

Learning Convolutional Neural Networks (1)

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In this talk

bit.ly/LDL_repo

Image Data



- Popular image dataset
- Image preprocessing

01

CNN Basics



- Origins & ideas
- CNN mechanism

02

CNN Variants



- Conv as feature extractor
- De-conv, 3d conv, ...
- FCN and GCN

03

Demo



- CNN in pytorch
- Save/load pytorch model
- Setup of colab env

04

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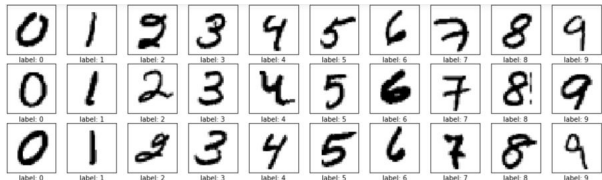


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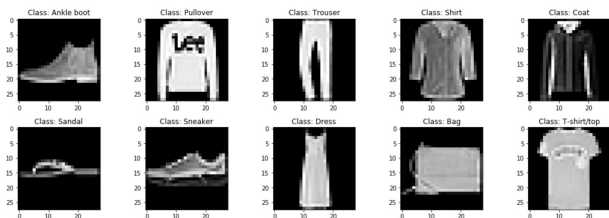
04

Popular Datasets for Computer Vision Tasks

- MNIST dataset of handwritten digits



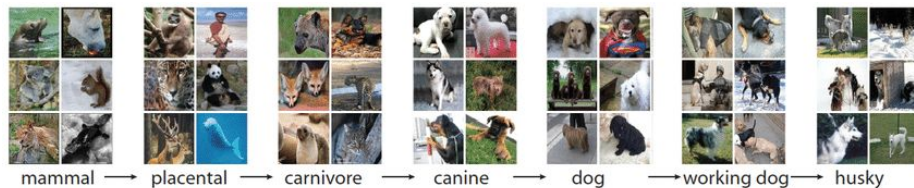
- Fashion MNIST dataset



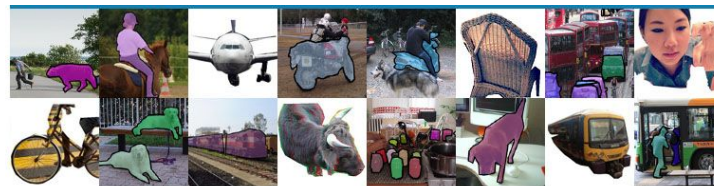
- CIFAR-10



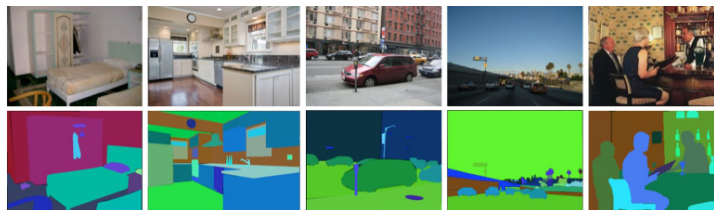
- IM🍌GENET



- Microsoft COCO



- ADE20K



Dogs vs. Cats Kaggle Challenge

- Redux: Kernels Edition

- Submission scored by the probability of dogs using log loss

$$L = -\frac{1}{n} \sum_{i=1}^n \left[y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i) \right]$$

- Dataset

- Training set: 25,000 dogs and cats images
- Testing set: 12,500 images
- Images with different sizes
 - Neural network needs fixed sized input.
 - We will resize images to 150x150 pixels
- Images are colored
 - Represented by Red-Green-Blue channels
 - One image \Rightarrow 150x150x3 matrices



Digitalization for Color Images

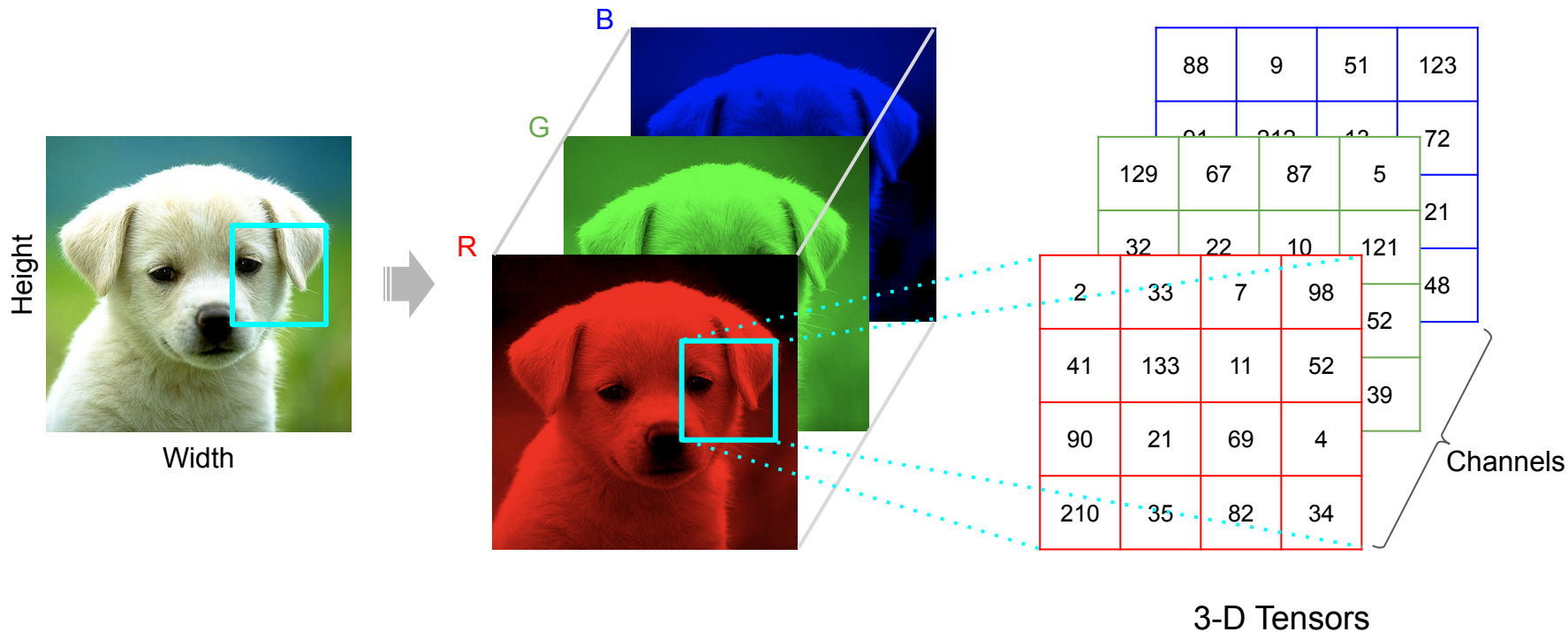


Image data conversion in PyTorch

- PIL to convert JPG to PIL Image
 - `pil.Image.open(path).convert('RGB')`
- Resize to the uniform sizes for all images
 - `torchvision.transforms.Resize((150, 150))`
- Convert to tensors:
 - `torchvision.transforms.ToTensor()`
 - Indexes ($H \times W \times C$) \Rightarrow ($C \times H \times W$)
 - Range $[0, 255] \Rightarrow [0.0, 1.0]$

Python Image Library (PIL)

- Pillow as newer versions
- Various image processing
- Per-pixel manipulations

Torchvision is a package for computer vision, containing:

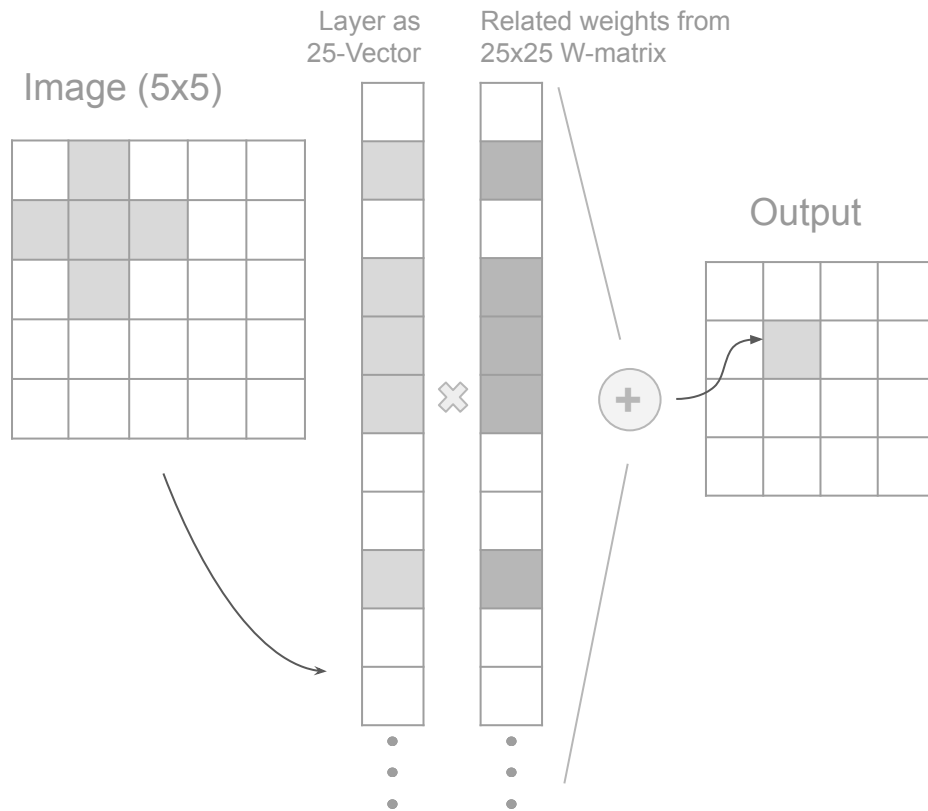
- Popular datasets
- Model architectures
- Image transformations

Datasets and Data loading

- Defining the dataset class
 - Subclassing `torch.utils.data.Dataset`
 - PyTorch dataset object requires 2 methods:
 - `__len__()`
 - `__getitem__()`
 - Wrapping conversions in `__getitem__()`
- Loading the dataset with `torch.utils.data.DataLoader`
 - Batching the data
 - Shuffling the data
 - Loading the data in parallel using multiprocessing workers

For Image Classification Tasks

- Naive steps:
 - a. Matrices \Rightarrow Vectors
 - b. Fully connected (FC) networks
- Limitations for FC models
 - Not scale well with pixel numbers
 - 1024x1024 RGB image
One 1024-feature hidden layer
 - \rightarrow 3 billion parameters
 \rightarrow 12 GB ram for 32-bit floats
 \rightarrow Hard to fit in a GPU
 - Not translation-equivariant
 - Shifting 1 pixel \rightarrow Re-learn!



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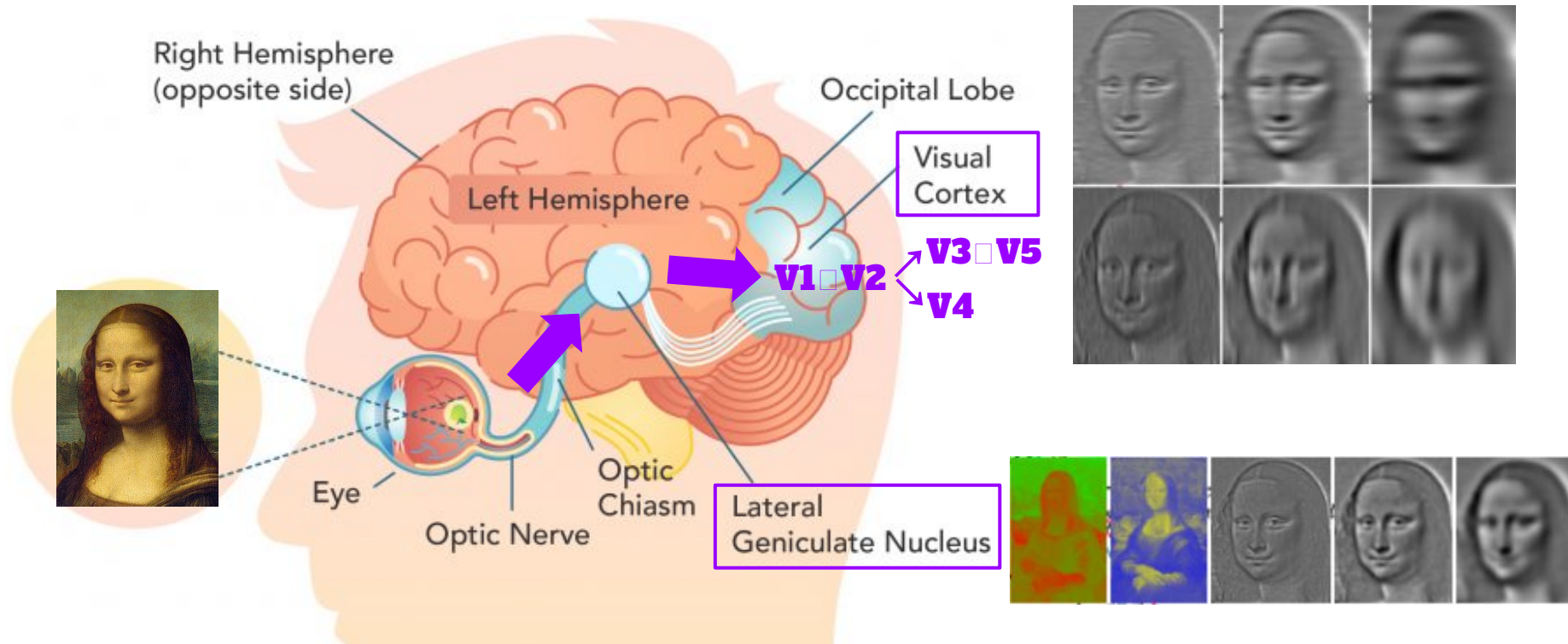
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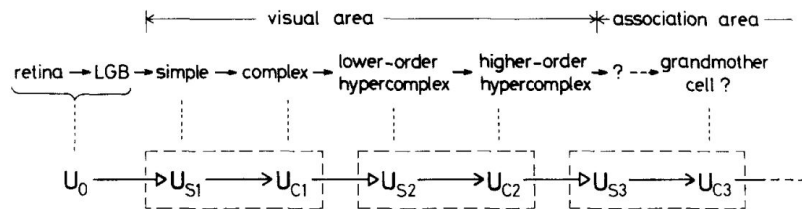
Inspiration from Cognitive Neuroscience



Convolutional Neural Networks (CNNs)

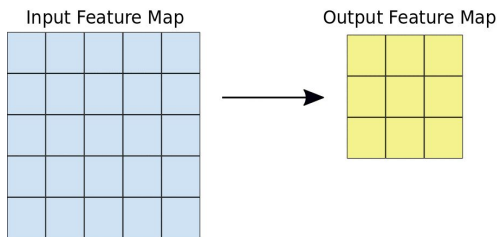
- Origins in computer vision

- Neocognitron: K. Fukushima (1980)
 - convolutional layers, and downsampling layers
- Modern CNN: Yann LeCun et al. (1989)
 - backpropagation

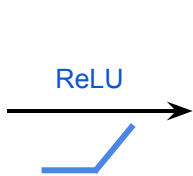


- Steps in CNNs:

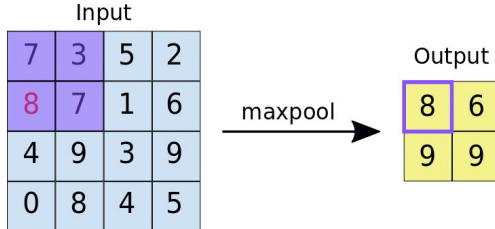
Convolutions to extract as tiles



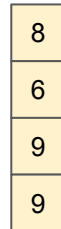
Activation



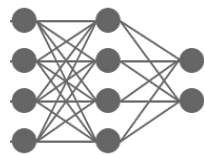
Poolings to downsample



Flattening



FCN



Training by backpropagation

One Channel, One Filter

0	0	0	0	0	0
0	105	102	100	97	96
0	103	99	103	101	102
0	101	98	104	102	100
0	99	101	106	104	99
0	104	104	104	100	98

Image Matrix

Kernel Matrix		
0	-1	0
-1	5	-1
0	-1	0

320				

Output Matrix

$$\begin{aligned} &0 * 0 + 0 * -1 + 0 * 0 \\ &+ 0 * -1 + 105 * 5 + 102 * -1 \\ &+ 0 * 0 + 103 * -1 + 99 * 0 = 320 \end{aligned}$$

**Convolution with horizontal and
vertical strides = 1**

Example Input Image

[Interactive Source](#)



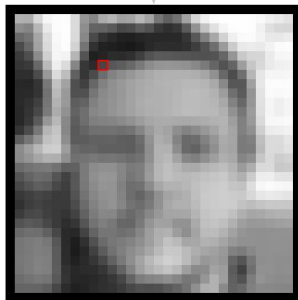
Identity

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$



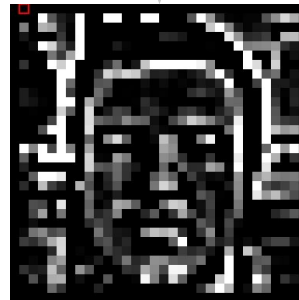
Blur

$$\begin{pmatrix} 0.0625 & 0.125 & 0.0625 \\ 0.125 & 0.25 & 0.125 \\ 0.0625 & 0.125 & 0.0625 \end{pmatrix}$$



Outline

$$\begin{pmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{pmatrix}$$



Sharpen

$$\begin{pmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{pmatrix}$$



Multiple Channels

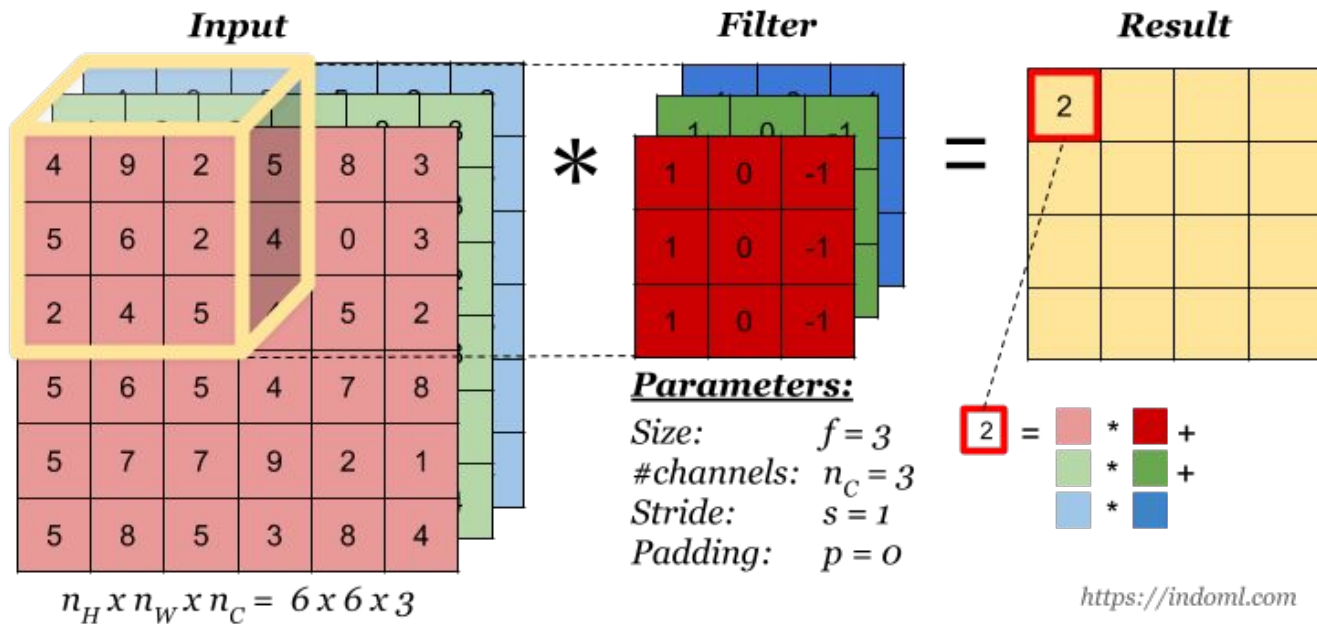
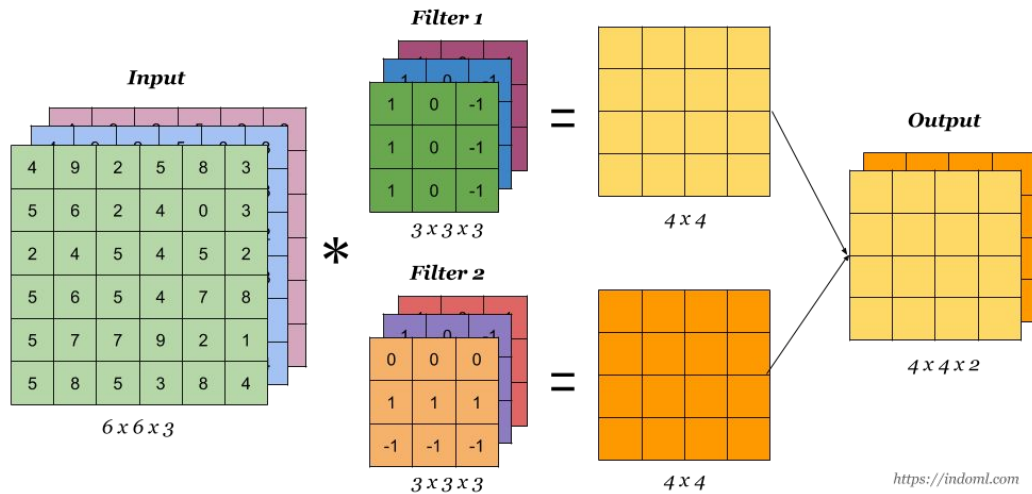
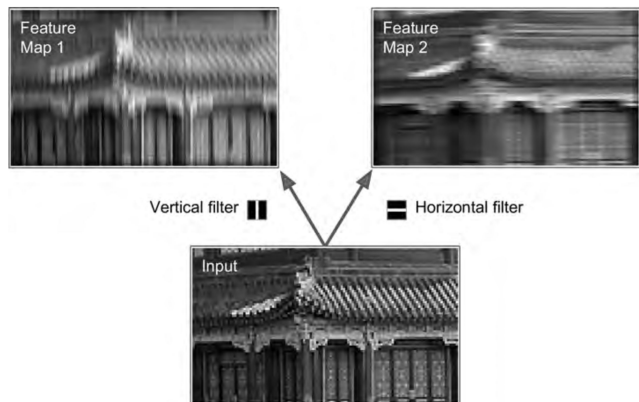


Figure [Source](#)

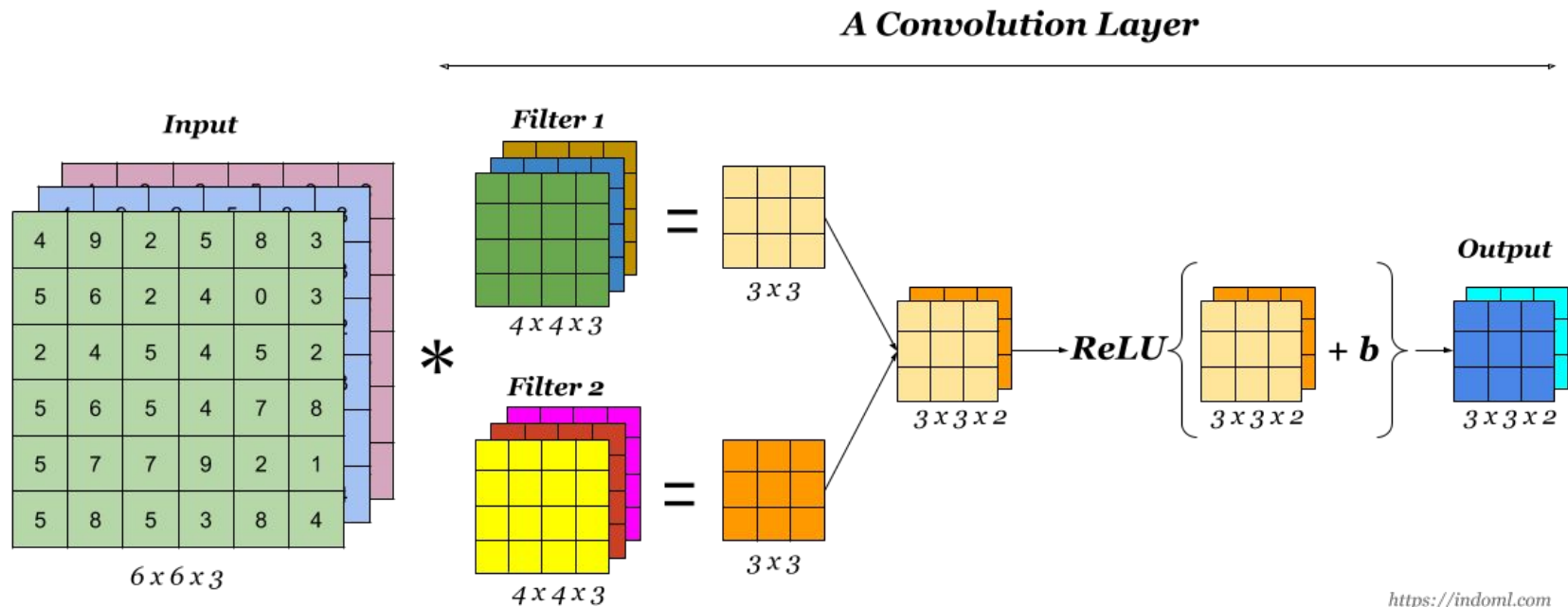
Stacking Multiple Filters (Feature Maps)



Figures from Aurélien Géron's [1st Ed. Book](#)

Figure [Source](#)

A Convolutional layer



<https://indoml.com>

Figure [Source](#)

Pooling Layer

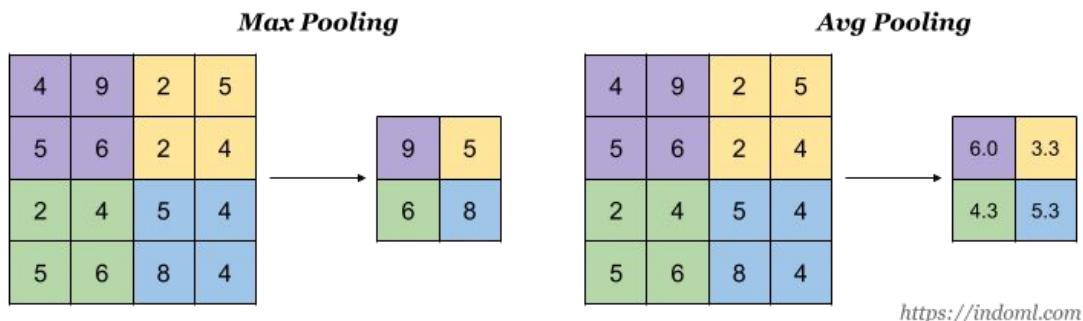
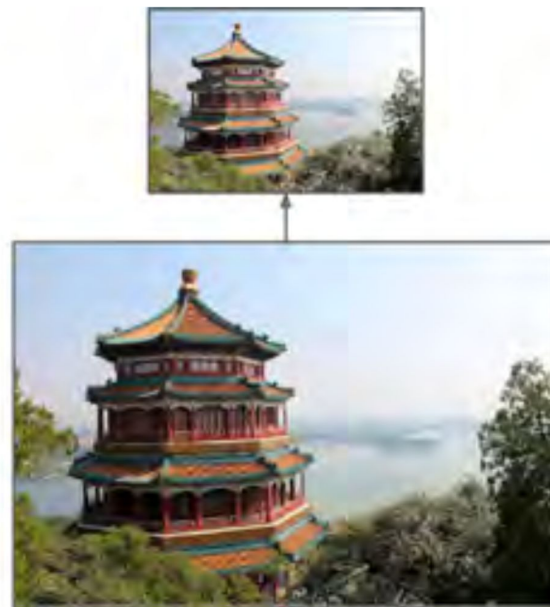


Figure [Source](#)

- Assuming downsampling will not lose the major information.



Figures from Aurélien Géron's [1st Ed. Book](#)

Architecture of Convolutional Neural Networks

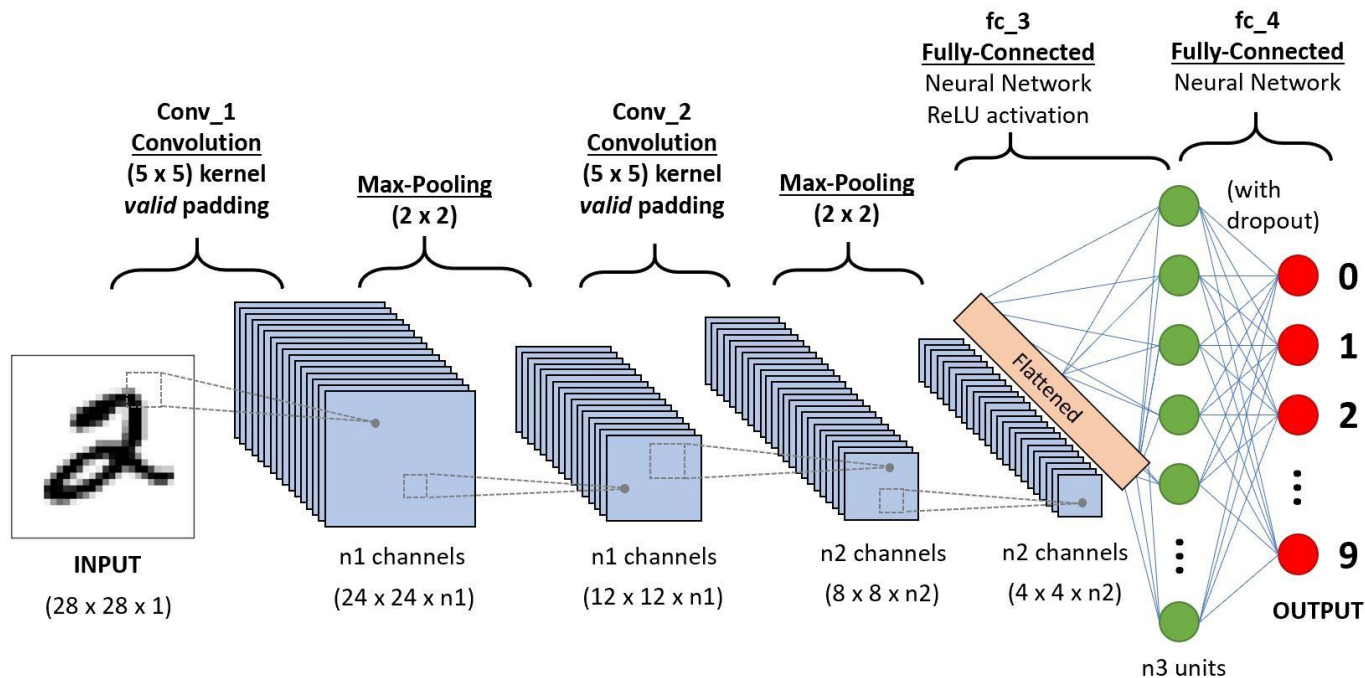


Figure [Source](#)

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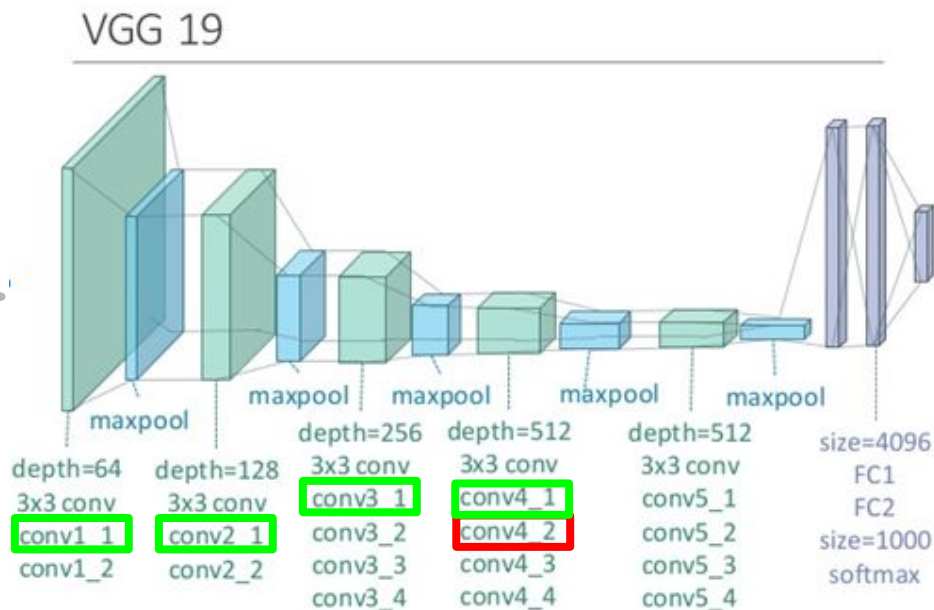
Convolutional layers as feature extractors



Content representation
of a photograph



Style representation
of the artwork



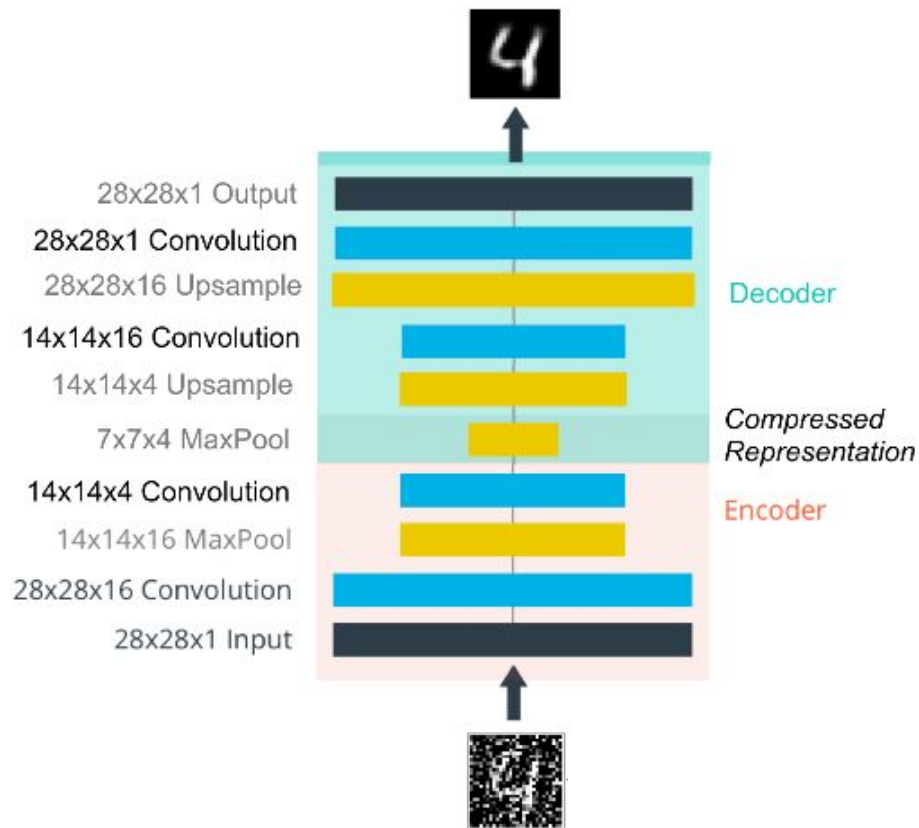
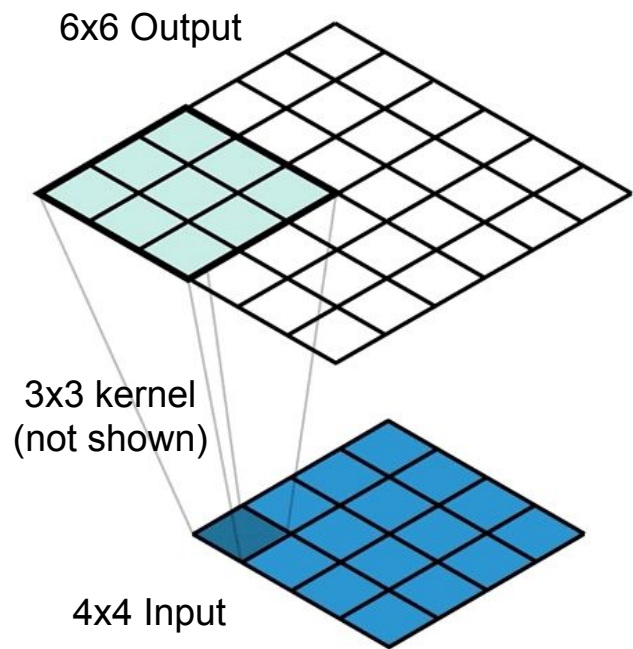
[Style Transfer
Paper \(2016\)](#)



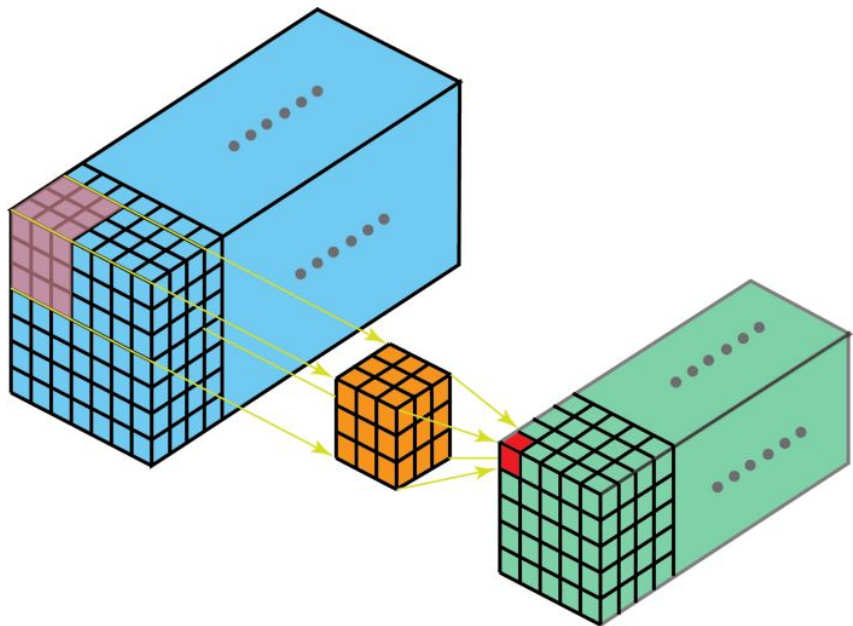
Style transferred
art image

Try it by yourself
using [Lucent!](#)

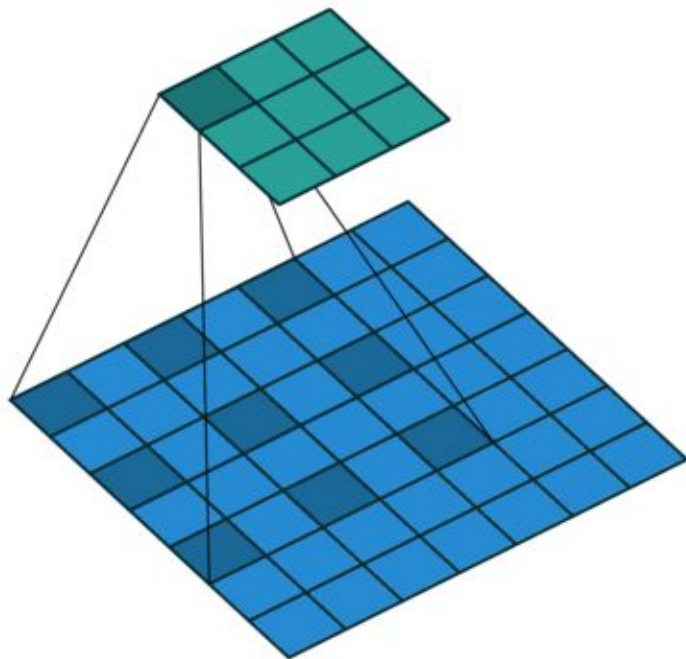
Convolution and “Deconvolution”: Autoencoder



3D Convolutions

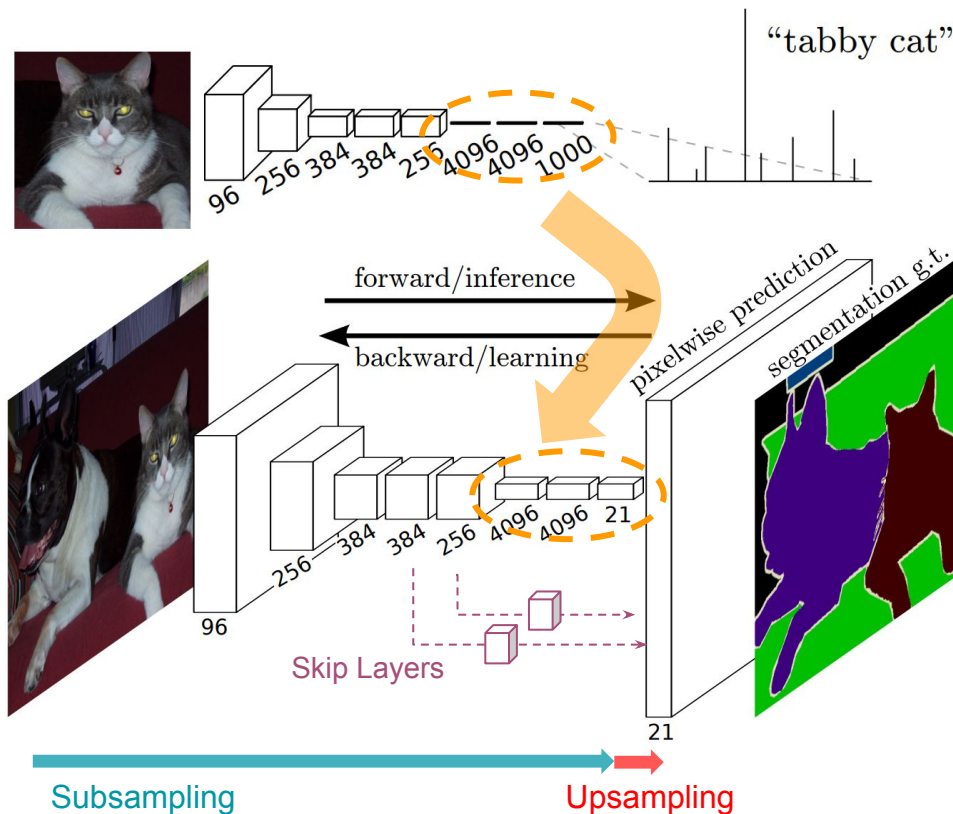


Dilated Convolutions



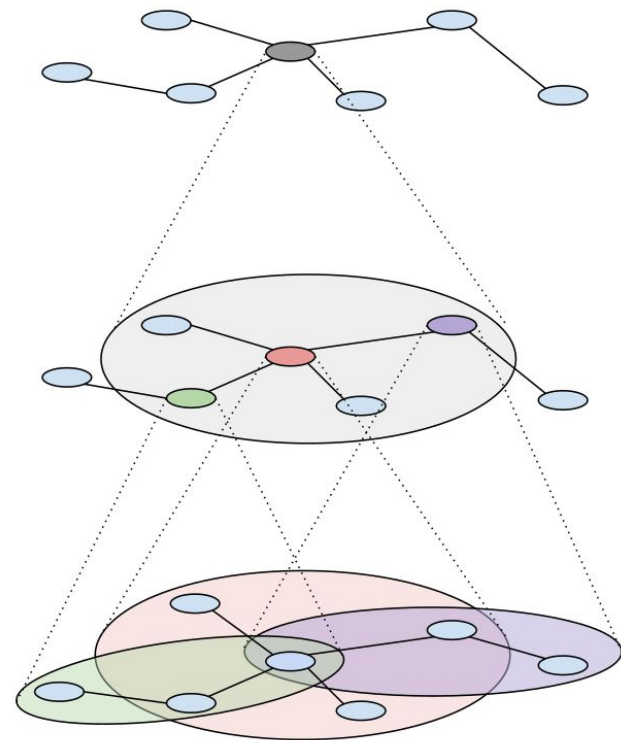
Fully Convolutional Neural Networks (FCNs)

- From image classification to semantic segmentation
 - Per-pixel classifications
 - CNN's fully connection layers:
 - throw away spatial coordinate
 - ~ applying an img-size kernel
- Ideas in [FCNs](#)
 - Convolutionalization
 - Upsampling by deconvolution
 - Skip layers
- Similar ideas and variants:
 - R-FCN, Mask R-FCN, SSD, ...



Graph Convolutional Neural Networks

- From images to graphs
 - Images: a special grid graph
 - Vertex: Pixel; Edges: indirectly connected to 4 neighbors
 - Graphs:
 - Embedding the info on both $V + E$
- Graph Neural Network:
 - Input: (X, A) , Latents: (H, A)
 - Predictions over nodes, graph, edges
- Graph Convolutional Neural Network:
 - Update with a symmetric normalisation on Adj Matrix
 - Popularized by Kipf & Welling, ICLR 2017
- MPNNs and GATs



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Construct CNN architecture for Dogs-vs.-Cats Problem

- 4 Convolution layers:

[`torch.nn.Conv2d\(in_channels, out_channels, kernel_size, ...\)`](#)

- Input size: (N, C_{in}, H, W)
- Output size: $(N, C_{out}, H_{out}, W_{out})$
- Activation function: [`torch.nn.functional.relu\(...\)`](#)

- MaxPooling layer:

[`torch.nn.max_pool2d\(...\)`](#)

- Kernel size: 2
- Default: stride=None, padding=0, dilation=1

- Flattened layer

- Manually flattening tensor by views

- Dense (linear) layer

[`torch.nn.Linear\(in_features, out_features\)`](#)

- Units: 512 and 2
- Activation: 'relu' and 'softmax'

```
class CatAndDogNet(nn.Module):
    def __init__(self):
        super().__init__()
        self.conv1 = nn.Conv2d(in_channels = 3, out_channels = 32, kernel_size=(3, 3))
        self.conv2 = nn.Conv2d(in_channels = 32, out_channels = 64, kernel_size=(3, 3))
        self.conv3 = nn.Conv2d(in_channels = 64, out_channels = 128, kernel_size=(3, 3))
        self.conv4 = nn.Conv2d(in_channels = 128, out_channels = 128, kernel_size=(3, 3))
        self.fc1 = nn.Linear(in_features= 128 * 7 * 7, out_features=512)
        self.fc2 = nn.Linear(in_features=512, out_features=2)

    def forward(self, X):
        X = F.relu(self.conv1(X))
        X = F.max_pool2d(X, 2)
        X = F.relu(self.conv2(X))
        X = F.max_pool2d(X, 2)
        X = F.relu(self.conv3(X))
        X = F.max_pool2d(X, 2)
        X = F.relu(self.conv4(X))
        X = F.max_pool2d(X, 2)
        X = X.view(-1, self.num_flat_features(X))
        X = F.relu(self.fc1(X))
        X = self.fc2(X)
        return X

    def num_flat_features(self, x):
        size = x.size()[1:] # all dimensions except the batch dimension
        num_features = 1
        for s in size:
            num_features *= s
        return num_features
```

Save and Load the model in PyTorch

- Need to save the trained model
 - Colab's active session time is limited.
 - Models can be re-used at user's end (e.g. browser with tf.js or phone with tf.lite)
- PyTorch 3 core functions:
 - `torch.save`: saves a serialized object to disk
 - `torch.load`: deserializes pickled object files to memory
 - `torch.nn.Module.load_state_dict`: loads parameters using a deserialized `state_dict`
- Recommended usage (for inference):
 - `torch.save(model.state_dict(), PATH)`
 - `model.load_state_dict(torch.load(PATH))`
 - `model.eval()`
- Saving & loading a checkpoint for resuming training ([link](#))

Before running the colab demo in this workshop

1. Register a Kaggle account
 - Kaggle.com → “Register”
2. Create Kaggle API token and download json file
 - Sign in → Your Profile → “Account” → “Create New API Token”
3. Join the competition → “Join Competition”
 - [Dogs-vs-Cats Challenge](#)

Colab Hands-on

bit.ly/LDL_cnn1

Questions to think about:

- How can we improve the performance of our CNNs model?
- Should we have to start from the scratch?
- Any guidelines to design a CNN model?
 - Kernel size? Channel number? Layer number?
- What's the latest development of CNNs?

See you next Friday!

Survey

bit.ly/**survey_cnn1**