory
32	Practical Code
33	Data
34	Stochastic Partial Differential Equations
35	Differential Equations

Definition 35.1. A simple ordinary differential equation is an uple $P = (J, U, \Lambda, \nu)$ where $J \subset \mathbb{R}$ is an interval, $U \subset \mathbb{R}^n$ is open, $\Lambda \subset \mathbb{R}^m$ is any set and $\nu : J \times \Lambda \rightarrow U$ is any map.

The set J is the interval of definition of the differential equation, U is domain of definition, Λ is a parameter space and ν gives the equation the derivative of the unknown function has to satisfy: $f'(x) = \nu(x)$.

We make the convention that if the equation does not depend on a variable parameter λ , $\Lambda = \{0\}$, and $\nu : J \rightarrow U$, instead of $\nu : J \times \Lambda \rightarrow U$.

We can rewrite the classical form of writing differential equations in this language, so that for example $x = x(t), f'(x) = x, t \in J$ becomes $(J, \mathbb{R}, \emptyset, \text{id})$.

Definition 35.2. Let $P = (J, U, \Lambda, \nu)$ be a simple ODE, and let $\lambda \in \Lambda$. A solution with parameter λ of P is a map $f : J \rightarrow U$ such that

$$f'(t) = \nu(t, \lambda) \text{ for all } t \in J, \text{ i.e., } f' = \nu(\cdot, \lambda).$$

36 Optimization and Control

36.1 Polyhedral Sets

36.2 Convexity

Definition 36.1. Let $X \subset \mathbb{R}^n$. We say that X is convex when

$$x, y \in X, t \in [0, 1] \implies tx + (1 - t)y \in X.$$

Lema 36.1. Let $X, Y \subset \mathbb{R}^n$ be convex, $v \in \mathbb{R}^n, t \in \mathbb{R}$. Then

1. $X + v$ is convex,
2. tX is convex,
3. $X \cap Y$ is convex,
4. \overline{X} is convex,
5. $X \times Y$ is convex,
6. $X + v$ is convex,

Example 36.1. If V is normed then for all $x \in V, r \geq 0, B(x, r)$ is convex

Example 36.2. Every linear subspace W of V is convex.

Example 36.3.

Definition 36.2. Let $x, y \in V$. The xy -segment is the set

$$\{tx + (1 - t)y \mid t \in [0, 1]\}$$

It is clear that $x, y \in [x, y]$ for all $x, y \in V$.

Definition 36.3. Let $X \subset \mathbb{R}^n$. The convex hull of X , denoted $\text{cvx}(X)$ is the set

$$\{z \in \mathbb{R}^n \mid \exists x, y \in X \text{ such that } z \in [x, y]\}.$$

Definition 36.4. Let $f : X \rightarrow \mathbb{R}^m$ be a map with $X \subset \mathbb{R}^n$. We say that f is convex when

$$x, y, tx + (1 - t)y \in X, t \in [0, 1] \implies f(tx + (1 - t)y) \leq tf(x) + (1 - t)f(y).$$

Definition 36.5. The epigraph of a map $f : V \rightarrow W$

36.3 Duality

36.4 Cones

Definition 36.6. Let V be a vector space. A cone is a subset C such that

$$x \in C, t > 0 \implies tx \in C$$

Definition 36.7. Let $x \in D \subset V$. We say that $v \in V$ is a viable direction with respect to D at x if

$$\exists \epsilon > 0 \text{ such that for all } t \in [0, \epsilon], x + tv \in D .$$

We call the set of all viable directions with respect to D at x by $\mathcal{V}_D(x)$.

Example 36.4. Let S^{n-1} be the n -sphere in \mathbb{R}^n , and let $x = (0, \dots, 0, 1)$ be the north pole. Then $\mathcal{V}_D(x) = \{(x_i); x_n < 0\}$.

Definition 36.8. Let $f : D \rightarrow \mathbb{R}$ with $D \subset V$. We say that $v \in V$ is a direction of descent of f when v is a viable direction wrt D at x and

$$\exists \epsilon > 0 \text{ such that for all } t \in [0, \epsilon], f(x + tv) \leq f(x) .$$

The set of all directions of descent for f at x is denoted $\mathcal{D}_f(x)$

Lema 36.2. Let $x \in D \subset V$ and $f : D \rightarrow \mathbb{R}$ be a function. Then the following sets are cones.

1. $\mathcal{V}_D(x)$,
2. $\mathcal{D}_f(x)$,

36.5 Optimization

Definition 36.9. An optimization problem is an uple $P = (J, D)$ where $D \subset \mathbb{R}$ and $J : D \rightarrow \mathbb{R}_\infty$ is a function.

For us, an optimization problem is a minimization problem, since maximization problems can always be solved by switching J with $-J$.

Definition 36.10. Let $P = (J, D)$ be an optimization problem. A solution to P is a point $\bar{x} \in D$ such that $J(\bar{x}) \leq J(x)$ for all $x \in D$.