### DroidScope:

Seamlessly Reconstructing the OS and Dalvik Semantic Views for Dynamic Android Malware Analysis

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### Android



**System Services** 

**Apps** 

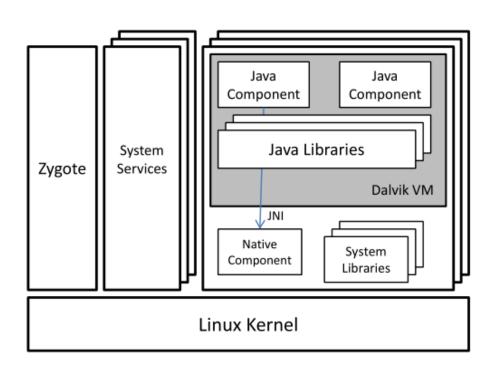


**Java Components** 

**Native Components** 

### Android





#### **Java Components**



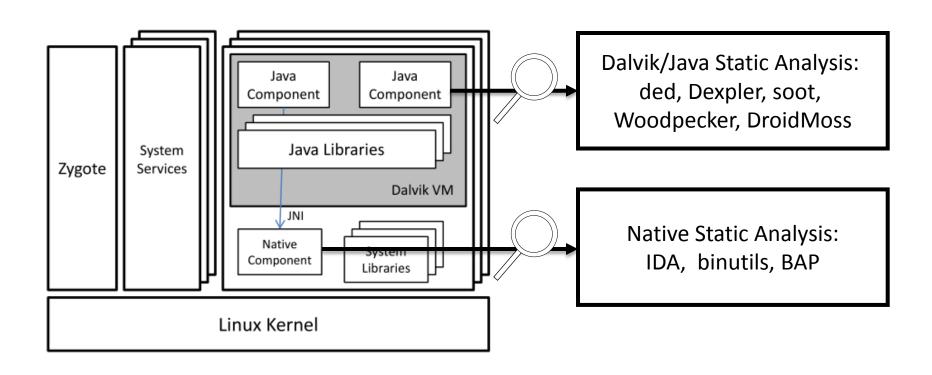
**Native Components** 

**System Services** 

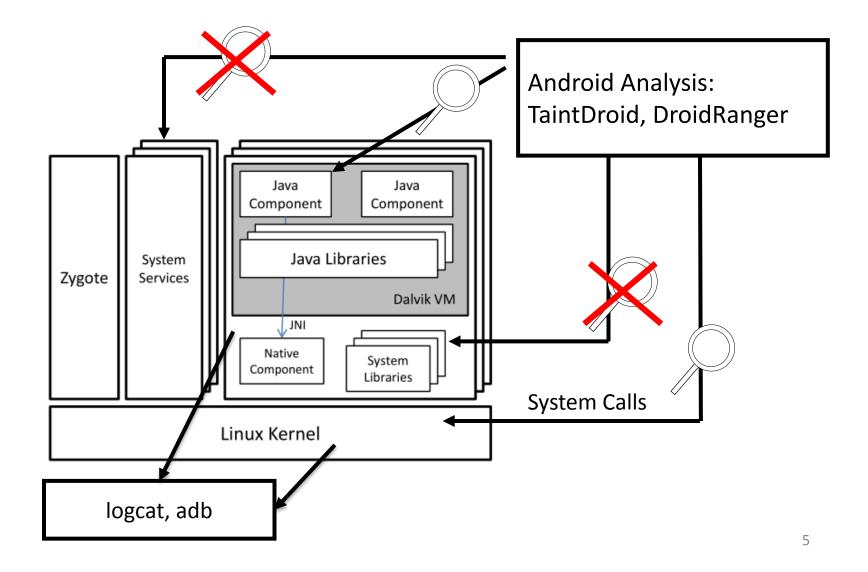
Apps

### Motivation: Static Analysis

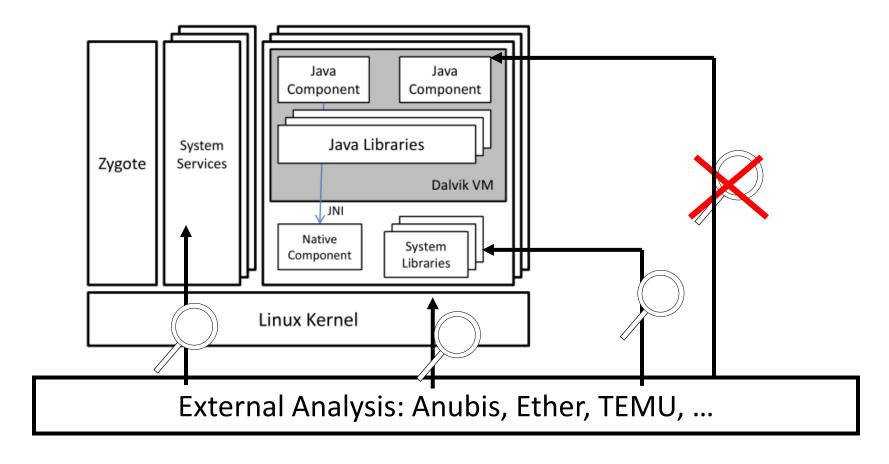




# Motivation: Dynamic Analysis

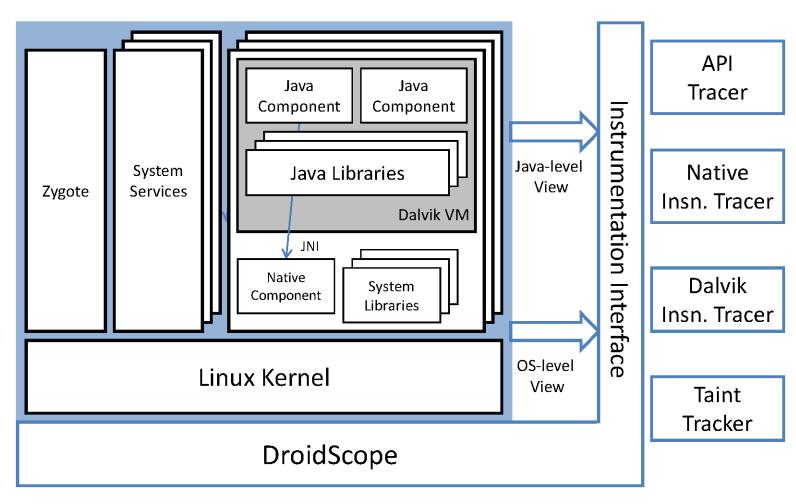


## Motivation: Dynamic Analysis



### DroidScope Overview





### Goals



- Dynamic binary instrumentation for Android
  - Leverage Android Emulator in SDK
  - No changes to Android Virtual Devices
  - External instrumentation
    - Linux context
    - Dalvik context
  - Extensible: plugin-support / event-based interface
  - Performance
    - Partial JIT support
    - Instrumentation optimization

### Roadmap



- > External instrumentation
  - Linux context
  - Dalvik context
- Extensible: plugin-support / event-based interface
- Evaluation
  - Performance
  - Usage

# Linux Context: Identify App(s)

- Shadow task list
  - pid, tid, uid, gid, euid, egid, parent pid, pgd, comm
  - *argv*[0]
- Shadow memory map
  - Address Space Layout Randomization (Ice Cream Sandwich)
- Update on
  - -fork, execve, clone, prctl and mmap2

### Java/Dalvik View



- Dalvik virtual machine
  - register machine (all on stack)
  - 256 opcodes
  - saved state, glue, pointed to by ARM R6, on stack in x86
- mterp
  - offset-addressing: fetch opcode then jump to (dvmAsmInstructionStart + opcode \* 64)
  - dvmAsmSisterStart for emulation overflow
- Which Dalvik opcode?
  - 1. Locate dvmAsmInstructionStart in shadow memory map
  - 2. Calculate opcode = (R15 dvmAsmInstructionStart) / 64.

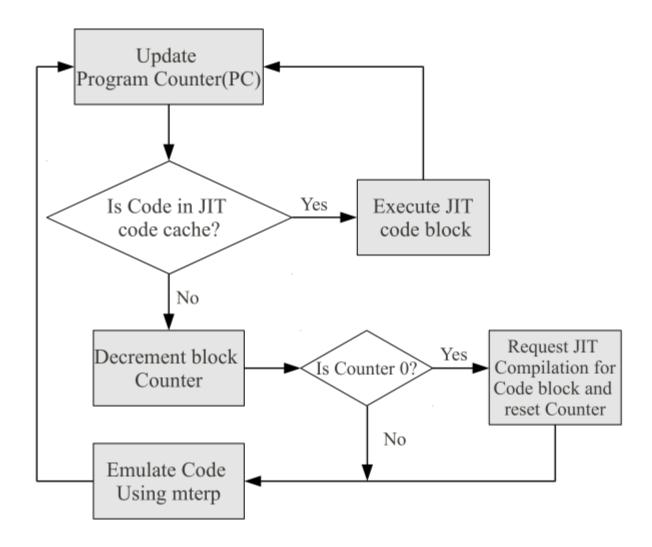
# Just In Time (JIT) Compiler



- Designed to boost performance
- Triggered by counter mterp is always the default
- Trace based
  - Multiple basic blocks
  - Multiple exits or chaining cells
  - Complicates external introspection
  - Complicates instrumentation

### Disabling JIT





### Roadmap



- ✓ External instrumentation
  - Linux context
  - Dalvik context
- Extensible: plugin-support / event-based interface
- Evaluation
  - Performance
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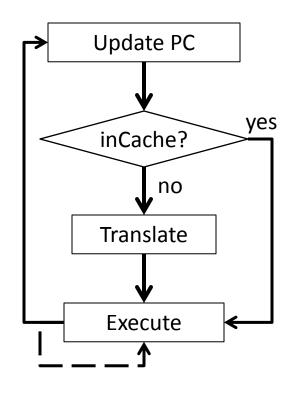
# Instrumentation Design

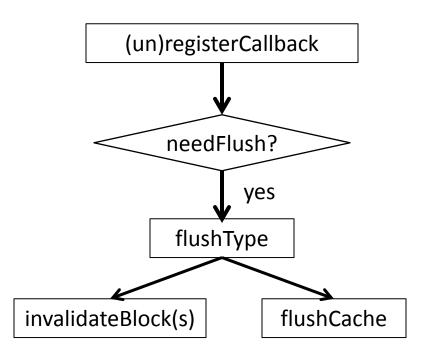


- Event based interface
  - Execution: e.g. native and Dalvik instructions
  - Status: updated shadow task list
- Query and Set, e.g. interpret and change cpu state
- Performance
  - Example: Native instructions vs. Dalvik instructions
  - Instrumentation Optimization

## Dynamic Instrumentation







### Instrumentation



	NativeAPI	LinuxAPI	DalvikAPI
Even	instruction begin/end	context switch	Dalvik instruction begir
	register read/write	system call	method begin
	memory read/write	task begin/end	
	block begin/end	task updated	
		memory map updated	
uery &	memory read/write	query symbol database	query symbol database
	memory r/w with pgd	get current context	interpret Java object
	register read/write	get task list	get/set DVM state
	taint set/check		taint set/check objects
			disable JIT

### Dalvik Instruction Tracer (Example)

```
1. void opcode callback(uint32 t opcode) {
      printf("[%x] %s\n", GET_RPC, opcodeToStr(opcode));
 2.
 3. }
 4.
 5. void module_callback(int pid) {
 6.
      if (bInitialized | (getIBase(pid) == 0))
 7.
        return;
 8.
 9.
      getModAddr("dfk@classes.dex", &startAddr, &endAddr);
10.
11.
      addDisableJITRange(pid, startAddr, endAddr);
12.
      disableJITInit(getGetCodeAddrAddress(pid));
13.
      addMterpOpcodesRange(pid, startAddr, endAddr);
      dalvikMterpInit(getIBase(pid));
14.
      registerDalvikInsnBeginCb(&opcode_callback);
15.
16.
     bInitialized = 1;
17. }
18.
19. void _init() {
20.
      setTargetByName("com.andhuhu.fengyinchuanshuo");
21.
      registerTargetModulesUpdatedCb(&module callback);
22. }
```

### Plugins



#### API Tracer

- System calls
  - open, close, read, write, includes parameters and return values
- Native library calls
- Java API calls
  - Java Strings converted to C Strings
- Native and Dalvik Instruction Tracers
- Taint Tracker
  - Taints ARM instructions
  - One bit per byte
  - Data movement & Arithmetic instructions including barrel shifter
  - Does not support control flow tainting

### Roadmap



- ✓ External instrumentation
  - Linux context
  - Dalvik context
- ✓ Extensible: plugin-support / event-based interface
- **Evaluation** 
  - Performance
  - Usage

## Implementation



- Configuration
  - QEMU 0.10.50 part of Gingerbread SDK
  - Gingerbread
    - "user-eng"
    - No changes to source
  - Linux 2.6.29, QEMU kernel branch

### Performance Evaluation



#### Seven free benchmark Apps

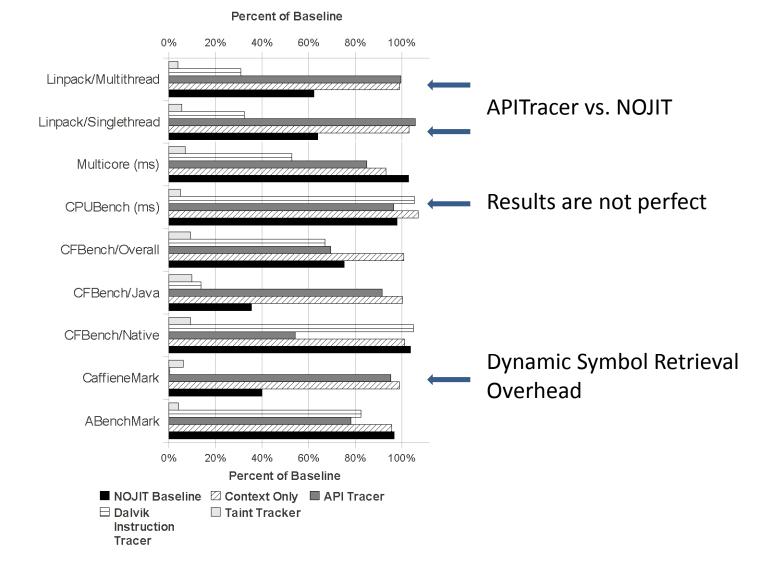
- AnTuTu Benchmark
- (ABenchMark) by AnTuTu
- CaffeineMark by Ravi Reddy
- CF-Bench by Chainfire
- Mobile processor benchmark (Multicore) by Andrei Karpushonak
- Benchmark by Softweg
- Linpack by GreeneComputing

#### • Six tests repeated five times each

- Baseline
- NO-JIT Baseline uses a build with JIT disabled at runtime
- Context Only
- API Tracer
- Dalvik Instruction Trace
- Taint Tracker

### Select Performance Results





# Usage Evaluation



- Use DroidScope to analyze real world malware
  - API Tracer
  - Dalvik Instruction Tracer + dexdump
  - Taint Tracker taint IMEI/IMSI @move\_result\_object after getIMEI/getIMSI
- Analyze included exploits
  - Removed patches in Gingerbread
  - Intercept system calls
  - Native instruction tracer

### Droid Kung Fu



### Three encrypted payloads

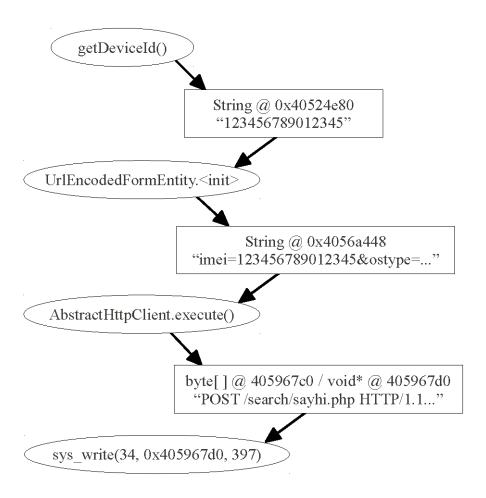
- ratc (Rage Against The Cage)
- killall (ratc wrapper)
- gjsvro (udev exploit)

#### Three execution methods

- piped commands to a shell (default execution path)
- Runtime.exec() Java API (instrumented path)
- JNI to native library terminal emulator (instrumented path)
- Instrumented return values for isVersion221 and getPermission methods

## Droid Kung Fu: TaintTracker





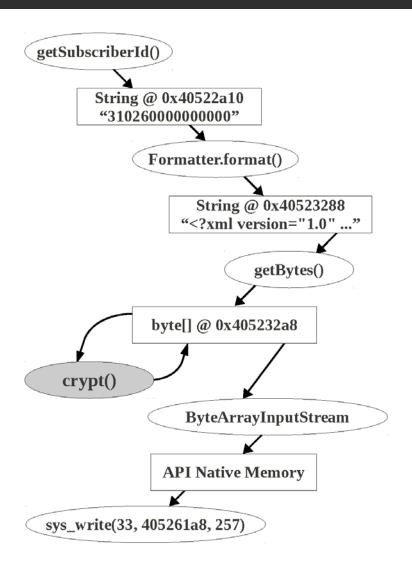
### DroidDream



- Same payloads as DroidKungFu
- Two processes
  - Normal *droiddream* process clears logcat
  - droiddream: remote is malicious
- xor-encrypts private information before leaking
- Instrumented sys\_connect and sys\_write

### Droid Dream: TaintTracker





### DroidDream: crypt trace



```
[43328f40] aget-byte v2(0x01), v4(0x405232a8), v0(186)
 Getting Tainted Memory: 40523372(2401372)
 Adding M@410accec(42c5cec) len = 4
[43328f44] sget-object v3(0x0000005e), KEYVALUE// field@0003
[43328f48] aget-byte v3(0x88), v3(0x4051e288), v1(58)
[43328f4c] xor-int/2addr v2(62), v3(41)
 Getting Tainted Memory: 410accec(42c5cec)
 Adding M@410accec(42c5cec) len = 4
[43328f4e] int-to-byte v2(0x17), v2(23)
 Getting Tainted Memory: 410accec(42c5cec)
 Adding M@410accec(42c5cec) len = 4
[43328f50] aput-byte v2(0x17), v4(0x405232a8), v0(186)
 Getting Tainted Memory: 410accec(42c5cec)
 Adding M@40523372(2401372) len = 1
```

### Summary



### DroidScope

- Dynamic binary instrumentation for Android
- Built on Android Emulator in SDK
- External Introspection & Instrumentation support
- Four plugins
  - API Tracer
  - Native Instruction Tracer
  - Dalvik Instruction Tracers
  - TaintTracker
- Partial JIT support

### Related Works



#### Static Analysis

- ded, Dexpler, soot
- Woodpecker, DroidMoss

#### Dynamic Analysis

- TaintDroid
- DroidRanger
- PIN, Valgrind, DynamoRIO
- Anubis, TEMU, Ether, PinOS

#### Introspection

- Virtuoso
- VMWatcher

## Challenges



- JIT
  - Full JIT support
  - Flushing JIT cache
- Emulation detection
  - Real Sensors: GPS, Microphone, etc.
  - Bouncer
- Timing assumptions, timeouts, events
- Closed source systems, e.g. iOS

# Questions?

Q0. Where can I get DroidScope?

