High Performance Computing (Master) in WS19

____ Exercise 2: one core programming, performance limitations, BLAS. ____

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Status:

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First, we have to provide a few basic benchmarks examples (A)-(E):

(A) The inner product of two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^N$:

$$\langle \mathbf{x}, \mathbf{y} \rangle := \sum_{i=0}^{N-1} x_i \cdot y_i$$

Use $x_i := (i \mod 219) + 1$ and $y_i := 1.0/x_i$ as test data. (Why!?)

(B) Matrix-Vector product using an $M \times N$ matrix A and vectors $\mathbf{x} \in \mathbb{R}^N$, $\mathbf{b} \in \mathbb{R}^M$:

$$\mathbf{b} := A \cdot \mathbf{x}$$

$$b_i := \sum_{j=0}^{N-1} A_{i,j} x_j \qquad \forall i = 0, \dots, M-1$$

Use $A_{i,j} := ((i+j) \mod 219) + 1$ and $x_j := 1.0/A_{17,j}$ as test data. (Why !?) See example code¹ and docu².

(C) Matrix-Matrix product: $C_{M\times N} := A_{M\times L} \cdot B_{L\times N}$

$$C_{i,j} := \sum_{k=0}^{L-1} A_{i,k} \cdot B_{k,j}$$
 $\forall i = 0, \dots, M-1, \quad \forall j = 0, \dots, N-1$

(D) Evaluation of a polynomial function of degree p with given coefficients $a_k, k = 0, \ldots, p$ for a vector $\mathbf{x} \in \mathbb{R}^N$, i.e., $\mathbf{y} := \mathtt{poly}_p(\mathbf{x}) \in \mathbb{R}^N$ with

$$y_i := \operatorname{poly}_p(x_i) = \sum_{k=0}^p a_k \cdot x^k \qquad \forall i = 0, \dots, N-1$$

¹http://imsc.uni-graz.at/haasegu/Lectures/Math2CPP/Examples/intro_vector_densematrix.tar

 $^{^2}$ http://imsc.uni-graz.at/haasegu/Lectures/Math2CPP/Examples/intro_vector_densematrix/html

(E) Alternative i):

Solve a sparse system of linear equations $K\underline{u} = \underline{f}$ resulting from a finite element discretization via the Jacobi iteration (code³ and docu⁴).

$$\underline{u}^{k+1} = \underline{u}^k + \omega D^{-1} \left(\underline{f} - K \cdot \underline{u}^k \right) \qquad k = 0, 1, 2, \dots$$

with $\underline{u}^0=0$, the right hand side $\underline{\mathbf{f}}$ and the positive definit and symmetric system matrix K.

See $\S4-\S5$ of an old exercise⁵ for details.

(F) Alternative ii):

Solving a system of equations originating from time fractional PDEs in 1D. The challenge consists in solving a block tridiagonal system with large square matrices as blocks.

$$\begin{pmatrix}
M \\
-B & A & -B \\
-B & A & -B \\
-B & A & -B \\
M
\end{pmatrix}_{n_b \times n_b}$$

$$\underline{u} = \underline{f} \tag{1}$$

Each block matrix M, A, B has dimensions $n_t \times n_t$.

System (1) is solved for $n_b := 2^k + 1$ via cyclic reduction [§4.41 in Haase at Teubner].

³http://imsc.uni-graz.at/haasegu/Lectures/Math2CPP/Codes/seq/jacobi_oo_stl.tar

⁴http://imsc.uni-graz.at/haasegu/Lectures/Math2CPP/Codes/seq/jacobi_oo_stl/html

 $^{^5}$ https://imsc.uni-graz.at/haasegu/Lectures/Math2CPP/Codes/par/mpi_course.pdf

1. Measure the achieved floating point performance and and memory bandwidth of your test system by compiling and using the codes⁶ for stream and flops. Have a look at the first lines in the source code for compiling options Benchmarking is science by itself - we need the above codes to have some numbers in our hands.

(1 Pkt.)

2. Some counting and calculating for benchmarks (A)–(D):

(1 Pkt.)

- Calculate the amount of memory needed for your data as function of the data dimensions M, N, L, p depending on the chosen data type.
- Calculate the number of floating point operations (+, -, *, / count as one operation) as function of the data dimensions M, N, L, p.
- Express the number of Read/Write operations from/to memory as function of the data dimensions M, N, L, p and the chosen data type.
- 3. Implement benchmarks (A)–(D) in C++ as **separate functions** where all data will be transferred via the parameter list, i.e., no global data are allowed. The data types for **double precision** should be preferred, but you might use also template functions. (4 Pkt.) In order to simplify code development and benchmarking you are encouraged to use the provided template for the scalar product. After extracting the files you have to type

make run

into your (LINUX-) Terminal to compile, link and run the code.

4. Measure the runtime of your implementations. Calculate the achieved double precision performance in GFLOPS and the achieved memory bandwidth in GiB/sec for your implementations.

(1 Pkt.)

Take care that you use compiler options wrt. optimization, i.e., "-O0" versus "-O3" and more advanced options.

Chose the data dimensions for each benchmark such that the code runs at least 10 sec. (Why?!), i.e.. If the runtime for (A) is too low although you use already 50% of your memory than you have to increase NLOOPS in the template accordingly. The memory required to store your data should be approximately 10–100 times larger than your largest cache.

5. Some special tasks:

(2 Pkt.)

- (a) Measure the performance in (A) by replacing the call to < x,y> by a call to $\parallel x \parallel:=\sqrt{\sum_{i=0}^{N-1}x_i^2}$. What do you observe? Why?
- (b) Implement a version of the scalar product that avoids round-off errors by using the Kahan⁷ summation. Check the run time.
- (c) Assume row-wise access to matrix A in (C). Compare performance issues for row-wise access of A versus column-wise access of A.

 Is there a chance to accelerate also the column-wise access function?

⁶http://imsc.uni-graz.at/haasegu/Lectures/Math2CPP/Examples/stream.tar

⁷https://en.wikipedia.org/wiki/Kahan_summation_algorithm

- 6. Write additional functions for (A)-(C) that use the cBLAS⁸ library⁹, especially the calls DOT, GEMV, GEMM, see the general reference card¹⁰ or the cblas description¹¹, see the example for cblas_dgemv¹². Measure run time and calculate GFLOPS and GiB/sec. (4 Pkt.) Hints:
 - Take care for the Leading Dimensions (LDA, LDB) in the parameter list for a dense matrix in BLAS. See the example for DGEMM in stackoverflow¹³ at IBM¹⁴ and at Intel¹⁵.
 - The LAPACK¹⁶ library is a superset of the BLAS routines based on FORTRAN. Note the additional parameter for cblas_dgemv from cBLAS¹⁷ in comparison to dgemv_from BLAS¹⁸.
 - The LAPACK interface including BLAS requires a columnwise storage of the matrix entries. Using the extension LAPACKE¹⁹ allows an optional rowise storage of the matrices similar to cBLAS.
 - Install the libraries in Ubuntu via sudo apt-get install libblas-dev liblapack-dev liblapacke-dev
 - (**) What is the best BLAS available? Atlas²⁰ with Fortran-Blas and cblas²¹, uBLAS²² (C++ boost) or the MKL-library by INTEL?
- 7. Solve a dense system of equations via factorization LAPACKE_dgetrf²³ of matrix $A_{n\times n}$ and application of the factorized matrix LAPACKE_dgetrs²⁴ to multiple right hand sides $b_{n\times n_{rhs}}$. (4 Pkt.)
 - Check for the correct result.
 - How does the solution time per right hand side depend on n_{rhs} for a fixed $n \in \{500, 1000, 2000\}$?
- 8. Run (E), the Jacobi code from directory seq/jacobi . (1 Pkt.)
- 9. Alternatively to 6.-8.: Run and improve (F) (9 Pkt.)

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8http://www.netlib.org/blas/faq.html
9ubuntu: libatlas-dev, libatlas-base-dev

10http://www.netlib.org/blas/blasqr.pdf
11https://software.intel.com/en-us/mkl-developer-reference-c-blas-and-sparse-blas-routines
12http://www.netlib.org/lapack/explore-html/d1/dff/cblas__example1_8c_source.html
13http://stackoverflow.com/questions/28654438/matrix-vector-product-with-dgemm-dgemv
14http://www.ibm.com/support/knowledgecenter/SSFHY8_5.2.0/com.ibm.cluster.essl.v5r2.essl100.
doc/am5gr_hsgemm.htm
15https://software.intel.com/en-us/node/429920
16http://www.netlib.org/lapack/
17https://software.intel.com/en-us/mkl-developer-reference-c-cblas-gemv
18http://www.netlib.org/lapack/explore-html/d7/d15/group__double__blas__level2_
gadd421a107a488d524859b4a64c1901a9.html
19http://www.netlib.org/lapack/explore-html/dir_01b0e9dedaacaaad221a964f5affeb80.html
20/usr/share/doc/libatlas-doc
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²¹http://www.gnu.org/software/gsl/manual/html_node/GSL-CBLAS-Library.html

²²https://www.boost.org/doc/libs/1_71_0/libs/numeric/ublas/doc/index.html

²³http://www.netlib.org/lapack/explore-html/d2/d96/lapacke__dgetrf_8c_ a285c069fa65d2b9954737240e0779889.html

²⁴http://www.netlib.org/lapack/explore-html/d8/d54/lapacke__dgetrs_8c_ a044782d17dd9592ab7d2b5b4f5c0f7a7.html