Università
della
Svizzera
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Faculty
of Informatics
Institute of
Computational
Science
ICS

Stochastic Methods

Solving optimization problems,
PCA in practice – feature selection, compression

Seminar 3

Spring 2019

<u>Outline</u>

- 1. More complaints about official tSNE Matlab implementation: magic parameters?
- 2. Some optimization problems
 - Equality constrained problem
 - Inequality constrained problem
- 3. PCA in practice:
 - feature selection
 - compression

2.) Some optimization problems

<u>Problem 1:</u> Find the dimensions of the box with largest volume if the total surface area is s>0.

Problem 2:

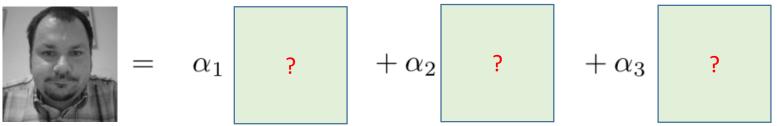
Find $\arg \min 4x^2 + 10y^2 - 3$ s.t. $x - y \ge 1$

3a) PCA: feature selection

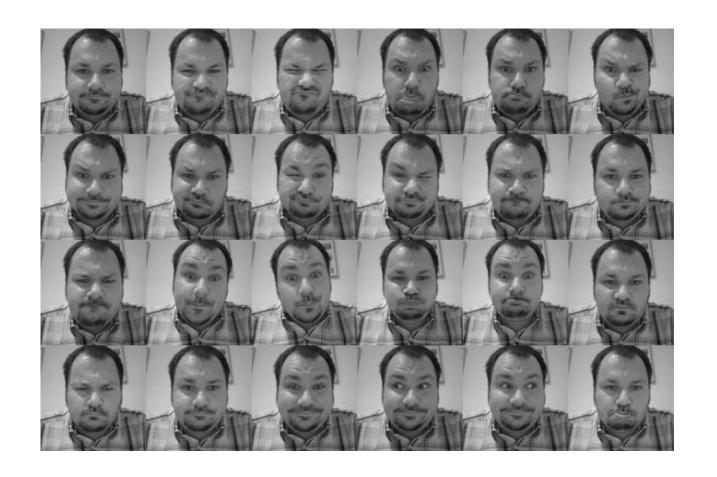




Find optimal basis such that every image can be written as linear combination:



("orthonormal" images)



See Atelier 3



Find optimal basis such that every image can be written as linear combination:



$$+\alpha_2$$

? $+\alpha_3$

? +

+ orig. mean

"optimal" approximation

- Matlab is ready for working with images (see "imread", "imwrite")
- Instead of working with rectangular images work with vectorized images (see "reshape")
- We can use command "pca", but it is too boring, let's implement it from the scratch
- Not from the total scratch use "eig"/"eigs"

- 1. substract mean value from the data
- 2. construct covariance matrix
- 3. compute m largest eigenvalues and corresponding orthonormal eigenvectors, construct Q
- 4. project the data $X_{\text{reduced}} = Q^T X_{\text{original}}$

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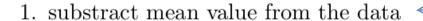
1. substract mean value from the data

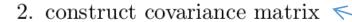


"Mean" image

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"Mean" image

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Be smart and avoid for-loop

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"Mean" image

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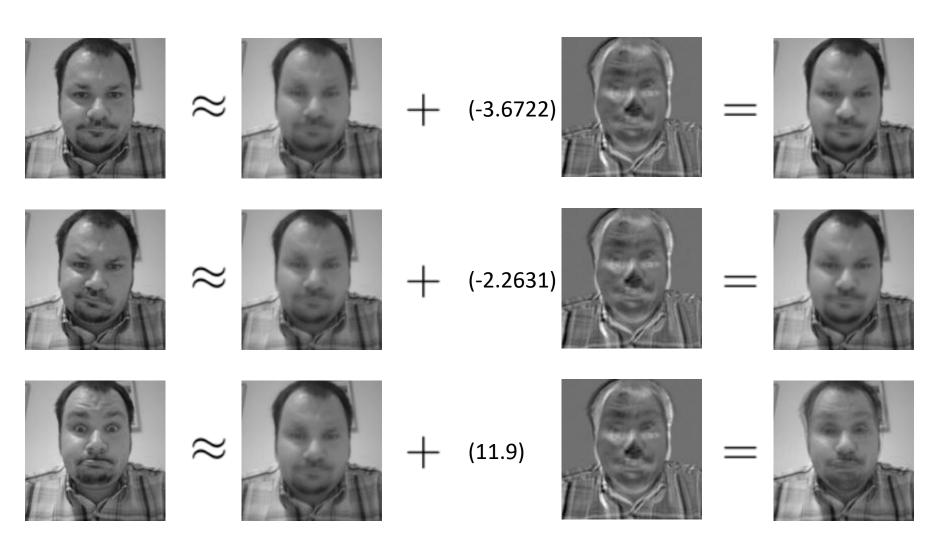
Be smart and avoid for-loop

You don't want to compute all of the eigenvectors!, use "eigs"

m = 1



m = 1



(only the largest deviations from mean are captured)



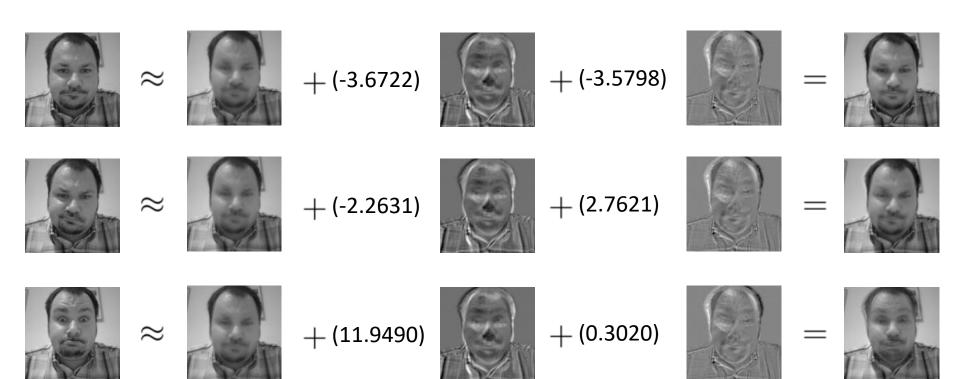
(only the largest deviations from mean are captured)

m = 2



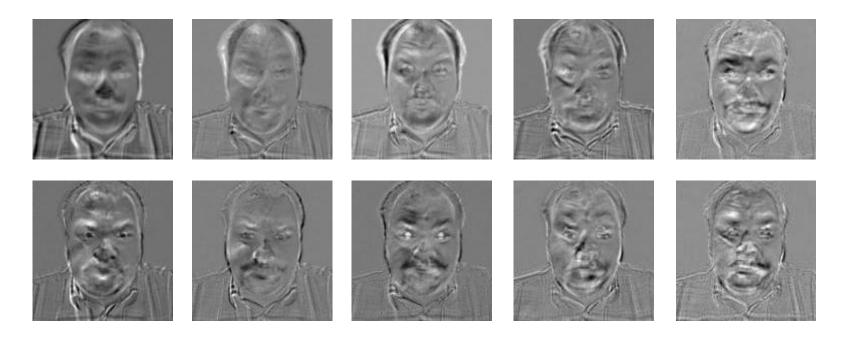


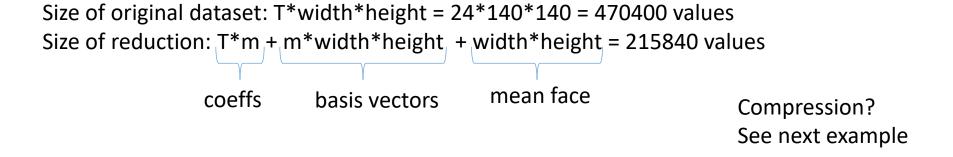
m = 2





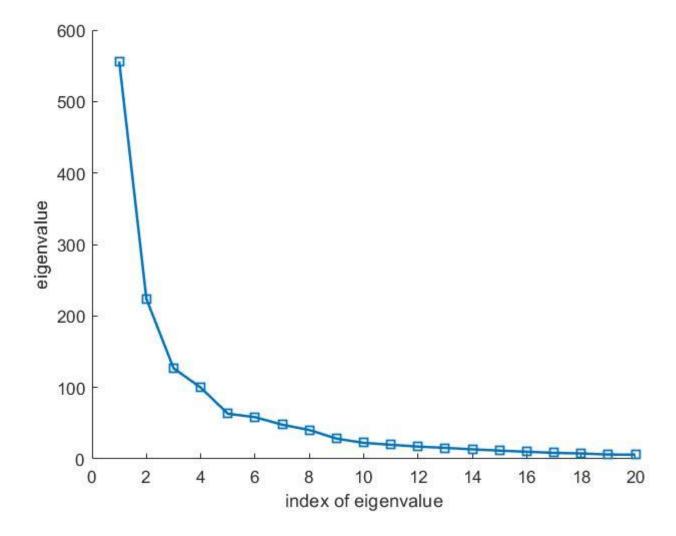
(only the two largest deviations from mean are captured)





m = 10





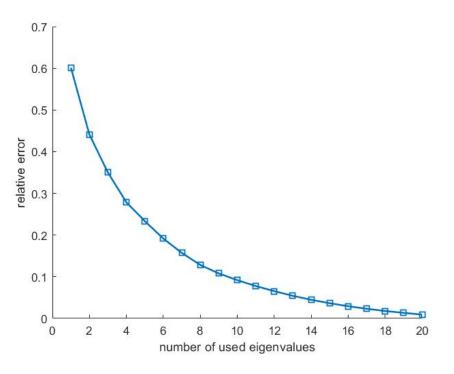
relative error
$$:= \frac{\sum\limits_{i=m+1}^{n} \lambda_i}{\sum\limits_{i=1}^{n} \lambda_i}$$
 remained in

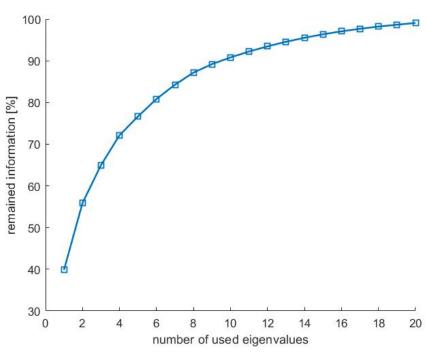
relative error :=
$$\frac{\sum\limits_{i=m+1}^{n}\lambda_{i}}{\sum\limits_{i=1}^{n}\lambda_{i}}$$
 remained information in the reduced data = $\left(1 - \frac{\sum\limits_{i=m+1}^{n}\lambda_{i}}{\sum\limits_{i=1}^{n}\lambda_{i}}\right) \cdot 100 [\%]$

relative error :=
$$\frac{\sum\limits_{i=m+1}^{n}\lambda_{i}}{\sum\limits_{i=1}^{n}\lambda_{i}}$$

remained information in the reduced data =
$$\left(1 - \frac{\sum_{i=m+1}^{n} \lambda_i}{\sum_{i=1}^{n} \lambda_i} \right) \cdot 100 [\%]$$

Hint: use trace instead of computing all eigenvalues!





- Method is completely knowledge free
- PCA can distiguish what is important and what is redundant
- By rearranging pixels column by column to a 1D vector, relations of a given pixel to pixels in neighboring rows are not taken into account.
- Another disadvantage is in the global nature of the representation; small change or error in the input images influences the whole eigen-representation.

More info: google "eigenface"

3b) PCA: compression

(motivated by previous example)



This is Illia.

Illia is too big. $3 \times 1024 \times 1024 = 3145728 \text{ values}$

Let's compress him.

(find optimal reduced space
and the representation of projection of this
image onto this space)

(note: actually this is JPEG image and it is already compressed)







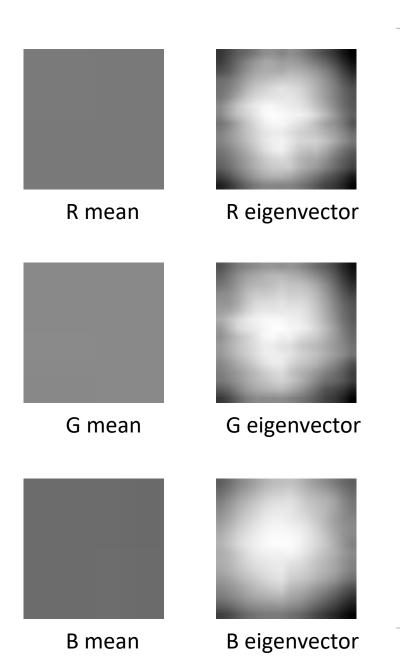
red green blue

We will deal with each channel individually.





- Divide the original 1024 x 1024 image into patches:
- Each patch is an instance that contains 16x16 pixels on a grid
- Patch = face in previous example
- Consider each as a 256-D vector and compress it using PCA
- T = 4096, n = 256







RGB mean

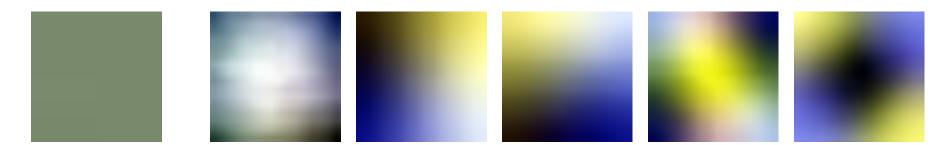
RGB eigenvector

m = 1





m = 5

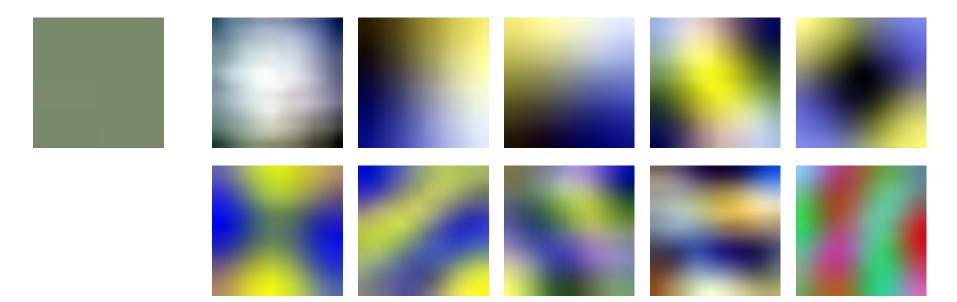


m = 5





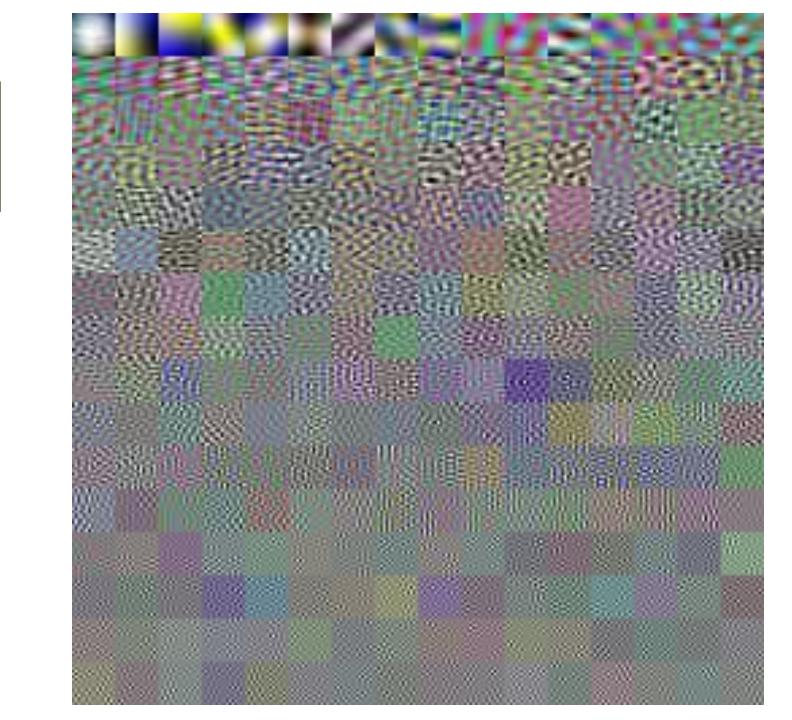
m = 10



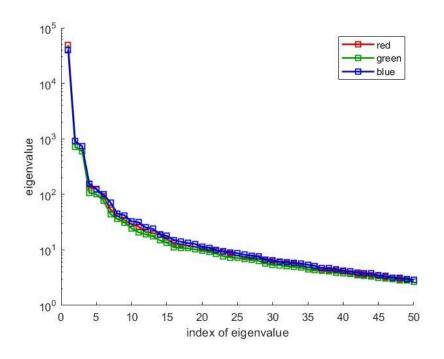
m = 10

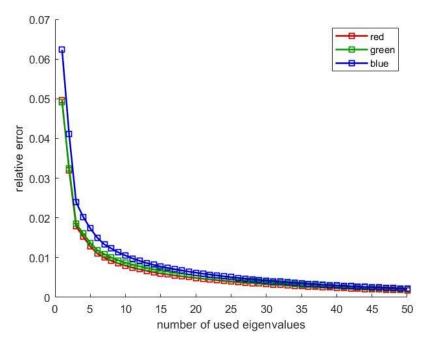


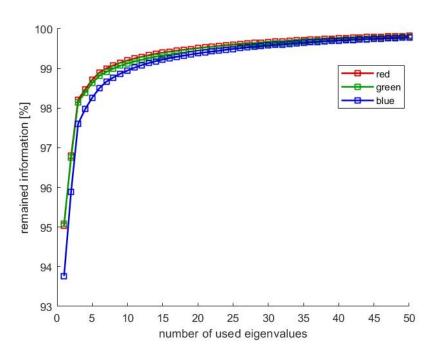




m = 256







(nmb_of_patches*m + m*patch_size* patch_size + patch_size*patch_size) * 3

coeffs basis vectors mean

(reduced data)

