

# FACULTY OF INFORMATION TECHNOLOGY

DEPARTMENT OF BIG DATA ANALYTICS

# Assignment IV Introduction to statistical Learning: Chapter8

Course: Data Mining and Information Retrieval

## Prepared by:

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## Exercise 8.4, Question 1: Partition and Decision Tree

This exercise requires constructing an example of a partition of a two-dimensional feature space using recursive binary splitting, resulting in at least six regions, and drawing the corresponding decision tree. All regions, cutpoints, and nodes must be labeled, resembling Figures 8.1 and 8.2 from the book. The partition and decision tree are visualized using Python-generated plots, included below.

## Partition of the Feature Space

The feature space is a  $10 \times 10$  square with predictors  $X_1$  (horizontal axis) and  $X_2$  (vertical axis), both ranging from 0 to 10. Recursive binary splitting is applied with the following cutpoints, as defined in the Python code:

- $t_1$ :  $X_1 = 5$  (vertical line across the entire space)
- $t_2$ :  $X_2 = 7$  (horizontal line from  $X_1 = 0$  to  $X_1 = 5$ )
- $t_3$ :  $X_2 = 3$  (horizontal line from  $X_1 = 5$  to  $X_1 = 10$ )
- $t_4$ :  $X_1 = 8$  (vertical line from  $X_2 = 3$  to  $X_2 = 10$ )
- $t_5$ :  $X_2 = 6$  (horizontal line from  $X_1 = 5$  to  $X_1 = 8$ )

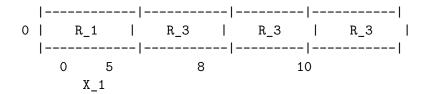
These cutpoints divide the space into six regions, labeled  $R_1, R_2, \ldots, R_6$ , with boundaries and centers as follows:

Table 1: Regions of the Feature Space

Region	Boundaries	Center
$R_1$	$0 \le X_1 \le 5, \ 0 \le X_2 \le 7$	(2.5, 3.5)
$R_2$	$0 \le X_1 \le 5,  7 < X_2 \le 10$	(2.5, 8.5)
$R_3$	$5 < X_1 \le 10, \ 0 \le X_2 \le 3$	(7.5, 1.5)
$R_4$	$5 < X_1 \le 8, \ 3 < X_2 \le 6$	(6.5, 4.5)
$R_5$	$5 < X_1 \le 8,  6 < X_2 \le 10$	(6.5, 8.0)
$R_6$	$8 < X_1 \le 10, \ 3 < X_2 \le 10$	(9.0, 6.5)

The partition is visualized in Figure 1, generated using Python (matplotlib). The plot shows a  $10 \times 10$  square with vertical lines at  $X_1 = 5$  ( $t_1$ ) and  $X_1 = 8$  ( $t_4$ ), and horizontal lines at  $X_2 = 7$  ( $t_2$ , from  $X_1 = 0$  to 5),  $X_2 = 3$  ( $t_3$ , from  $X_1 = 5$  to 10), and  $X_2 = 6$  ( $t_5$ , from  $t_1 = 5$  to 8). Each region is labeled at its center.

A textual representation of the partition is:



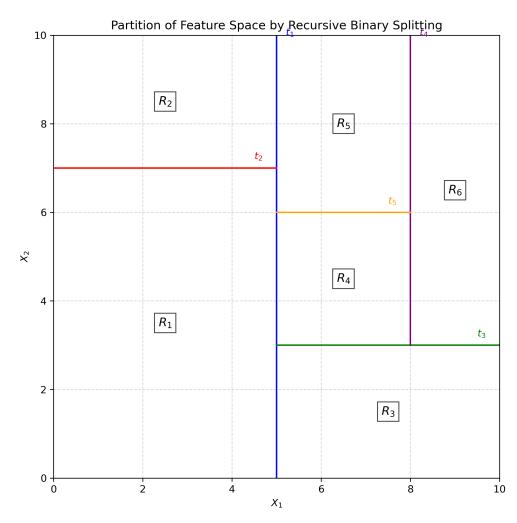


Figure 1: Partition of the feature space by recursive binary splitting, showing six regions  $(R_1 \text{ to } R_6)$  and cutpoints  $(t_1 \text{ to } t_5)$ .

## **Decision Tree**

The decision tree corresponding to the partition is shown in Figure 2, generated using Python. It follows the sequence of splits:

- Root: Split at  $X_1 \leq 5$   $(t_1)$ .
- Left Branch  $(X_1 \le 5)$ : Split at  $X_2 \le 7$   $(t_2)$ .
  - Left: Region  $R_1$   $(0 \le X_1 \le 5, 0 \le X_2 \le 7)$ .
  - Right: Region  $R_2$  ( $0 \le X_1 \le 5, 7 < X_2 \le 10$ ).

- Right Branch  $(X_1 > 5)$ : Split at  $X_2 \le 3$   $(t_3)$ .
  - Left: Region  $R_3$  (5 <  $X_1 \le 10, 0 \le X_2 \le 3$ ).
  - Right: Split at  $X_1 \leq 8$   $(t_4)$ .
    - \* Left: Split at  $X_2 \leq 6$   $(t_5)$ .
      - · Left: Region  $R_4$  (5 <  $X_1 \le 8, 3 < X_2 \le 6$ ).
      - · Right: Region  $R_5$  (5 <  $X_1 \le 8, 6 < X_2 \le 10$ ).
    - \* Right: Region  $R_6$  (8 <  $X_1 \le 10, 3 < X_2 \le 10$ ).

Decision Tree for Recursive Binary Splitting

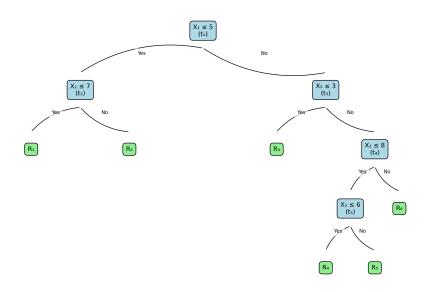


Figure 2: Decision tree corresponding to the feature space partition, with splits labeled  $t_1$  to  $t_5$  and leaves labeled  $R_1$  to  $R_6$ .

## Exercise 8.4, Question 6: Regression Tree Algorithm

This exercise requires a detailed explanation of the algorithm used to fit a regression tree. Algorithm 8.1 from An Introduction to Statistical Learning outlines the process for building a regression tree to predict a continuous response variable Y based on predictors  $X_1, X_2, \ldots, X_p$ . Below is a step-by-step explanation.

#### Algorithm 8.1: Building a Regression Tree

The algorithm consists of four steps, applied to a training dataset with n observations  $\{(x_i, y_i)\}_{i=1}^n$ , where  $x_i = (x_{i1}, x_{i2}, \dots, x_{ip})$  and  $y_i$  is continuous.

## 1. Grow a Large Tree Using Recursive Binary Splitting:

- Objective: Partition the feature space into regions by minimizing the sum of squared errors (SSE).
- Process:
  - Start with all observations in the root node.
  - For each node, evaluate splits on each predictor  $X_j$  (j = 1, ..., p) at split points s:

$$R_1(j,s) = \{x \mid x_j \le s\}, \quad R_2(j,s) = \{x \mid x_j > s\}$$

- Compute SSE:

SSE = 
$$\sum_{i:x_i \in R_1(j,s)} (y_i - \hat{y}_{R_1})^2 + \sum_{i:x_i \in R_2(j,s)} (y_i - \hat{y}_{R_2})^2$$

where  $\hat{y}_{R_m} = \frac{1}{n_m} \sum_{i:x_i \in R_m} y_i$ .

- Choose the (j, s) minimizing SSE, split into two child nodes, and assign observations.
- Recursively split each child node.
- Stopping Criterion: Stop when a node has fewer than a minimum number of observations (e.g., 5).
- Output: Large tree  $T_0$  with regions  $R_1, \ldots, R_J$ .

## 2. Apply Cost-Complexity Pruning:

- Objective: Generate a sequence of subtrees to reduce overfitting.
- Criterion: Minimize the cost-complexity:

$$C_{\alpha}(T) = \sum_{m=1}^{|T|} \sum_{i:x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$

where |T| is the number of leaves, and  $\alpha$  is a tuning parameter.

- Process: For each  $\alpha$ , find the subtree  $T_{\alpha} \subset T_0$  minimizing  $C_{\alpha}(T)$ .
- Output: Sequence of subtrees  $T_{\alpha_1}, T_{\alpha_2}, \ldots$

### 3. Choose $\alpha$ Using K-Fold Cross-Validation:

- Process:
  - Divide data into K folds (e.g., K = 5).
  - For each fold  $k = 1, \ldots, K$ :
    - (a) Grow and prune a tree on all but the kth fold.
    - (b) Compute mean squared error on the kth fold:

$$MSE_k(\alpha) = \frac{1}{n_k} \sum_{i \in fold} (y_i - \hat{y}_i)^2$$

- Average MSE:

$$CV(\alpha) = \frac{1}{K} \sum_{k=1}^{K} MSE_k(\alpha)$$

- Choose  $\alpha$  minimizing  $CV(\alpha)$ .
- Output: Optimal  $\alpha$ .

# 4. Return the Optimal Subtree:

- Select subtree  $T_{\alpha}$  for the chosen  $\alpha$ .
- Predict  $\hat{y}_{R_m}$  for observation x in region  $R_m$ .
- Output: Pruned tree  $T_{\alpha}$ .

# **Key Features**

- Greedy Approach: Local SSE minimization ensures efficiency.
- Overfitting Control: Pruning and cross-validation improve generalization.
- Interpretability: The tree is a sequence of decisions, as in Question 1.