

Stochastic Calculus

Problem Set 7

2. ATC 15.1

pricing function $F(t, x)$, $\Phi(X(T))$

prove proposition 15.4 ($dF = rF dt + \{ \} dW$ form)

→ dynamics of X under measure \mathbb{Q}

$$dX = \underbrace{(\mu - \lambda \delta)}_{=r} X_t dt + \delta X_t dW_t \quad (dX^2 = \delta^2 X^2 dt)$$

→ Ito's formula on F

$$dF = \frac{\partial F}{\partial t} dt + \frac{\partial F}{\partial x} dX + \frac{1}{2} \frac{\partial^2 F}{\partial x^2} dX^2$$

$$= \underbrace{\left(\frac{\partial F}{\partial t} + X(\mu - \lambda \delta) \frac{\partial F}{\partial x} + \frac{1}{2} \delta^2 X^2 \frac{\partial^2 F}{\partial x^2} \right)}_{=rF} dt + X \delta \frac{\partial F}{\partial x} dW_t^{\mathbb{Q}} = rF dt + \delta F_x dW^{\mathbb{Q}}.$$

$\underbrace{\hspace{10em}}_{=rF \text{ (given in the question)}}$

$$\therefore \frac{\partial F}{\partial t} + \underbrace{(\mu - \lambda \delta)}_r X \frac{\partial F}{\partial x} + \frac{1}{2} \delta^2 X^2 \frac{\partial^2 F}{\partial x^2} - rF = 0 \quad (\text{satisfying PDE})$$

3.a) $F = C(t, X_t)$, $G = 0$ $dC_t = rC_t dt + \delta C_t dW_t$

Itô's lemma $dF = \frac{\partial F}{\partial t} dt + \frac{\partial F}{\partial X} dX_t + \frac{1}{2} \frac{\partial^2 F}{\partial X^2} dX_t^2$

$$= \frac{\partial F}{\partial t} dt + \frac{\partial F}{\partial X} (-\lambda(X_t - \bar{X}) dt + \delta dW_t) + \frac{1}{2} \delta^2 \frac{\partial^2 F}{\partial X^2} dt$$

$$= \left[\frac{\partial F}{\partial t} - \lambda(X_t - \bar{X}) \frac{\partial F}{\partial X} + \frac{1}{2} \delta^2 \frac{\partial^2 F}{\partial X^2} \right] \frac{F}{F} dt + \delta \frac{\partial F}{\partial X} \frac{F}{F} dW_t$$

$$\therefore \frac{\partial F}{\partial t} - \lambda(X_t - \bar{X}) \frac{\partial F}{\partial X} + \frac{1}{2} \delta^2 \frac{\partial^2 F}{\partial X^2} = 0, \quad \delta F = \frac{\partial F}{\partial X} F$$

Form riskless portfolio with F and G .

$$dV = \underbrace{(u_F \frac{\partial F}{\partial t} + u_G \frac{\partial G}{\partial t}) V}_{\rightarrow r} dt + \underbrace{(u_F \delta F + u_G \delta G) V}_{\rightarrow 0} dW_t$$

$$\Rightarrow \begin{cases} 1. u_F + u_G = 1 \\ 2. u_F \delta F + u_G \delta G = 0 \end{cases} \Rightarrow u_F = -\frac{\delta G}{\delta F - \delta G}, \quad u_G = \frac{\delta F}{\delta F - \delta G}$$

$$\therefore dV = V \left[-\frac{\delta G}{\delta F - \delta G} (\frac{\partial F}{\partial t} dt + \delta F dW_t) + \frac{\delta F}{\delta F - \delta G} (\frac{\partial G}{\partial t} dt + \delta G dW_t) \right]$$

$$= V \left[\frac{1}{\delta F - \delta G} (-\frac{\partial F}{\partial t} \delta G dt - \delta F \delta G dW_t + \frac{\partial G}{\partial t} \delta F dt + \delta F \delta G dW_t) \right]$$

$$= V \left[\frac{\frac{\partial G}{\partial t} \delta F - \frac{\partial F}{\partial t} \delta G}{\delta F - \delta G} \right] dt$$

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From Q2, $\frac{\frac{\partial F}{\partial t} - r}{\delta F} = \lambda(t, X_t)$

$$\frac{\partial F}{\partial t} = \frac{\partial C}{\partial t} = r$$

$$\therefore \frac{r - r}{\delta F} = \boxed{0 = \lambda(t, X_t)}$$

3. b) Analytical price for the option with payoff (1): $\max(X_T - K, 0)$

$$dC_t = rC_t dt + \delta C_t d\bar{W}_t$$

let's put $Z_t = e^{-rt} C_t$ (discounted process of C_t).

$$\begin{aligned} \therefore dZ_t &= -r e^{-rt} C_t dt + e^{-rt} dC_t \\ &= -r e^{-rt} C_t dt + e^{-rt} (r C_t dt + \delta C_t d\bar{W}_t) \\ &= \delta e^{-rt} C_t d\bar{W}_t \\ &= \delta Z_t d\bar{W}_t \quad (\text{martingale}) \end{aligned}$$

$$\begin{aligned} Z_T - Z_t &= \int_t^T \delta Z_s d\bar{W}_s \\ Z_T &= Z_t + \int_t^T \delta Z_s d\bar{W}_s \end{aligned} \Rightarrow E(Z_T) = Z_t + E\left[\int_t^T \delta Z_s d\bar{W}_s\right] \xrightarrow{0}$$

$$\therefore E(Z_T) = E(e^{-rT} C_T) = e^{-rt} C_t$$

$$\begin{aligned} \therefore C_t &= e^{-r(T-t)} E(C_T | \mathcal{X}_t) \\ &= e^{-r(T-t)} E(\max(X_T - K, 0) | \mathcal{X}_t) \end{aligned} \xrightarrow{\lambda \cdot P(\lambda)}$$

$$d\mathcal{X}_t = -\lambda(\mathcal{X}_t - \bar{\lambda})dt + \delta d\bar{W}_t$$

let's put $Y_t = e^{\lambda t} \mathcal{X}_t$

$$\therefore dY_t = \lambda e^{\lambda t} \mathcal{X}_t dt + e^{\lambda t} d\mathcal{X}_t$$

$$\begin{aligned} E\left[\left(\int_t^T \delta e^{-\lambda(T-s)} d\bar{W}_s\right)^2\right] &= \lambda e^{\lambda t} \mathcal{X}_t dt + e^{\lambda t} (-\lambda(\mathcal{X}_t - \bar{\lambda})dt + \delta d\bar{W}_t) \\ &= \lambda \bar{\lambda} e^{\lambda t} dt + \delta e^{\lambda t} d\bar{W}_t \end{aligned}$$

$$-2\lambda(T-s) = u$$

$$\frac{du}{ds} = 2\lambda \Rightarrow ds = \frac{1}{2\lambda} du$$

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$$\delta^2 \frac{1}{2\lambda} E\left[\int_t^T e^u du\right]$$

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$$\delta^2 \frac{1}{2\lambda} \left[e^{-2\lambda(T-T)} - e^{-2\lambda(T-t)} \right]$$

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$$\delta^2 \frac{1 - e^{-2\lambda(T-t)}}{2\lambda}$$

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$$\text{Var}\left(\int_t^T \delta e^{-\lambda(T-s)} d\bar{W}_s\right)$$

$$\xrightarrow{\lambda = u \Rightarrow \frac{du}{ds} = \lambda \Rightarrow ds = \frac{1}{\lambda} du} \bar{\lambda} \cdot \lambda \cdot \frac{1}{\lambda} \int_t^T e^u du = \bar{\lambda} (e^{\lambda T} - e^{\lambda t})$$

$$Y_T - Y_t = \lambda \bar{\lambda} \int_t^T e^{\lambda s} ds + \int_t^T \delta e^{\lambda s} d\bar{W}_s$$

$$= \bar{\lambda} (e^{\lambda T} - e^{\lambda t}) + \int_t^T \delta e^{\lambda s} d\bar{W}_s$$

$$\therefore E(Y_T) = Y_t + \bar{\lambda} (e^{\lambda T} - e^{\lambda t}) + \int_t^T \delta e^{\lambda s} d\bar{W}_s \xrightarrow{0}$$

$$E(\mathcal{X}_T) = e^{-\lambda(T-t)} \mathcal{X}_t + \bar{\lambda} (1 - e^{-\lambda(T-t)}) + \int_t^T \delta e^{-\lambda(T-s)} d\bar{W}_s$$

$$\therefore \mathcal{X}_T \sim N\left(e^{-\lambda(T-t)} (\mathcal{X}_t - \bar{\lambda}) + \bar{\lambda}, \delta^2 \frac{1 - e^{-2\lambda(T-t)}}{2\lambda}\right)$$

$$\delta_2 = \delta \sqrt{\frac{1 - e^{-2\lambda(T-t)}}{2\lambda}}$$

$$\therefore C_t = e^{-r(T-t)} \int_0^\infty \max(\mathcal{X}_T - K, 0) f(\mathcal{X}) d\mathcal{X} = e^{-r(T-t)} \int_K^\infty (\mathcal{X} - K) f(\mathcal{X}) d\mathcal{X}$$

$$= e^{-r(T-t)} \int_K^\infty \mathcal{X} f(\mathcal{X}) d\mathcal{X} - K e^{-r(T-t)} \int_K^\infty f(\mathcal{X}) d\mathcal{X}$$

$$= e^{-r(T-t)} \int_K^\infty \mathcal{X} f(\mathcal{X}) d\mathcal{X} - K e^{-r(T-t)} N(d_2)$$

$$f(\mathcal{X}) = \frac{1}{\sqrt{2\pi} \delta_2} e^{-\frac{1}{2} \left(\frac{\mathcal{X} - \bar{\lambda}}{\delta_2}\right)^2}$$

$$d_2 = \frac{e^{\lambda(T-t)} (\mathcal{X}_t - \bar{\lambda}) + \bar{\lambda} - K}{\delta \sqrt{1 - e^{-2\lambda(T-t)}} / 2\lambda}$$

$$\delta \sqrt{1 - e^{-2\lambda(T-t)}} / 2\lambda$$