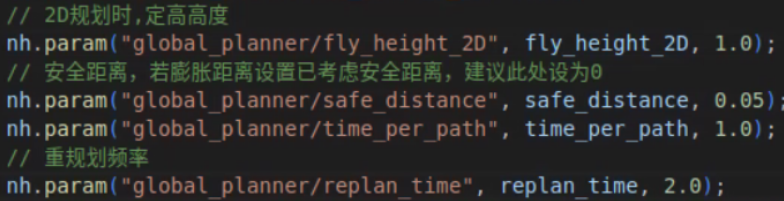
/home/amov/Prometheus/Modules/planning/global\_planning/src/global\_planner.cpp

1. 参数



fly\_height\_2D：1.0 👉 0.4

time\_per\_path：1.0 👉 1.5