Huaze (Patrick) Liu

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EDUCATION

Harvey Mudd College   Claremont, CA

B.S., Computer Science & Mathematics │ Major GPA: 3.899 | Dean's List   *Aug 2022 - May 2026*

Selected Coursework: Data Structures, Algorithms, Computer Vision, Neural Networks, Machine Learning, Reinforcement Learning, Natural Language Processing, ODEs, Intermediate Probability, Real Analysis, Optimization[1], Advanced Systems Engineering, Digital Signal Processing, State Estimation.

SKILLS

Programming Language: Python • C++ • C# • Java • SQL • MATLAB • R

Software/Tools: Visual Studio • GitHub/Git • Linux • ROS2 • Issac Sim/Lab/Gym • MuJoCo • Docker • Jupyter

Technical Skills: 2D/3D Computer Vision • Sensor Fusion • Robotics Manipulation • Autonomous Navigation • Reinforcement Learning

EXPERIENCE

Visiting Scholar | Hao Su's Lab

University of California, San Diego   *La Jolla, CA, June 2025 - Present*

- Designed an egocentric object trajectory prediction module and integrated it into upper-body catching policy training for humanoid robots using Isaac Gym.
- Built a graph-structured design and control pipeline for robotic hands, combining model predictive path integral control, structural mutation, and reward-driven optimization in MuJoCo.

Undergraduate Research Intern | MADD Lab | Website

Harvey Mudd College   *Claremont, CA, July 2024 - Present*

- Designed a traffic scene scoring system to adapt GPS measurement weights based on visual context, improving localization accuracy by 16.8% in low-satellite and high-noise urban settings.
- Built a multimodal anomaly detection pipeline that integrates image and LiDAR semantic segmentation, using distributional and geometric cues to identify structural scene changes in urban maps.
- Evaluated split conformal prediction on segmentation and detection tasks using CLIPSeg and Grounding DINO, demonstrating reliable pixel-level coverage and uncovering design limitations in object-level uncertainty estimation.

Teaching Assistant

Harvey Mudd College   *Claremont, CA, January 2024 - Present*

- Held weekly tutoring sessions and graded homework for CSCI070 – Data Structures & Program Development (2024 Spring, 2024 Fall), CSCI153 – Computer Vision (2024 Fall, 2025 Spring, 2025 Fall), and ENGR207 – Digital Signal Processing (2025 Spring).

Undergraduate Research Intern | Spike Lab | Website

Pomona College   *Claremont, CA, April - Dec. 2024*

- Developed and analyzed biologically inspired RNNs trained via Evolutionary Algorithms, integrating custom loss and comparing with Back Propagation.

Research Intern | Lab for CATS (Cognition & Attention in Time & Space)

Harvey Mudd College   *Claremont, CA, August 2023 - May 2024*

- Investigated the effects of padding-induced non-veridical representation on CNN performance with Mask R-CNN reveal significant spatial performance degradation near image boundaries.

UCSF ci2 Summer Fellowship | Biomagnetic Imaging Laboratory | Website

Univ. of California, San Francisco   *San Francisco, CA, May - August, 2023*

- Built and trained Machine Learning models for Tinnitus classification using fMRI and MEG data, achieving 72.4% accuracy and benchmarking against a Graph-CNN baseline.

PROJECTS

A Vision-based Localization and Path Planning TurtleBot System | Language: Python | Report   *Mar. - May 2025*

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[1] *Optimization* is a graduate-level course at Claremont Graduate University taught by Prof. Marina Chugunova.

- Developed a vision-based search TurtleBot 4, implementing and comparing EKF and UKF for state estimation and target tracking in the Webot Simulation Software.
- Used the A* algorithm to compute and follow an optimal path to the GPS coordinates.

A Multi-Objective Acquisition Function of Bayesian Optimization | Language: Python | Report   *Mar. - May 2025*
- Developed a lightweight multi-objective acquisition function (Scalarized-UCB) for Bayesian Optimization
- Tested by benchmarking on SVM and CNN models, reducing latency by 8% at equivalent accuracy compared to EI and UCB.

A Study of Vision Transformer for Traffic Object Detection | Language: Python | GitHub Repo   *Nov. - Dec. 2024*
- Fine-tuned DETR, Deformable DETR, and RT-DETR on the KITTI dataset, integrating custom metrics, class-wise AP, and inference time analysis.
- Achieved 71.0% mAP (50) and 43.5% mAP (50:95) with 18.1ms inference time, showcasing efficient transfer learning and real-time performance.

Dynamic Time Warping with Confidence Intervals | Language: Python | GitHub Repo   *April - May 2024*
- Applied Dynamic Time Warping (DTW) with dynamic programming to develop new metrics and visualizations for alignment confidence in time series.
- Enhanced signal alignment reliability using "valley width" in cost matrices and sliding window comparisons with the FlexDTW algorithm.

Real-Time Object Detection Software | Language: Python | GitHub Repo   *Oct. - Dec. 2023*
- Worked with three members to create an efficient YOLO v.1 model that classifies objects using bounding boxes
- Conducted extensive testing using the PASCAL VOC dataset to achieve advanced predictions (65% mAP)

Spampede Game | Language: Java | GitHub Repo   *April - May 2023*
- Designed a custom "Snake Game" UI and backend functionality in Java using the MVC software design pattern.
- Developed an automated game mode that prompts the AI to find optimal paths using BFS algorithms.

Connect-Four Board Game | Language: Python, JavaScript, CSS | GitHub Repo   *Nov. - Dec. 2022*
- Built a full-stack Connect Four app with a Flask backend and React frontend.
- Integrated AI for automated gameplay and RESTful APIs for client-server interaction.

AWARDS & SCHOLARSHIP

- Harvey Mudd College Shanahan Projects Fund – Awarded **$11,000** for the development of an underwater autonomous pool-cleaning system.   *October 2024 – May 2025*
- Harvey Mudd College Student Travel Grant – Awarded **$2,500** to attend the 38th International Technical Meeting of the Satellite Division of the Institute of Navigation (ION GNSS+) in Baltimore, Maryland.   *May 2025*

PUBLICATIONS

Liu, H.*, Mohanty, A. (2025). Conformal Prediction Meets Test-Time Uncertainty in Vision Foundation Models. Trustworthy FMs Workshop at the International Conference on Computer Vision (ICCV) 2025, Honolulu.

Liu, H.*, Gao, Z*., Mohanty, A. (2025). Language-Driven Semantic Change Detection in Urban Maps via Multi-Modal Deep Learning. the 38th International Technical Meeting of the Satellite Division of the Institute of Navigation (ION GNSS+ 2025), Baltimore.

Qu, I., **Liu, H.**, Li, J., Zhu, Y. (2024). Evolutionary algorithms support recurrent plasticity in spiking neural network models of neocortical task learning (Poster). Bernstein Conference, Frankfurt, Germany. https://doi.org/10.12751/nncn.bc2024.128.