Likelihoods Posterior probabilities Factor graphs Summary

# Phylogenetic trees Likelihood computations and inference

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#### Outline

- Likelihoods
- Posterior probabilities
- Factor graphs

#### Tree Notation

Notation and model: let...

Xn	be (actual) state of node n
Уn	be (observed) character at leaf node n
$X = \{x_n\}$	be the set of all node states
$Y = \{y_n\}$	be the set of all observed characters at leaf nodes
$Y_n$	be the set of all $y_m$ descended from node $n$
$\overline{Y_n} = Y \setminus Y_n$	be the set of all remaining $y_m$
$t_{mn}$	be evolutionary "distance" (time) from <i>m</i> to <i>n</i>

Root node is node 1.

For convenience, number nodes with parents < kids



#### Conditional & Prior Probabilities

Parent  $x_p$ , child  $x_c$ :

$$P(x_c|x_p) = M(t_{pc})_{x_px_c} = \exp(\mathbf{R}t_{pc})_{x_px_c}$$

Leaf node c:

$$P(y_c|x_c) = \delta_{x_cy_c}$$

i.e. observation  $y_c$  fully specifies state  $x_c$ . We can drop the  $x_c$ :

$$P(y_c|x_p) = \sum_{x_c} P(x_c|x_p) P(y_c|x_c) = M(t_{pc})_{x_p y_c}$$

Assumption: Ur-ancestor was in evolutionary equilibrium

$$P(x_1)=\pi_{x_1}$$

(Root node is always node 1)



# Felsenstein's Algorithm: Two Taxa

- Felsenstein's pruning algorithm: our first DP
  - Consider tree  $T_1$ : 1 with the following dependencies



between state variables *X* and observations *Y*:



Joint likelihood of all nodes:

$$P(X, Y) = P(x_1)P(x_2|x_1)P(x_3|x_1)P(y_2|x_2)P(y_3|x_3)$$

Marginal likelihood of leaves:

$$P(Y) = \sum_{X} P(X, Y)$$

$$= \sum_{x_1} P(x_1) P(y_2|x_1) P(y_3|x_1)$$

# Felsenstein's Algorithm: Four Taxa

Now consider tree  $T_2$ :

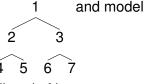


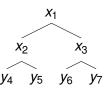
Joint likelihood of all nodes:

$$= P(x_1)P(x_2|x_1)P(x_3|x_1)P(x_4|x_2)P(x_5|x_2)P(x_6|x_3)P(x_7|x_3)\prod_{n=4}^{7}P(y_n|x_n)$$

# Felsenstein's Algorithm: Rearranging Terms

Tree  $T_2$ :





Marginal likelihood of leaves:

$$P(Y) = \sum_{X} P(X, Y)$$

$$= \sum_{x_1} \sum_{x_2} \sum_{x_3} P(x_1) P(x_2 | x_1) P(x_3 | x_1) P(y_4 | x_2) P(y_5 | x_2) P(y_6 | x_3) P(y_7 | x_3)$$

$$= \sum_{x_1} P(x_1) \left[ \left( \sum_{x_2} P(x_2 | x_1) [P(y_4 | x_2) P(y_5 | x_2)] \right) \left( \sum_{x_3} P(x_3 | x_1) [P(y_6 | x_3) P(y_7 | x_3)] \right) \right]$$

Terms in square brackets have the form:

$$F_n(x_n) = P(\{y_i : i \text{ descended from } n\} | x_n) = P(Y_n | x_n)$$

# Felsenstein's Algorithm: Generalization

- Let  $C_n$  be the set of immediate children of n (so e.g.  $C_1 = \{2,3\}$ )
- Rule to compute  $F_n$  is then

$$F_n(x_n) = \begin{cases} \prod_{c \in C_n} \left( \sum_{x_c} P(x_c | x_n) F_c(x_c) \right) & \text{if } n \text{ is internal} \\ P(y_n | x_n) & \text{if } n \text{ is a leaf} \end{cases}$$

$$P(Y) = \sum_{x_1} P(x_1) F_1(x_1)$$

• This is the pruning algorithm (Felsenstein, 1981).



# Felsenstein's Algorithm: Recursion

$$F_n(x_n) = \begin{cases} \prod_{c \in C_n} \left( \sum_{x_c} P(x_c|x_n) F_c(x_c) \right) & \text{if } n \text{ is internal} \\ P(y_n|x_n) & \text{if } n \text{ is a leaf} \end{cases}$$

$$P(Y) = \sum_{x_1} P(x_1) F_1(x_1)$$

- Term after " $\prod$ " sign in  $F_n$  can be written  $E_c(x_p) = P(Y_c|x_p) = \sum_{x_c} P(x_c|x_p) F_c(x_c)$  where p is parent of c
- An instance of the sum-product algorithm on a factor graph



# **Pulley Principle**

• "Pulley principle" for reversible models.

• Using  $\pi_i M(t)_{ij} = \pi_j M(t)_{ji}$  and  $\mathbf{M}(t) \mathbf{M}(t') = \mathbf{M}(t + t')$ 

$$P(y_2, y_3) = \sum_{x_1} \pi_{x_1} M(t_{12})_{x_1 y_2} M(t_{13})_{x_1 y_3}$$

$$= \sum_{x_1} \pi_{y_2} M(t_{12})_{y_2 x_1} M(t_{13})_{x_1 y_3}$$

$$= \pi_{y_2} M(t_{12} + t_{13})_{y_2 y_3}$$

$$= \pi_{y_3} M(t_{12} + t_{13})_{y_3 y_2}$$

- $P(y_2, y_3)$  depends only on  $t_{12} + t_{13}$
- Can slide root node (like a pulley) w/out affecting likelihood
- Corollorary: can re-root tree at any node, including any leaf



# **Alignment Probability**

- So far we have looked at P(C|T), the probability of an individual alignment column, conditioned on a tree
- Probability of an entire alignment conditioned on tree,
   P(A|T), is product of column probabilities:

$$P(A|T) = \prod_{C \in A} P(C|T)$$

- Denote maximum likelihood tree by  $T_{ML} = \operatorname{argmax}_T P(A|T)$
- Note that so far we have neglected the indel history that is also (partially) specified by the alignment



## Ancestral State Reconstruction on a Phylogeny

- Motivation:
  - Probability distribution of ancestral state,  $P(x_n|Y)$
  - Probability distribution of  $p \to c$  branch,  $P(x_p, x_c | Y)$
- Recall tree notation:
  - $Y = \{y_i\}$  is the set of all leaf states
  - Y<sub>n</sub> contains all y<sub>i</sub> descended from node n
  - $\overline{Y_n}$  contains all  $y_i$  not descended from node n
    - Note  $Y_1 \equiv Y$ , since node 1 is the root node.

#### **Probabilities of Ancestral States**

- Felsenstein's pruning algorithm computes  $F_n(x_n) = P(Y_n|x_n)$ 
  - and thus  $P(Y) = \sum_{x_1} \pi(x_1) F_1(x_1)$
- We will now give recursions for  $G_n(x_n) = P(x_n, \overline{Y_n})$ .
- With these we can easily get posterior probabilities for...
  - State of ancestral node
  - State of ancestral branch



#### State of Ancestral Node

$$F_{n}(x_{n}) = P(Y_{n}|x_{n})$$

$$G_{n}(x_{n}) = P(x_{n}, \overline{Y_{n}})$$

$$P(x_{n}|Y) = \frac{P(x_{n}, Y)}{P(Y)}$$

$$= \frac{1}{P(Y)}P(x_{n}, \overline{Y_{n}})P(Y_{n}|x_{n})$$

$$= \frac{1}{P(Y)}G_{n}(x_{n})F_{n}(x_{n})$$

#### State of Ancestral Branch

Joint state of ancestral branch

$$\stackrel{p}{\widehat{c} s}$$

$$P(x_p, x_c|Y) = \frac{P(x_p, x_c, Y)}{P(Y)}$$

$$= \frac{1}{P(Y)} P(x_p, \overline{Y_p}) P(x_c|x_p) P(Y_c|x_c) P(Y_s|x_p)$$

$$= \frac{1}{P(Y)} G_p(x_p) P(x_c|x_p) F_c(x_c) E_s(x_p)$$

where  $E_s(x_p) = \sum_{x_c} P(x_c|x_p) F_s(x_s)$  as before



# **Peeling Recursion**

• Recursion for  $G_c(x_c) = P(x_c, \overline{Y_c})$ 

$$G_c(x_c) = \left\{ egin{array}{ll} \sum_{x_p} G_p(x_p) P(x_c|x_p) E_s(x_p) & ext{if } c > 1 ext{ (not root)} \\ P(x_c) & ext{if } c = 1 ext{ (root)} \end{array} 
ight.$$

aka Elston-Stewart peeling algorithm

# Degenerate characters

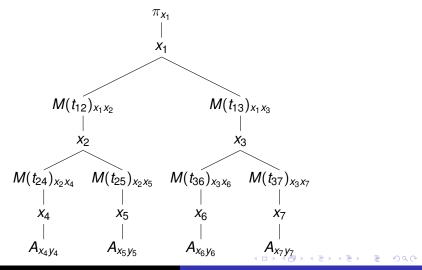
IUPAC ambiguity code	Possibilities
R	A G
Υ	CT
M	A C
K	GT
S	CG
W	ΑT
Н	ACT
В	CGT
V	ACG
D	AGT
N or X	ACGT

- Recall the hidden state  $x_i$  behind observation  $y_i$
- $P(y_i|x_i) = A_{x_iy_i}$  reflects ambiguous  $y_i$
- Can be extended to read quality scores, etc.
- P(X, Y) is product of  $\pi_i$ 's,  $M_{ii}$ 's and  $A_{ii}$ 's

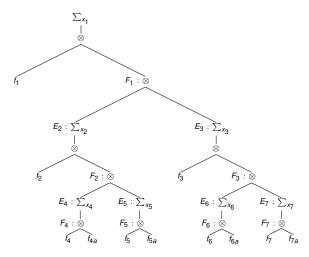
# Bigraph representation of P(X, Y)

2-coloring: variables  $X = \{x_i\}$ , functions  $\mathcal{F} = \{f_n\}$ 

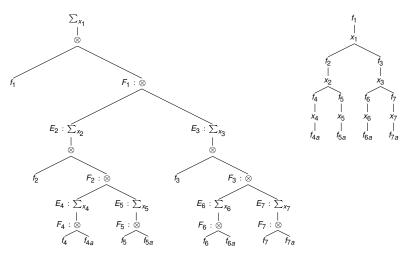
# Bigraph representation of P(X, Y) showing functions



# Expression tree of P(Y)



# Expression tree of P(Y) and factor graph of P(X, Y)



# **Factor Graphs**

- The idea of computing marginals and posteriors on a graphical network of variables has been generalized
  - "Factor graphs", "Graphical models", "Bayesian networks", "Markov random fields"
  - "Sum-product algorithm", "Message-passing", "Belief propagation"
- Here we use the Factor Graph variant of the formalism
  - Kschichang, Frey & Loeliger, IEEE 47:2, February 2001.

# The summary operator

- ullet The "summary" or "not-sum" operator,  $\sum_{\sim \{\}} f(\cdot)$ 
  - Suppose  $V \subseteq W \subseteq X$ .
  - The summary of f(W) w.r.t. V is obtained by summing f(W) over all  $x_i \notin V$ . The result is a function of V.
    - For example...

$$\sum_{\substack{\sim \{x_3, x_4\}}} f(x_2, x_3, x_4, x_5, x_6) = \sum_{\substack{x_2 \ x_5}} \sum_{\substack{x_6 \ x_2, x_3, x_4, x_5, x_6}} f(x_2, x_3, x_4, x_5, x_6)$$

• Define the summary of f w.r.t. its own arguments as f itself:

$$\sum_{\sim\{W\}}f(W)\equiv f(W)$$

• The summaries of a joint likelihood are the marginals: If g(X) = P(X), then  $\sum_{x \in V} g(Y) = P(Y)$ 



# Message-passing

- Factor graphs contain
  - function nodes (f<sub>i</sub>)
  - variable nodes (x<sub>i</sub>)
  - An edge  $f_i$ — $x_j$  indicates  $x_j$  is a parameter of  $f_i$
- Computation proceeds by message-passing
- A "message" is actually a pre-computed function over some subset of the variables in the graph
- The message from node a to node b is written  $\mu_{a \rightarrow b}$

# Message-passing

• Message from  $f_i$  to  $x_i$ :

$$\mu_{f_i \to x_j} = \sum_{\substack{\sim \{x_j\}}} f_i \prod_{k \neq j} \mu_{x_k \to f_i}$$

where  $\{\mu_{X_{\nu} \to f_i}\}$  are the incoming messages to  $f_i$ 

• Message from x<sub>i</sub> to f<sub>i</sub>:

$$\mu_{\mathbf{X}_i \to \mathbf{f}_j} = \prod_{\mathbf{k} \neq j} \mu_{\mathbf{f}_{\mathbf{k}} \to \mathbf{X}_i}$$

where  $\{\mu_{f_k \to x_i}\}$  are the incoming messages to  $x_i$ 



# Message-passing

$$\mu_{f_i \to x_j} = \sum_{\substack{\sim \{x_j\}}} f_i \prod_{k \neq j} \mu_{x_k \to f_i}$$

$$\mu_{x_i \to f_j} = \prod_{k \neq j} \mu_{f_k \to x_i}$$

The message sent from a node n on an edge e is...

- the product of:
  - the local function at n (or the unit function,  $x_n \to 1$ , if n is a variable node);
  - all messages received at n on edges other than e,
- summarized for the variable associated with e.



## Phylogenetic message-passing

For a phylogenetic tree, the messages are as follows (c - p - s denoting child—parent—sibling)

Leaves-to-root:

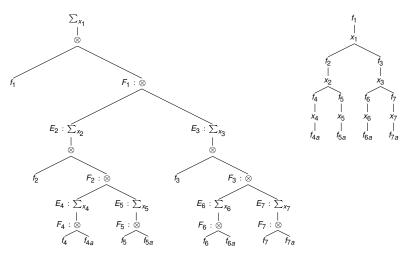
$$\mu_{f_{na} \to x_n} = f_{na}(x_n)$$
 $\mu_{x_n \to f_n} = F_n(x_n)$ 
 $\mu_{f_c \to x_p} = E_c(x_p)$ 

Root-to-leaves:

$$\mu_{f_n \to x_n} = G_n(x_n)$$
  
 $\mu_{x_p \to f_c} = G_p(x_p) E_s(x_p)$ 



# Expression tree of P(Y) and factor graph of P(X, Y)



# **Factor Graphs**

- Many applications in biology...
  - Markov models
  - Phylogenetic trees
  - Hidden Markov models
  - Inference on ontologies
  - Markov random fields (images, gene networks, ...)
- ...and beyond...
  - Error-correcting codes

# Changing the Operators

- The "sum" and "product" operators in the sum-product algorithm are arbitrary
  - The sum-product algorithm works by factorising terms like

$$\sum_{x_1} \sum_{x_2} f(x_1) f(x_2) = \left( \sum_{x_1} f(x_1) \right) \left( \sum_{x_2} f(x_2) \right)$$

• This in turn relies on the distributive law,

$$a \times (b + c) = a \times b + a \times c$$

and can be applied to any semiring with operators  $(\otimes, \oplus)$ 



# Changing the Operators: ML inference

• For example, consider

$$a \oplus b \equiv \max(a, b)$$
  
 $a \otimes b \equiv ab$ 

- The pruning algorithm now calculates  $\max_X P(X, Y)$
- It is straightforward to recover  $argmax_X P(X, Y)$ 
  - i.e. the MAP (Maximum A Posteriori) ancestral state history
  - note that  $\operatorname{argmax}_{X} P(X, Y) = \operatorname{argmax}_{X} P(X|Y)$
  - this may not give the same results as  $\operatorname{argmax}_{x_i} P(x_i | Y)$



# **Changing the Operators: Parsimony**

Another example: consider

$$a \oplus b \equiv \min(a, b)$$
  
 $a \otimes b \equiv a + b$ 

and set 
$$M(t)_{ij} = A_{ij} = 1 - \delta_{ij}$$
 and  $\pi_i = 0$ 

- Then M counts the number of substitutions, and pruning returns the most parsimonious imputation of  $\{x_i\}$
- A number of neat results for parsimony exist
  - e.g. a branch-and-bound algorithm to find the most parsimonious tree
- but parsimony is v restrictive "model"; strong assumptions:
  - all substitutions equally likely, no back-substitutions...
  - parsimony not really compatible w/ probabilistic methods

### Summary

- Message-passing on phylogenetic trees
  - Felsenstein's pruning algorithm
  - Elston-Stewart peeling algorithm
- Pulley principle & reversibility