

Jing Huang

huangjing@mae.cuhk.edu.hk [🏠](#) [🌐](#) [in](#)

Hong Kong Science Park, Hong Kong SAR

EDUCATION

The Chinese University of Hong Kong (CUHK)	2017 - 2022
Ph.D. in Mechanical and Automation Engineering	Hong Kong
– Research Interests: robot manipulation, robot vision, motion and path planning	
Tsinghua University	2013 - 2017
B.Eng. in Automotive and Mechanical Engineering	Beijing

WORK EXPERIENCE

University of California San Diego	2024 - present
Exchange Postdoctoral Fellow at Department of Computer Science and Engineering	San Diego
Multi-Scale Medical Robotics Center, CUHK	2023 - present
Postdoctoral Fellow	Hong Kong

PUBLICATION

1. **Jing Huang**, Yunxi Tang, and Kwok Wai Samuel Au, "Homotopic path set planning for robot manipulation and navigation", *Robotics: Science and Systems (RSS)*, 2024. [\[PDF\]](#) [\[Video\]](#)
2. Yunxi Tang, Xiangyu Chu, **Jing Huang**, and K. W. Samuel Au, "Learning-based MPC with safety filter for constrained deformable linear object manipulation," *IEEE Robotics and Automation Letters (RAL)*, 2024. [\[PDF\]](#) [\[Video\]](#)
3. **Jing Huang**, Xiangyu Chu, Xin Ma, and K. W. Samuel Au, "Deformable object manipulation with constraints using path set planning and tracking," *IEEE Transactions on Robotics (TRO)*, 2023. [\[PDF\]](#) [\[Video\]](#)
4. Xiangyu Chu, Shengzhi Wang, Minjian Feng, Yuxuan Zhao, Jiayi Zheng, **Jing Huang**, and K. W. Samuel Au, "Model-free large-scale cloth spreading with mobile manipulation: Initial feasibility study," *IEEE International Conference on Automation Science and Engineering (CASE)*, 2023. [\[PDF\]](#)
5. **Jing Huang** and K. W. Samuel Au, "Task-oriented grasping position selection in deformable object manipulation," *IEEE Robotics and Automation Letters (RAL)*, 2022. [\[PDF\]](#) [\[Video\]](#)
6. **Jing Huang**, Yuanpei Cai, Xiangyu Chu, Russell H. Taylor, and K. W. Samuel Au, "Non-fixed contact manipulation control framework for deformable objects with active contact adjustment," *IEEE Robotics and Automation Letters (RAL)*, *ICRA option*, 2021. [\[PDF\]](#) [\[Video\]](#)
7. **Jing Huang**, Yuanpei Cai, Xiangyu Chu, and K. W. Samuel Au, "Task-oriented contact adjustment in deformable objects manipulation with non-fixed contact," *Workshop on Managing Deformation: A Step Towards Higher Robot Autonomy, IEEE/RSJ International Conference on Intelligent Robotics and Systems (IROS)*, 2020. [\[PDF\]](#)
8. Ru Yang, **Jing Huang**, and Ping Guo, "Frequency dependence of levitation force in near-field acoustic levitation." *International Symposium on Flexible Automation*, 2018. [\[PDF\]](#)

TEACHING

Department of Mechanical and Automation Engineering, CUHK	
– MAEG4070 Engineering Optimization	Spring, 2020
– ENGG1410C Linear Algebra and Vector Calculus for Engineers	Spring, 2019
– MAEG3050 Introduction to Control Systems	Fall, 2018

PROFESSIONAL SERVICE & CODING

Reviewer: RAL, ICRA, IROS Coding: C/C++, MATLAB, Python, ROS