Makespan Scheduling

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Section 1

Formalism

Formalism of an Optimization Problem

Definition 2.3.2.2. An optimization problem is a 7-tuple $U = (\Sigma_I, \Sigma_O, L, L_I, \mathcal{M}, cost, goal)$, where

- (i) Σ_I is an alphabet, called the input alphabet of U,
- (ii) Σ_O is an alphabet, called the output alphabet of U,
- (iii) $L \subseteq \Sigma_I^*$ is the language of feasible problem instances,
- (iv) $L_I \subseteq L$ is the language of the (actual) problem instances of U,
- (v) \mathcal{M} is a function from L to $Pot(\Sigma_{\mathcal{O}}^*)$, 30 and, for every $x \in L$, $\mathcal{M}(x)$ is called the set of feasible solutions for x,
- (vi) cost is the cost function that, for every pair (u, x), where $u \in \mathcal{M}(x)$ for some $x \in L$, assigns a positive real number cost(u, x),
- (vii) $goal \in \{minimum, maximum\}.$

Makespan Scheduling Problem (MS)

Input: Positive integers p_1, p_2, \dots, p_n and an integer $m \geq 2$ for some $n \in \mathbb{N} - \{0\}$.

 $\{p_i \text{ is the processing time of the } i\text{th job on any of the } m \text{ available machines}\}.$

Constraints: For every input instance (p_1, \ldots, p_n, m) of MS,

 $\begin{array}{ll} \mathcal{M}(p_1,\ldots,p_n,m) = \{S_1,S_2,\ldots,S_m\,|\,S_i\subseteq\{1,2,\ldots,n\} \text{ for } i=1,\ldots,m,\,\bigcup_{k=1}^m S_k=\{1,2,\ldots,n\}, \text{ and } S_i\cap S_j=\emptyset \text{ for } i\neq j\}.\\ \{\mathcal{M}(p_1,\ldots,p_n,m) \text{ contains all partitions of } \{1,2,\ldots,n\} \text{ into } m \text{ subsets. The meaning of } (S_1,S_2,\ldots,S_m) \text{ is that, for } i=1,\ldots,m, \text{ the jobs with indices from } S_i \text{ have to be processed on the } i\text{th} \end{array}$

machine}. Costs: For each $(S_1, S_2, \dots, S_m) \in \mathcal{M}(p_1, \dots, p_n, m)$.

 $cost((S_1,...,S_m),(p_1,...,p_n,m)) = \max \{\sum_{l \in S_i} p_l | i = 1,...,m \}.$

Goal: minimum.

Input

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Input

Input

- $\Sigma_I := \{0, 1, \#\}$
- A *number* is a word of $\{0,1\}$.
 - 1
 - 101
- An *instance* is a sequence of numbers with '#'s spliting them.
 - A number is an instance.
 - If A, B are two instances, then A # B is an instance.
 - There is no other way to obtain an instance.
- L is the set of all instances. L_I is a subset of L. $(L_I = L)$ generates the generalized problem.

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Output

Output

- $\Sigma_O := \{0, 1, \&, \#\}$
- An *load* is a sequence of numbers with '&'s spliting them.
 - A number is a load.
 - If A, B are two loads, then A&B is a load.
 - There is no other way to obtain a load.
- An schedule is a sequence of loads with '#'s spliting them.
 - A load is a schedule.
 - If A, B are two schedules, then A#B is a schedule.
 - There is no other way to obtain a schedule.
- $\mathcal{M}(x)$ is the set of all schedules s that if x contains n '#'s and the last number is m, then s contains m-1 '#'s and its numbers are 1 to n.

cost

 cost(s) is the maximum value of sums of numbers in each set of s.

Section 2

The (Sorted) Greedy Approach

Description

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Algorithm 4.2.1.3 (GMS (GREEDY MAKESPAN SCHEDULE)).
Input: I = (p_1, \dots, p_n, m), n, m, p_1, \dots, p_n positive integers and m \ge 2.
Step 1: Sort p_1, \ldots, p_n.
         To simplify the notation we assume p_1 \geq p_2 \geq \cdots \geq p_n in the rest
         of the algorithm.
Step 2: for i = 1 to m do
             begin T_i := \{i\}:
                Time(T_i) := p_i
             end
         In the initialization step the m largest jobs are distributed to the
         m machines. At the end, T_i should contain the indices of all jobs
         assigned to the ith machine for i = 1, ..., m.
Step 3: for i = m + 1 to n do
             begin compute an l such that
                Time(T_i) := \min\{Time(T_i)|1 < j < m\};
                T_I := T_I \cup \{i\}:
                Time(T_l) := Time(T_l) + p_i
             end
Output: (T_1, T_2, \ldots, T_m).
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Why is it not optimal?

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Why is it not optimal?



A Lower Bound

In fact, (sorted) GMS is proved to be ⁴/₃-approximation by R.
L. Graham in 1969. Consider the following instance (See Bounds on Multiprocessing Timing Anomalies for details):

•

$$I = (2m-1, 2m-1, 2m-2, 2m-2, \cdots, m+1, m+1, m, m, m)$$

[2]

$$R_{GMS}(I) = \frac{4}{3} - \frac{1}{3m}$$

A Tight Bound

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A Tight Bound



- In fact, $\frac{4}{3}$ is not only a lower bound, but also an upper bound.
- Unfortunately, I haven't go through the proof. If anyone is interested, see [Graham, 1969].

Section 3

Acknowledgements



J. Hromkovič.

Algorithmics for Hard Problems: Introduction to Combinatorial Optimization, Randomization, Approximation, and Heuristics. Texts in Theoretical Computer Science. An EATCS Series. Springer Berlin Heidelberg, 2013.



Ronald L. Graham.

Bounds on multiprocessing timing anomalies. *SIAM journal on Applied Mathematics*, 17(2):416–429, 1969.