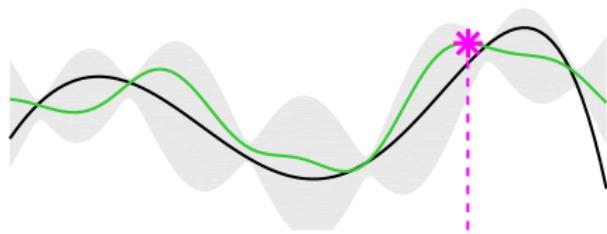


# An Introduction to Bayesian Optimisation and (Potential) Applications in Materials Science



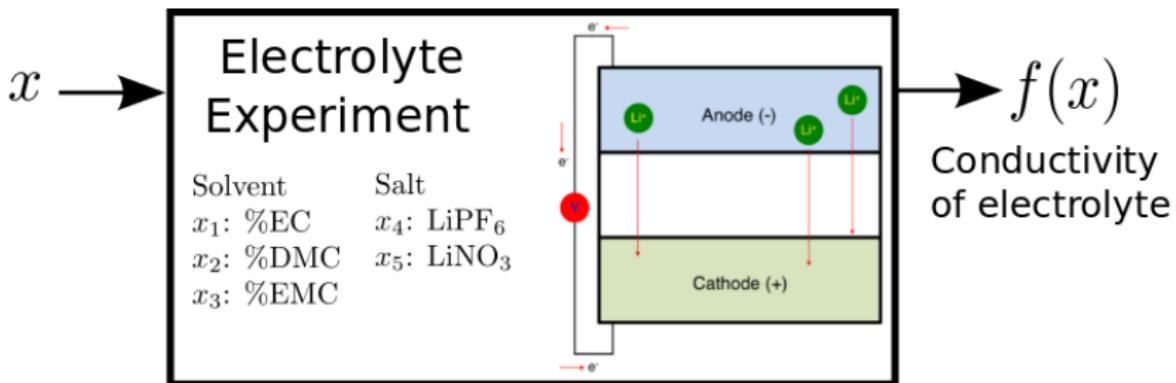
**Kirthevasan Kandasamy**

Machine Learning Dept, CMU

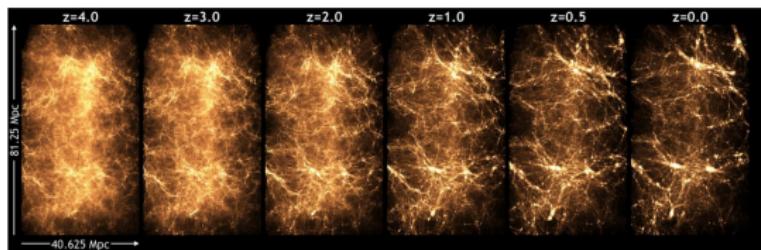
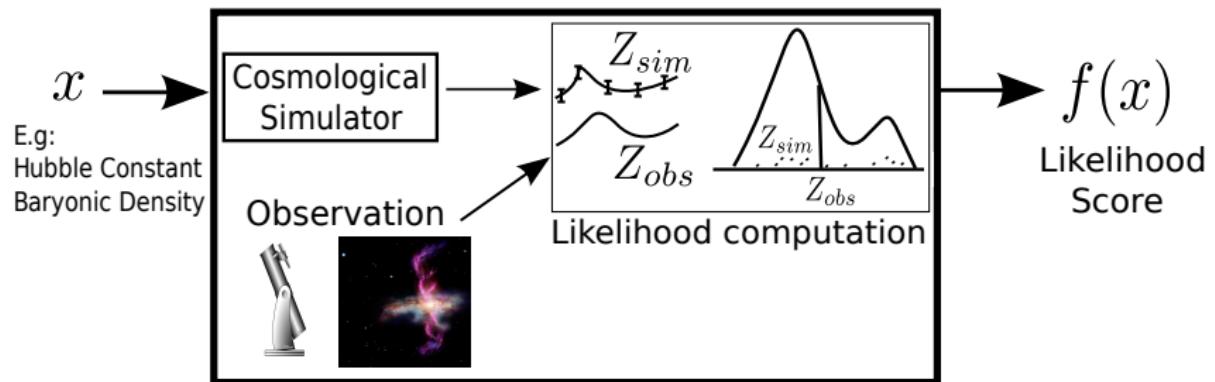
Electrochemical Energy Symposium

Pittsburgh, PA, November 2017

# Designing Electrolytes in Batteries



# Black-box Optimisation in Computational Astrophysics

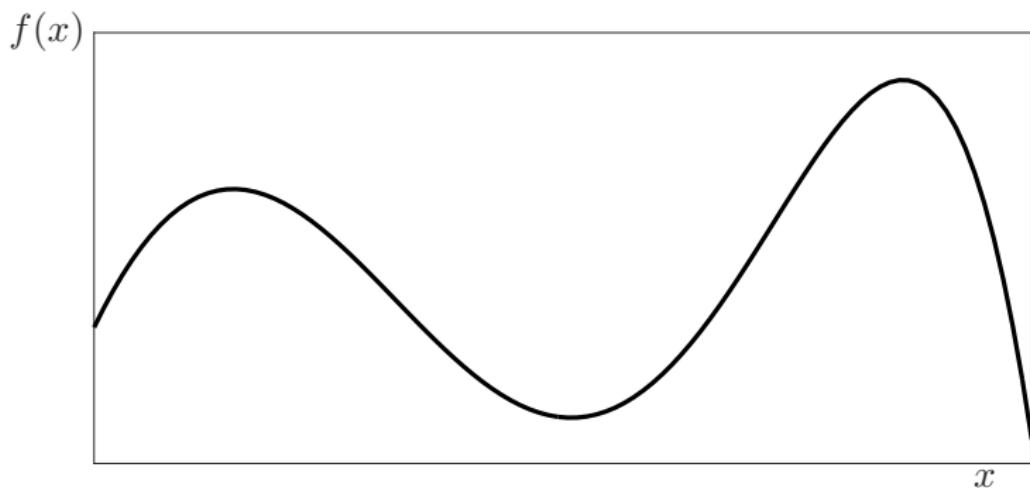


# Black-box Optimisation



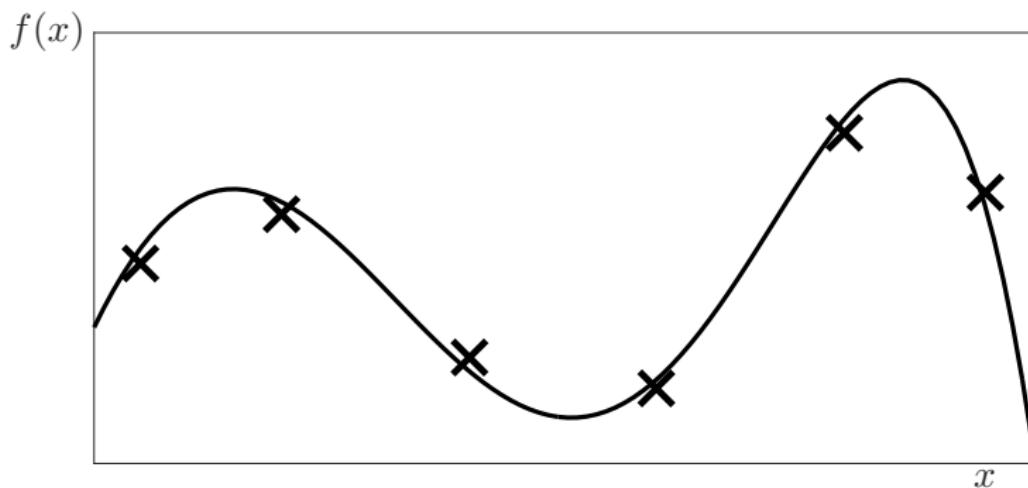
# Black-box Optimisation

$f : \mathcal{X} \rightarrow \mathbb{R}$  is an expensive, black-box function, accessible only via noisy evaluations.



# Black-box Optimisation

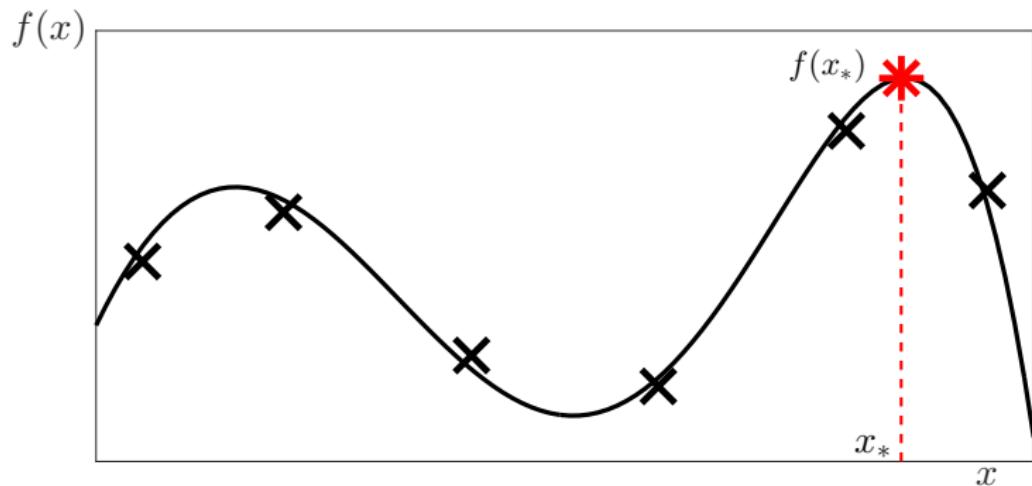
$f : \mathcal{X} \rightarrow \mathbb{R}$  is an expensive, black-box function, accessible only via noisy evaluations.



# Black-box Optimisation

$f : \mathcal{X} \rightarrow \mathbb{R}$  is an expensive, black-box function, accessible only via noisy evaluations.

Let  $x_* = \operatorname{argmax}_x f(x)$ .



# Outline

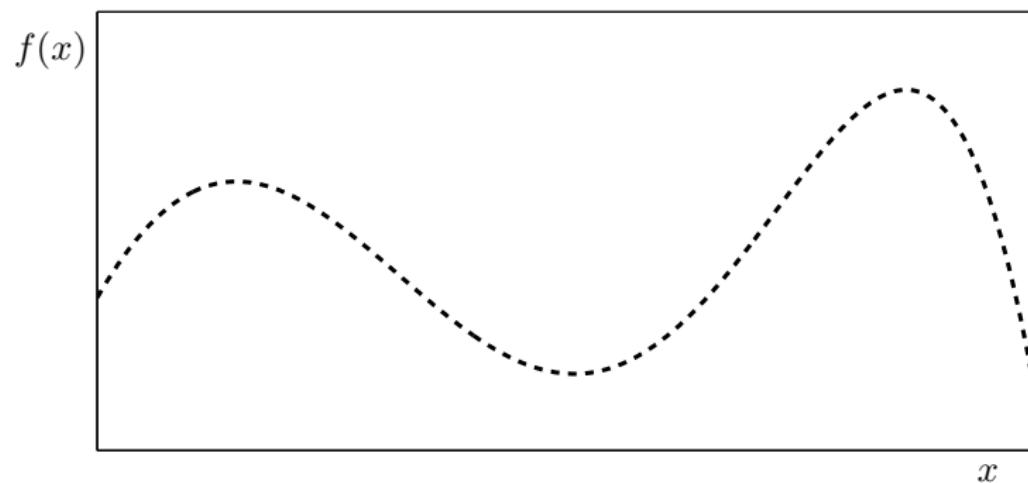
- ▶ Part I: Bayesian Optimisation
  - ▶ Bayesian Models for  $f$
  - ▶ Two algorithms: upper confidence bounds & Thompson sampling
- ▶ Part II: Some Modern Challenges
  - ▶ Multi-fidelity Optimisation
  - ▶ Parallelisation

## Bayesian Models for $f$      e.g. Gaussian Processes ( $\mathcal{GP}$ )

$\mathcal{GP}$ : A distribution over functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

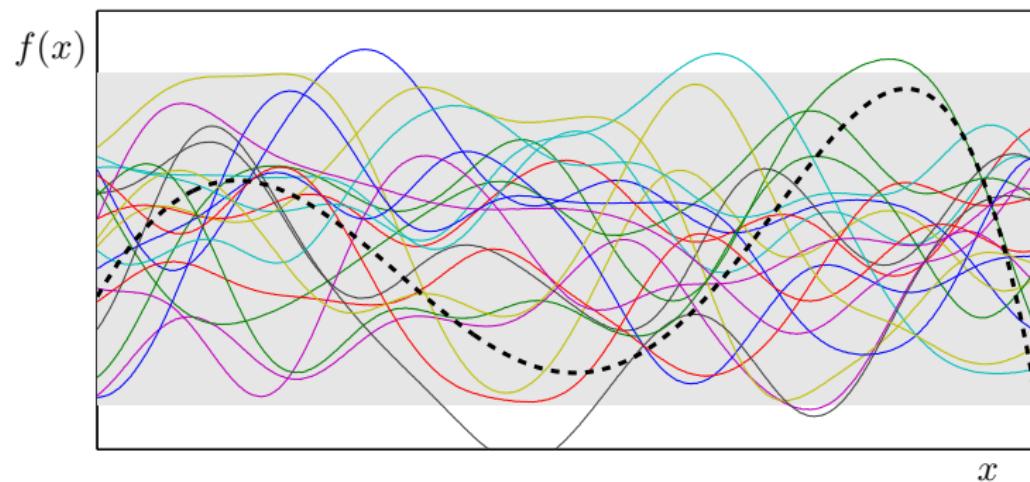
$\mathcal{GP}$ : A distribution over functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

Functions with no observations



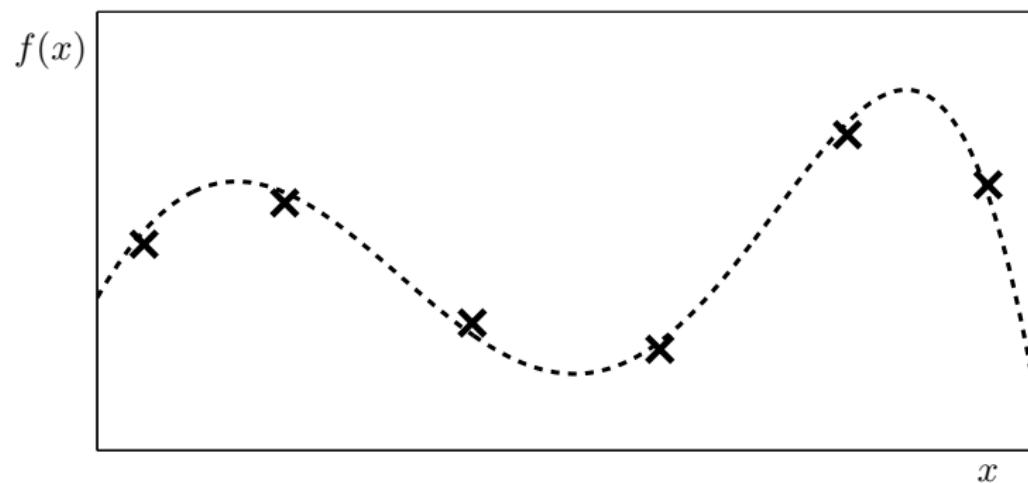
$\mathcal{GP}$ : A distribution over functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

Prior  $\mathcal{GP}$



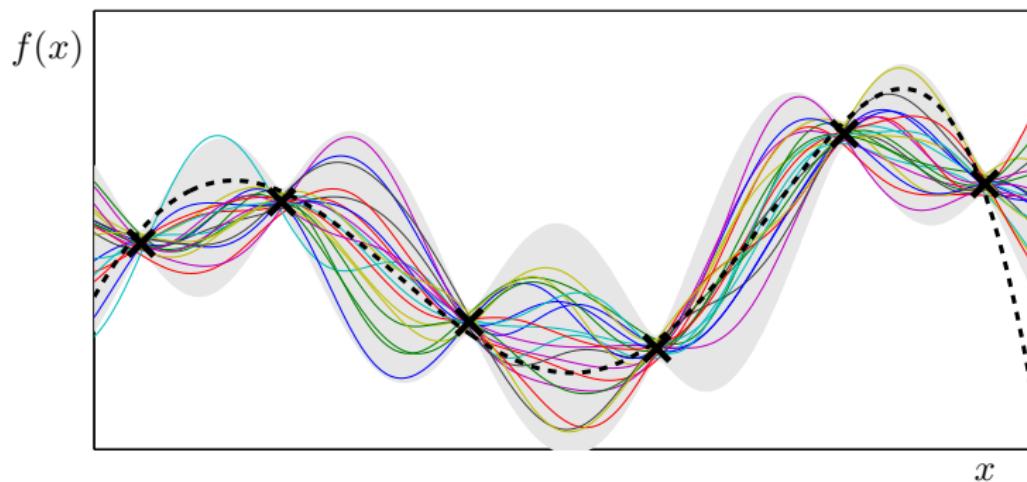
$\mathcal{GP}$ : A distribution over functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

Observations



$\mathcal{GP}$ : A distribution over functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

Posterior  $\mathcal{GP}$  given observations

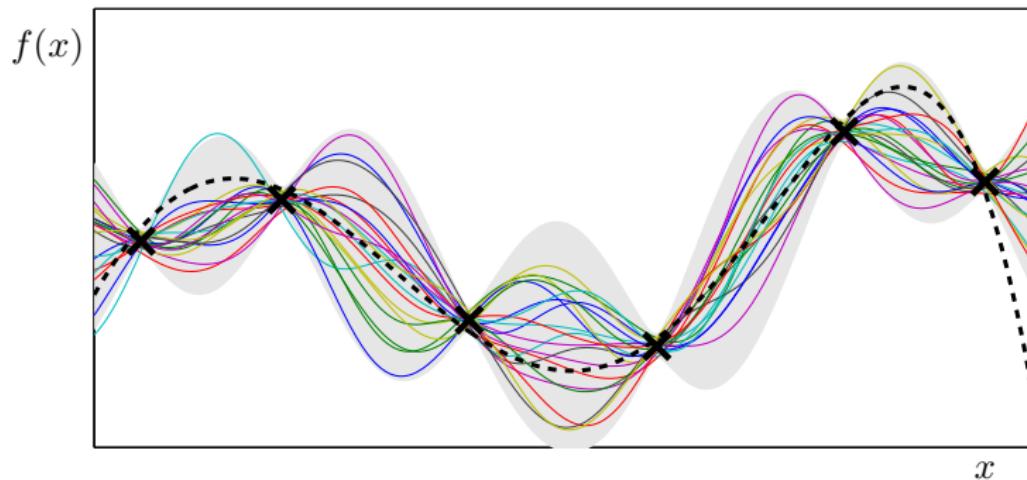


# Bayesian Models for $f$

e.g. Gaussian Processes ( $\mathcal{GP}$ )

$\mathcal{GP}$ : A distribution over functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

Posterior  $\mathcal{GP}$  given observations



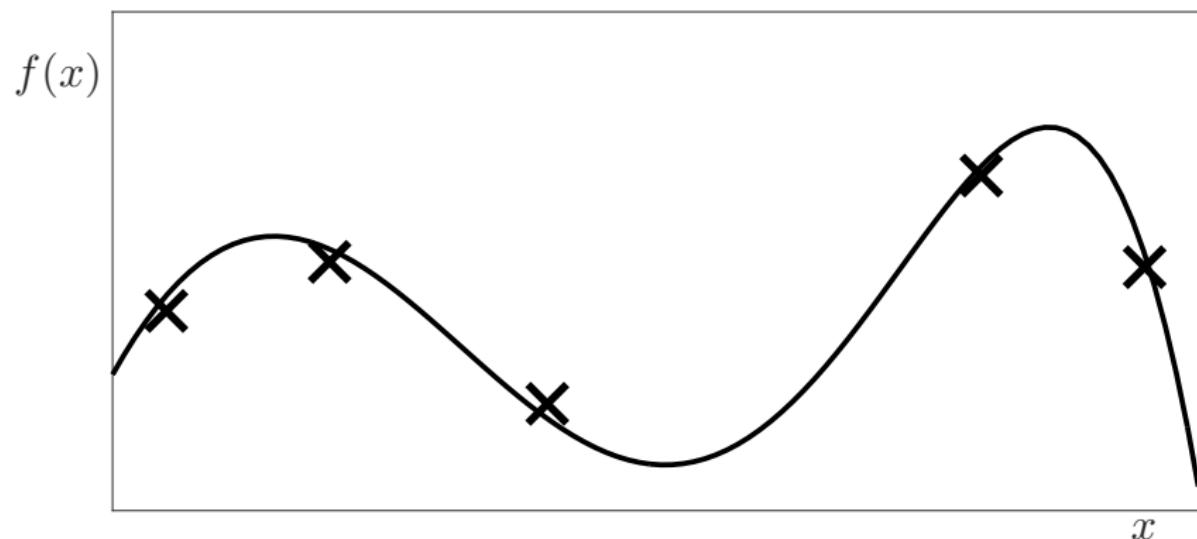
After  $t$  observations,  $f(x) \sim \mathcal{N}(\mu_t(x), \sigma_t^2(x))$ .

# Bayesian Optimisation with Upper Confidence Bounds

Model  $f \sim \mathcal{GP}$ .

Gaussian Process Upper Confidence Bound (GP-UCB)

(Srinivas et al. 2010)

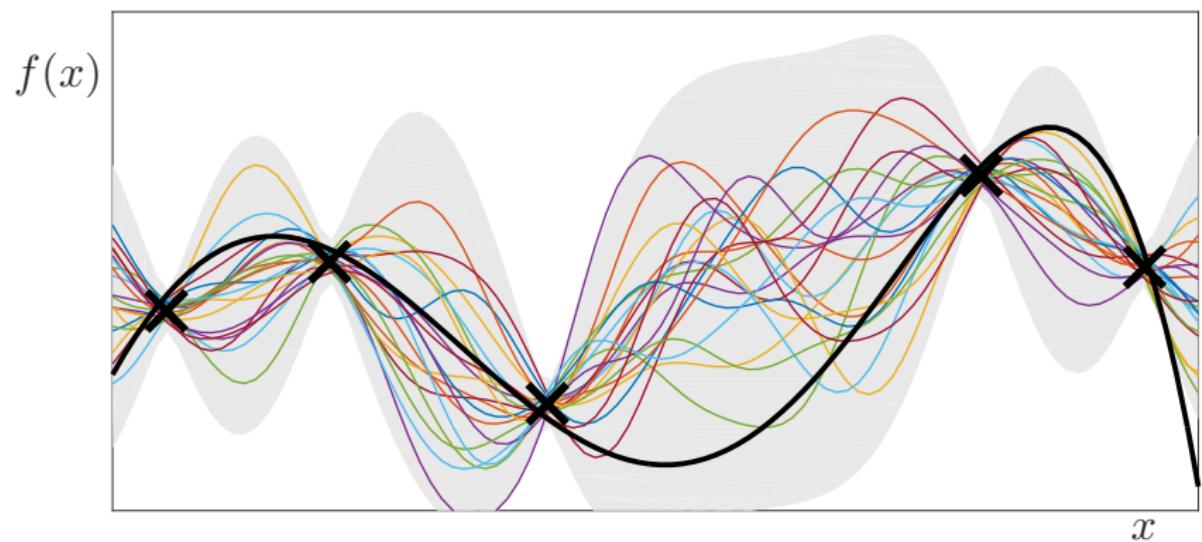


# Bayesian Optimisation with Upper Confidence Bounds

Model  $f \sim \mathcal{GP}$ .

Gaussian Process Upper Confidence Bound (GP-UCB)

(Srinivas et al. 2010)



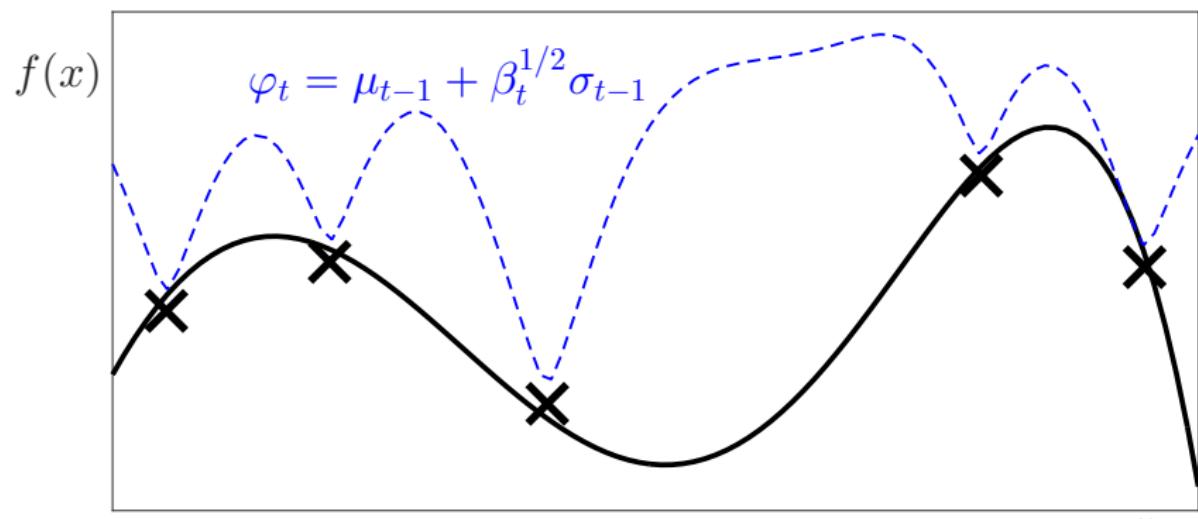
- 1) Construct posterior  $\mathcal{GP}$ .

# Bayesian Optimisation with Upper Confidence Bounds

Model  $f \sim \mathcal{GP}$ .

Gaussian Process Upper Confidence Bound (GP-UCB)

(Srinivas et al. 2010)



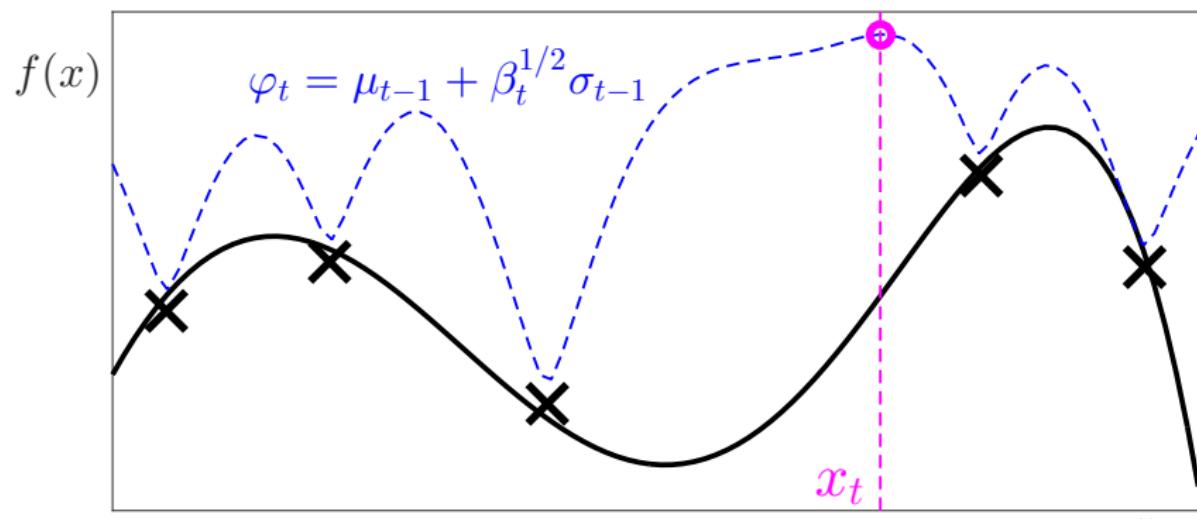
- 1) Construct posterior  $\mathcal{GP}$ .
- 2)  $\varphi_t = \mu_{t-1} + \beta_t^{1/2} \sigma_{t-1}$  is a UCB.

# Bayesian Optimisation with Upper Confidence Bounds

Model  $f \sim \mathcal{GP}$ .

Gaussian Process Upper Confidence Bound (GP-UCB)

(Srinivas et al. 2010)



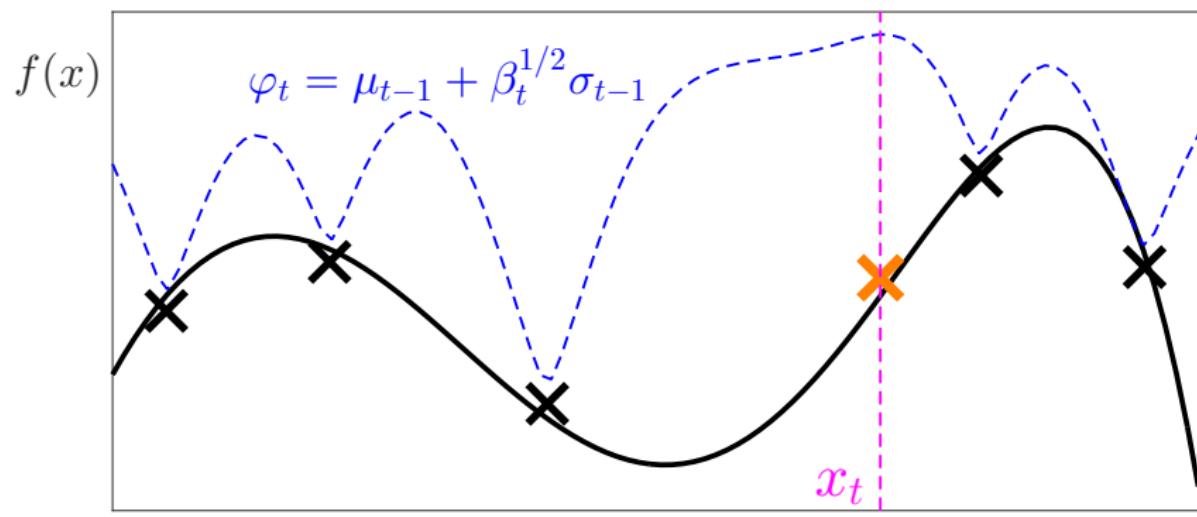
- 1) Construct posterior  $\mathcal{GP}$ .
- 2)  $\varphi_t = \mu_{t-1} + \beta_t^{1/2} \sigma_{t-1}$  is a UCB.
- 3) Choose  $x_t = \operatorname{argmax}_x \varphi_t(x)$ .

# Bayesian Optimisation with Upper Confidence Bounds

Model  $f \sim \mathcal{GP}$ .

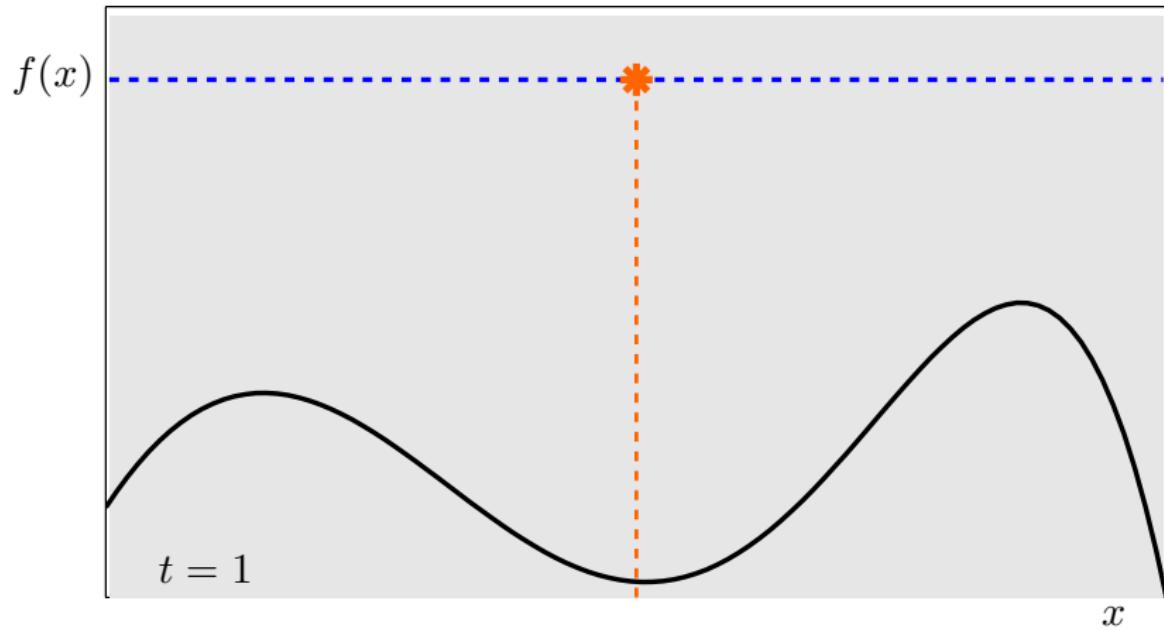
Gaussian Process Upper Confidence Bound (GP-UCB)

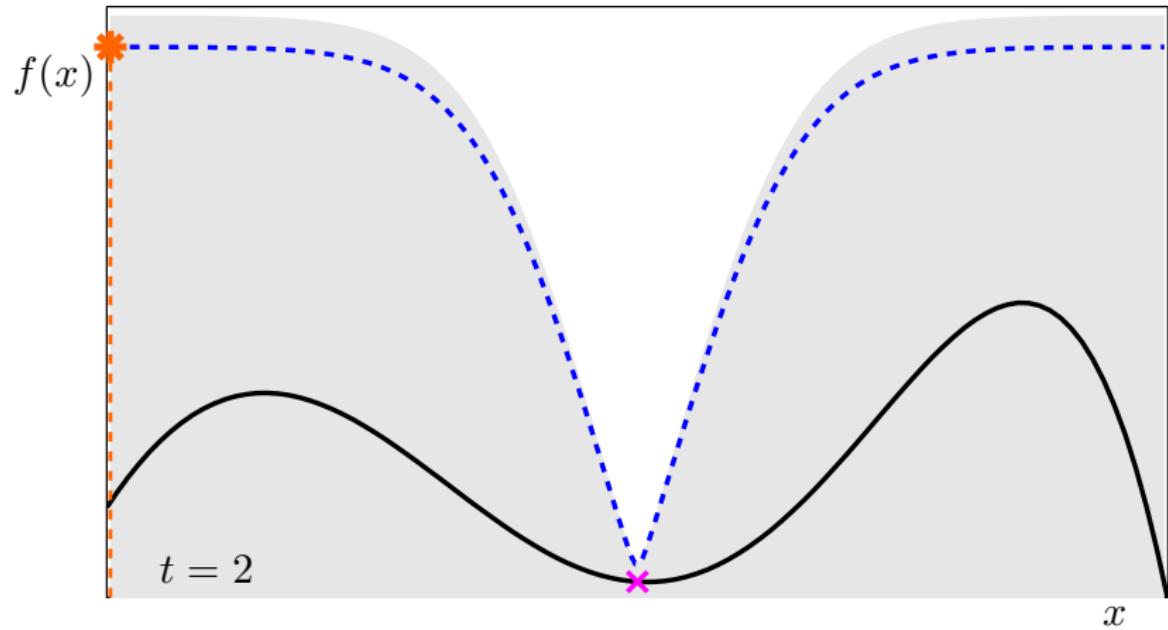
(Srinivas et al. 2010)

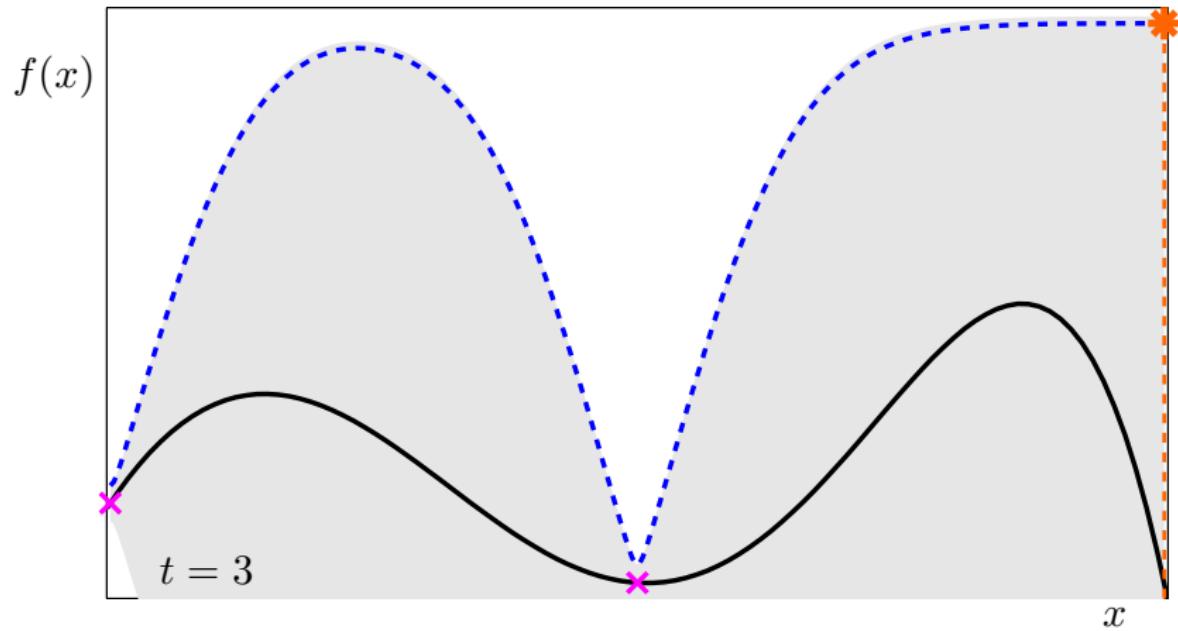


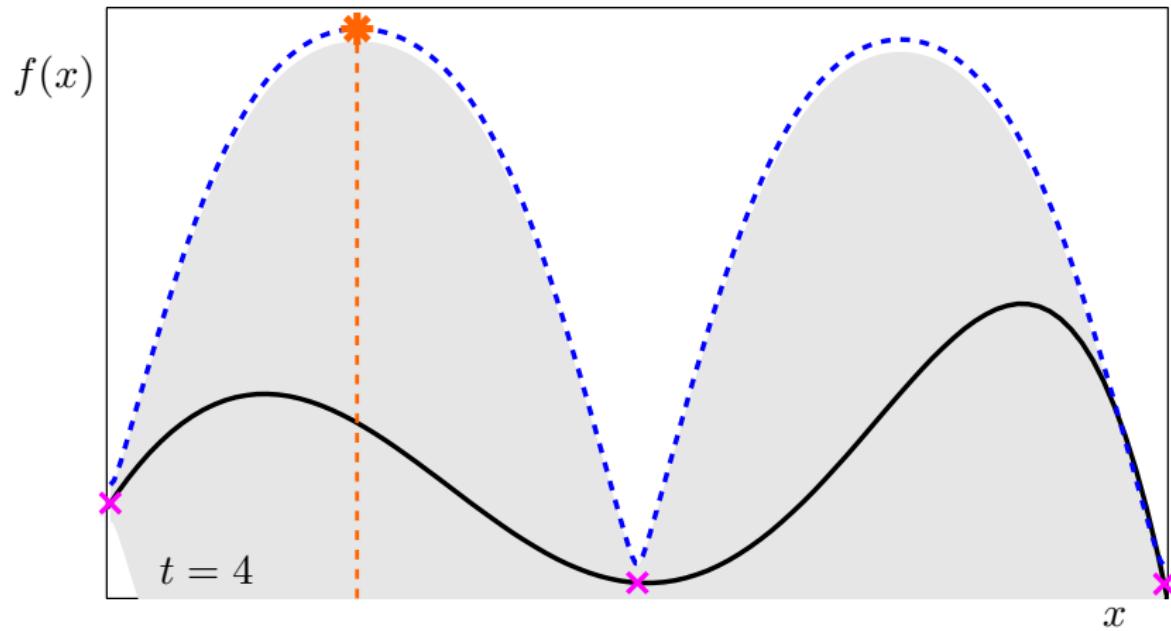
- 1) Construct posterior  $\mathcal{GP}$ .
- 2)  $\varphi_t = \mu_{t-1} + \beta_t^{1/2} \sigma_{t-1}$  is a UCB.
- 3) Choose  $x_t = \operatorname{argmax}_x \varphi_t(x)$ .
- 4) Evaluate  $f$  at  $x_t$ .

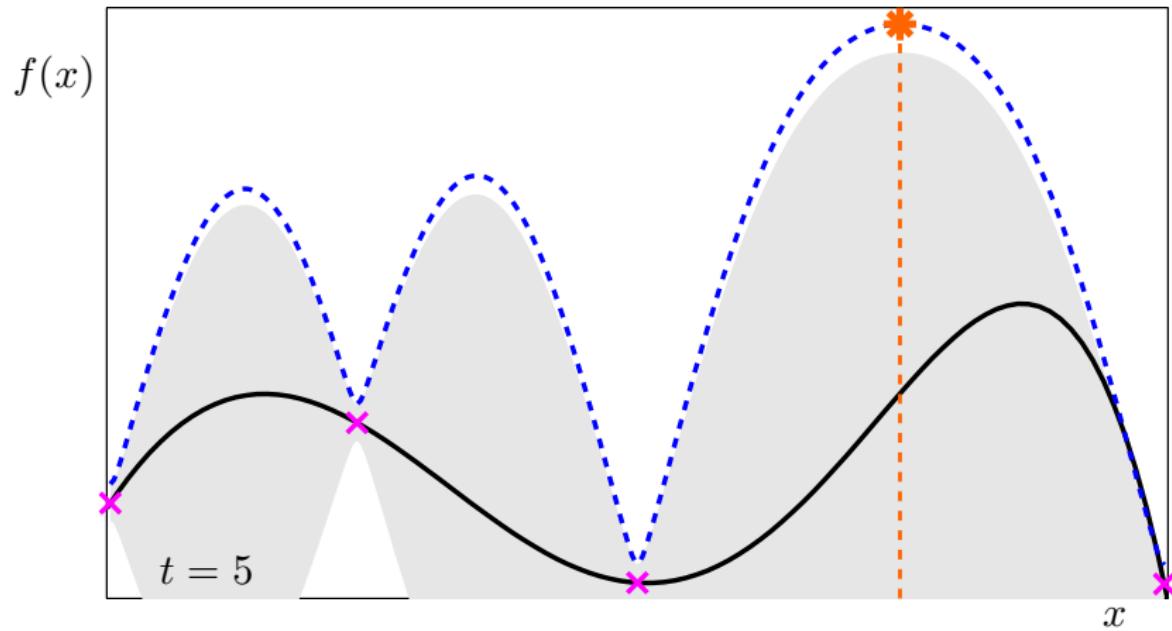
$f(x)$  $x$

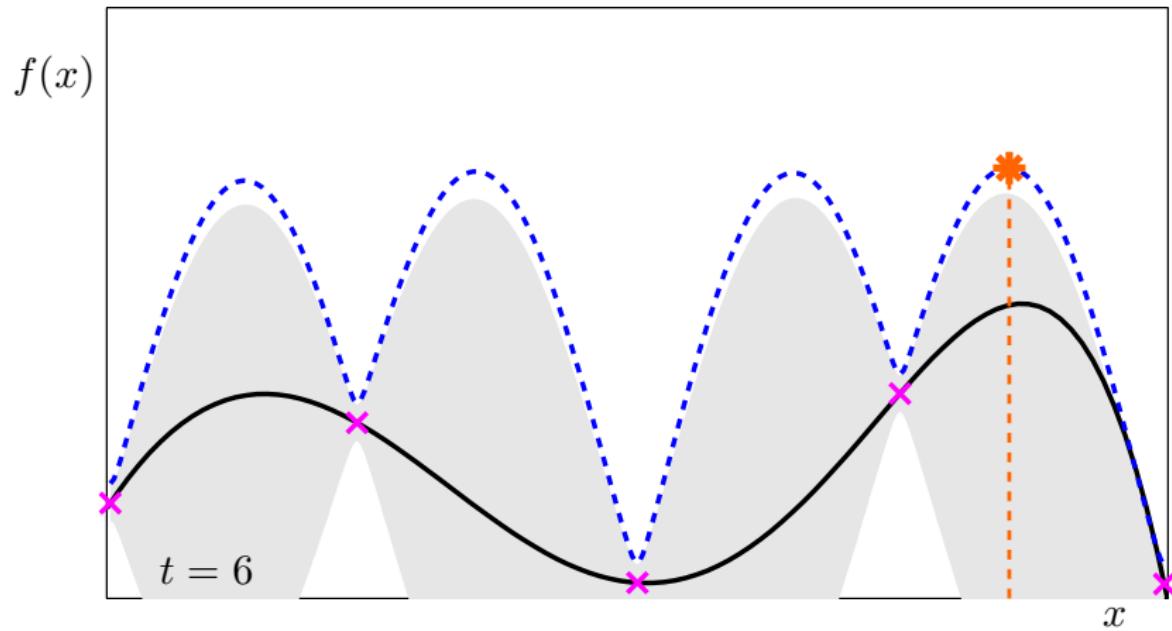


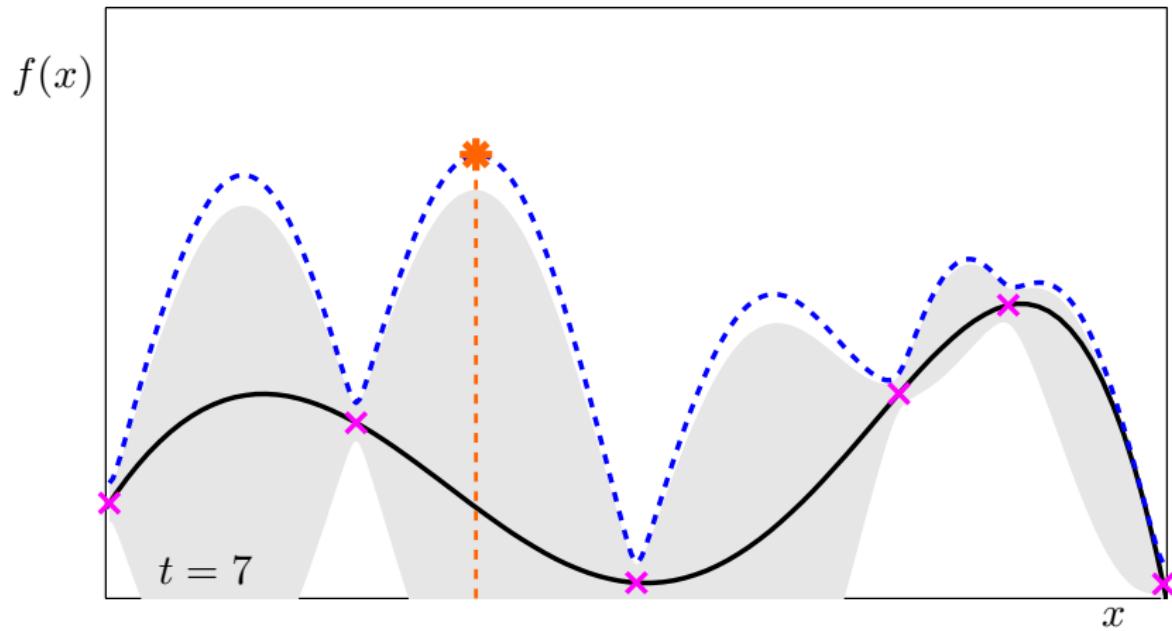


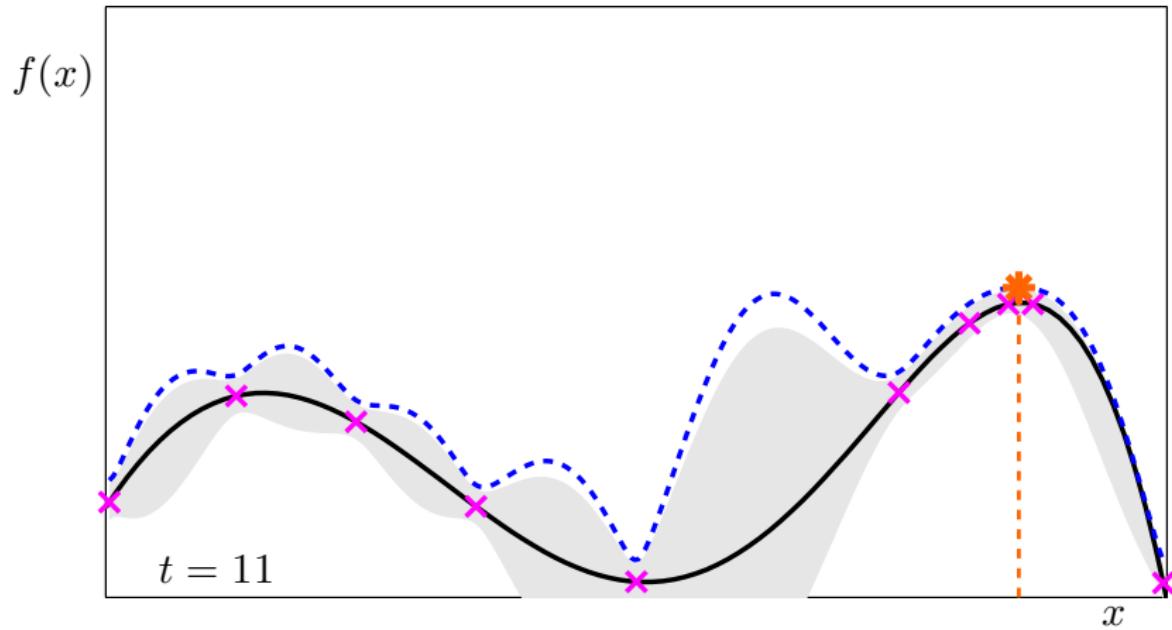


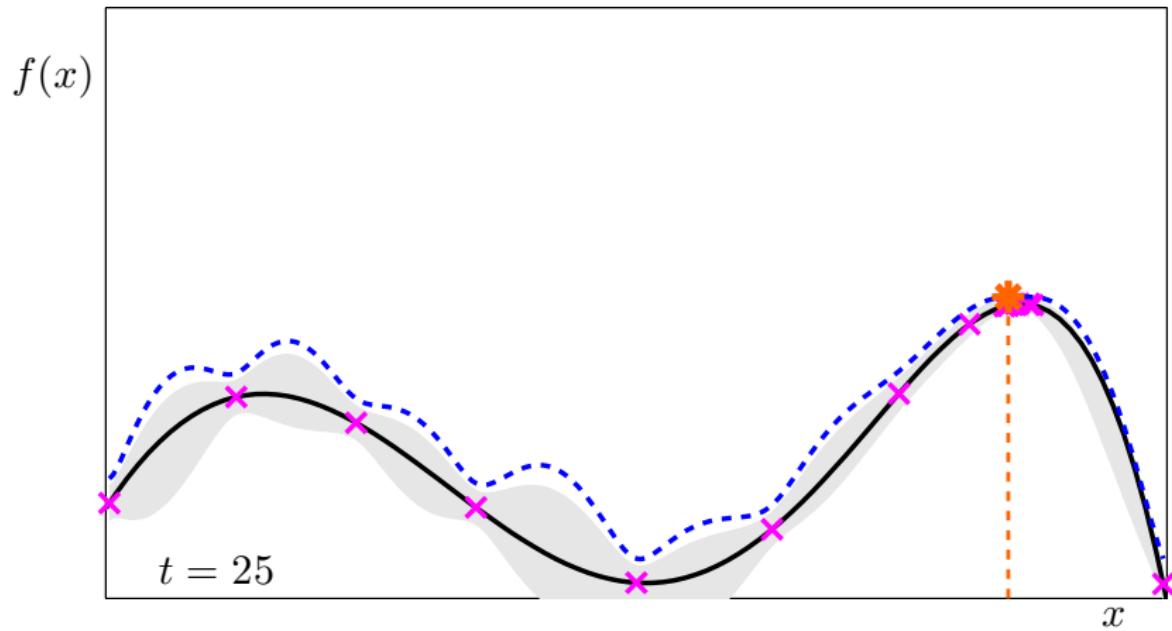










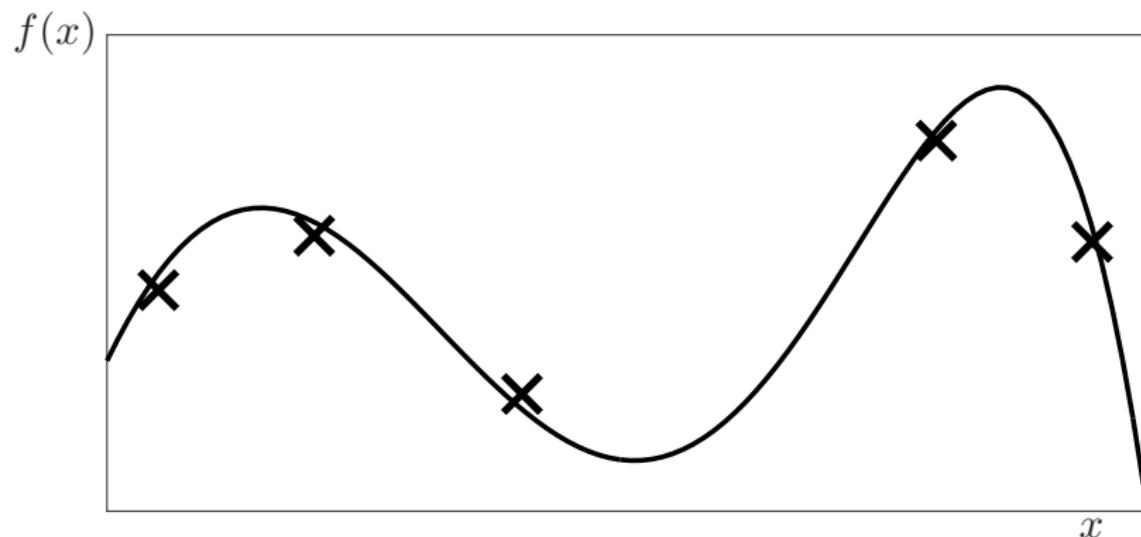


# Bayesian Optimisation with Thompson Sampling

Model  $f \sim \mathcal{GP}(\mathbf{0}, \kappa)$ .

Thompson Sampling (TS)

(Thompson, 1933).



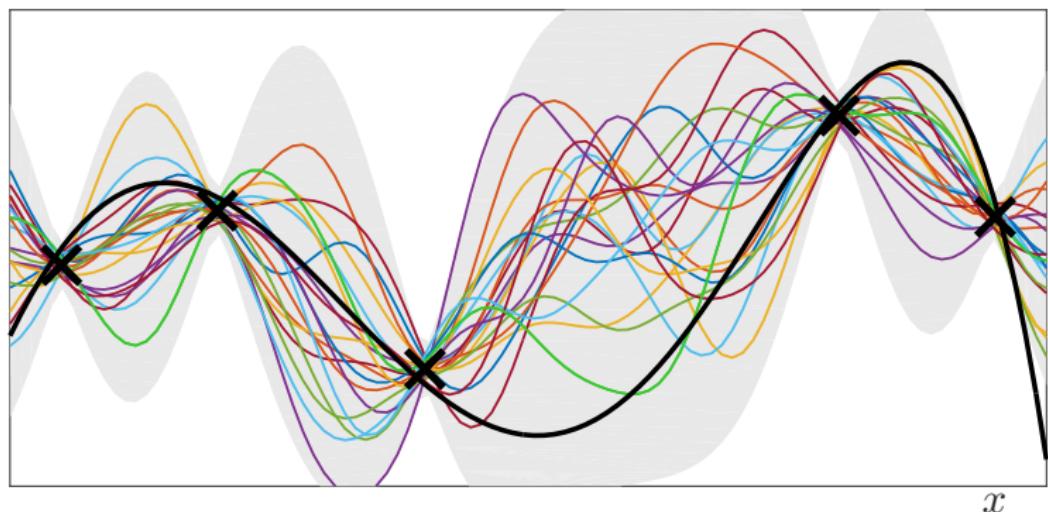
# Bayesian Optimisation with Thompson Sampling

Model  $f \sim \mathcal{GP}(\mathbf{0}, \kappa)$ .

Thompson Sampling (TS)

(Thompson, 1933).

$f(x)$



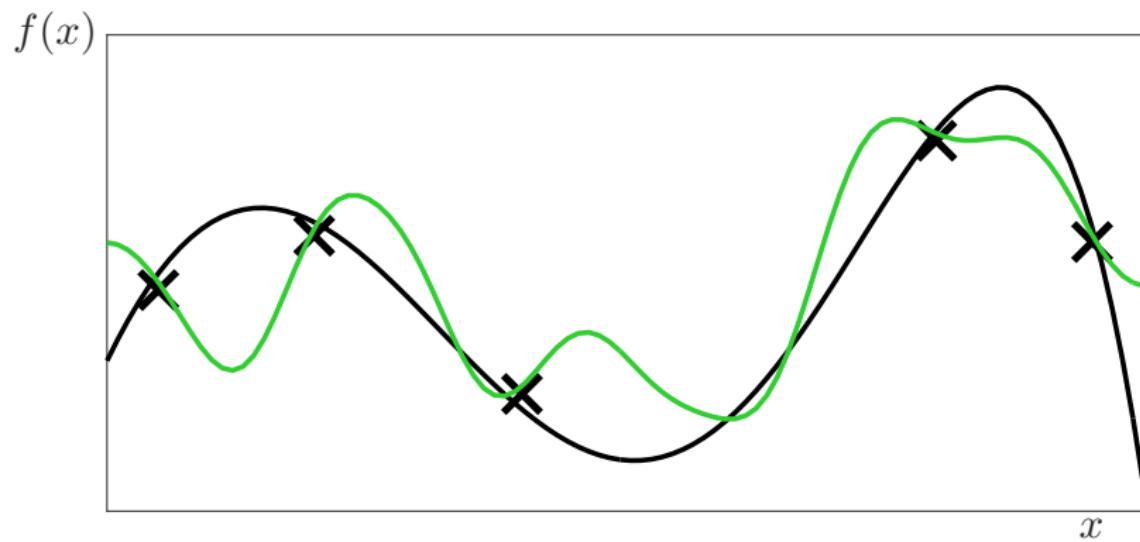
- 1) Construct posterior  $\mathcal{GP}$ .

# Bayesian Optimisation with Thompson Sampling

Model  $f \sim \mathcal{GP}(\mathbf{0}, \kappa)$ .

Thompson Sampling (TS)

(Thompson, 1933).



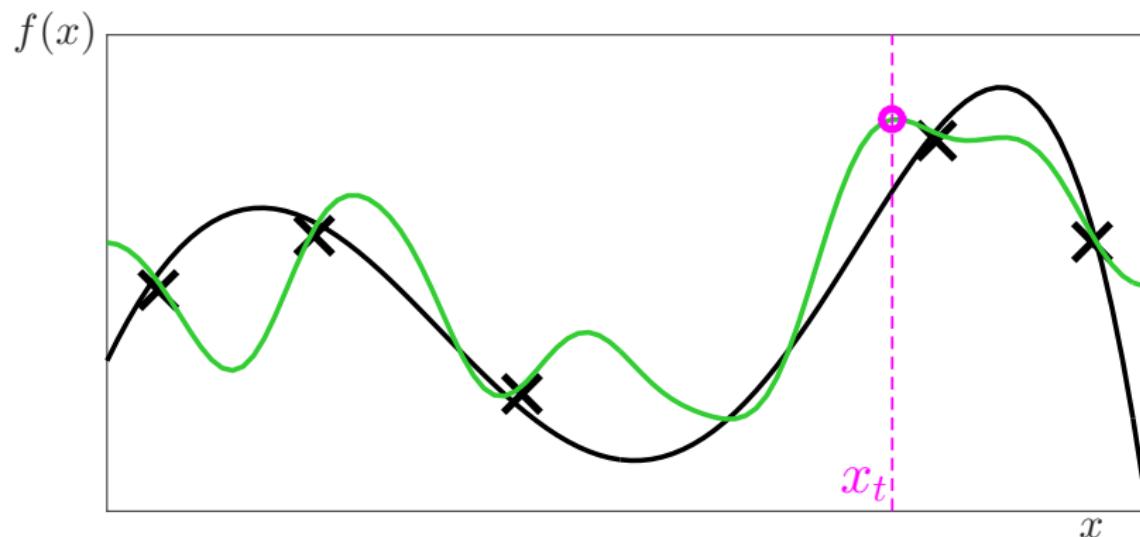
- 1) Construct posterior  $\mathcal{GP}$ .
- 2) Draw sample  $g$  from posterior.

# Bayesian Optimisation with Thompson Sampling

Model  $f \sim \mathcal{GP}(\mathbf{0}, \kappa)$ .

Thompson Sampling (TS)

(Thompson, 1933).



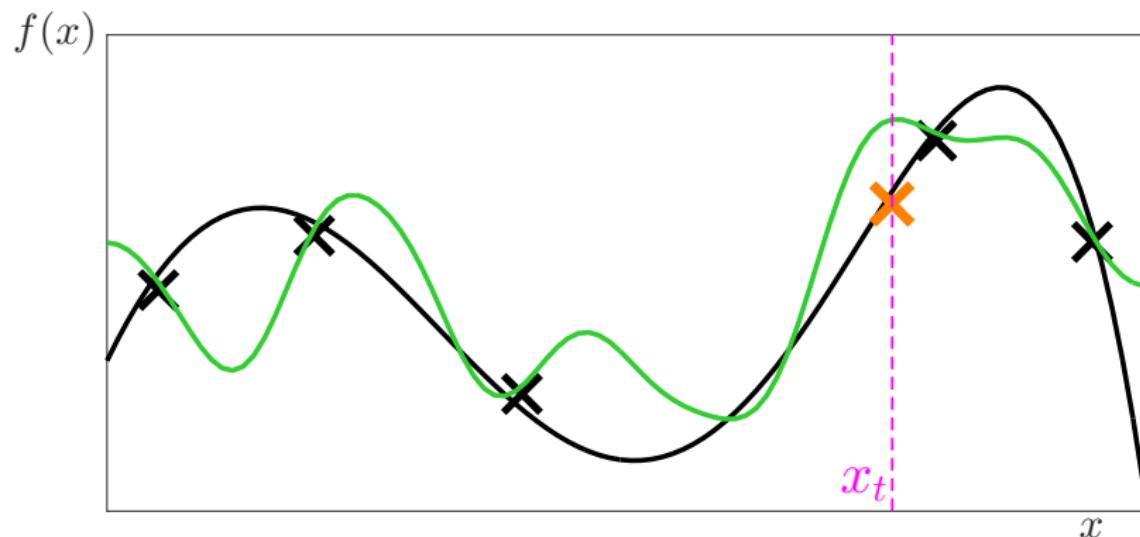
- 1) Construct posterior  $\mathcal{GP}$ .
- 2) Draw sample  $g$  from posterior.
- 3) Choose  $x_t = \operatorname{argmax}_x g(x)$ .

# Bayesian Optimisation with Thompson Sampling

Model  $f \sim \mathcal{GP}(\mathbf{0}, \kappa)$ .

Thompson Sampling (TS)

(Thompson, 1933).



- 1) Construct posterior  $\mathcal{GP}$ .
- 2) Draw sample  $g$  from posterior.
- 3) Choose  $x_t = \operatorname{argmax}_x g(x)$ .
- 4) Evaluate  $f$  at  $x_t$ .

## More on Bayesian Optimisation

Theoretical results: Both UCB and TS will eventually find the optimum under certain smoothness assumptions of  $f$ .

## More on Bayesian Optimisation

Theoretical results: Both UCB and TS will eventually find the optimum under certain smoothness assumptions of  $f$ .

Other criteria for selecting  $x_t$ :

- ▶ Expected improvement (Jones et al. 1998)
- ▶ Probability of improvement (Kushner et al. 1964)
- ▶ Predictive entropy search (Hernández-Lobato et al. 2014)
- ▶ Information directed sampling (Russo & Van Roy 2014)

## More on Bayesian Optimisation

Theoretical results: Both UCB and TS will eventually find the optimum under certain smoothness assumptions of  $f$ .

Other criteria for selecting  $x_t$ :

- ▶ Expected improvement (Jones et al. 1998)
- ▶ Probability of improvement (Kushner et al. 1964)
- ▶ Predictive entropy search (Hernández-Lobato et al. 2014)
- ▶ Information directed sampling (Russo & Van Roy 2014)

Other Bayesian models for  $f$ :

- ▶ Neural networks (Snoek et al. 2015)
- ▶ Random Forests (Hutter 2009)

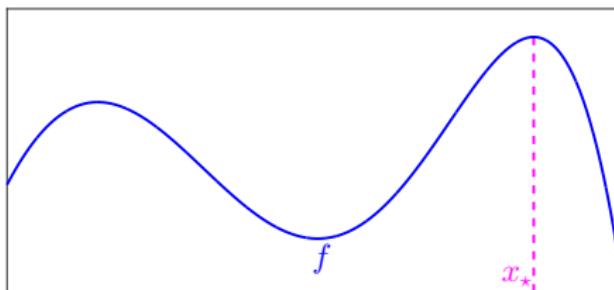
## Some Modern Challenges/Opportunities

1. Multi-fidelity Optimisation (Kandasamy et al. NIPS 2016 a&b, Kandasamy et al. ICML 2017)
  2. Parallelisation (Kandasamy et al. Arxiv 2017)

# 1. Multi-fidelity Optimisation

(Kandasamy et al. NIPS 2016 a&b, Kandasamy et al. ICML 2017)

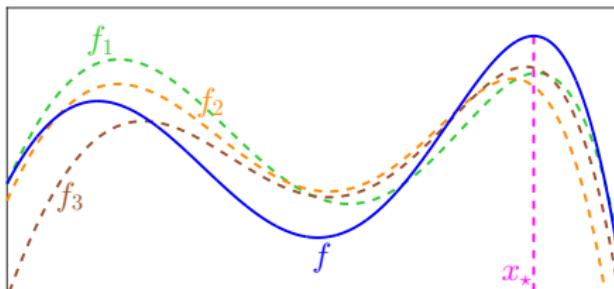
Desired function  $f$  is very expensive, but ...  
we have access to cheap approximations.



# 1. Multi-fidelity Optimisation

(Kandasamy et al. NIPS 2016 a&b, Kandasamy et al. ICML 2017)

Desired function  $f$  is very expensive, but ...  
we have access to cheap approximations.

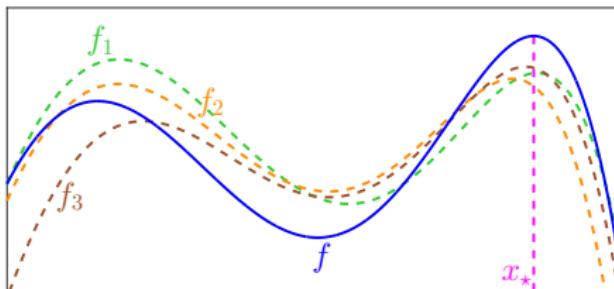


$f_1, f_2, f_3 \approx f$  which  
are cheaper to evaluate.

# 1. Multi-fidelity Optimisation

(Kandasamy et al. NIPS 2016 a&b, Kandasamy et al. ICML 2017)

Desired function  $f$  is very expensive, but ...  
we have access to cheap approximations.

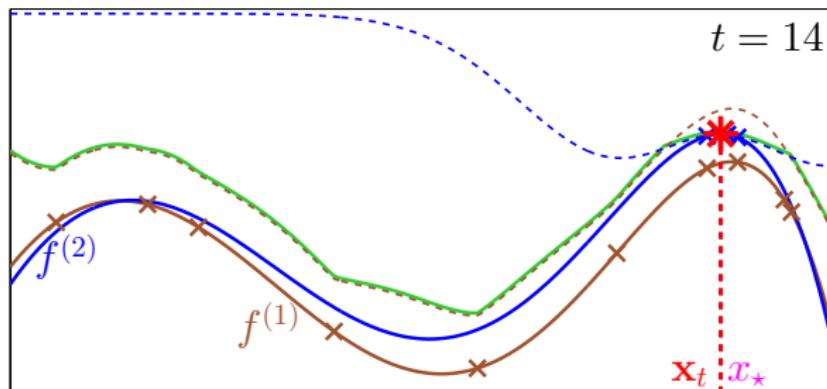


$f_1, f_2, f_3 \approx f$  which  
are cheaper to evaluate.

E.g.  $f$ : a real world battery experiment  
 $f_2$ : lab experiment  
 $f_1$ : computer simulation

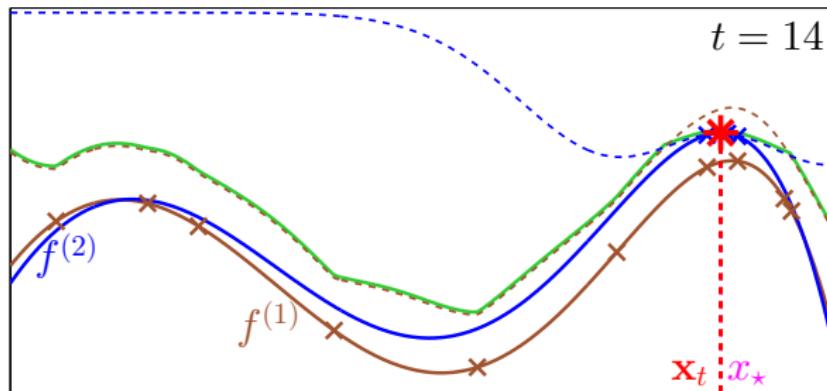
## Multi-fidelity Gaussian Process Upper Confidence Bound

With 2 fidelities (1 Approximation),



## Multi-fidelity Gaussian Process Upper Confidence Bound

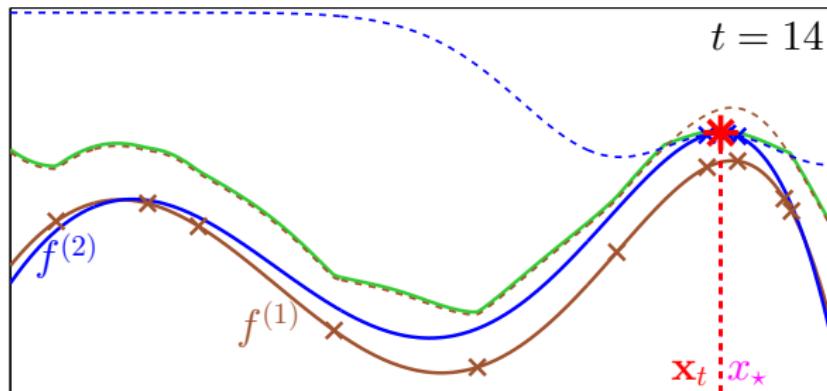
With 2 fidelities (1 Approximation),



**Theorem:** MF-GP-UCB finds the optimum  $x_*$  with less resources than GP-UCB on  $f^{(2)}$ .

## Multi-fidelity Gaussian Process Upper Confidence Bound

With 2 fidelities (1 Approximation),



**Theorem:** MF-GP-UCB finds the optimum  $x_*$  with less resources than GP-UCB on  $f^{(2)}$ .

Can be extended to multiple approximations and continuous approximations.

## Experiment: Cosmological Maximum Likelihood Inference

- ▶ Type Ia Supernovae Data
- ▶ Maximum likelihood inference for 3 cosmological parameters:
  - ▶ Hubble Constant  $H_0$
  - ▶ Dark Energy Fraction  $\Omega_\Lambda$
  - ▶ Dark Matter Fraction  $\Omega_M$
- ▶ Likelihood: Robertson Walker metric (Robertson 1936)  
Requires numerical integration for each point in the dataset.

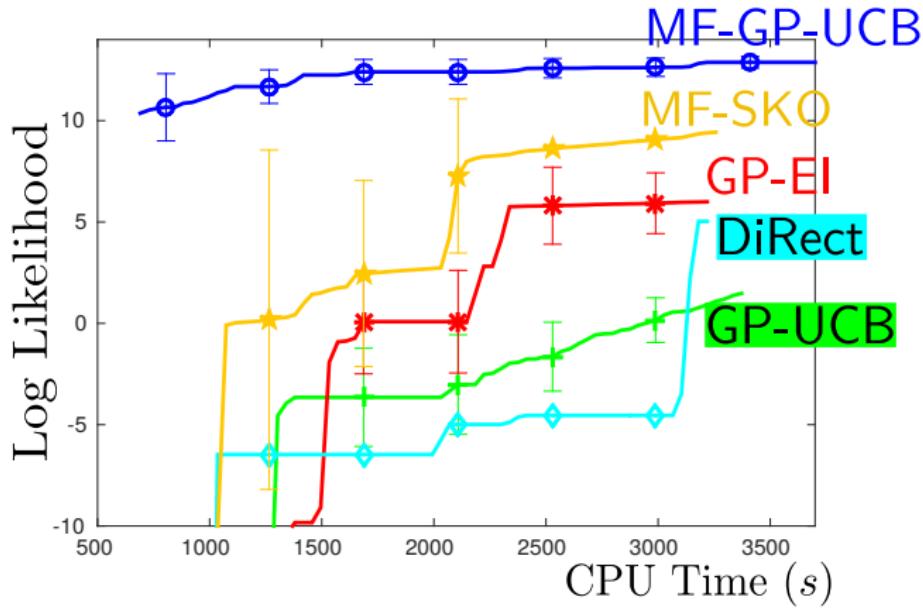
# Experiment: Cosmological Maximum Likelihood Inference

3 cosmological parameters.

$$(d = 3)$$

Fidelities: integration on grids of size  $(10^2, 10^4, 10^6)$ .

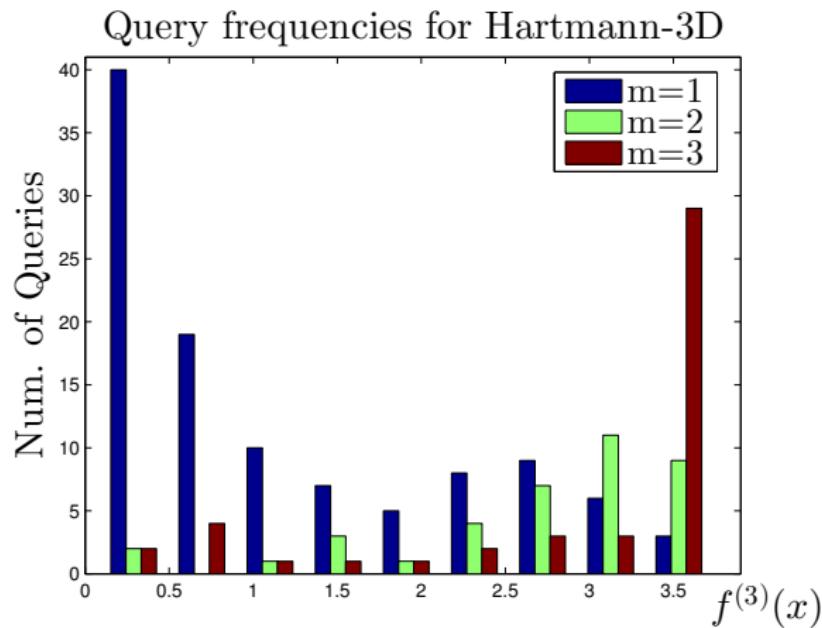
$$(M = 3)$$



## Experiment: Hartmann-3D

2 Approximations (3 fidelities).

We want to optimise the  $m = 3^{\text{rd}}$  fidelity, which is the most expensive.  $m = 1^{\text{st}}$  fidelity is cheapest.



## 2. Parallelising function evaluations

Parallelisation with  $M$  workers: can evaluate  $f$  at  $M$  different points at the same time.

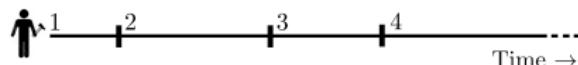
E.g.: Test  $M$  different battery solvents at the same time.

## 2. Parallelising function evaluations

Parallelisation with  $M$  workers: can evaluate  $f$  at  $M$  different points at the same time.

E.g.: Test  $M$  different battery solvents at the same time.

Sequential evaluations with one worker

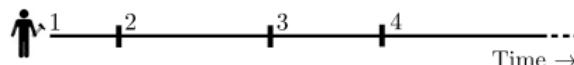


## 2. Parallelising function evaluations

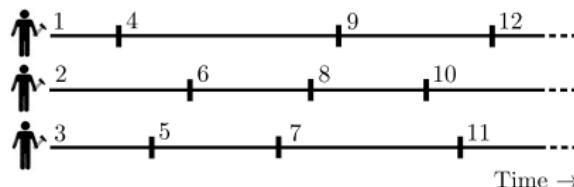
Parallelisation with  $M$  workers: can evaluate  $f$  at  $M$  different points at the same time.

E.g.: Test  $M$  different battery solvents at the same time.

Sequential evaluations with one worker



Parallel evaluations with  $M$  workers (Asynchronous)

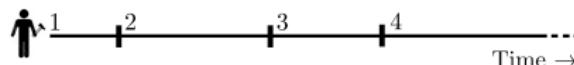


## 2. Parallelising function evaluations

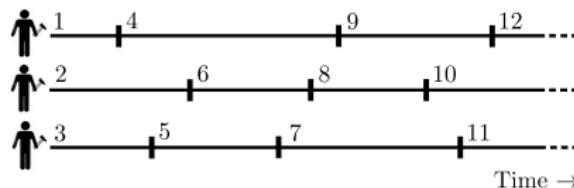
Parallelisation with  $M$  workers: can evaluate  $f$  at  $M$  different points at the same time.

E.g.: Test  $M$  different battery solvents at the same time.

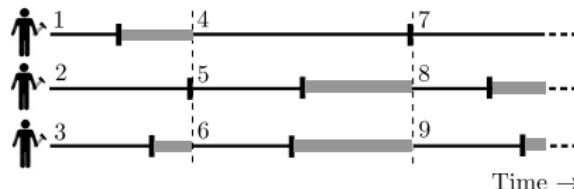
Sequential evaluations with one worker



Parallel evaluations with  $M$  workers (Asynchronous)



Parallel evaluations with  $M$  workers (Synchronous)

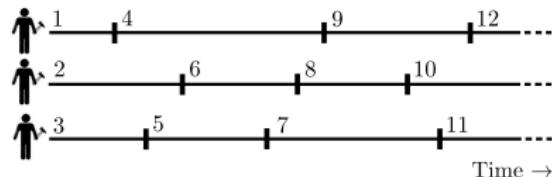


## Asynchronous: asyTS

---

At any given time,

1.  $(x', y') \leftarrow$  Wait for  
a worker to finish.
  2. Compute posterior  $\mathcal{GP}$ .
  3. Draw a sample  $g \sim \mathcal{GP}$ .
  4. Re-deploy worker at  
 $\text{argmax } g$ .
- 



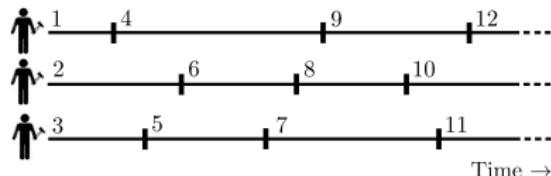
# Parallel Thompson Sampling

(Kandasamy et al. Arxiv 2017)

## Asynchronous: asyTS

At any given time,

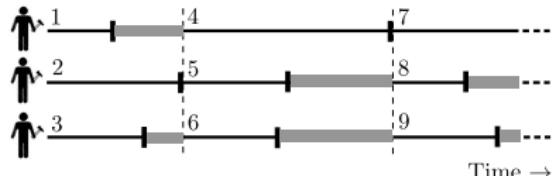
1.  $(x', y') \leftarrow$  Wait for a worker to finish.
2. Compute posterior  $\mathcal{GP}$ .
3. Draw a sample  $g \sim \mathcal{GP}$ .
4. Re-deploy worker at  $\text{argmax } g$ .



## Synchronous: synTS

At any given time,

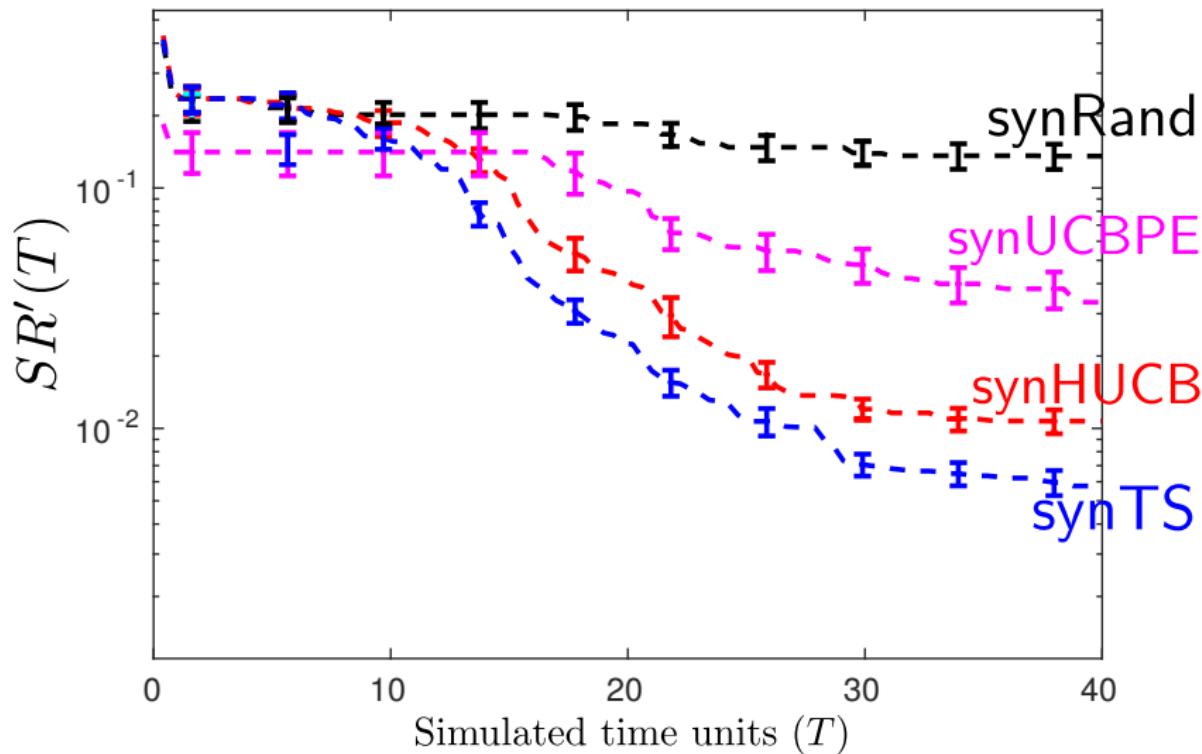
1.  $\{(x'_m, y'_m)\}_{m=1}^M \leftarrow$  Wait for all workers to finish.
2. Compute posterior  $\mathcal{GP}$ .
3. Draw  $M$  samples  $g_m \sim \mathcal{GP}, \forall m$ .
4. Re-deploy worker  $m$  at  $\text{argmax } g_m, \forall m$ .



# Experiment: Branin-2D

$M = 4$

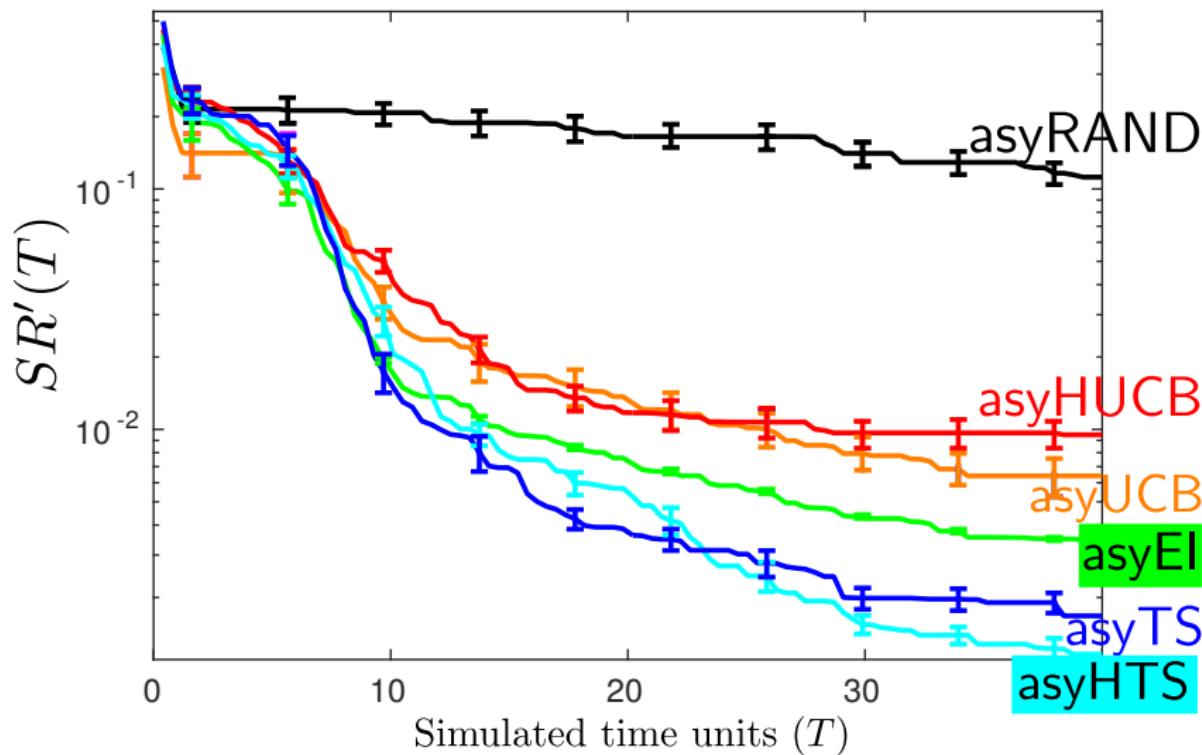
Evaluation time sampled from a uniform distribution



# Experiment: Branin-2D

$M = 4$

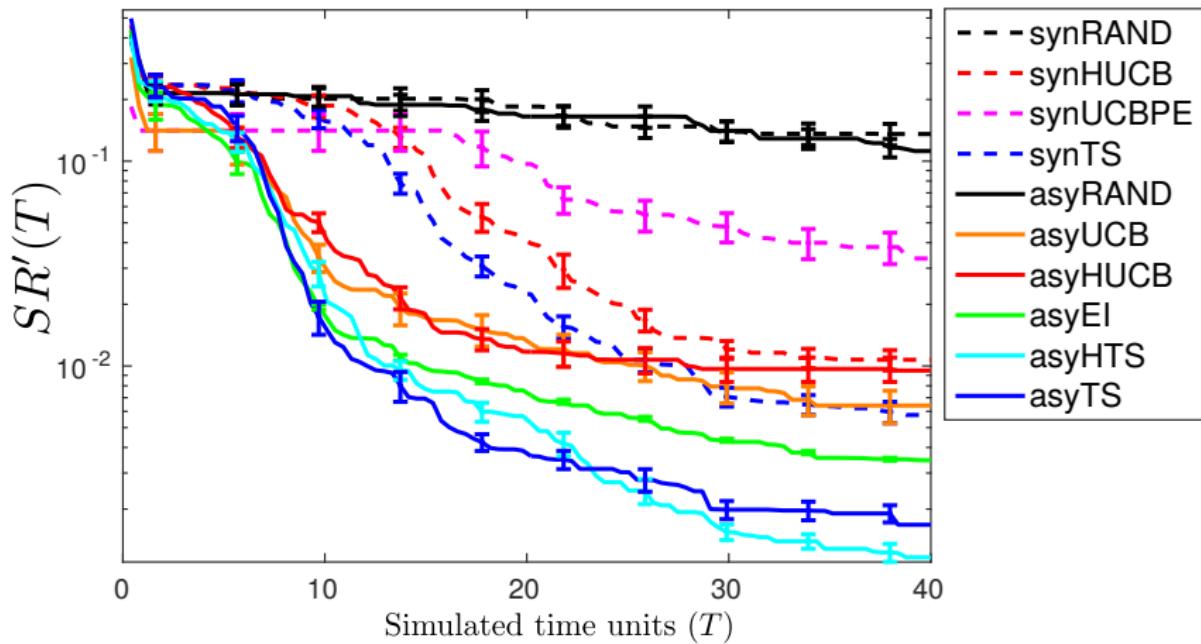
Evaluation time sampled from a uniform distribution



# Experiment: Branin-2D

$M = 4$

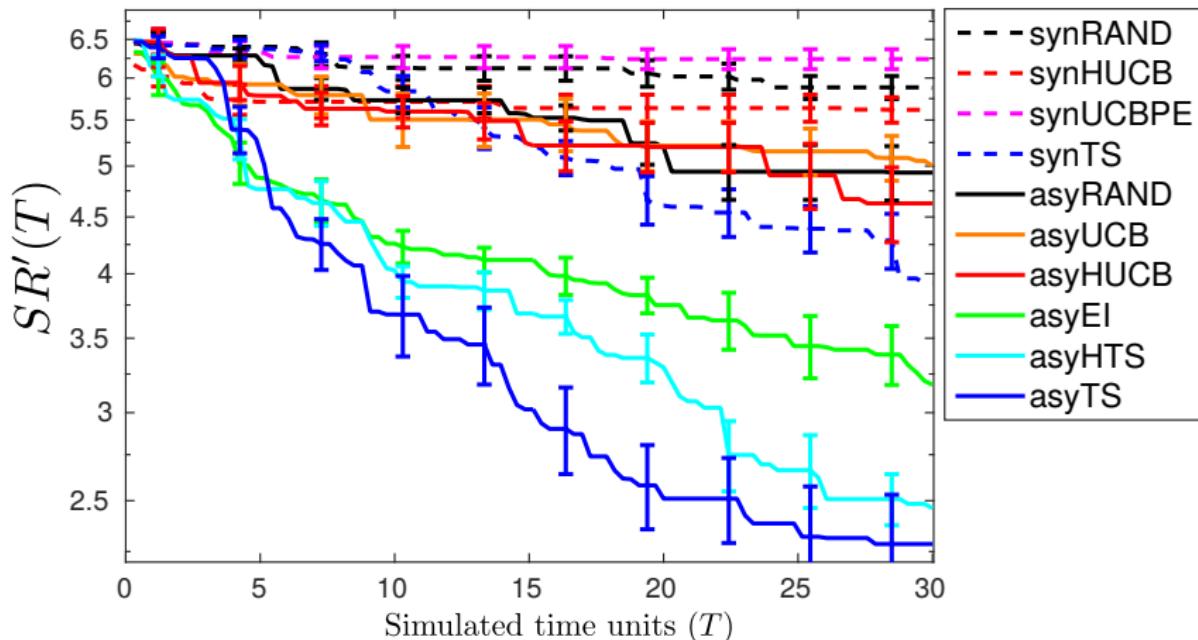
Evaluation time sampled from a uniform distribution



# Experiment: Hartmann-18D

$M = 25$

Evaluation time sampled from an exponential distribution



# Summary

- ▶ Black-box Optimisation methods are used in several scientific and engineering applications.
- ▶ Bayesian Optimisation: A method for black-box optimisation which uses Bayesian uncertainty estimates for  $f$ .
- ▶ Some modern challenges
  - ▶ Multi-fidelity optimisation
  - ▶ Parallel evaluations
  - ▶ and several more ...

## Summary

- ▶ Black-box Optimisation methods are used in several scientific and engineering applications.
- ▶ Bayesian Optimisation: A method for black-box optimisation which uses Bayesian uncertainty estimates for  $f$ .
- ▶ Some modern challenges
  - ▶ Multi-fidelity optimisation
  - ▶ Parallel evaluations
  - ▶ and several more ...

Thank you.

Slides are up on my website: [www.cs.cmu.edu/~kkandaswamy](http://www.cs.cmu.edu/~kkandaswamy)