HW4 Solutions

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1. First, let $y \in \mathcal{N}(A)$, $\forall z = A^T x \in \mathcal{R}(A^T)$.

$$\langle y, z \rangle = \langle y, A^T x \rangle$$
$$= \langle Ay, x \rangle$$
$$= \langle 0, x \rangle$$
$$= 0.$$

$$\Rightarrow y \in \mathcal{R}(A^T)^{\perp}$$
.

$$: \mathcal{N}(A) \subseteq \mathcal{R}(A^T)^{\perp}.$$

Second, let $y \in \mathcal{R}(A^T)^{\perp}$.

Thus

$$\langle y, A^T x \rangle = 0, \quad \forall x$$

 $\Rightarrow \langle Ay, x \rangle = 0, \quad \forall x$
 $\Rightarrow Ay = 0.$

$$\Rightarrow y \in \mathcal{N}(A).$$

$$\therefore \mathcal{R}(A^T)^{\perp} \subseteq \mathcal{N}(A).$$

Combining two steps, $\mathcal{R}(A^T)^{\perp} = \mathcal{N}(A)$.

2. We verify that x^* satisfies the optimality condition. The gradient of the objective function at x^* is

$$\nabla f_0(x^*) = (-1, 0, 2).$$

Therefore the optimality condition is that

$$\nabla f_0(x^*)^T(y-x) = -1(y_1-1) + 2(y_2+1) \ge 0$$

for all y satisfying $-1 \le y_i \le 1$, which is clearly true.

3. (a) Suppose that x is feasible in the original problem. Define $t = 1/(c^T x + d)$, $y = x/(c^T x + d)$. Then t > 0 and it is easily verified that t, y are feasible in the transformed problem, with the objective value $g_0(y,t) = f_0(x)/(c^T x + d)$.

Conversely, suppose that y, t are feasible for the transformed problem. We must have t > 0, by definition of the domain of the perspective function. Let x = y/t. We have $x \in \mathbf{dom} f_i$ for i = 0, ..., m. x is feasible in the original problem, because

$$f_i(x) = g_i(y, t)/t \le 0, \quad i = 1, ..., m, \qquad Ax = A(y/t) = b.$$

From the last equality, $c^T x + d = (c^T y + dt)/t = 1/t$, and hence,

$$t = 1/(c^T x + d),$$
 $f_0(x)/(c^T x + d) = t f_0(x) = g_0(y, t).$

Therefore x is feasible in the original problem, with objective value $g_0(y,t)$.

In conclusion, from any feasible point of the problem we can derive a feasible point of the other problem, with the same objective value.

(b) We must prove that the objective function, $f_0(x)/(c^Tx + d)$ is convex function. Suppose x_1, x_2 are feasible in the problem, and $0 \le \theta \le 0$.

$$\frac{f_0(\theta x_1 + (1 - \theta)x_2)}{c^T(\theta x_1 + (1 - \theta)x_2) + d} \le \frac{\theta f_0(x_1) + (1 - \theta)f_0(x_2)}{c^T(\theta x_1 + (1 - \theta)x_2) + d} \qquad (f_0(x) \text{ is convex})$$

$$= \frac{\theta f_0(x_1) + (1 - \theta)f_0(x_2)}{\theta (c^T x_1 + d) + (1 - \theta)(c^T x_2 + d)}$$

$$= \mu \frac{f_0(x_1)}{(c^T x_1 + d)} + (1 - \mu) \frac{f_0(x_2)}{(c^T x_2 + d)},$$

where
$$\mu = \frac{\theta(c^T x_1 + d)}{\theta(c^T x_1 + d) + (1 - \theta)(c^T x_2 + d)}$$
, and $0 \le u \le 1$.

Because $f_i(x)$ are convex functions, Ax - b is affine, this is a convex optimization problem.

4. This can be formulated as the LP

minimize
$$C = \sum_{i=1}^{n} \sum_{j=1}^{n} c_{ij} x_{ij}$$

subject to $b_i - \sum_{j=1}^{n} x_{ij} + \sum_{j=1}^{n} x_{ji} = 0$, $i = 1, ..., n$

$$\sum_{i=1}^{n} b_i = 1$$

$$l_{ij} \le x_{ij} \le u_{ij}$$
.

5. We make a change of variables

$$y = A^{1/2}(x - x_c), \qquad x = A^{-1/2}y + x_c,$$

and consider the problem

minimize
$$c^T A^{-1/2} y + c^T x_c$$

subject to $y^T y \le 1$.

The objective function that we minimize is a linear function over the unit ball with

$$-\nabla f(y) = -(A^{-1/2}c).$$

Then the solution is

$$y^* = -(1/||A^{-1/2}c||_2)A^{-1/2}c, x^* = x_c - (1/||A^{-1/2}c||_2)A^{-1}c.$$