

FalseType

```
classDiagram
    class FalseType {
    }
    class ros_message_traits {
        ::IsFixedSize< ::common
        ::PointCloudSensor_< Container
        Allocator > >
    }
    FalseType <|-- ros_message_traits
```

The diagram illustrates a class hierarchy. At the top is a class box labeled 'FalseType'. It has three horizontal compartments: the top one contains the class name, and the two below it are empty. Below this box is a blue arrow pointing upwards, ending in a hollow triangle. This arrow points to the top compartment of a larger class box below. This lower box is divided into three horizontal sections. The top section is shaded gray and contains the text 'ros::message_traits', '::IsFixedSize< ::common', '::PointCloudSensor_< Container', and 'Allocator > >'. The two bottom sections are also shaded gray but are empty.

ros::message_traits
::IsFixedSize< ::common
::PointCloudSensor_< Container
Allocator > >